# **Antonio Martin-Ozimek**

antoniolmartino.com | LinkedIn | GitHub | Devpost



#### Education

**The University of Alberta** – Bilingual BSc in Computer Engineering, Co-op Class of 2025 **Key Classes** – Object Oriented, Tangible Computing, Computer Logic, Microprocessors, Databases **Skills** – Python, C++, MATLAB, Arduino, HTML5, CSS, C, JavaScript, Unity Engine, C#, OpenCV, React, Tensorflow, NextJS, Keras, Google Colab, SQL, YOLOv8

### Experience

#### **HONDA Research Institute - ML Researcher**

May 2024 - December 2024

- Acted as the principal researcher for two published papers on human-robot-interactions to HRI2025
- Implemented two generative models: an Implicit Behavior Cloning and a Diffusion Behavior Cloning model to generate non-verbal cues from 360-degree images using Tensorflow and PyTorch
- Extracted feature data using YOLOPose and Gaze360 to then be filtered using pandas for thresholding, normalization, and interpolation
- Tracked training results using **Tensorboard** and **WandB** for **MLOps** backbone

## Enterprises Macay - ML Engineer

May 2023 – September 2023

- Headed the implementation of a **CNN model** to synchronously detect moisture level in **infrared images** and catch contaminants in **RGB** images in quality control line
- Designed and implemented two models: a pre-trained YOLO-v8 CNN model finetuned on IR images and a CNN using Keras and TensorFlow trained from scratch on our data

#### **University of Alberta - ML Researcher**

January 2023 – April 2023

- Developed sensor fusion PID controller that combined YOLOv8 object tracking from a live camera feed with live distance measurements from ultrasonic sensors
- Set up an OPCUA standard client & server for legacy Windows 7 systems to enable communication between embedded controller on the server and client on remote PC
- Implemented data processing with **scikit-learn** to facilitate **regression analysis** and **normalization** for model training and evaluation

#### **Projects**

**Autonomous Driving Robot** | Python, Docker, Duckietown, ROS2

• Developing an **intelligent agent** for an **autonomous driving** robot to complete **lane-following** and **localization** tasks using **ROS2** to maintain system

Personal Website | TypeScript, JavaScript, React, Next-Js

Created a mobile & desktop friendly site using React and NextJs to implement a simple dynamic front-end

JournAi, HackED | HTML5, Tailwind CSS, JavaScript, React, Firebase

- Collaborated with a team of 4 to develop a web app to classify emotion of journal entries
- Created a personalized data visualization page to show users a breakdown of emotional trends

#### Volunteering

# Future Creators | Arduino

January 2022 – August 2022

- Led two term-long projects using the Arduino framework to teach 13 children from grades 5-12
- Took input from an **ultrasonic wave sensor** and outputted the distance traveled by the waves to the terminal while activating a **servo** to release a catapult

#### **Non-Technical Skills**

• Bilingual: French & English