

Multimodal Continuous Visual Attention Mechanisms

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Outline

- Visual attention mechanisms are an important component of deep learning models.
- Most models for visual attention operate over discrete domains (Bahdanau et al., 2015).
- Recently, continuous attention mechanisms have been proposed, limiting the attention to a simple unimodal density (Martins et al., 2020).

This paper: we introduce **multimodal** continuous attention mechanisms.

From Discrete to Continuous Attention

Discrete Attention

Images are represented using L feature vectors in \mathbb{R}^D (e.g., grid-level or object-level representations).

- Feature matrix $V \in \mathbb{R}^{D \times L}$
- Score vector $f = [f_1, \dots, f_L]^\top \in \mathbb{R}^L$
- Probability vector via $p = \text{softmax}(f)$

Output:

- Weighted average $c = Vp \in \mathbb{R}^D$

How many planes are in this photograph?



This paper: multimodal continuous attention

We let the attention density be a mixture of unimodal distributions, specifically Gaussians

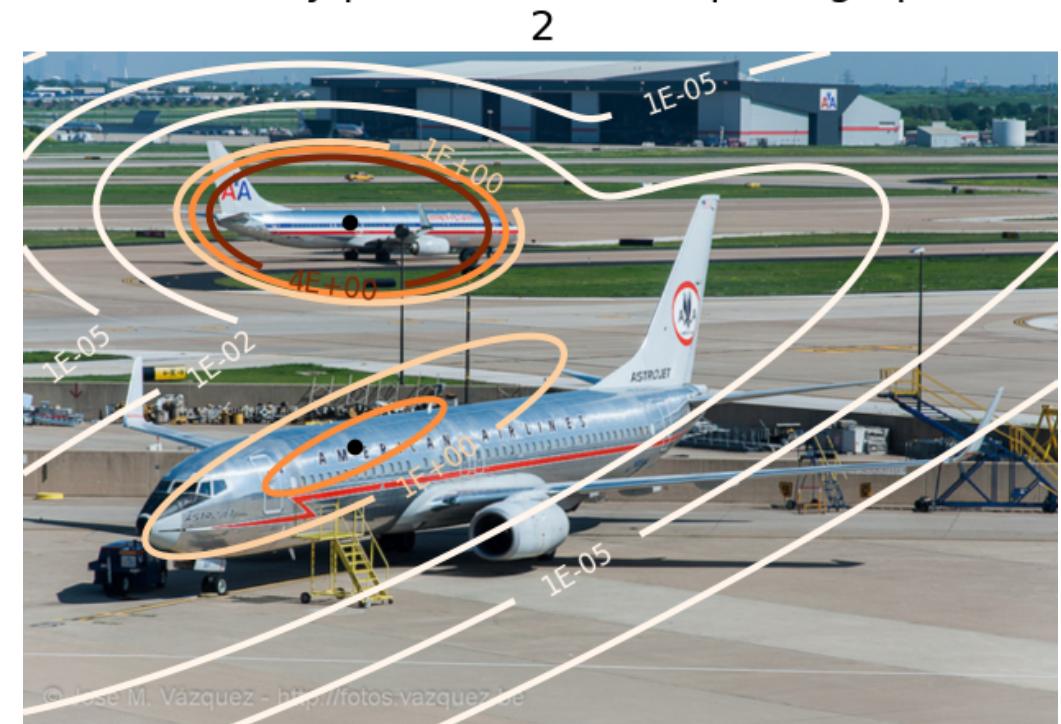
$$p(x) = \sum_{k=1}^K \pi_k p_k(x). \quad (1)$$

Forward step. The context vector is a mixture of the context representations for each component,

$$c = \mathbb{E}_p[B\psi(x)] = \sum_{k=1}^K \pi_k \underbrace{\mathbb{E}_{p_k}[B\psi(x)]}_{c_k} = \sum_{k=1}^K \pi_k c_k. \quad (2)$$

Backward step. Linear combination of unimodal attention mechanisms.

How many planes are in this photograph?



The EM algorithm with weighted data

Parameters: Centers of grid regions and weights $\mathcal{X} = \{(x_\ell, w_\ell)\}_{\ell=1}^L$, initialization $\Theta(K) = \{(\pi_k, \mu_k, \Sigma_k)\}_{k=1}^K$, iterations I .

```
Function WeightedEM( $\mathcal{X}, \Theta(K), I$ ):
for  $i \leftarrow 1$  to  $I$  do
    for  $\ell \leftarrow 1$  to  $L$  do
        for  $k \leftarrow 1$  to  $K$  do
             $\gamma_{\ell k} \leftarrow \frac{\pi_k \mathcal{N}(x_\ell | \mu_k, \Sigma_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(x_\ell | \mu_j, \Sigma_j)}$ 
        end
    end
    for  $k \leftarrow 1$  to  $K$  do
         $\pi_k \leftarrow \sum_{\ell=1}^L w_\ell \gamma_{\ell k}$ 
         $\mu_k \leftarrow \frac{1}{\pi_k} \sum_{\ell=1}^L w_\ell \gamma_{\ell k} x_\ell$ ,  $\Sigma_k \leftarrow \frac{1}{\pi_k} \sum_{\ell=1}^L w_\ell \gamma_{\ell k} (x_\ell - \mu_k)(x_\ell - \mu_k)^\top$ 
    end
end
return  $\Theta = \{(\pi_k, \mu_k, \Sigma_k)\}_{k=1}^K$ 
```

// Evaluate the responsibilities
// Re-estimate the mixing coefficients
// Re-estimate the means and covariances

Estimating the number of components

Parameters: Centers of grid regions and weights $\mathcal{X} = \{(x_\ell, w_\ell)\}_{\ell=1}^L$, initialization $\Theta(K) = \{(\pi_k, \mu_k, \Sigma_k)\}_{k=1}^K$, iterations I .

```
Function ModelSelection( $\mathcal{X}, \{\Theta(k)\}_{k=1}^{k_{\max}}, I, \lambda$ ):
for  $k \leftarrow 1$  to  $k_{\max}$  do
     $\hat{\Theta}_k \leftarrow \text{WeightedEM}(\mathcal{X}, \Theta(k), I)$  // Obtain parameters using WeightedEM
     $\log(p(\mathcal{X}|\hat{\Theta}_k)) \leftarrow \sum_{\ell=1}^L w_\ell \log \left\{ \sum_{k=1}^K \hat{\pi}_k \mathcal{N}(x_\ell | \hat{\mu}_k, \hat{\Sigma}_k) \right\}$ ,  $c(\hat{\Theta}_k, k) \leftarrow -2\log(p(\mathcal{X}|\hat{\Theta}_k)) + \lambda k$  // Evaluate criterion
end
 $k^* = \operatorname{argmin}_k \{c(\hat{\Theta}_k, k)\}$  // Choose the optimum number of components
return  $k^*, \hat{\Theta}_{k^*}$ 
```

How many zebras facing in the left direction?



Attention model

Each attention density is a **K-component mixture of Gaussians**.

- At training time, we pick the number of components *randomly* from a uniform distribution, up to a predefined maximum.
- At test time, we select the *optimum K** from a set of possible choices, using a model selection criterion.

Experiments: Visual Question Answering (VQA)

- Unimodal continuous attention faces difficulties in complex scenes with **multiple regions of interest** far from each other. Multimodal attention densities tend to perform better.
- For a **single complex-shaped interest region**, discrete attention may be too scattered and unimodal attention too focused. Multimodal continuous attention is a good compromise.



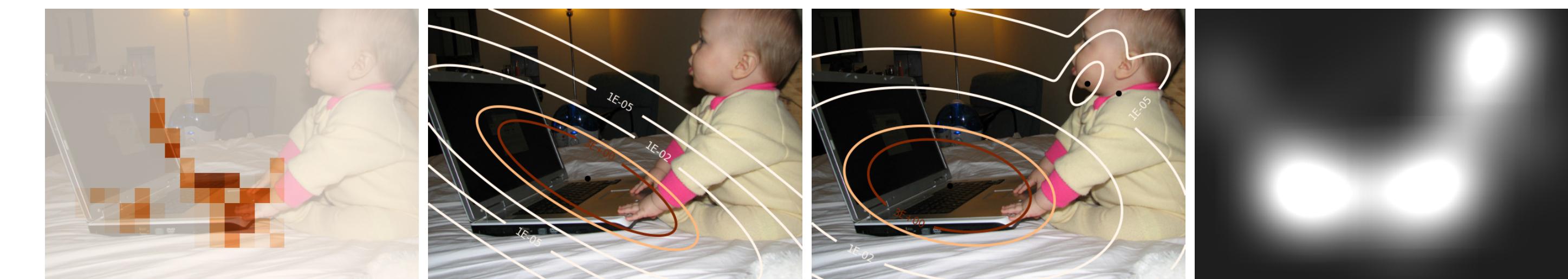
Human attention

- The attention distributions obtained with multimodal continuous attention are **more similar to human attention** than the ones obtained with discrete or unimodal attention.

| Attention | JS divergence ↓ |
|-----------------------|-----------------|
| Discrete softmax | 0.64 |
| Unimodal continuous | 0.59 |
| Multimodal continuous | 0.54 |

- Humans **sequentially look for regions** in the image, until they found the information they need. Our model replicates this process by identifying multiple regions of interest.

Is the baby using the computer?



Conclusions

- New continuous attention mechanisms that produce multimodal densities with tractable and efficient forward and gradient backpropagation steps.
- Weighted version of the EM algorithm to obtain a selection of relevant regions. Penalized likelihood method to select the number of components in the mixture.
- Experiments on VQA mimic human attention and present increased interpretability.
- Future work:** Mixtures of sparse family distributions and other vision tasks.

Open-source code:

<https://github.com/deep-spin/vqa-multimodal-continuous-attention>

References

- Bahdanau, D., Cho, K., and Bengio, Y. (2015). Neural machine translation by jointly learning to align and translate. In Proc. of ICLR.
- Martins, A., Farinhas, A., Treviso, M., Niculae, V., Aguiar, P., and Figueiredo, M. (2020). Sparse and Continuous Attention Mechanisms. In Advances in Neural Information Processing Systems, volume 33, pages 20989–21001.