Linear Regression

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In [1]: import numpy as np
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1 Linear Regression

1.1 Least-squares method of fitting

The idea is the minimize the residual sum of squares:

$$RSS(\beta) = \sum_{i=1}^{N} (y_i - x_i^T \beta)^2$$

We can write that in matrix form as follows:

$$RSS(\beta) = (y - X\beta)^{T}(y - X\beta)$$

where *X* is an $N \times p$ matrix with each row representing an input vector and *y* is a an *N*-vector of the outputs in the training set

Differentiating with respect to β , we get

$$\frac{\partial}{\partial \beta} RSS(\beta) = X^{T}(y - X\beta) = 0$$

If X^TX is nonsingular, that is, if it has an inverse (i.e. determinant is non zero), then

$$\hat{\beta} = (X^T X)^{-1} X^T y$$

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In [3]: def least_squares(X, y):
    N = X.shape[0]
    p = X.shape[1]

assert(y.shape[0] == N)

beta = np.linalg.inv(X.T.dot(X)).dot(X.T.dot(y))

return beta
```