
Assignment 4

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Question 1 and 2 - PA 9 and Transient Circuit Simulation

The simulation was run:

```
MNA_Q1  
pause(2);
```

$C =$

0	0	0	0	0	0
-0.2500	0.2500	0	0	0	0
0	0	0	0	0	0
0	0	0	0	0	0
0	0	0	0	0	0
0	0	0	0	0	0.2000

$G =$

1.0000	0	0	0	0	0
-1.0000	1.5000	0	0	0	1.0000
0	0	0.1000	0	0	-1.0000
0	0	-10.0000	1.0000	0	0
0	0	0	-10.0000	10.0010	0
0	-1.0000	1.0000	0	0	0

Figure 1: Voltage as a Function of Input Voltage

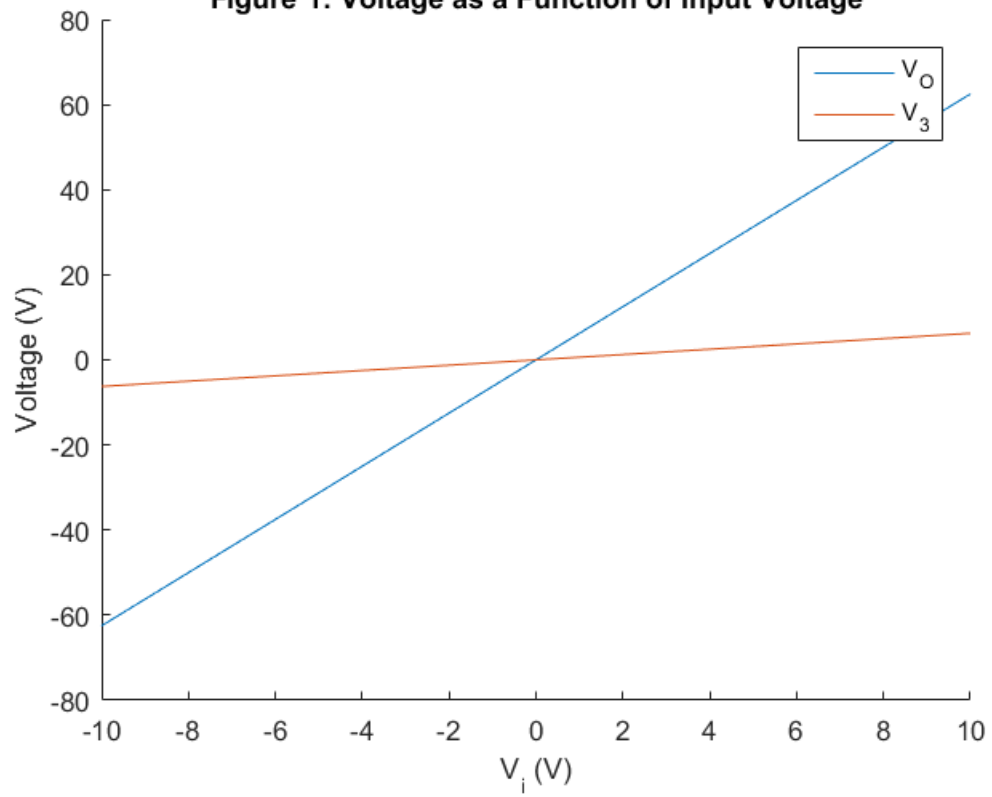
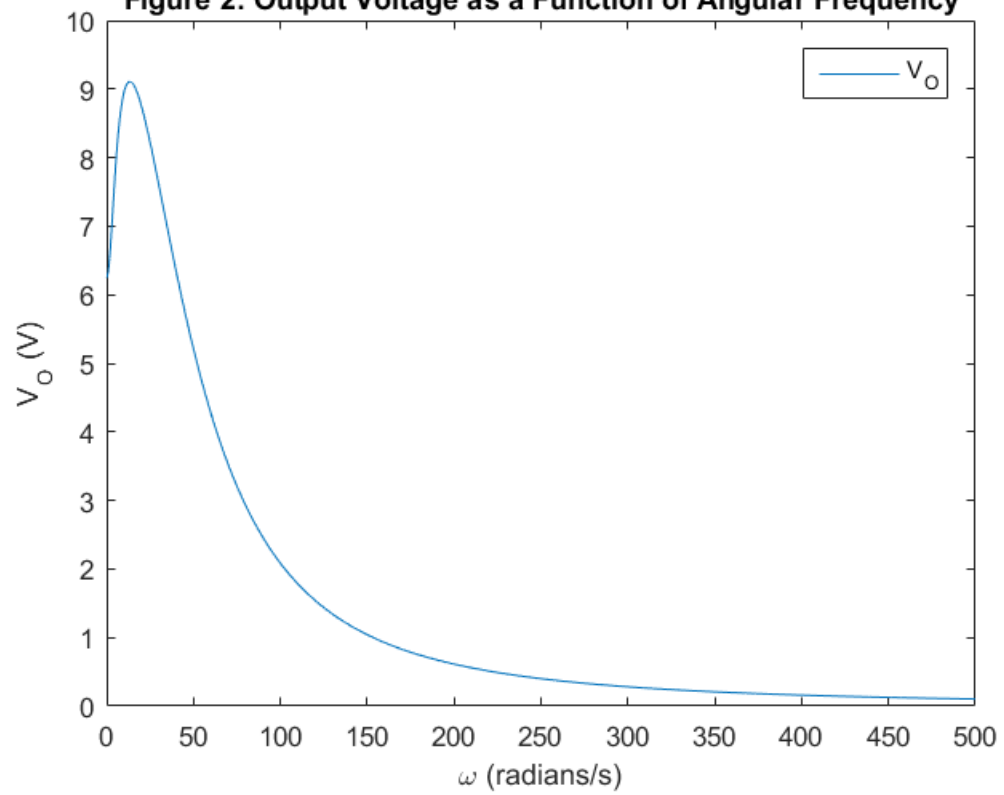
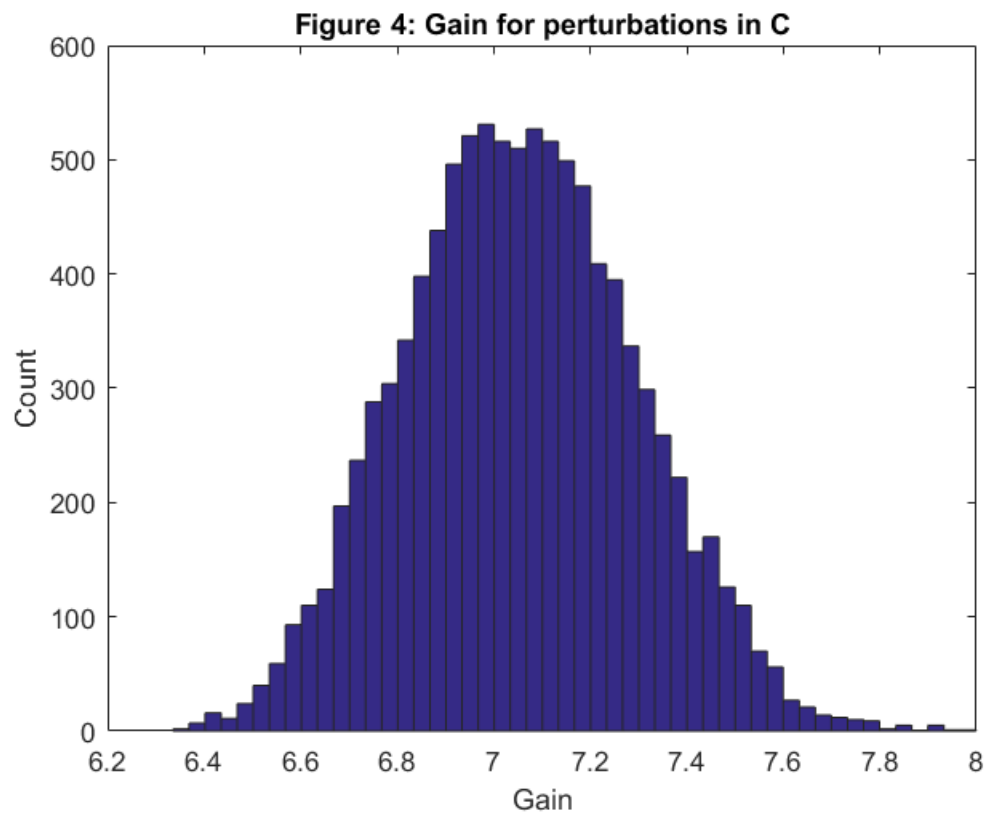
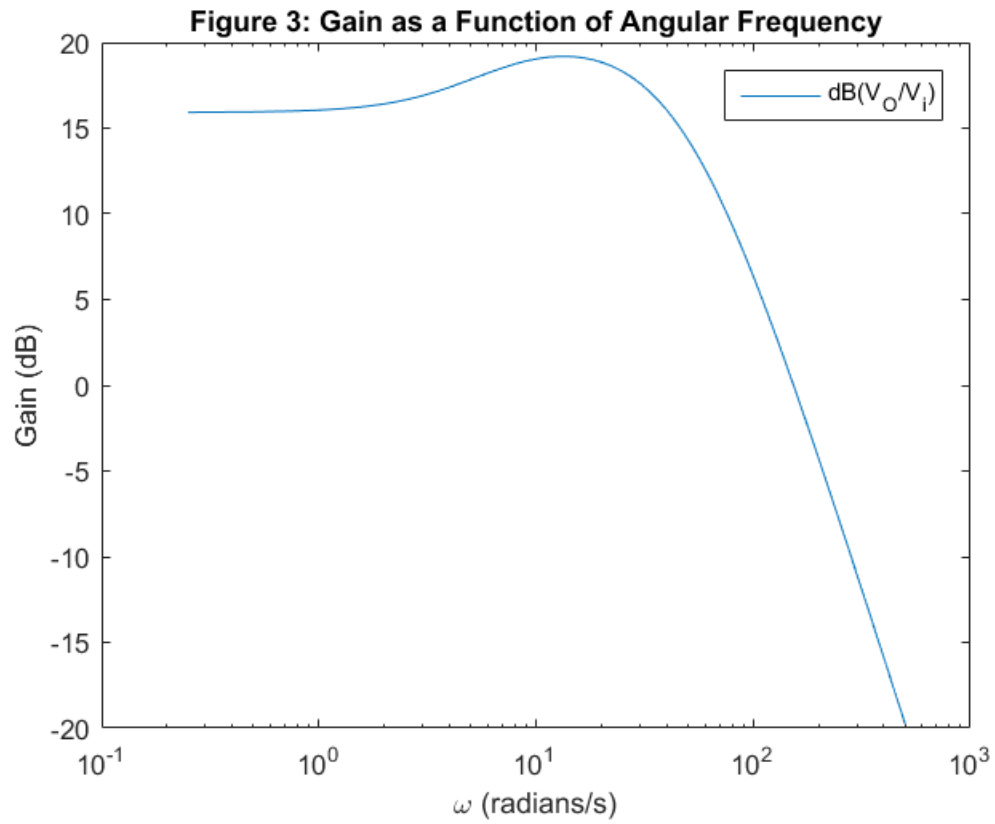


Figure 2: Output Voltage as a Function of Angular Frequency





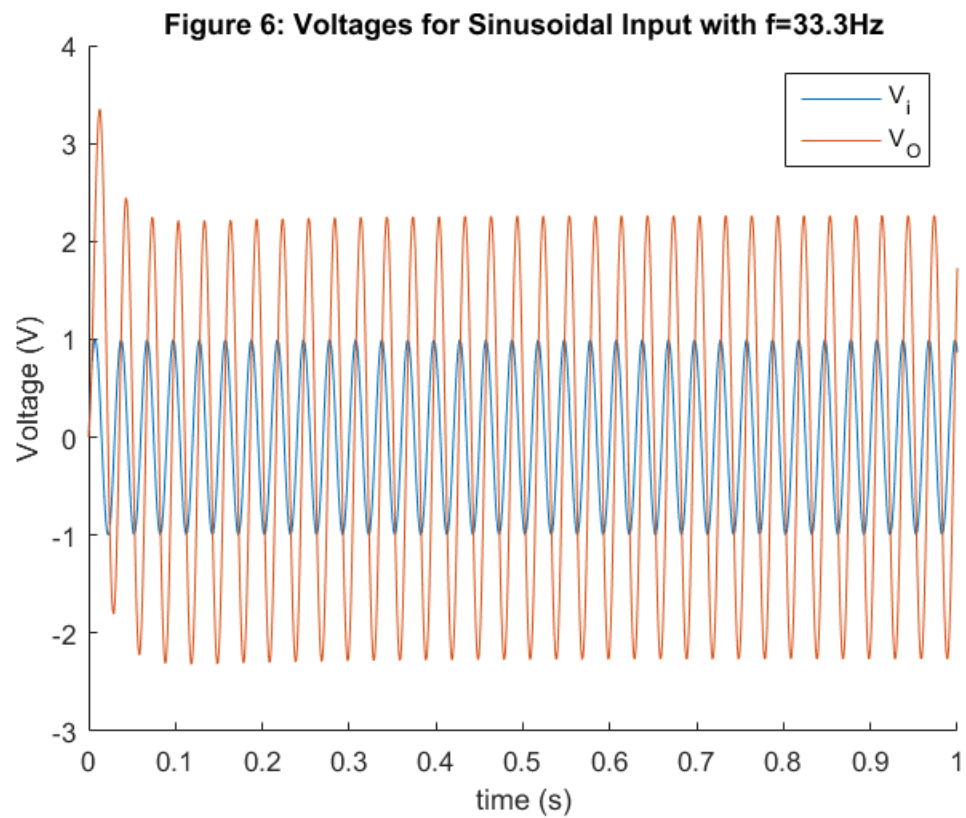
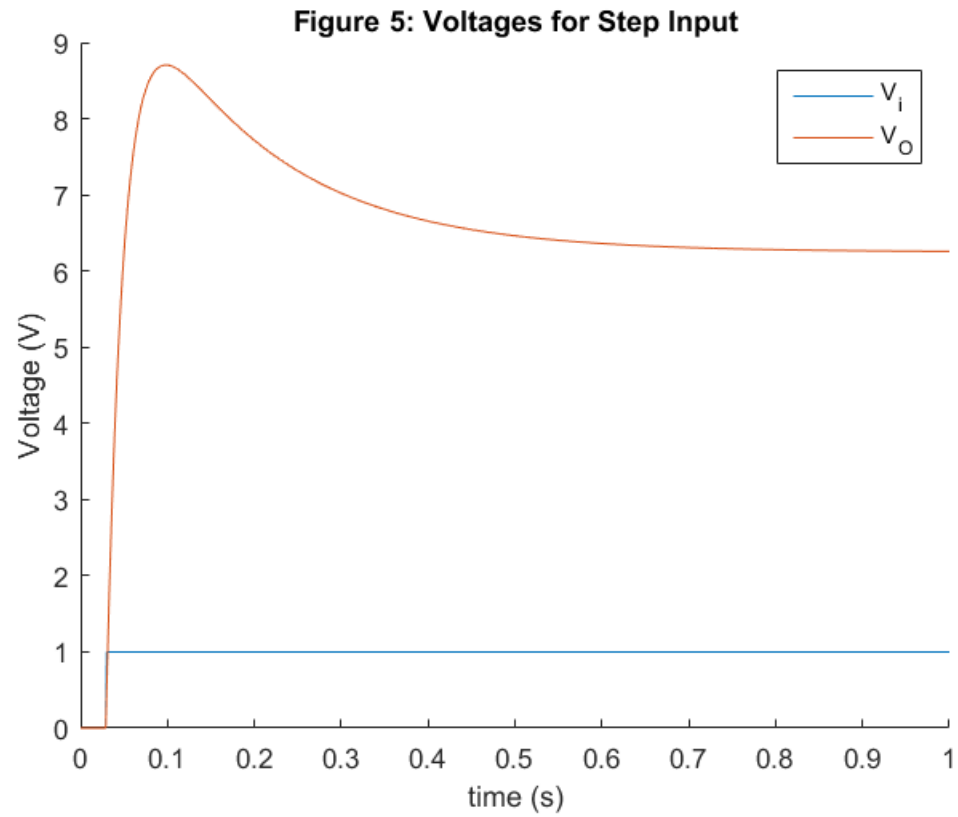


Figure 7: Voltages for Gaussian Pulse Input

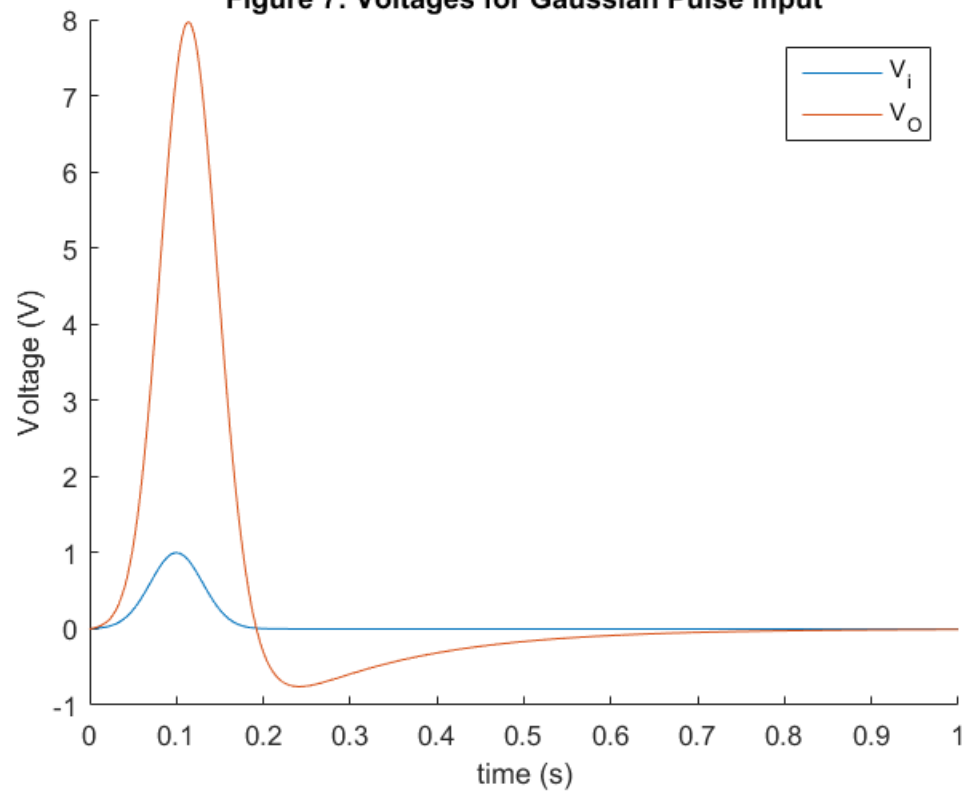
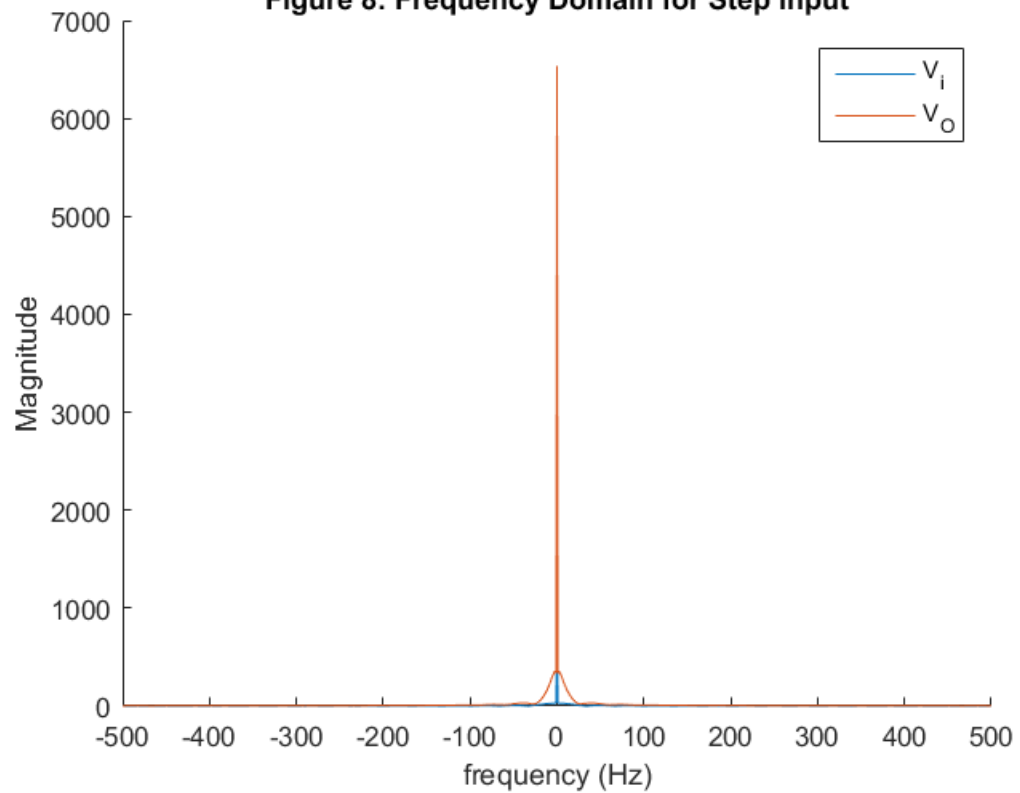
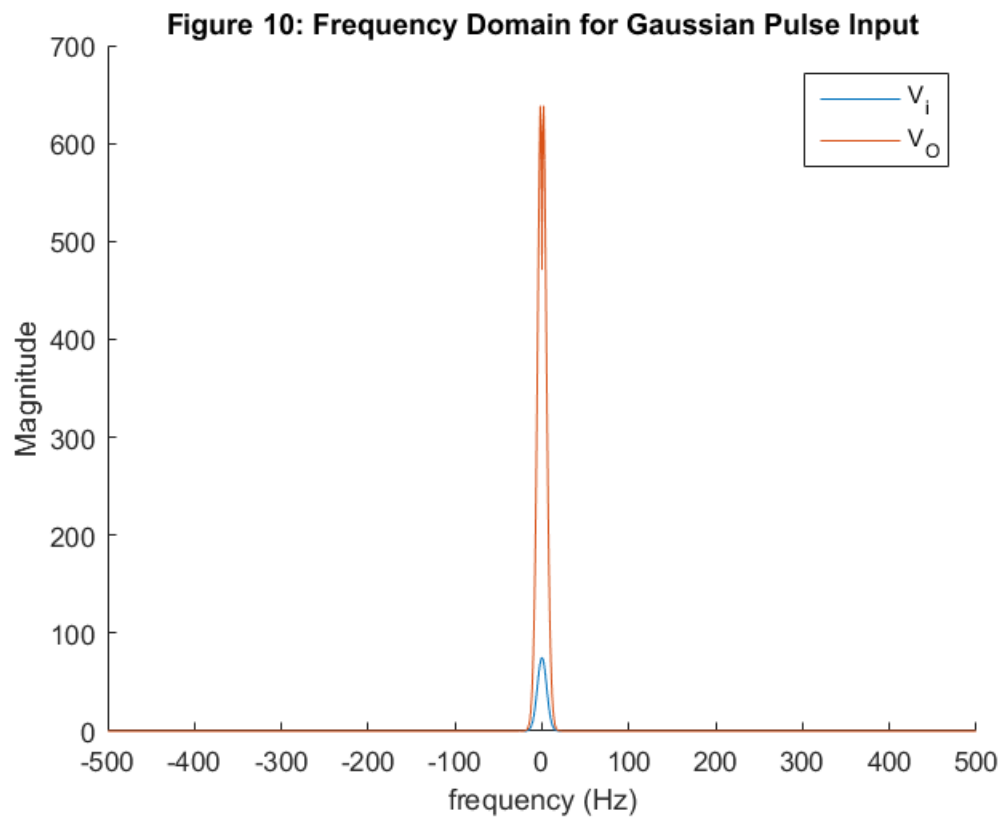
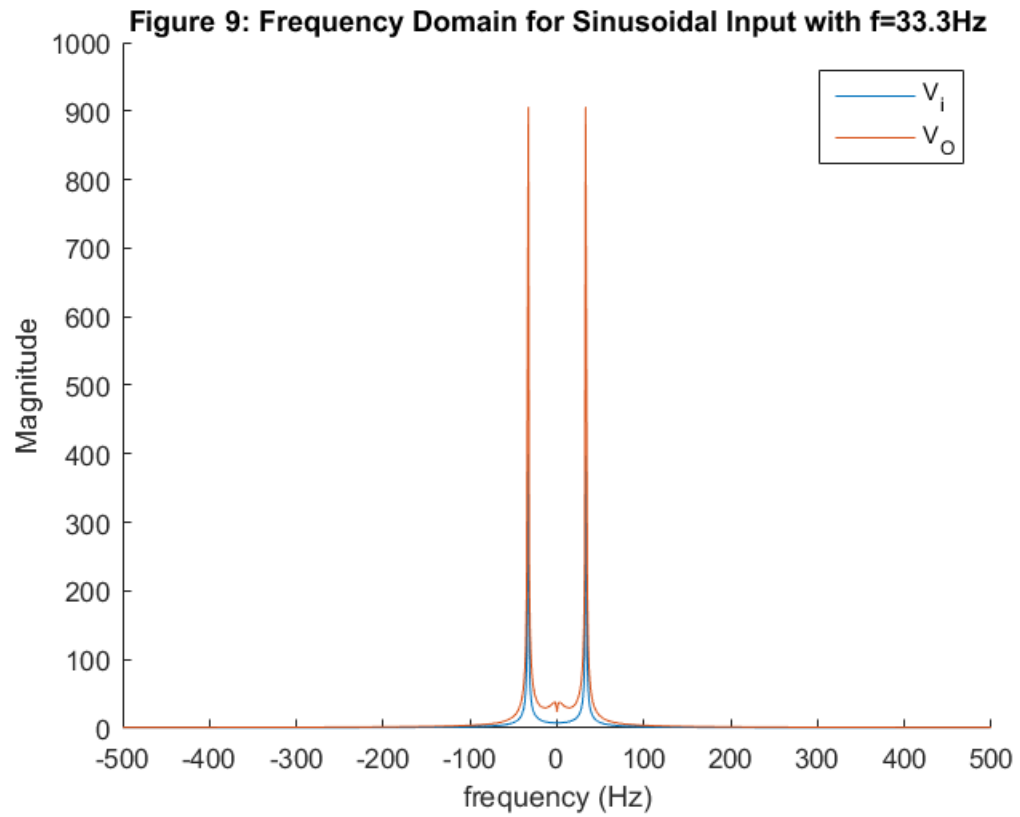


Figure 8: Frequency Domain for Step Input





(a)

The values of the C and G matrices are shown above.

The G matrix is:

$$\begin{array}{cccccc} 1 & 0 & 0 & 0 & 0 & 0 \\ -\frac{1}{R_1} & \left(\frac{1}{R_2} + \frac{1}{R_1}\right) & 0 & 0 & 0 & 1 \\ 0 & 0 & \frac{1}{R_3} & 0 & 0 & -1 \\ 0 & 0 & -\frac{\alpha}{R_3} & 1 & 0 & 0 \\ 0 & 0 & 0 & -\frac{1}{R_4} & \left(\frac{1}{R_4} + \frac{1}{R_O}\right) & 0 \\ 0 & -1 & 1 & 0 & 0 & 0 \end{array}$$

The C matrix is:

$$\begin{array}{cccccc} 0 & 0 & 0 & 0 & 0 & 0 \\ -C_1 & C_1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & L_1 \end{array}$$

The V matrix is:

$$\begin{array}{c} V_1 \\ V_2 \\ V_3 \\ V_4 \\ V_5 \\ I_L \end{array}$$

(b)

Figure 1 shows a plot of the DC sweep. The relationship of V_O and V_3 to V_i is linear.

(c)

Figure 2 shows the output voltage as a function of the angular frequency. Figure 3 shows the gain as a function of the angular frequency. The circuit acts like a low pass filter.

Figure 4 shows a histogram of Gain for perturbation in C. It has a normal distribution just like the perturbation in C.

(d)

Figure 5 shows the input and output voltage for a step input. The output voltage overshoots and then exponentially approaches a final voltage.

Figure 6 shows the input and output voltage for a sinusoidal input. The output voltage is also a sinusoidal signal but it has a higher amplitude and a phase shift. There is some irregularity since the input voltage starts from a steady state of 0V.

Figure 7 shows the input and output voltage for a Gaussian pulse input. The output voltage resembles the Gaussian input but overshoots below 0V before gradually returning to 0V.

(e)

Figure 8 shows the frequency domain for the step input. The input and output both resemble a dirac-delta centred at a frequency of 0Hz. The output is a slightly worse dirac-delta.

Figure 9 shows the frequency domain for the sinusoidal input. The input and output both resemble two dirac-delta at -33.3Hz and 33.3Hz. The output is a slightly worse pair of dirac-deltas.

Figure 10 shows the frequency domain for the Gaussian pulse input. The input and output both resemble Gaussian distributions. The output has larger magnitude.

Question 3 - Circuit with Noise

The simulation was run:

```
MNA_Q3
pause(2);
```

C =

0	0	0	0	0	0
-0.2500	0.2500	0	0	0	0
0	0	0.0000	0	0	0
0	0	0	0	0	0
0	0	0	0	0	0
0	0	0	0	0	0.2000

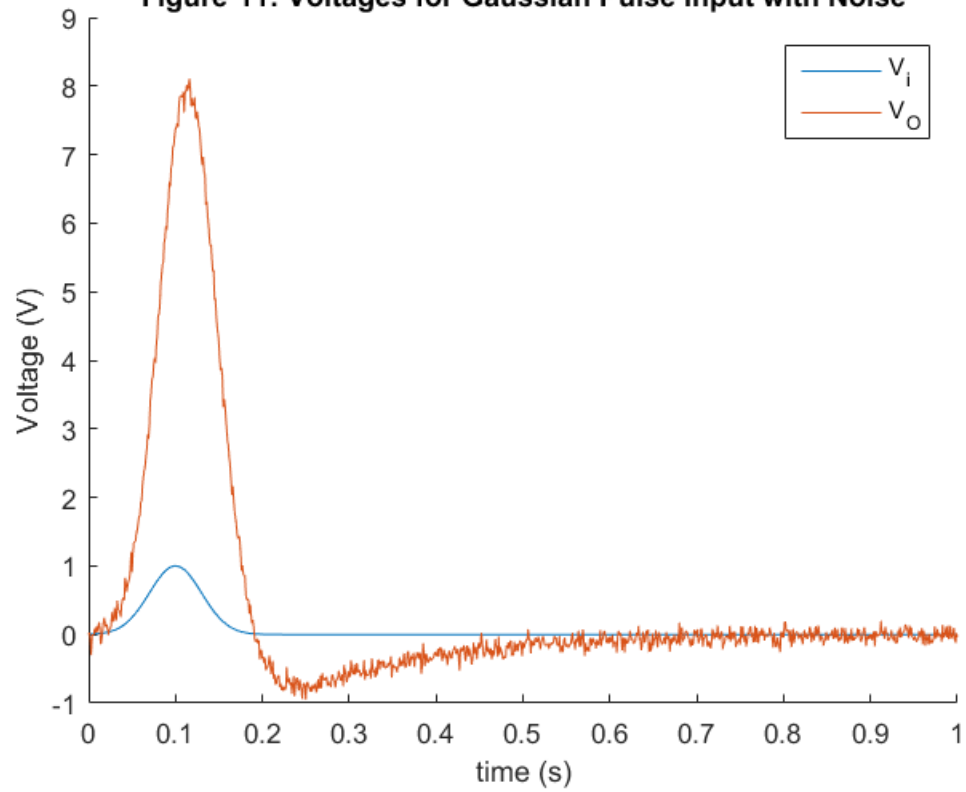
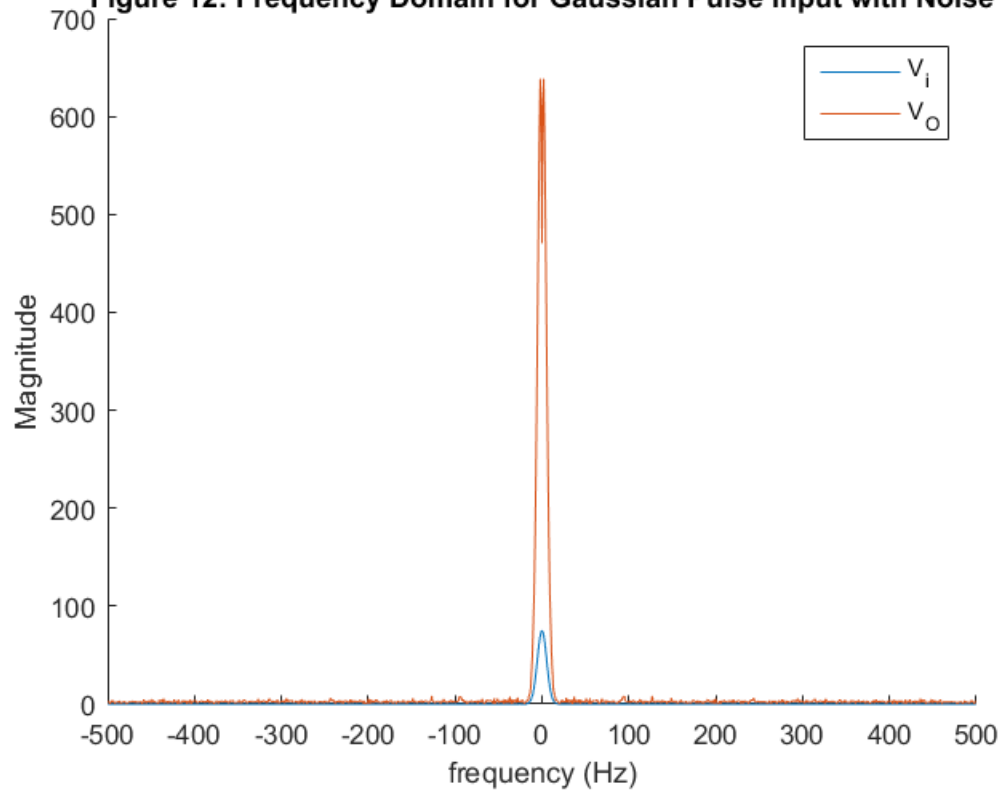
Figure 11: Voltages for Gaussian Pulse Input with Noise**Figure 12: Frequency Domain for Gaussian Pulse Input with Noise**

Figure 13: Voltages with Noise for Different C_n

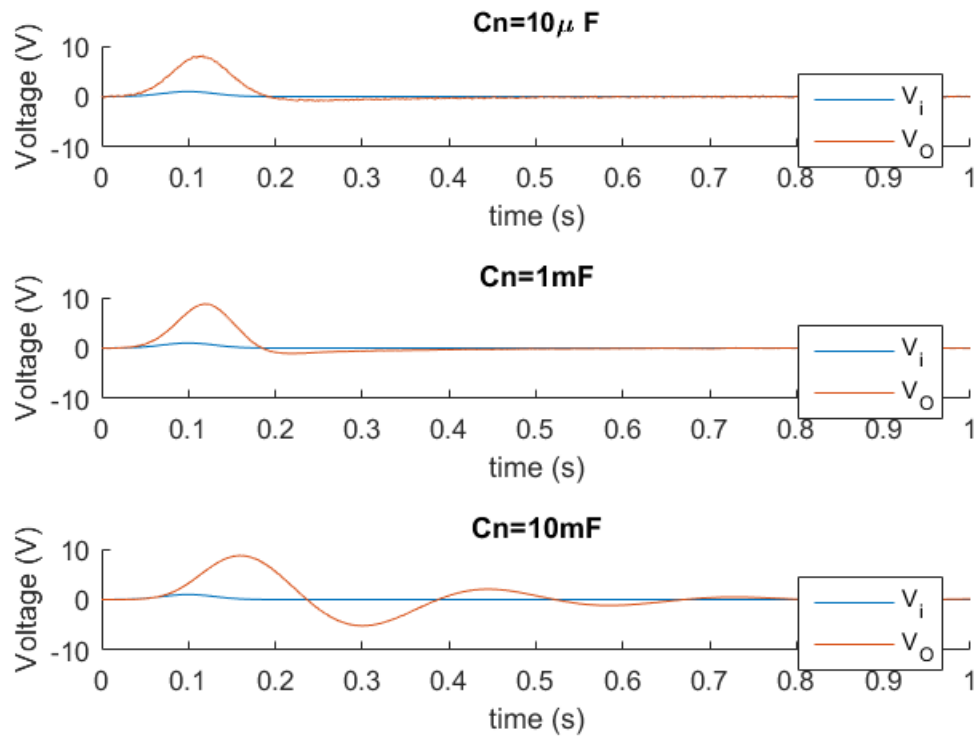
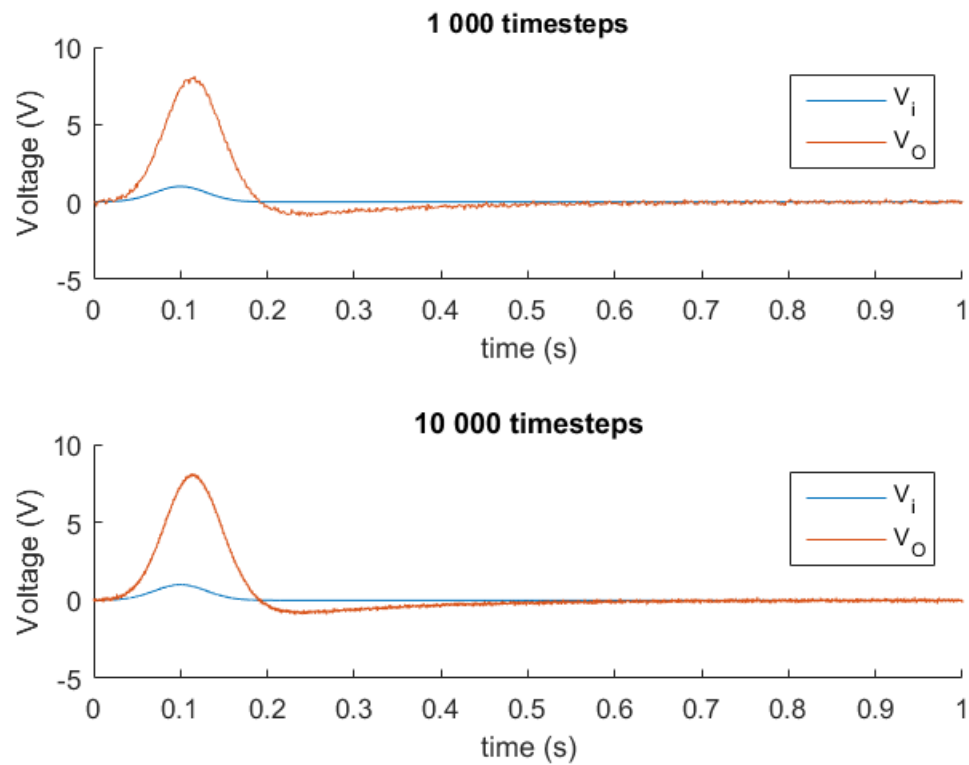


Figure 14: Voltages with Noise for Different Timesteps



(a)

The value of the new C matrix is shown above.

The new C matrix is:

$$\begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ -C_1 & C_1 & 0 & 0 & 0 & 0 \\ 0 & 0 & C_n & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & L_1 \end{bmatrix}$$

(b)

Figure 11 shows the input and output voltages for added noise.

(c)

Figure 12 shows the frequency domain for added noise.

(d)

Figure 13 shows the input and output voltages for different values of C_n . The initial C_n used was $10\mu\text{F}$ which has noise visible on the output signal. For the middle subplot, a larger C_n of 1mF which eliminated most of the noise. For the bottom subplot, an even larger C_n of 10mF resulted in the output signal oscillating.

(e)

Figure 14 shows the input and output voltages for different numbers of timesteps. The upper subplot has 1000 timesteps. The lower subplot has 10 000 timesteps. The subplot with more timesteps appears to be more noisy. This is due to the higher sampling rate.

Question 4 - Non-linearity

(a)

In order to implement a non-linear output stage voltage, the B matrix would need to be used. The new MNA equation that should be used is:

$$C \frac{dV}{dt} + GV + B(V) = F(t)$$

(b) The MNA equation should be rearranged to the form:

$$\left(\frac{C}{\Delta t} + G \right) V_n - \frac{C}{\Delta t} V_{n-1} + -B(V) - F(t) = 0$$

Newton Raphson would need to be solved iteratively. I would create a H matrix. This H matrix would be used to iteratively solve for the V matrix.

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