



# Secure PLC Coding Tips and Tricks

Jacob Brodsky, PE; Jacobs Cyber Security Group

S4 Technical Branch Conference 2020

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# Why Discuss This?

- Security specialists do not know how process works
- Engineers are not taught good programming habits
- Good code leads to more rapid diagnostics
  - Can determine and isolate hacks more rapidly
  - Make working with protocol sensitive firewalls easier



Here there be dragons

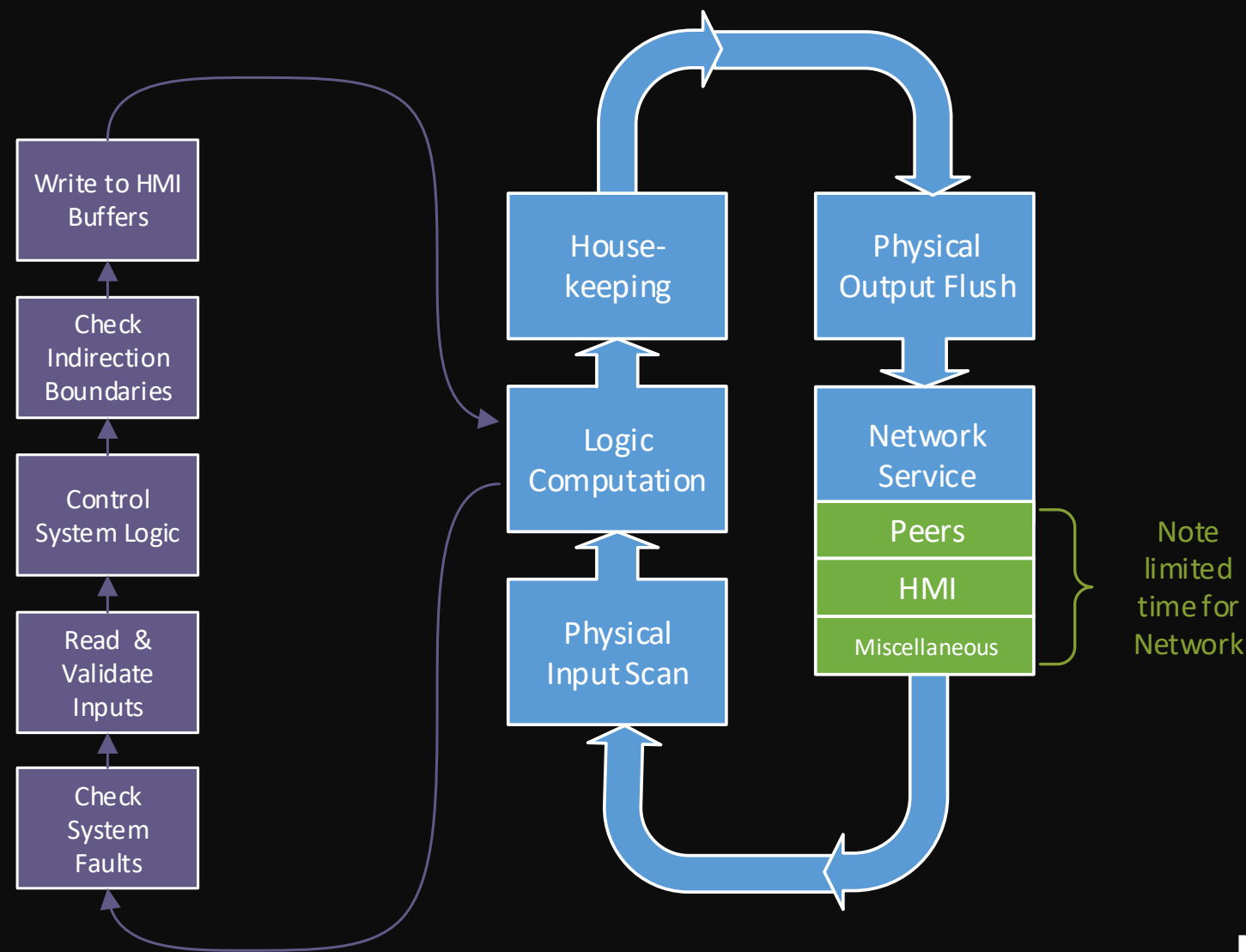
# What Languages to use?

- Four Primary Languages
  - Instruction **L**ist (**IL**)
  - Ladder **D**iagrams (**LD**)
  - Function **B**lock **D**iagram (**FBD**)
  - Structured **T**ext (**ST**)
- **S**equential **F**unction **C**harts (**SFC**) for handling state changes
- **IL** good for speed and portability
- **ST** good for high level math
- **LD** and **FBD** good for permissives, interlocks, timed operations

# Avoid Programming All Logic in One Controller

- Keep Program segments small
  - Use more complex blocks to simplify ladder
  - Break LD or ST segments in to smaller parts
- Use peer to peer networking among other controllers
  - Code for failure of Peer Communications
  - Consider what each small controller should do if isolated
- Keep Controller close to I/O

# Typical PLC Scan Cycle

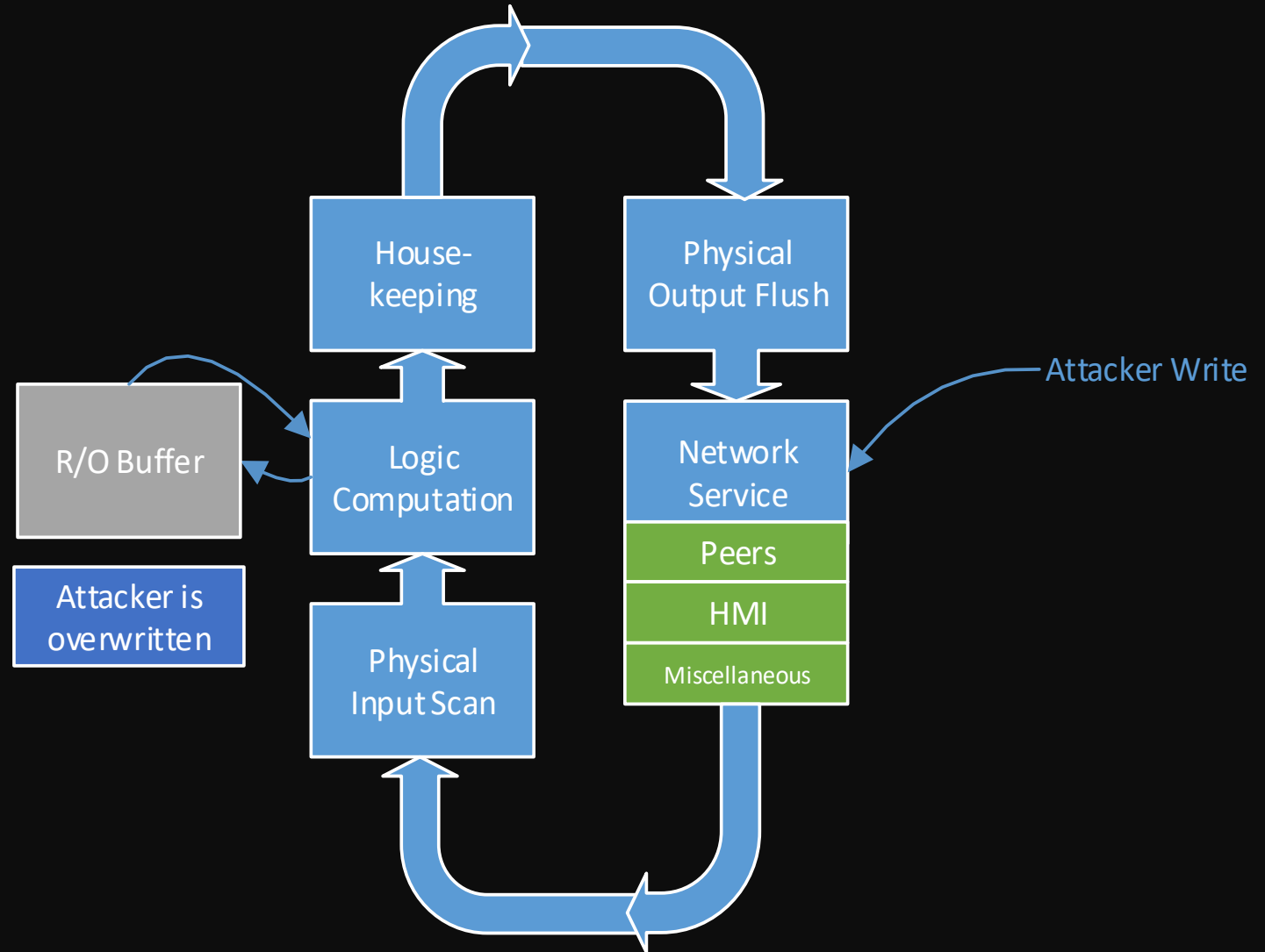


# HMI Reads/Writes ONLY from Designated Array/Structure

- All Display Values in R/O Buffer
- All Values written by HMI are Validated
- Context Sensitive Firewall rules easier to handle

# How This Keeps Attackers At Bay

1. Attacker Writes to Buffer
2. Logic Recomputes
3. Overwrites Attack Data
4. Network Service Reports no change

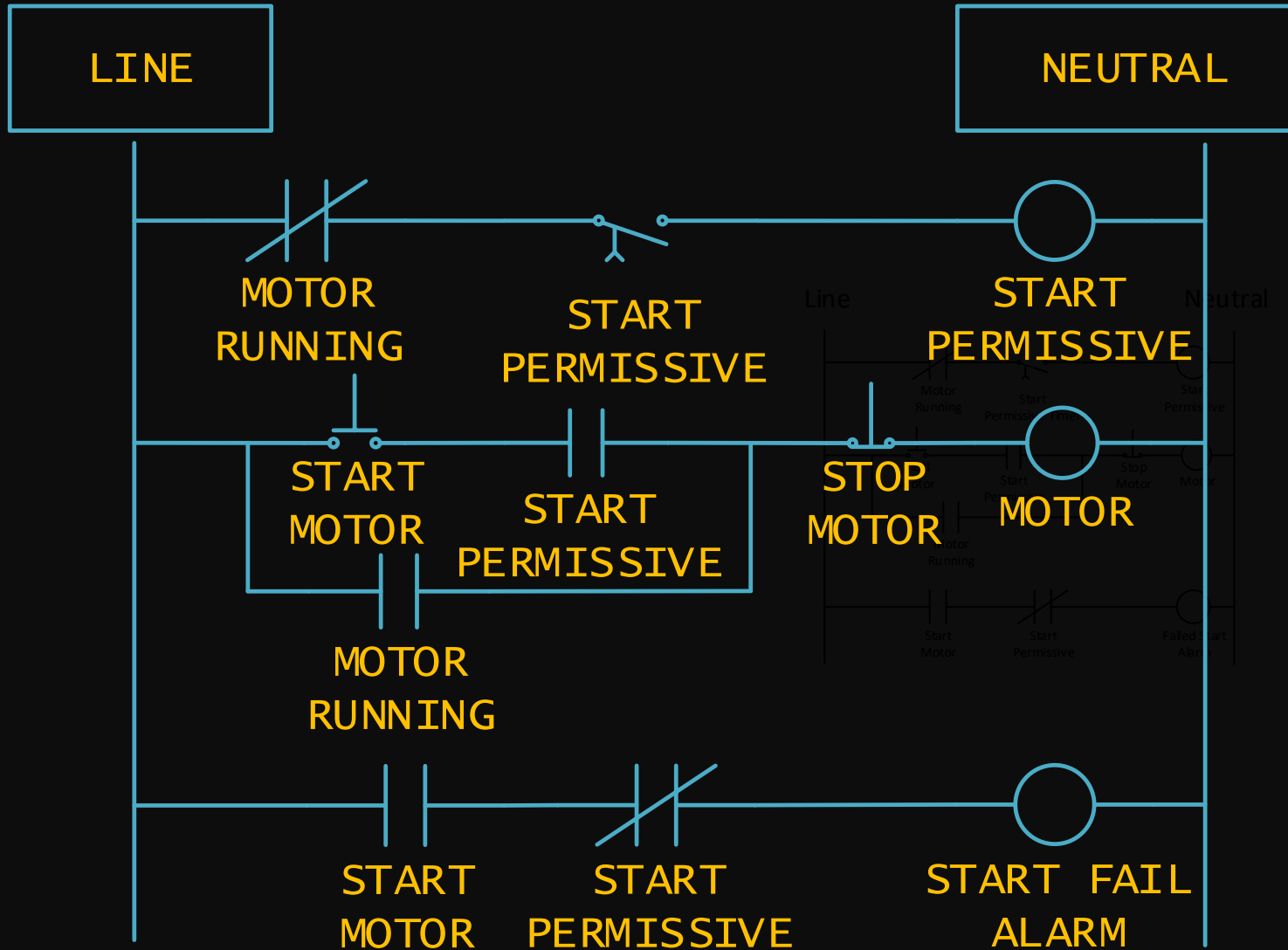


# Validate Inputs and Outputs

- Validate Counter/Timer inputs
  - Do you WANT a value of 655.35 seconds for a 1.35 second timer?
- Debounce/Filter Inputs
- **Forward** & **Reverse**, **Open** & **Close**, **Start** & **Stop** asserted together?
- Have PLC Application Alarm points for HMI
- Limit what you can send/receive to Variable Frequency Drives
  - Consider using 4-20 mA control lines instead of network
- Are motors/actuators being restarted or moved too frequently?



# Motor Restart Delay



**Motor NOT Running**  
must Time Out before  
permitting **Start Motor**  
Command.

If Attempt to start Motor during this time, raise **Start Fail Alarm**

This is very over-simplified, please do not use for design purposes

# Motor Restart Delay Notes

- Goal: Inhibit restarting a motor until enough energy bleeds off to safely restart
- Note that this is NOT in the PLC
  - Placing hardware inside motor bucket prevents stupid human tricks
  - PLC code can be subverted, this timer prevents damage
- If “Start Fail” alarm triggered, INVESTIGATE

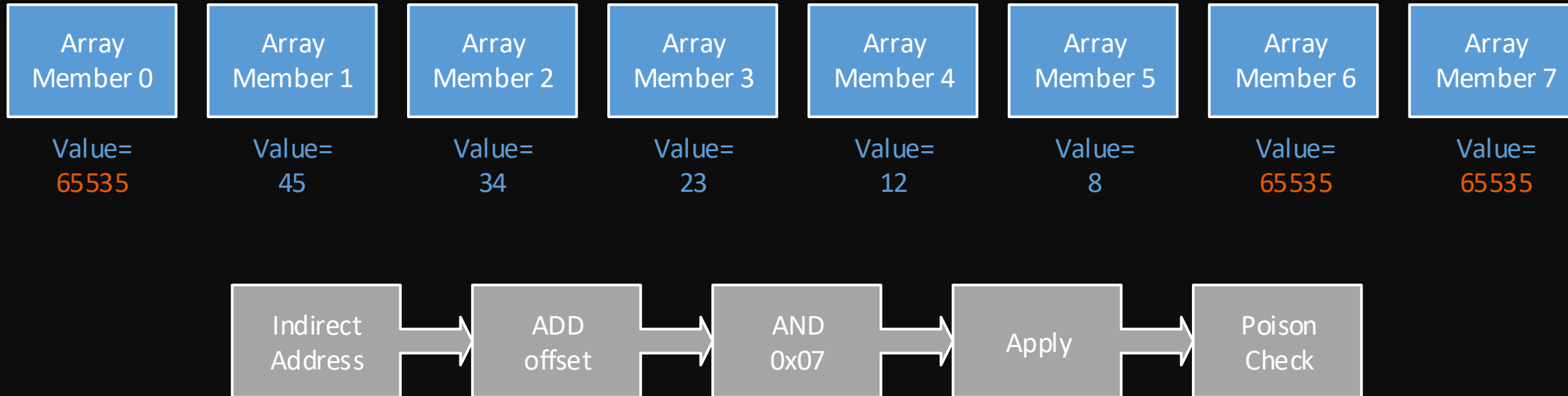
# Rapid Diagnostics

- Do not reuse registers/variables/coils
- General Rule: If PLC Cycle Time longer than AC cycle, WHY?
  - 16.67 mSec in North America
  - 20 mSec in Europe
- Allow for logic disable so inputs and outputs can be validated
- Monitor the control voltage in a motor bucket
- Monitor 4-20 mA loop current from power supply
- Latch transient events in PLC in case remote polling is not frequent enough to catch them

# Validate Indirect Addresses

- Avoid indirect addressing if you can
  - Reasons for using them:
    - Lookup Tables for Non-linear functions
    - Sequencing & Staging many of the same assets
  - Set Hard Boundaries for Indirect addresses
- Consider using array w/ binary sizes: 8, 16, 32, etc.
- Check addresses before reading/writing them
  - ADD offset, AND with mask to prevent anything past boundaries
  - Catch fence-post errors by poisoning ends of array
  - Alarm on poisoned values

# Safety with Indirect Addressing



# Peer To Peer Automation

- For critical PLC to PLC traffic
  - Use separate port
  - Consider using a Crossover Cable
  - **YOU STILL NEED TO VALIDATE YOUR INPUTS!**
- Do Not use OPC DA through an HMI
  - This used to be popular
  - HMI would become a critical asset
  - HMI attack surface is large
- Monitor Peer to Peer with a heartbeat function
  - Validates that both PLCs are live and operating somewhat nominally

# Using Internal Status Registers

- Trap and report flags
  - Integer overflow
  - Divide by zero
  - Scan Overrun
- Track communications statistics (errors, total packets received, etc.)
  - Synchronous reporting of packets sent and received
  - Compare to Master station –should match!
- Report code version with hash
- Report changes in communications port states

# Avoid Sets and Resets

- Hazards similar to Goto Command
  - Sometimes there is no substitute
  - Discourage its use
- There shall be only one Set/Reset instance per point
- Group S&R together so that you can find them both
- Do not assert a Set or Reset continuously
- Do not assert Set and Reset together
- Set up and latch alerts to let you know if this happens
  
- Why? It makes diagnostics easier!



# Secure PLC Programming

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March 16, 2020

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