Anton Bobkov

CONTACT INFORMATION Graduate Student

Department of Mathematics

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EDUCATION

University of California, Los Angeles (graduate)

Fall 2011 to present

PhD, Mathematics (in progress)

Advisor: Matthias Aschenbrenner

Research interests: Mathematical logic, model theory, NIP theories, vc-density

University of California, Los Angeles (undergraduate)

Graduated Spring 2011

- \bullet B.S. in Mathematics, B.A. in Physics
- Sherwood Prize
- Departmental Highest Honors in Mathematics, College Honors
- GPA: 3.82 (Magna Cum Laude)
- William Lowell Putnam Mathematics Competition
 - -2008 score 30
 - 2009 score 19

UNDERGRADUATE Cryptography REU at Northern Kentucky University Summer 2009 Implemented a variant of MXL algorithm in computational algebra system MAGMA

Research assistant for Vladimir Vassiliev

2008 - 2011

I did various numerical simulations in C++ for AGIS gamma-ray telescope. This included forward and inverse kinematics for Stewart platform, ray casting focusing simulations, and laser calibration. I have also worked on network interfacing with Gumstix boards using CORBA as well as installing and configuring a custom linux kernel.

TEACHING

RESEARCH

Intermediate C++ Programming, Linear Algebra, Calculus

PAPERS

Bobkov, A. VC-density for trees, in preparation

SOFTWARE EXPERIENCE Unix-like systems

I am comfortable working in command line environment, including tasks such as

- installing and managing web-server, repository server, ssh server
- code building, editing, and version control

C++, C#, bash, Java, PHP, MAGMA Languages

Code management CMake, Makefile, git, subversion, Visual Studio, Unity3D

Standards TCP/IP, .NET, CORBA

INDEPENDENT PROJECTS

For more information and links visit www.math.ucla.edu/~bobkov/projects.html

Burn and Turn 2008 - 2011

Cross-platform arcade style video game featured on Kotaku and IndieGames. It was coded in C++ and used OpenGL as a backend for graphics. It was created by a team of three people over a course of four years and released on iOS and Android markets.

Self Balancing Robot

Summer 2012

A vertical self-balancing robot ran by an arduino controller coded in C++. A numerical simulation was used to determine weight distribution. Robot's position is determined by data from an accelerometer and a gyroscope combined through a Kalman filter. Balancing is done with a DC motor using PID controller.

UCLA Graduate Student Wiki

Summer 2014

Official wiki for graduate math department at UCLA that maintains a database of qualifying exam problems. It is made on top of Semantic Media Wiki using custom extension written in PHP that allows to users to search, filter, and tag the solutions.

Decentralized Online Game

Fall 2014 - Present

Exploration multiplayer online game that manages players and game data using peer-to-peer connections instead of relying on a central server. It is coded with C# in Unity3D using standard TCP/IP network.

SAMPLE CODE

gitorious.org/~antonbobkov