

# Quarta Lista de Exercícios - OTIMIZACAO NAO LINEAR

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Chapter 6: Read Sections 6.1, 6.9 and 6.11

```
In [1]: import numpy as np
import numdifftools as nd
import matplotlib.pyplot as plt
import warnings
warnings.filterwarnings('ignore')
```

## Problem 6.8

Plot the contours of the following function over the region,  $(-5 \leq x_1 \leq 5, -3 \leq x_2 \leq 6)$  and identify the optimum point:

$$f(x_1, x_2) = (x_1 + 2x_2 - 7)^2 + (2x_1 + x_2 - 5)^2$$

```
In [2]: def f1(x1, x2):
return ((x1+2*x2-7)**2)+((2*x1+x2-5)**2)

def df1(x1, x2):
return np.vstack((2*(x1+2*x2-7), 2*(2*x1+x2-5)))
```

```
In [3]: a1 = np.linspace(-5, 5, 50)
a2 = np.linspace(-3, 6, 50)
A1, A2 = np.meshgrid(a1, a2)
Z1 = f1(A1, A2)
```

Gradient of  $f(x_1, x_2)$ :

$$\begin{bmatrix} 10 & 8 \\ 8 & 10 \end{bmatrix} x \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 34 \\ 38 \end{bmatrix} \quad (1)$$

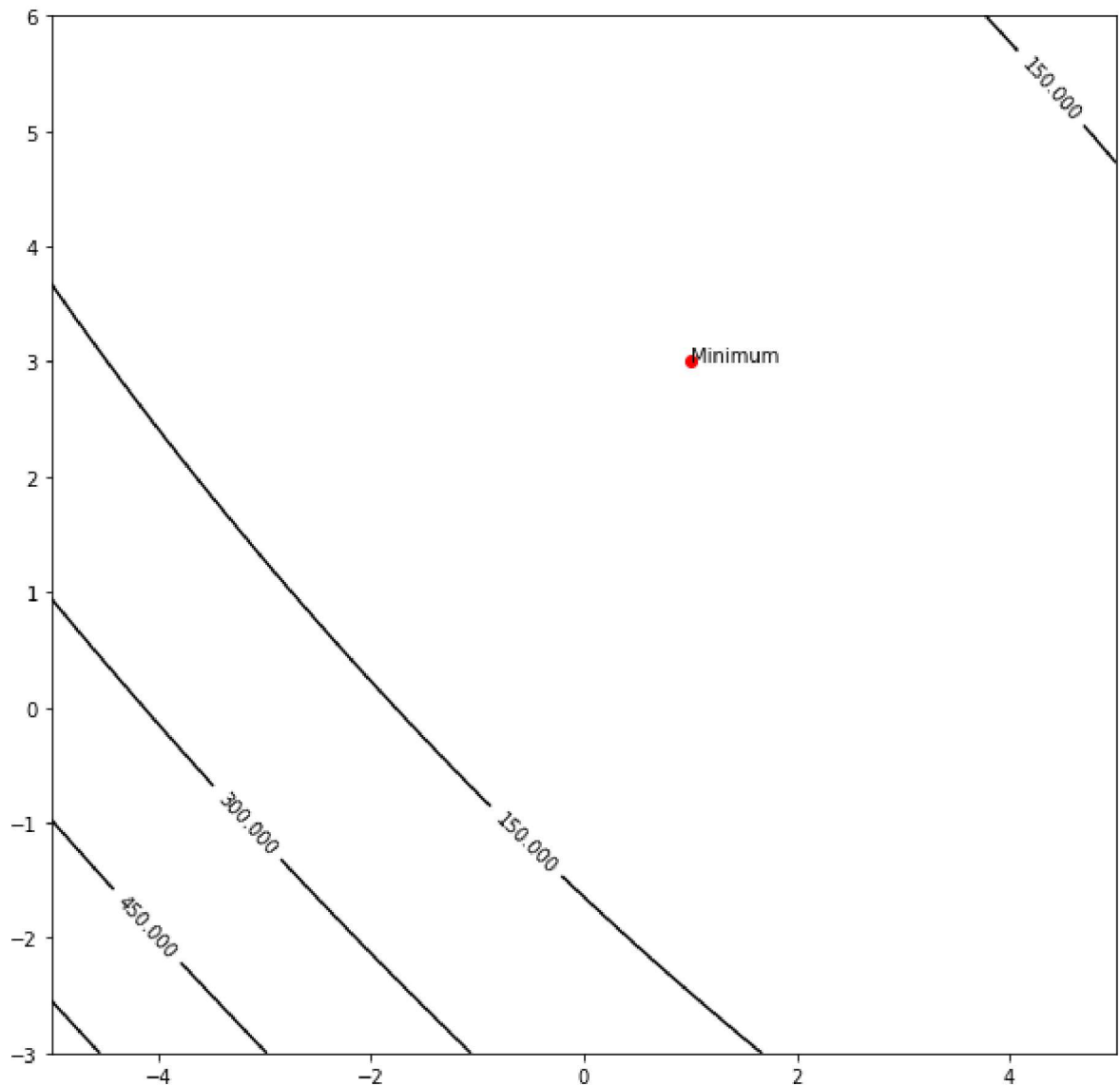
Hessian Matrix:

$$H(X) = \begin{bmatrix} 10 & 8 \\ 10 & 8 \end{bmatrix} \quad (2)$$

```
In [4]: X1 = np.dot(np.linalg.inv(np.array([[10, 8], [8, 10]])), np.array([[34], [38]]))
```

```
In [5]: plt.figure(figsize=(10,10))
contours = plt.contour(A1, A2, Z1, 5, colors='black')
plt.clabel(contours, inline=True, fontsize=10)
plt.scatter(X1[0], X1[1], color='red')
```

```
plt.annotate("Minimum", X1, fontsize=10)
plt.show()
```



### Problem 6.9:

Plot the contours of the following function in the two dimensional ( $x_1, x_2$ ) space over the region  $(-4 \leq x_1 \leq 4, -3 \leq x_2 \leq 6)$  and identify the optimum point:

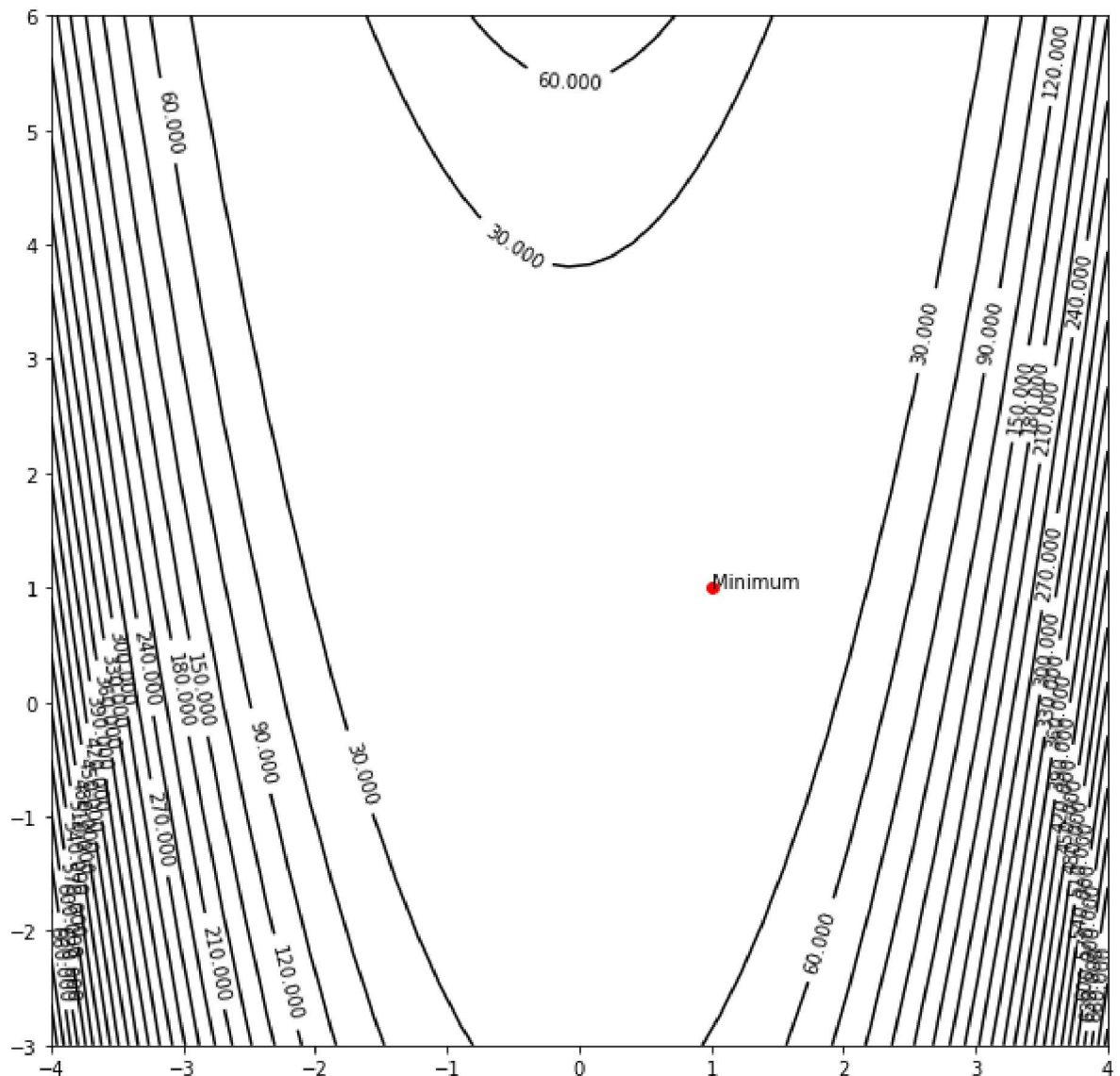
$$f(x_1, x_2) = 2(x_2 - x_1^2)^2 + (1 - x_1)^2$$

```
In [6]: def f2(x1,x2):
        return 2*(x2-x1**2)**2+(1-x1)**2

        def gradf2(x1,x2):
            return np.vstack((-8*(x1*x2-x1**3)-2*(1-x1), 2*(x2-x1**2)))
```

```
In [7]: b1 = np.linspace(-4, 4, 50)
        b2 = np.linspace(-3, 6, 50)
        B1, B2 = np.meshgrid(b1, b2)
        Z2 = f2(B1, B2)
```

```
In [8]: plt.figure(figsize=(10,10))
contours = plt.contour(B1, B2, Z2, 25, colors='black')
plt.clabel(contours, inline=True, fontsize=10)
plt.scatter(1, 1, color='red')
plt.annotate("Minimum", [1,1], fontsize=10)
plt.show()
```



```

def hessianF620(x):
    return np.array([[-400*x[1]+1200*x[0]**2+2, -400*x[0]], [-400*x[0], 200]])

def newtonMethod(start, function, gradFunction, hessianFunction, maxiter, tol = 0.00
x1, iteration, erro = start, 0, 10**10
historic = []

while iteration < (maxiter+1):
    print("Iteracao:", iteration, "Erro:", erro)
    x1 = np.reshape(x1, start.shape)
    historic.append(x1)
    g = gradFunction(x1)
    j_inv = np.linalg.inv(hessianFunction(x1))
    x2 = x1 - np.transpose(np.dot(j_inv, g))
    erro = 0.5*np.sqrt(np.sum(x2-x1)**2)
    x1 = x2
    x2 = np.reshape(x2, start.shape)
    iteration = iteration + 1
    if erro < tol:
        print("Erro final:", erro)
        break

return x2, historic

```

```

In [10]: x0 = np.array([-1.2, 1])
Xmin, historic = newtonMethod(x0, F620, gradF620, hessianF620, 2, 0.00001)
print("xmin:", Xmin, "f(xmin):", F620(Xmin))

```

```

Iteracao: 0 Erro: 10000000000
Iteracao: 1 Erro: 0.20269662921348286
Iteracao: 2 Erro: 1.3086561209990717
xmin: [0.76342968 0.58282478] f(xmin): 0.0559655168340664

```

```

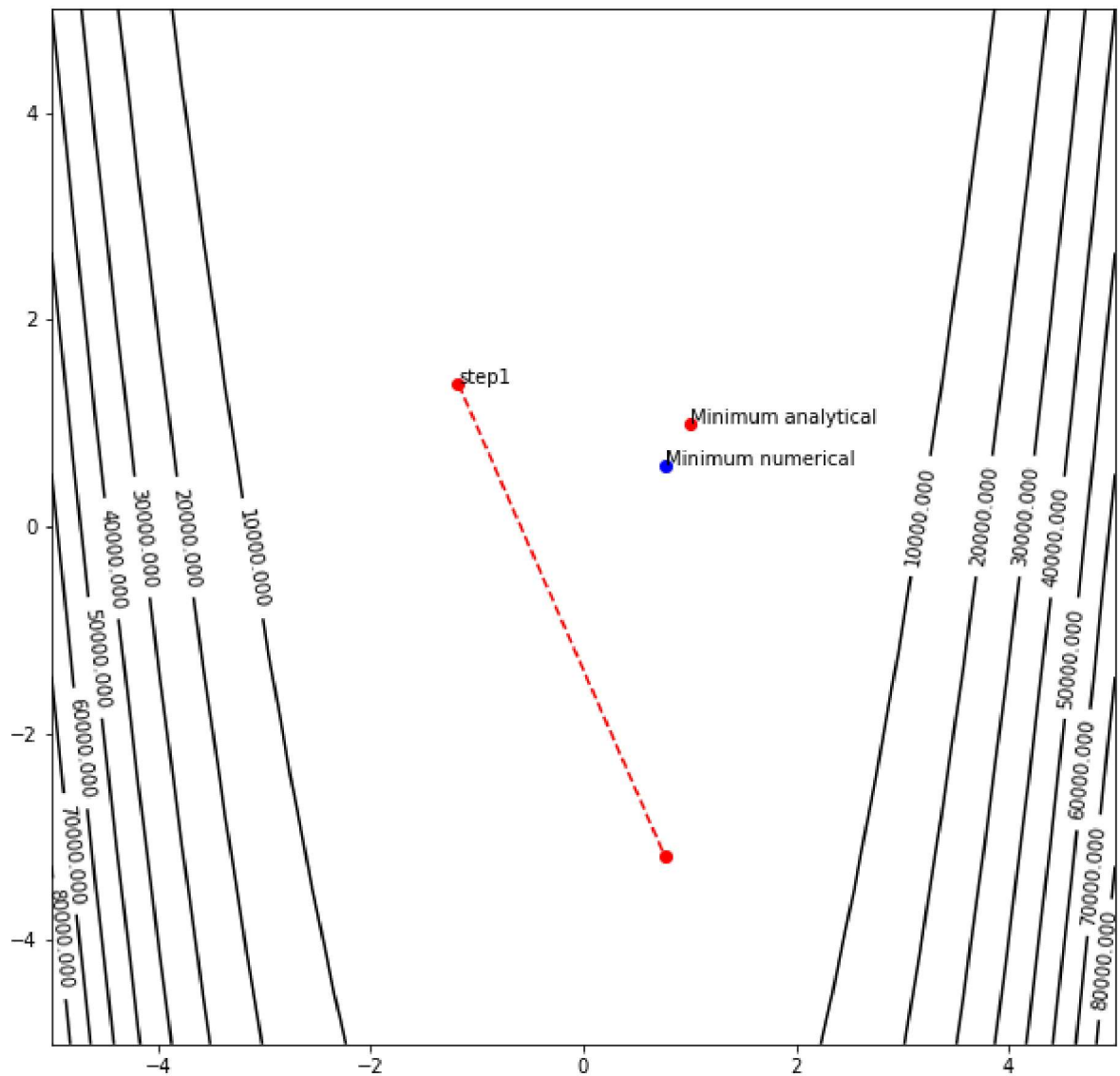
In [11]: c1 = np.linspace(-5, 5, 50)
c2 = np.linspace(-5, 5, 50)
C1, C2 = np.meshgrid(c1, c2)
Z3 = f3(C1, C2)

```

```

In [12]: plt.figure(figsize=(10,10))
contours = plt.contour(C1, C2, Z3, 10, colors='black')
plt.clabel(contours, inline=True, fontsize=10)
for i in range(1, len(historic)-1):
    plt.plot([historic[i][0], historic[i+1][0]], [historic[i][1], historic[i+1][1]],
    plt.annotate("step"+str(i), historic[i], fontsize=10)
plt.scatter(1, 1, color='red')
plt.annotate("Minimum analytical", [1,1], fontsize=10)
plt.scatter(Xmin[0], Xmin[1], color='blue')
plt.annotate("Minimum numerical", [Xmin[0],Xmin[1]], fontsize=10)
plt.show()

```



### Problem 6.33

Compare the gradients of the function:

$$f(x_1, x_2) = 100(x_2 - x_1^2)^2 + (1 - x_1)^2$$

at  $X = (0.5, 0.5)$ , given by the following methods:

Use a perturbation of 0.005 for  $x_1$  and  $x_2$  in the finite-difference methods.

```
In [13]: def F633(x1, x2):
          return 100*(x2-x1**2)**2+(1-x1)**2

          def gradF633(x1, x2):
              return 400*(x1**3-x1*x2)+2*(x1-1), 200*(x2-x1**2)
```

```
In [14]: gradF633(0.5,0.5)
```

```
Out[14]: (-51.0, 50.0)
```

(a) Analytical differentiation

$$\nabla f(x_1, x_2) = [400(x_1^3 - x_1x_2), 200(x_2 - x_1^2)]$$

$$\nabla f(0.5, 0.5) = [400(0.5^3 - 0.5 \times 0.5), 200(0.5 - 0.5^2)]$$

$$\nabla f(0.5, 0.5) = [-51.0, 50.0]$$

(b) Central difference method

```
In [15]: def difCentral(x1, x2, function, delta1, delta2):
          fx1, fx2 = (function(x1+delta1, x2)-function(x1-delta1, x2))/(2*delta1), (
                    function(x1, x2+delta2)-function(x1, x2-delta2))/(2*delta2)
          return fx1, fx2
```

```
In [16]: difCgradx1, difCgradx2 = difCentral(0.5, 0.5, F633, 0.005, 0.005)
          print("Central Difference:", format(difCgradx1, '.4f'), ", ", format(difCgradx2, '.4f'))
```

Central Difference: -50.9950 , 50.0000

(c) Forward difference method

```
In [17]: def difForward(x1, x2, function, delta1, delta2):
          fx1, fx2 = (function(x1+delta1, x2)-function(x1, x2))/(delta1), (
                    function(x1, x2+delta2)-function(x1, x2))/(delta2)
          return fx1, fx2
```

```
In [18]: difFgradx1, difFgradx2 = difForward(0.5, 0.5, F633, 0.005, 0.005)
          print("Forward Difference:", format(difFgradx1, '.4f'), ", ", format(difFgradx2, '.4f'))
```

Forward Difference: -50.7400 , 50.5000

(d) Backward difference method

```
In [19]: def difBackward(x1, x2, function, delta1, delta2):
          fx1, fx2 = (function(x1, x2)-function(x1-delta1, x2))/(delta1), (
                    function(x1, x2)-function(x1, x2-delta2))/(delta2)
          return fx1, fx2
```

```
In [20]: difBgradx1, difBgradx2 = difBackward(0.5, 0.5, F633, 0.005, 0.005)
          print("Backward Difference:", format(difBgradx1, '.4f'), ", ", format(difBgradx2, '.4f'))
```

Backward Difference: -51.2500 , 49.5000

## Problem 6.43

Minimize

$$f(x_1, x_2) = 2x_1^2 + x_2^2$$

by using the steepest descent method with the starting point (1, 2) (two iterations only).

To steepest descent we have:

$$X_{i+1} = X_i - \lambda^* \nabla f(X_i)$$

with:

$$\lambda^* = \operatorname{argmin}[f(X_i + \lambda \nabla f(X_i))]$$

```
In [21]:
def F643(x):
    return 2*x[0]**2+x[1]**2

def gradF643(x):
    return np.array([[4*x[0]], [2*x[1]]])

def lambd(x, gradF):
    lamb = (2*x[0]*gradF(x)[0]+x[1]*gradF(x)[1])/(2*gradF(x)[0]**2+gradF(x)[1]**2)
    return lamb

def steepestDescent(x, gradFunction, lambdaFunction, itermax, tol = 0.001):
    x1, x2, iteration, erro = x, 0, 0, 10**10

    while iteration < itermax+1:
        x1 = np.reshape(x1, x.shape)
        lamb = lambdaFunction(x1, gradFunction)
        historic.append(x1)
        x2 = x1-np.transpose(lamb*gradFunction(x1))
        erro = 0.5*np.sqrt(np.sum(x2-x1)**2)
        x1 = x2
        x2 = np.reshape(x2, x.shape)
        print("Minimun step", iteration+1, ":", x2)

        if erro < tol:
            print("Erro final:", erro)
            break
        iteration = iteration + 1

    return x2, historic
```

```
In [22]:
x, tol = np.array([1,2]), 10**(-3)
xmin, hist = steepestDescent(x, gradF643, lambd, 2)
```

```
Minimun step 1 : [-0.33333333  0.66666667]
Minimun step 2 : [0.11111111  0.22222222]
Erro final: 5.551115123125783e-17
```

## Problem 6.44

Minimize

$$f(x_1, x_2, x_3) = x_1^2 + 3x_2^2 + 6x_3^2$$

by the Newton's method using the starting point as (2, -1, 1).

```
In [23]:
def f4(x):
    return (x[0]**2+3*x[1]**2+6*x[2]**2)

def gradf4(x):
    return (np.vstack((2*x[0], 6*x[1], 12*x[2])))

def F644(x):
    return (x[0]**2+3*x[1]**2+6*x[2]**2)

def gradF644(x):
    return np.array([[2*x[0]], [6*x[1]], [12*x[2]]])
```

```
def hessianF644(x):
    return np.array([[2, 0, 0], [0, 6, 0], [0, 0, 12]])
```

In [24]:

```
x0 = np.array([2, -1, 1])
Xmin, historic = newtonMethod(x0, F644, gradF644, hessianF644, 10, 0.01)
print("xmin:", Xmin, "f(xmin):", F644(Xmin))
```

```
Iteracao: 0 Erro: 10000000000
Iteracao: 1 Erro: 1.0
Erro final: 0.0
xmin: [0. 0. 0.] f(xmin): 0.0
```

---

## Problem 6.47

Solve the following system of equations using Newton's method of unconstrained minimization with the starting point  $\mathbf{X} = (0,0,0)$

$$\begin{bmatrix} 2 & -1 & 1 \\ 1 & 2 & 0 \\ 3 & 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 3 \end{bmatrix} \quad (3)$$

In [25]:

```
def F647(x):
    return 14*x[0]**2+6*x[1]**2+5*x[2]**2+6*x[0]*x[1]+2*x[1]*x[2]+16*x[0]*x[2]-14*x[0]-8*x[1]-10*x[2]+10

def gradF647(x):
    return np.array([28*x[0]+6*x[1]+16*x[2]-14], [6*x[0]+12*x[1]+2*x[2]-8], [16*x[0]+2*x[1]+10*x[2]-10])

def hessianF647(x):
    return np.array([28, 6, 16], [6, 12, 2], [16, 2, 10])
```

In [26]:

```
x0 = np.array([0, 0, 0])
X, historic = newtonMethod(x0, F647, gradF647, hessianF647, 10, 0.01)
print("Final solution:", X)
```

```
Iteracao: 0 Erro: 10000000000
Iteracao: 1 Erro: 1.4999999999999999
Erro final: 4.440892098500626e-16
Final solution: [-2.  1.  4.]
```

## References:

1. Engineering Optimization Theory and Practice, 4th, Singiresu S. Rao

Link:

<https://github.com/antonioanunciacao/Otimizacao-Nao-Linear>