# Quarta Lista de Exercícios - OTIMIZACAO NAO LINEAR

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Chapter 6: Read Sections 6.1, 6.9 and 6.11

```
import numpy as np
import numdifftools as nd
import matplotlib.pyplot as plt
import warnings
warnings.filterwarnings('ignore')
```

#### Problem 6.8

Plot the contours of the following function over the region,  $(-5 \le x1 \le 5, -3 \le x2 \le 6)$  and identify the optimum point:

$$f(x_1, x_2) = (x_1 + 2x_2 - 7)^2 + (2x_1 + x_2 - 5)^2$$

```
def f1(x1, x2):
    return ((x1+2*x2-7)**2)+((2*x1+x2-5)**2)

def df1(x1, x2):
    return np.vstack((2*(x1+2*x2-7), 2*(2*x1+x2-5)))
```

```
a1 = np.linspace(-5, 5, 50)
a2 = np.linspace(-3, 6, 50)
A1, A2 = np.meshgrid(a1, a2)
Z1 = f1(A1, A2)
```

Gradient of f(x1, x2):

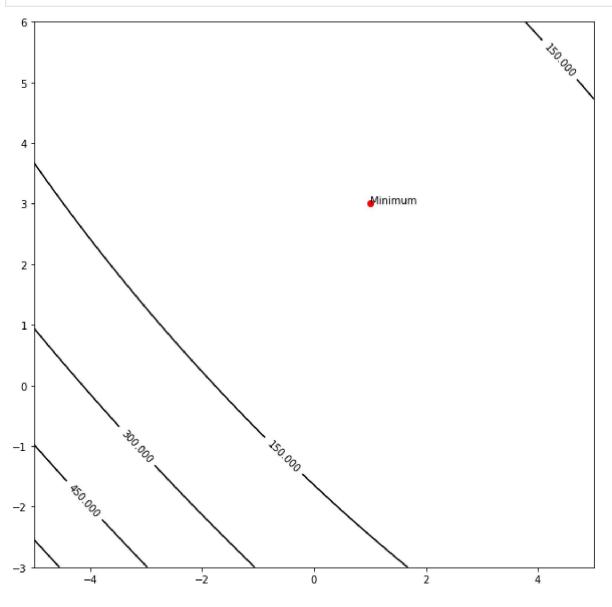
$$\begin{bmatrix} 10 & 8 \\ 8 & 10 \end{bmatrix} x \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 34 \\ 38 \end{bmatrix} \tag{1}$$

Hessian Matrix:

$$H(X) = \begin{bmatrix} 10 & 8 \\ 10 & 8 \end{bmatrix} \tag{2}$$

```
plt.figure(figsize=(10,10))
  contours = plt.contour(A1, A2, Z1, 5, colors='black')
  plt.clabel(contours, inline=True, fontsize=10)
  plt.scatter(X1[0], X1[1], color='red')
```

plt.annotate("Minimum", X1, fontsize=10)
plt.show()



## Problem 6.9:

Plot the contours of the following function in the two dimensional (x1, x2) space over the region  $(-4 \le x1 \le 4, -3 \le x2 \le 6)$  and identify the optimum point:

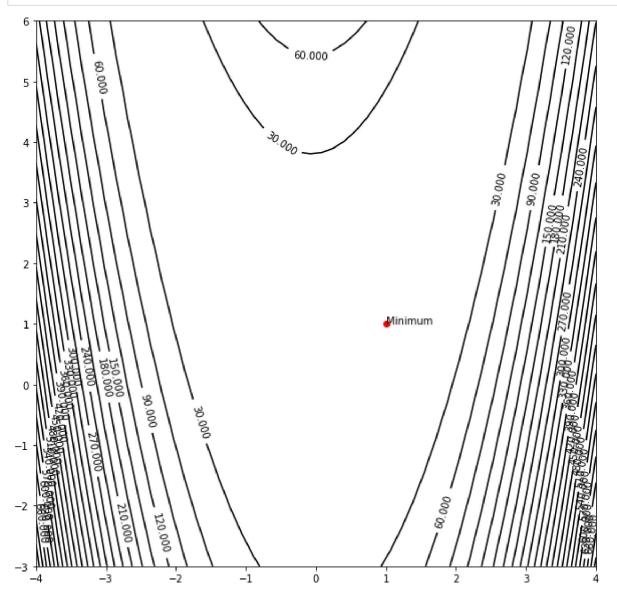
$$f(x_1,x_2) = 2(x_2 - x_1^2)^2 + (1 - x_1)^2$$

```
In [6]:
    def f2(x1,x2):
        return 2*(x2-x1**2)**2+(1-x1)**2

    def gradf2(x1,x2):
        return np.vstack((-8*(x1*x2-x1**3)-2*(1-x1), 2*(x2-x1**2)))
In [7]:
```

```
In [7]:
b1 = np.linspace(-4, 4, 50)
b2 = np.linspace(-3, 6, 50)
B1, B2 = np.meshgrid(b1, b2)
Z2 = f2(B1, B2)
```

```
In [8]: plt.figure(figsize=(10,10))
    contours = plt.contour(B1, B2, Z2, 25, colors='black')
    plt.clabel(contours, inline=True, fontsize=10)
    plt.scatter(1, 1, color='red')
    plt.annotate("Minimum", [1,1], fontsize=10)
    plt.show()
```



## Problem 6.20

Perform two iterations of the Newton's method to minimize the function:

$$f(x_1,x_2) = 100(x_2 - x_1^2)^2 + (1 - x_1)^2$$

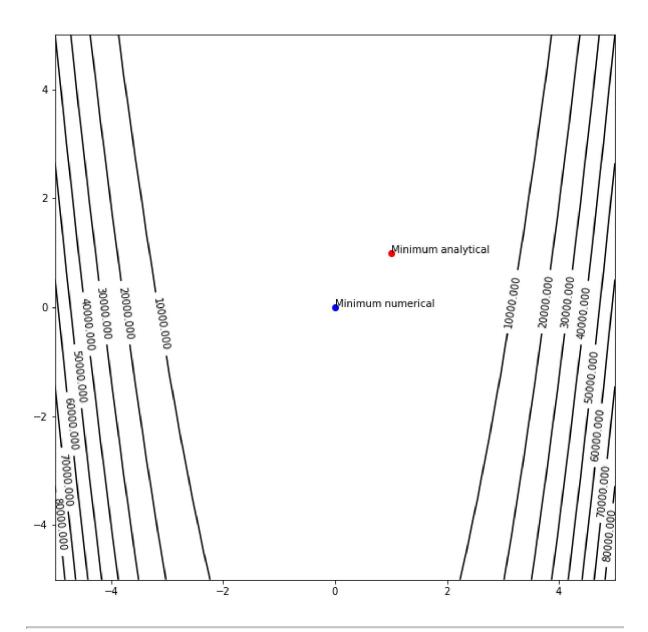
from the starting point (-1.2, 1.0)

```
In [9]:
    def f3(x1, x2):
        return 100*(x2-x1**2)**2+(1-x1)**2

def F620(x):
        return 100*(x[1]-x[0]**2)**2+(1-x[0])**2

def gradF620(x):
    return np.array([[-400*x[0]*(x[1]-x[0]**2)-2*(1-x[0])], [200*(x[1]-x[0]**2)]])
```

```
def hessianF620(x):
               return np.array([[-400*x[1]+1200*x[0]**2+2, -400*x[0]], [-400*x[0], 200]])
           def newtonMethod(start, function, gradFunction, hessianFunction, maxiter, tol = 0.00
               x1, iteration, erro = start, 0, 10**10
               historic = []
               while iteration < (maxiter+1):</pre>
                   print("Iteracao:", iteration, "Erro:", erro)
                   x1 = np.reshape(x1, start.shape)
                   historic.append(x1)
                   g = gradFunction(x1)
                   j_inv = np.linalg.inv(hessianFunction(x1))
                   x2 = x1 - np.transpose(np.dot(j_inv, g))
                   erro = 0.5*np.sqrt(np.sum(x2-x1)**2)
                   x1 = x2
                   x2 = np.reshape(x2, start.shape)
                   iteration = iteration + 1
                   if erro < tol:</pre>
                       print("Erro final:", erro)
                       break
               return x2, historic
In [10]:
           x0 = np.array([-1.2, 1])
           Xmin, historic = newtonMethod(x0, F620, gradF620, hessianF620, 2, 0.00001)
           print("xmin:", Xmin, "f(xmin):", F620(Xmin))
          Iteracao: 0 Erro: 10000000000
          Iteracao: 1 Erro: 0.20269662921348286
          Iteracao: 2 Erro: 1.3086561209990717
          xmin: [0.76342968 0.58282478] f(xmin): 0.0559655168340664
In [11]:
          c1 = np.linspace(-5, 5, 50)
           c2 = np.linspace(-5, 5, 50)
           C1, C2 = np.meshgrid(c1, c2)
           Z3 = f3(C1, C2)
In [28]:
           plt.figure(figsize=(10,10))
           contours = plt.contour(C1, C2, Z3, 10, colors='black')
           plt.clabel(contours, inline=True, fontsize=10)
           for i in range(1, len(historic)-1):
               plt.plot([historic[i][0], historic[i+1][0]], [historic[i][1], historic[i+1][1]],
               plt.annotate("step"+str(i), historic[i], fontsize=10)
           plt.scatter(1, 1, color='red')
           plt.annotate("Minimum analytical", [1,1], fontsize=10)
           plt.scatter(Xmin[0], Xmin[1], color='blue')
           plt.annotate("Minimum numerical", [Xmin[0],Xmin[1]], fontsize=10)
           plt.show()
```



# Problem 6.33

Compare the gradients of the function:

$$f(x_1, x_2) = 100(x_2 - x_1^2)^2 + (1 - x_1)^2$$

at X = (0.5, 0.5), given by the following methods:

Use a perturbation of 0.005 for x1 and x2 in the finite-difference methods.

Out[14]: (-51.0, 50.0)

(a) Analytical differentiation

$$abla f(x_1,x_2) = [400(x_1^3 - x_1x_2), 200(x_2 - x_1^2)]$$

$$abla f(0.5,0.5) = [400(0.5^3 - 0.5 \times 0.5), 200(0.5 - 0.5^2)]$$

$$abla f(0.5,0.5) = [-51.0, 50.0]$$

(b) Central difference method

```
In [15]:
           def difCentral(x1, x2, function, delta1, delta2):
               fx1, fx2 = (function(x1+delta1, x2)-function(x1-delta1, x2))/(2*delta1), (
                   function(x1, x2+delta2)-function(x1, x2-delta2))/(2*delta2)
               return fx1, fx2
In [16]:
           difCgradx1, difCgradx2 = difCentral(0.5, 0.5, F633, 0.005, 0.005)
           print("Central Difference:", format(difCgradx1,'.4f'),", ", format(difCgradx2,'.4f')
          Central Difference: -50.9950 , 50.0000
         (c) Forward difference method
In [17]:
           def difForward(x1, x2, function, delta1, delta2):
               fx1, fx2 = (function(x1+delta1, x2)-function(x1, x2))/(delta1), (
                   function(x1, x2+delta2)-function(x1, x2))/(delta2)
               return fx1, fx2
In [18]:
           difFgradx1, difFgradx2 = difForward(0.5, 0.5, F633, 0.005, 0.005)
           print("Forward Difference:", format(difFgradx1,'.4f'),", ", format(difFgradx2,'.4f')
          Forward Difference: -50.7400 , 50.5000
         (d) Backward difference method
In [19]:
           def difBackward(x1, x2, function, delta1, delta2):
               fx1, fx2 = (function(x1, x2)-function(x1-delta1, x2))/(delta1), (
                   function(x1, x2)-function(x1, x2-delta2))/(delta2)
               return fx1, fx2
In [20]:
           difBgradx1, difBgradx2 = difBackward(0.5, 0.5, F633, 0.005, 0.005)
           print("Backward Difference:", format(difBgradx1,'.4f'),", ", format(difBgradx2,'.4f')
          Backward Difference: -51.2500 , 49.5000
```

## Problem 6.43

Minimize

$$f(x_1,x_2)=2x_1^2+x_2^2$$

by using the steepest descent method with the starting point (1, 2) (two iterations only).

To steepest descent we have:

$$X_{i+1} = X_i - \lambda^* \nabla f(X_i)$$

with:

```
In [21]:
           def F643(x):
               return 2*x[0]**2+x[1]**2
           def gradF643(x):
               return np.array([[4*x[0]], [2*x[1]]])
           def lambd(x, gradF):
               lamb = (2*x[0]*gradF(x)[0]+x[1]*gradF(x)[1])/(2*gradF(x)[0]**2+gradF(x)[1]**2)
               return lamb
           def steepestDescent(x, gradFunction, lambdaFunction, itermax, tol = 0.001):
               x1, x2, iteration, erro = x, 0, 0, 10**10
               while iteration < itermax+1:</pre>
                   x1 = np.reshape(x1, x.shape)
                   lamb = lambdaFunction(x1, gradFunction)
                   historic.append(x1)
                   x2 = x1-np.transpose(lamb*gradFunction(x1))
                   erro = 0.5*np.sqrt(np.sum(x2-x1)**2)
                   x1 = x2
                   x2 = np.reshape(x2, x.shape)
                   print("Minimun step", iteration+1, ":", x2)
                   if erro < tol:</pre>
                       print("Erro final:", erro)
                   iteration = iteration + 1
               return x2, historic
```

```
In [22]:
    x, tol = np.array([1,2]), 10**(-3)
    xmin, hist = steepestDescent(x, gradF643, lambd, 2)
```

Minimun step 1 : [-0.3333333 0.66666667] Minimun step 2 : [0.11111111 0.22222222] Erro final: 5.551115123125783e-17

### Problem 6.44

Minimize

$$f(x_1, x_2, x_3) = x_1^2 + 3x_2^2 + 6x_3^2$$

by the Newton's method using the starting point as (2,-1, 1).

```
In [23]:
    def f4(x):
        return (x[0]**2+3*x[1]**2+6*x[2]**2)

    def gradf4(x):
        return (np.vstack((2*x[0], 6*x[1], 12*x[2])))

    def F644(x):
        return (x[0]**2+3*x[1]**2+6*x[2]**2)

    def gradF644(x):
        return np.array([[2*x[0]], [6*x[1]], [12*x[2]]])
```

```
return np.array([[2, 0, 0], [0, 6, 0], [0, 0, 12]])

x0 = np.array([2, -1, 1])
    Xmin, historic = newtonMethod(x0, F644, gradF644, hessianF644, 10, 0.01)
    print("xmin:", Xmin, "f(xmin):", F644(Xmin))

Iteracao: 0 Erro: 10000000000
    Iteracao: 1 Erro: 1.0
    Erro final: 0.0
    xmin: [0. 0. 0.] f(xmin): 0.0
```

#### Problem 6.47

def hessianF644(x):

Solve the following system of equations using Newton's method of unconstrained minimization with the starting point  $\mathbf{X} = (0,0,0)$ 

$$\begin{bmatrix} 2 & -1 & 1 \\ 1 & 2 & 0 \\ 3 & 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 3 \end{bmatrix}$$
 (3)

```
In [25]:
          def F647(x):
              return 14*x[0]**2+6*x[1]*2+5*x[2]**2+6*x[0]*x[1]+2*x[1]*x[
                  2]+16*x[0]*x[2]-14*x[0]-8*x[1]-10*x[2]+10
          def gradF647(x):
              return np.array([[28*x[0]+6*x[1]+16*x[2]-14], [6*x[0]+12*x[
                  1]+2*x[2]-8], [16*x[0]+2*x[1]+10*x[2]-10]])
          def hessianF647(x):
              return np.array([[28, 6, 16],[6, 12, 2], [16, 2, 10]])
In [26]:
          x0 = np.array([0, 0, 0])
          X, historic = newtonMethod(x0, F647, gradF647, hessianF647, 10, 0.01)
          print("Final solution:", X)
         Iteracao: 0 Erro: 10000000000
         Erro final: 4.440892098500626e-16
```

# References:

Final solution: [-2. 1. 4.]

1. Engineering Optimization Theory and Practice, 4th, Singiresu S. Rao