Deep Learning for Soybean Classification Binary Classification of Healthy vs Unhealthy Grains

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Introduction to Machine Learning

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Outline

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Problem Context

Agricultural Challenge

- Brazil produces 40% of global soybean
- Production losses exceed 20% due to:
 - Diseases and pests
 - Climate change impacts
 - Quality control challenges
- Manual monitoring is unfeasible at scale
- Computer vision offers automation potential

Research Question: Can deep learning effectively classify healthy vs unhealthy soybean grains from proximal images?

Dataset Overview

Key Characteristics:

- Public dataset (Lin et al., 2023)
- Proximal grain images
- Automated segmentation
- Binary classification task

Class Distribution:

- Healthy: 1,201 samples (22%)
- Unhealthy: 4,312 samples (78%)
- Significant class imbalance!

Class	Count
Healthy	1,201
Unhealthy	4,312

Dataset Overview

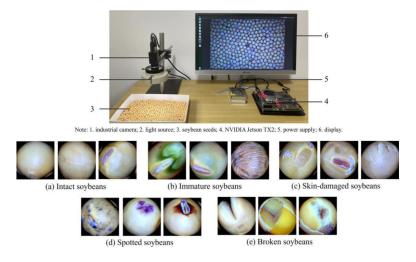


Figure: Data extraction process

Algorithm overview

Model Architecture

Convolutional Neural Network (CNN):

Design Choices:

- Grayscale input (single channel)
- Progressive feature reduction
- MaxPooling for translation invariance
- Sigmoid output for probability

Training Strategy

Hyperparameters:

Learning rate: 0.00001 (conservative approach)

Batch size: 128Optimizer: Adam

Class weights to handle imbalance

Evaluation Strategy:

5-fold cross-validation

ROC curve analysis for threshold optimization

Metrics: Accuracy, Precision, Recall, F1-score

Early stopping to prevent overfitting

Data Split:

Training: 40% (computational constraint)

Testing: 60%

Addressing Class Imbalance

Challenge: 78% unhealthy vs 22% healthy samples

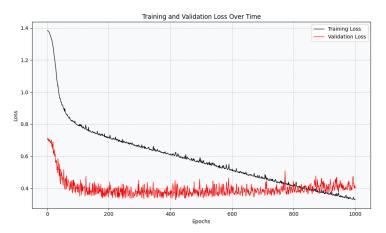
Solutions Implemented:

- Class weighting: Penalize misclassification of minority class more heavily
- Threshold optimization: Find optimal decision boundary using ROC curve
- **Appropriate metrics:** Focus F1-score rather than just accuracy. Balance best Recall and Precision relation

Results

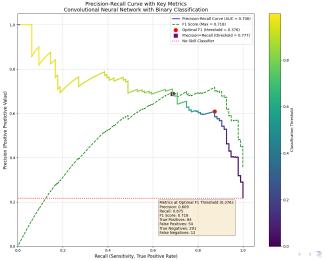
1-fold Simulation - Loss Over time

We are able to overfit, so a 5 fold training can give us a statistically better goal of epochs.



1-fold simulation - Decision Threshold

- Our final layer is a sigmoid function
- A threshold can be set for model decision-making



5-fold simulation - Training Dynamics

Overfitting Analysis:

- Training loss continuously decreases
- Validation loss shows more noise
- Early stopping around epoch 185

Cross-Validation Results:

Fold	F1 Score	Threshold	Epochs
1	0.689	0.649	174
2	0.692	0.684	188
3	0.687	0.729	184
4	0.744	0.580	185
5	0.683	0.706	197
Mean	0.699	0.670	185

Key Insight: Consistent performance across folds suggests stable learning.

ROC Analysis & Threshold Optimization

Key Findings:

- Optimal threshold: 67% probability
- AUC performance indicates discriminative ability
- Trade-off between precision and recall clearly visible

Decision Strategy:

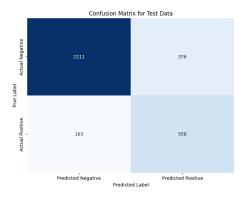
- Classify as "healthy" if P(healthy) > 0.67
- Maximizes F1-score (harmonic mean of precision/recall)
- Balances false positives vs false negatives

Business Implication: The threshold choice depends on whether it's more costly to reject good grains or accept bad ones.

Final Model

Final Model Performance

Test Results:

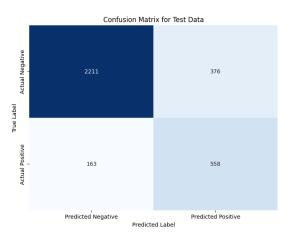


Interpretation:

- Model identifies most healthy grains (77% recall)
- But includes unhealthy grains in selection (60% precision)
- Better than random (50% baseline)
- Room for significant improvement

Practical Impact: Model would correctly identify healthy grains but would also incorrectly include a substantial number of unhealthy grains in the "healthy" classification.

Metric	Value
Accuracy	83.71%
Precision	59.74%
Recall	77.39%
F1-Score	67.43%



Critical Analysis

Limitations & Challenges

Current Limitations:

- Grayscale only: Missing color information (maturity indicators)
- Limited training data: Only 40% used due to computational constraints
- Local minima uncertainty: No guarantee of global optimization
- Architecture simplicity: Basic CNN without advanced techniques

Immediate Enhancements:

- RGB channels: Incorporate color information for maturity detection
- Data augmentation: Rotation, flipping, brightness adjustments
- Advanced architectures: ResNet, EfficientNet, Vision Transformers
- Hyperparameter optimization: Grid search, Bayesian optimization

Thank You!

Questions & Discussion

"Complex problems require robust solutions"

Attachments

Deep Learning - Manyfold Hypothesis

 Manifold Hypothesis: High-dimensional data lies on lower-dimensional manifolds

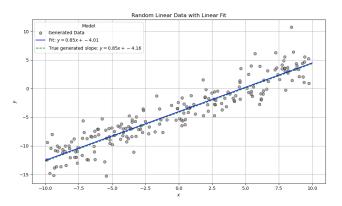


Figure: $y_{predict} = f(x) = \alpha x + \beta$

For real complex problems:

For complex problems, we stack multiple transformations:

$$f(x) = f_n(f_{n-1}(...f_1(x)))$$

Where each f_i represents a neural network layer with learnable parameters.

- Core Concept: "Deep learning is curve fitting, not magic" François Chollet
- Layer Structure: Each layer performs space transformation

Training Steps

The training happens in 3 main steps

- Calculate loss
- Find its local gradient
- **Backpropagate** for *n*—layered system

Loss Function: Binary Cross-Entropy

Loss function is the machine learning metric we want to minimize

- ullet Measures the "distance" between y_{real} and $y_{predicted}$
- Our goal is to minimize Loss to a optimal value

Why BCE for Binary Classification?

$$H_{BCE} = -\frac{1}{N} \sum_{i=1}^{N} [y_i \log(p_i) + (1 - y_i) \log(1 - p_i)]$$

	Уtrue	$p_{predicted} = 1$	$p_{predicted} = 0$
	1	$H_{BCE} ightarrow 0$	$H_{BCE} ightarrow \infty$
ĺ	0	$H_{BCE} ightarrow \infty$	$H_{BCE} ightarrow 0$

Key Properties:

- Penalizes confident wrong predictions heavily
- Differentiable for gradient-based optimization

Optimization: Gradient Descent & Backpropagation

The gradient of our loss function can lead us to a local minima **Gradient Descent:**

$$\theta_{i+1} = \theta_i - \gamma \nabla H_{BCE}(\theta_i)$$

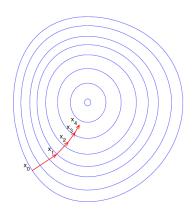


Figure: Gradient descent where each step leads us to a local minima

Optimization: Gradient Descent & Backpropagation

Gradient Descent:

$$\theta_{i+1} = \theta_i - \gamma \nabla H_{BCE}(\theta_i)$$

Global function f(x)

$$f(x) = f_n(f_{n-1}(...f_1(x)))$$

Backpropagation Process:

- Forward pass: compute predictions and loss
- Backward pass: compute gradients using chain rule
- Update parameters in direction of negative gradient
- Repeat until convergence

Practical Implementation:

- TensorFlow/Keras handles automatic differentiation
- Adam optimizer for adaptive learning rates
- Batch processing for computational efficiency