# More convolutional nets

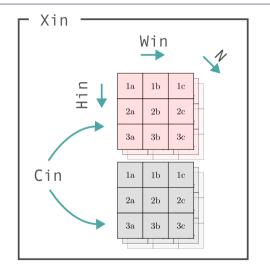
Lecture 09 — CS 577 Deep Learning

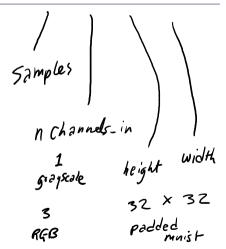
Instructor: Yutong Wang

Computer Science Illinois Institute of Technology

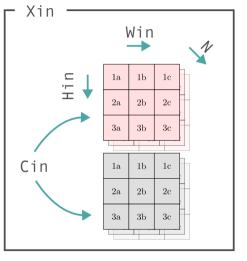
October 16, 2024

# Input image tensor with shape $(N, C_{\text{in}}, H_{\text{in}}, W_{\text{in}})$

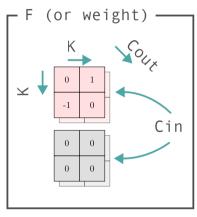




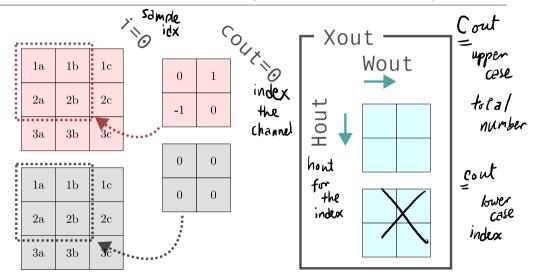
# A single convolution layer $(C_{\text{out}}, C_{\text{in}}, K, K)$

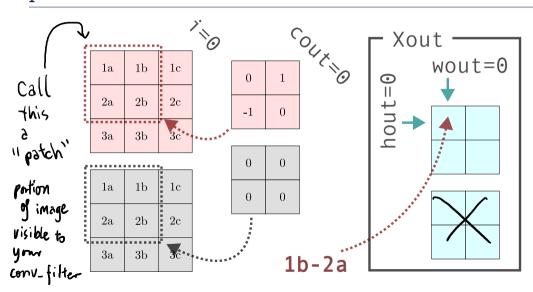


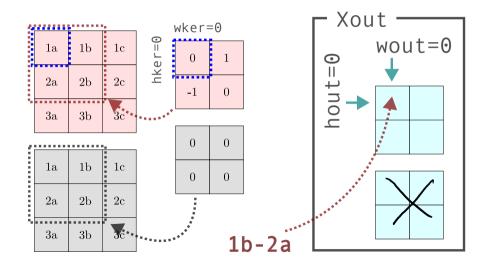
#### Achamels\_out

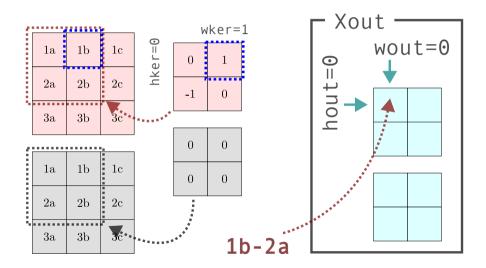


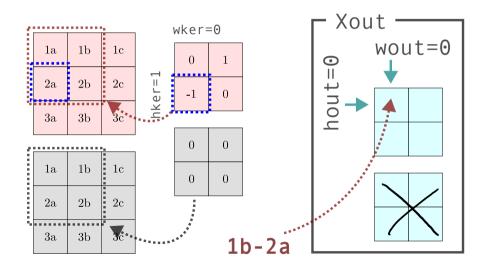
# Output: Yout with shape $(N, C_{\text{out}}, H_{\text{out}}, W_{\text{out}})$

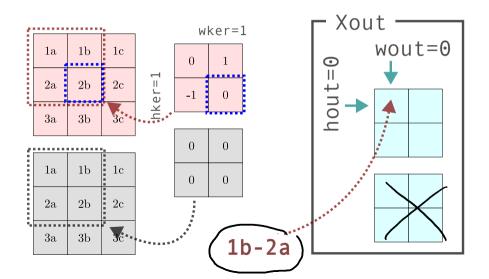


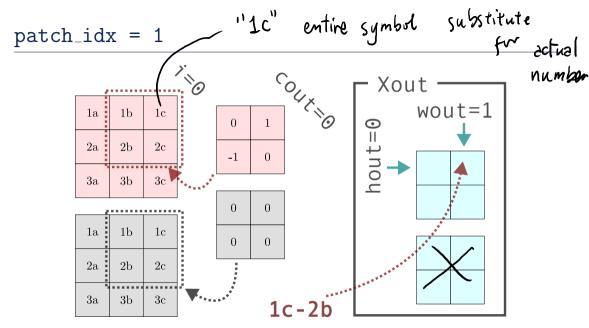


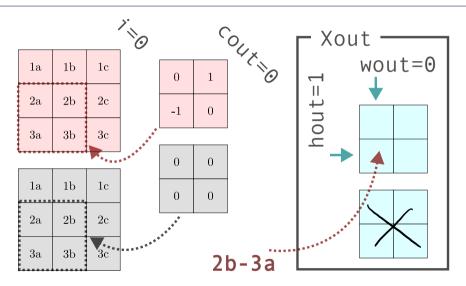


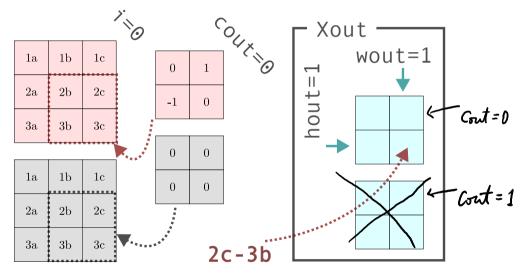




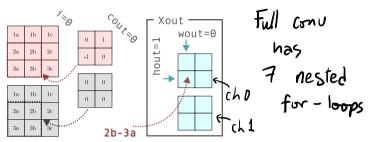








# Sliding window (simple but slow)



```
# Suppose i, c_out, h_out, w_out are already defined, and

# X_out is initialized to all zeros

for cin in range(Cin): # Input channels

for hker in range(K): # Kernel height

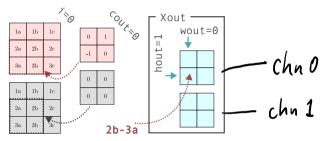
for wker in range(K): # Kernel width

Xout[i, cout, hout, wout] += (

F[cout, cin, hker, wker] *

Xin[i, cin, hout + hker, wout + wker])
```

# Sliding window (simple but slow)



```
# Suppose i, c_out, h_out, w_out are already defined, and
# X_out is initialized to all zeros

for cin in range(Cin): # Input channels

for hker in range(K): # Kernel height

for wker in range(K): # Kernel width

Xout[i, cout, hout, wout] += (

F[cout, cin, hker, wker] *

Xin[i, cin, hout + hker, wout + wker])
```

There's gotta be a better way! "im2col" (Next)

#### "im2col"

Conv-Filter

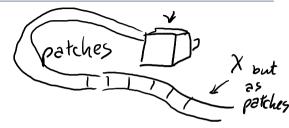
Main idea (in theory)

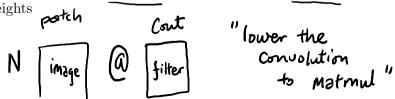
- Keep the window fixed in one spot
- Move the image tensor

Main idea (in theory) practice

- Create patches of the data
- Each patch has the same shape as the convolution filter

• Do matrix multiplication between the (flattened) patches and the (flattened) convolutional filter weights





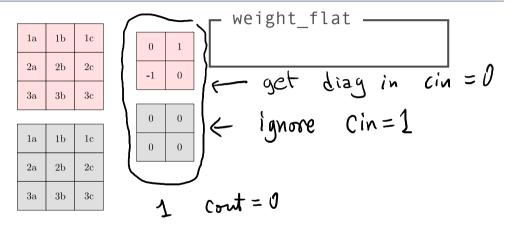
#### "im2col"

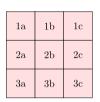
#### Main idea (in theory)

- Keep the window fixed in one spot
- Move the image tensor

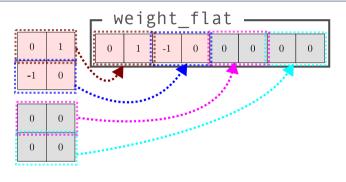
#### Main idea (in theory)

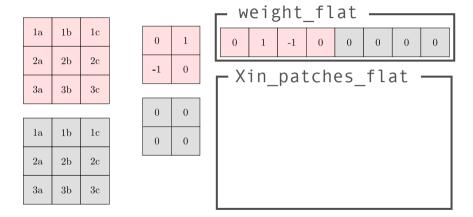
- Create patches of the data
- Each patch has the same shape as the convolution filter
- Do matrix multiplication between the (flattened) patches and the (flattened) convolutional filter weights



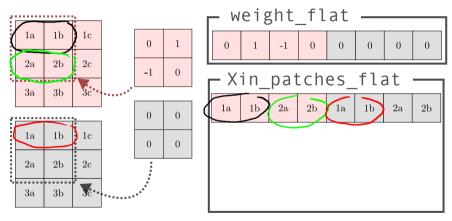


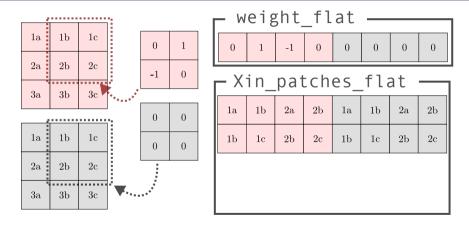
1a	1b	1c
2a	2b	2c
3a	3b	3c

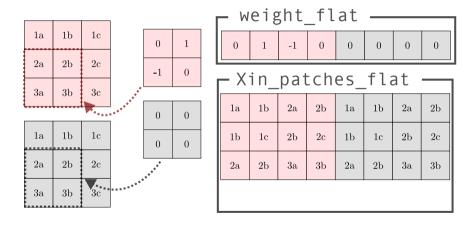


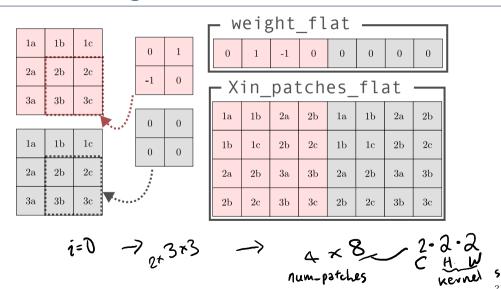


mat-vec multiply

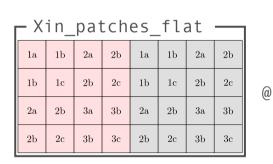




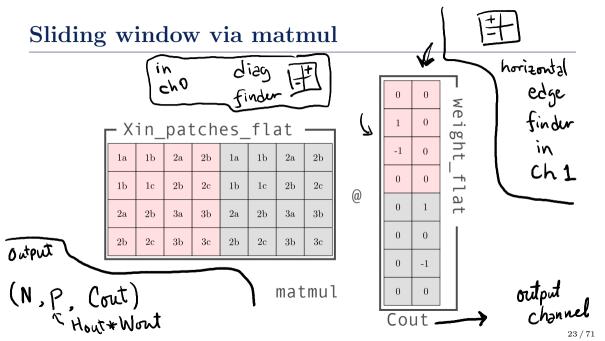


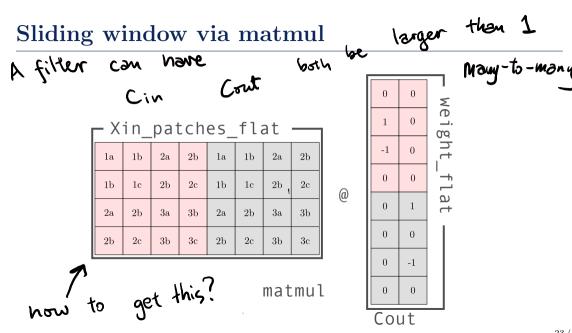


# Sliding window via matmul

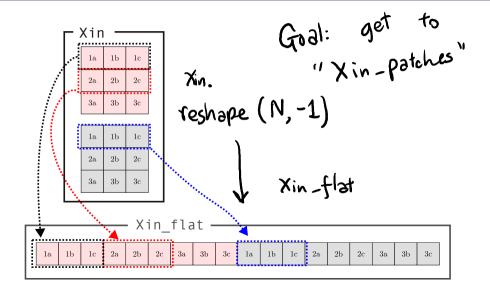


matmul

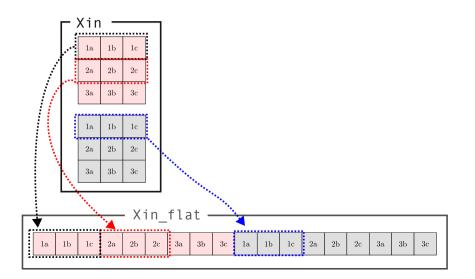




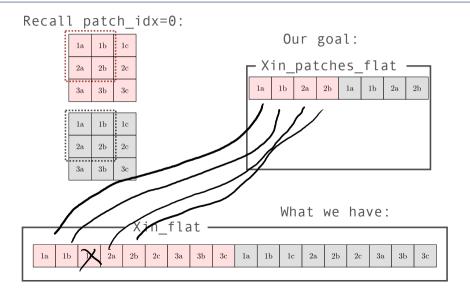
# Flattening Xin into Xin\_flat

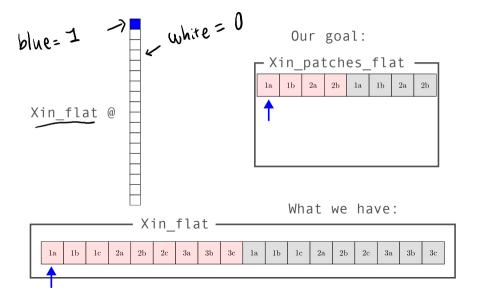


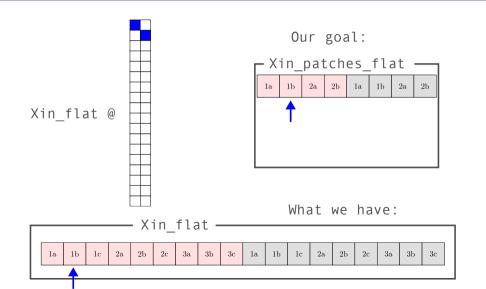
# Flattening Xin into Xin\_flat

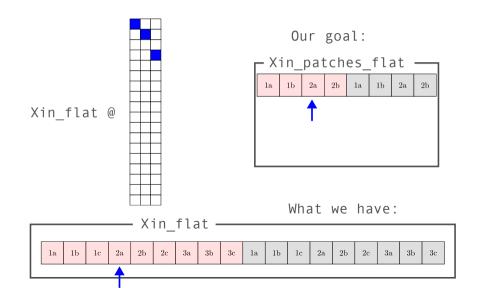


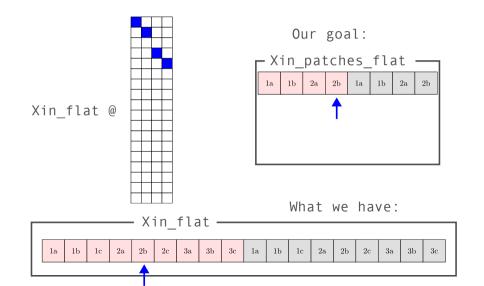
# Flattening Xin into Xin\_flat

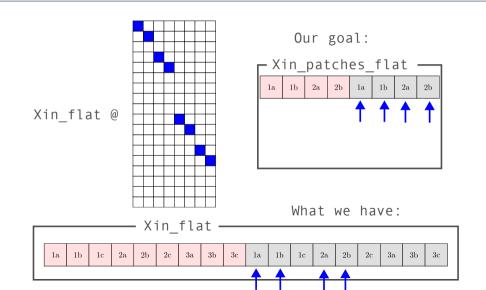


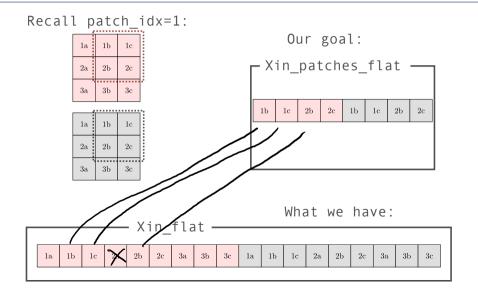


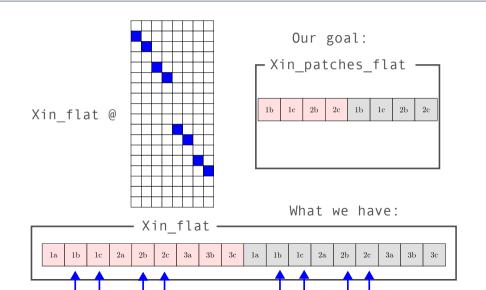


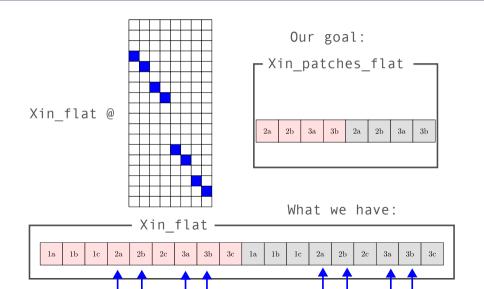


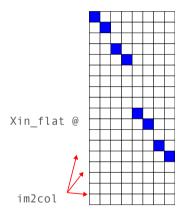






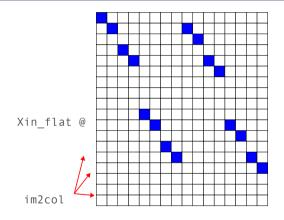






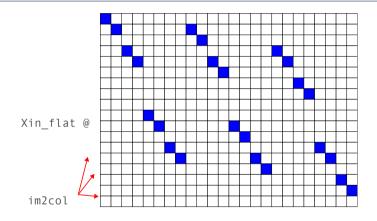
Xin\_im2col



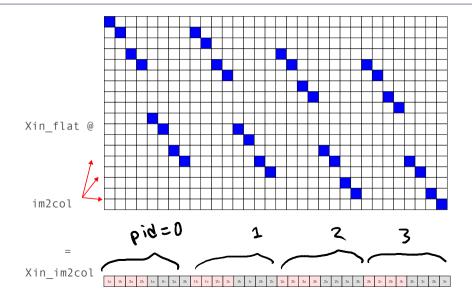


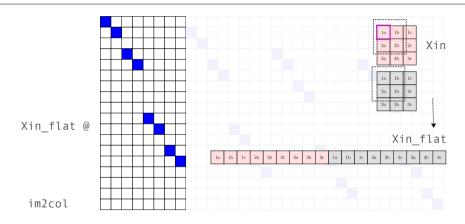
Xin\_im2col





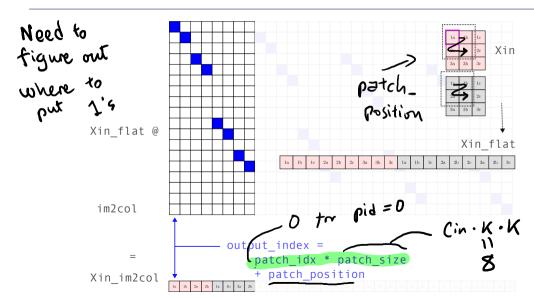
Xin\_im2col

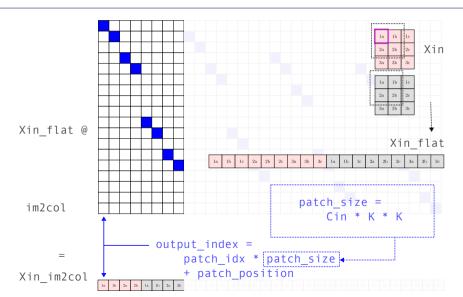


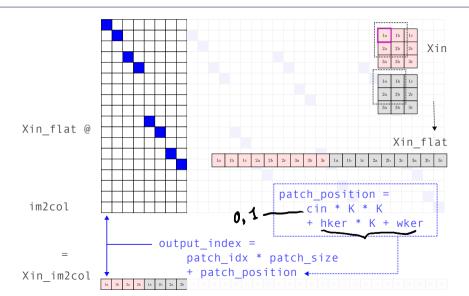


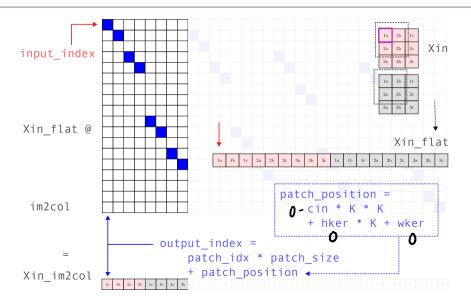
Xin\_im2col



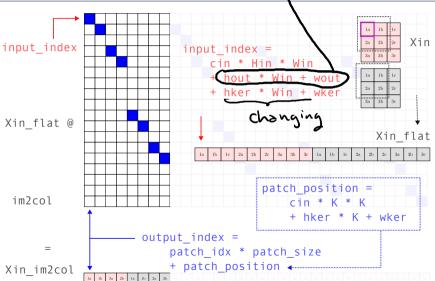


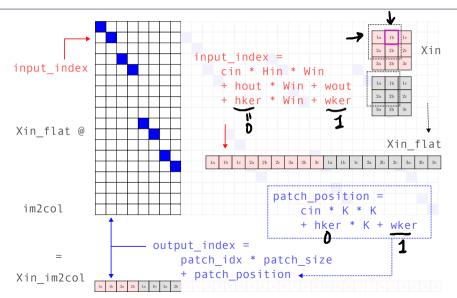


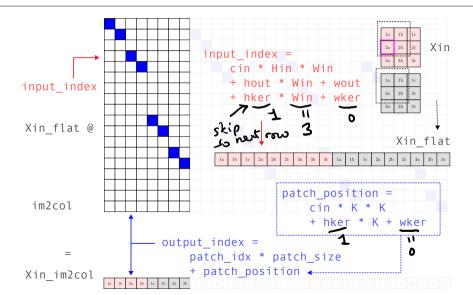


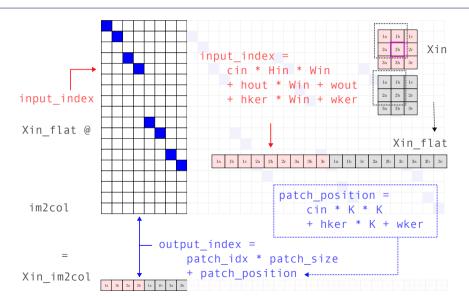


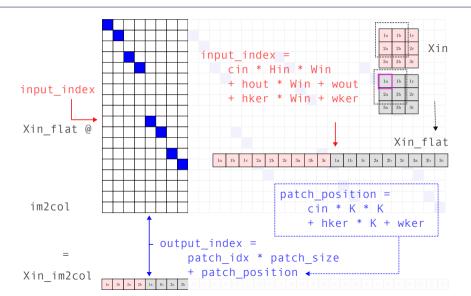
patch-ity = 0

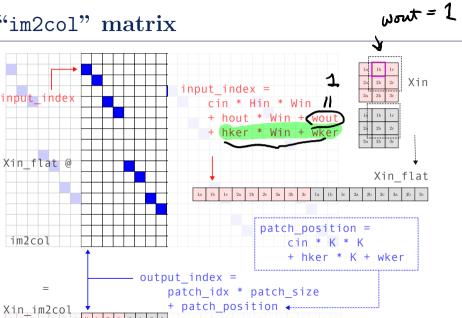


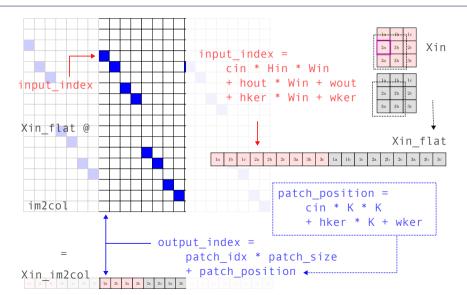












## Putting it all together

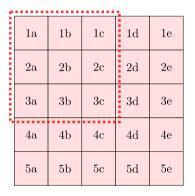
tride create the

```
def im2col_matrix_dense(Xin, K, S=1):
      N, Cin, Hin, Win = Xin.shape
2
      Hout, Wout = Hin - K + 1, Win - K + 1
3
      P = Hout * Wout # Total number of patches per image
4
      patch_size = Cin * K * K # Size of each flattened patch
5
      im2col_mat_dense = np.zeros((Cin * Hin * Win, P * patch_size))
6
      # [main loop on next slide...]
8
Q
      return im2col_mat_dense
10
```

### Putting it all together

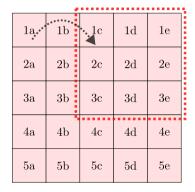
```
# [continued from previous slide...]
      patch_idx = 0
2
      for hout in range(Hout):
3
                                              which vow to place a 1
          for wout in range(Wout):
              for cin in range(Cin):
                  for hker in range(K):
                      for wker in range (K):
                          input index = cin * Hin * Win + hout * Win +
     wout + hker * Win + wker
                          patch_position = cin * K * K + hker * K + wker
9
                          output_index = patch_idx * patch_size +
10
     patch_position
                          im2col_mat_dense[input_index, output_index] = 1
              patch_idx += 1
      which column to place the 1
```

### Stride = 2



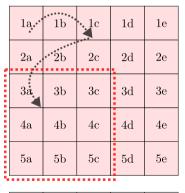
1a	1b	1c	1d	1e
2a	2b	2c	$2\mathrm{d}$	2e

### Stride = 2



1a	1b	1c	1d	1e
2a	2b	2c	2d	2e

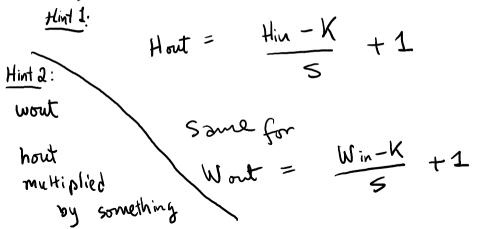
#### Stride = 2



1a	1b	1c	1d	1e
$_{2a}$	2b	2c	2d	2e

### Implement im2col\_matrix\_dense with stride

See lec09-in-class-ex1-im2col.ipynb End of part 1.



## Goal for today: implement LeNet5

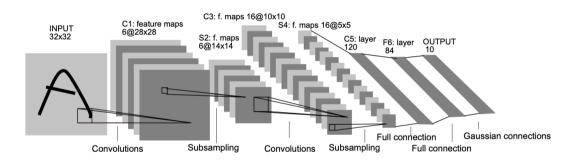
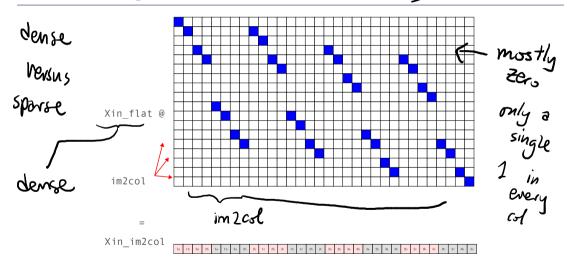


Image from LeCun et al. 1998

# im2col.shape = $C_{\mathrm{in}} \cdot H_{\mathrm{in}} \cdot W_{\mathrm{in}}$ -by- $P \cdot C_{\mathrm{out}} \cdot K^2$



## im2col.shape = $C_{\mathrm{in}} \cdot H_{\mathrm{in}} \cdot W_{\mathrm{in}}$ -by- $P \cdot C_{\mathrm{in}} \cdot K^2$

For 1st convolution layer in LeNet5.

• 
$$H_{\rm in} = W_{\rm in} = 32$$

• 
$$C_{\rm in} = 1$$

• 
$$K = 5$$

• 
$$S = 1$$

• 
$$H_{\text{out}} = H_{\text{in}} - K + 1 = 28$$

• 
$$W_{\text{out}} = W_{\text{in}} - K + 1 = 28$$

• 
$$P = 28 * 28 < 25$$

- Final shape of im2col = 1024 -by- 19600
- 20,070,400 float64's to store  $\approx 160$  MB

### Sparse matrices

#### Pros

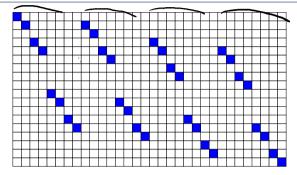
everything else assume to zero

- Store just the non-zero values of the matrix (memory efficient)
- Faster than dense matmul when matrices are mostly zeros (speedier)

#### Cons

- Irregular memory access (less cache-optimization friendly)
- Nightmare for GPUs (as of now, to the best of my knowledge)

### from scipy.sparse import csr\_matrix



### Example

```
data = (1), 2(3)
2 \text{ row\_indices} = (1)2(0,1]
3 \text{ col\_indices} = (0)
 sparse_mat_example = csr_matrix((data, (row_indices, col_indices)),
     shape=(3, 3)
5 sparse_mat_example.toarray()
                                converts back to numpy
 Output:
 array([[0, 0, 3])
      → [1, 1, V]
2
        [0, 2, 0]])
```

### Dense-sparse multiplication

### Implement im2col\_matrix\_sparse

• lec09-in-class-ex2-sparse.ipynb

### Quick update

Can add/mul constants both on left and right now.

```
def __radd__(self, other):
    return self + other

def __rmul__(self, other):
    return self * other

def __rsub__(self, other):
    return (-self) + other

def __rtruediv__(self, other):
    return ag.Tensor(other) / self
```

### Quick update

```
np.movaxis(X, s, d) if s = -1 d = -2
= transpose
```

```
def moveaxis(input, source, destination):
    output = ag.Tensor(np.moveaxis(input.value, source, destination)
, inputs=[input], op="moveaxis")

def _backward():
    input.grad += np.moveaxis(output.grad, source, destination)
    return None
    output._backward = _backward
return output
```

29. moved xis

### Enabling autograd for dense-sparse matmul

- Problem: our current autograd-enabled matmul only supports when both inputs are numpy arrays
- Observation: we don't need to track gradients on the im2col\_mat
- Solution:

12

```
# [sp]arse [c]onstant (non-AG-enabled) [mat]rix [mul]tiplication
        def spcmatmul(input, sparse_mat: csr_matrix):
            output = ag. Tensor(input.value @ sparse_mat,
Xin @ im2col inputs = [input op="spcmatmul")

Spcmot def _backward():
                                  inputs = [input],
                 input.grad += output.grad @ sparse_mat.T
                                                          don't update
sparse_mat
grad
                 return None
            output._backward = _backward
            return output
```

#### lec 09\_ data.csv Exercise 3 • Create the Conv2d layer tiny\_mnist • Create the AvgPool2d layer — • Create the LeNet5 model C3: f. maps 16@10x10 C1: feature maps S4: f. maps 16@5x5 INPUT 6@28x28 32x32 S2: f. maps C5: layer F6: laver OUTPUT 6@14x14

Convolutions

Subsampling

• Create the nn.CrossEntropyLoss ←

Convolutions

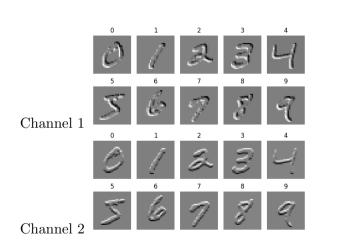
Gaussian connections

Full connection

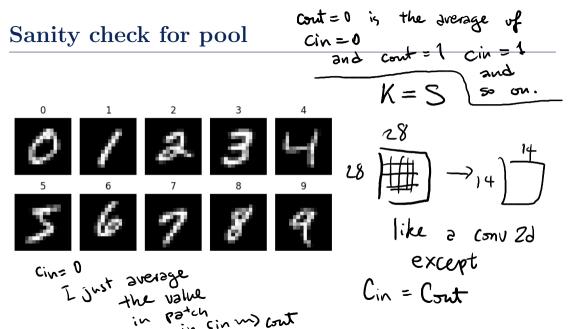
Full connection

Subsampling

### Sanity check for conv2d



tlinks: movezxis sponztmul from EX1:



### Sanity check for training run

You should achieve 100 percentage training accuracy

#### References I

[LeC+98] Yann LeCun, Léon Bottou, Yoshua Bengio, and Patrick Haffner. "Gradient-based learning applied to document recognition". In: Proceedings of the IEEE 86.11 (1998), pp. 2278–2324.