# Fundamentals of Computer Graphics

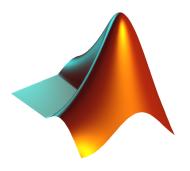
Shape visualization II

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## Exercises

- Voronoi basis
- ICP



Sometimes it is useful to modify the colormap to get saturation effects We can increase the maximum value represented in the colormap:



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The colors remain fixed, but the mapping from values to colors changes

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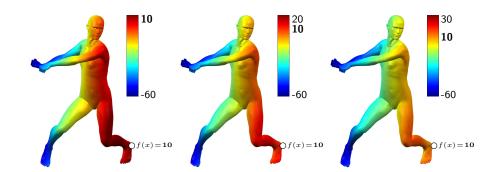
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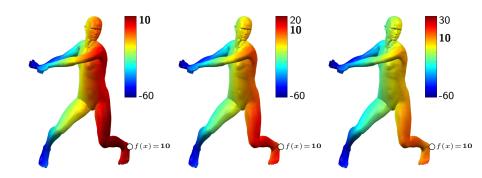


- Values ≥ the max limit are mapped to the max
- Values ≤ the min limit are mapped to the min
- Values between min and max are linearly interpolated

## Increasing the max limit

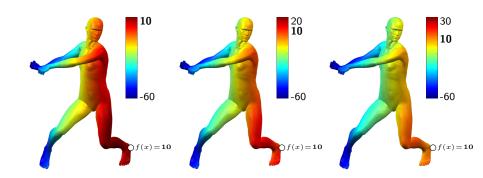


#### Increasing the max limit



For smooth colormaps, the effect is to "flatten out" the colors and make variations less evident

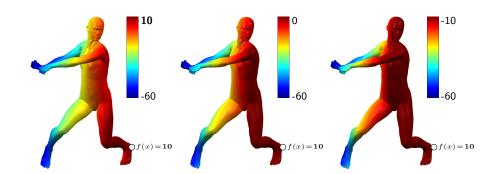
#### Increasing the max limit



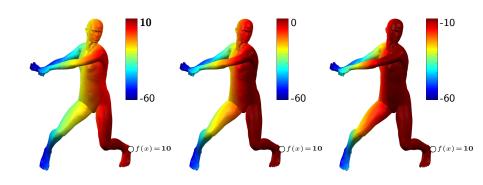
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In Matlab: caxis ([min max]) sets the colormap limits and does all the saturation and interpolation for us

# Decreasing the max limit



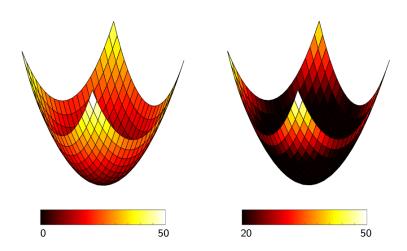
#### Decreasing the max limit



For smooth colormaps, the effect is to saturate the colors and make variations more evident

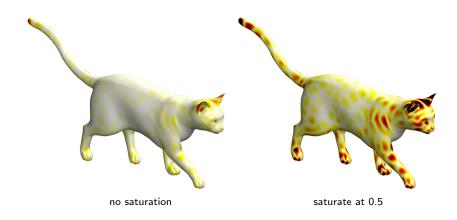
## Example: Visualizing maxima

Increasing the min limit can be useful for visualizing maxima



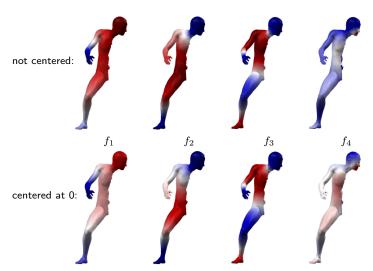
## Example: Visualizing point-wise error

Emphasize areas of large error:



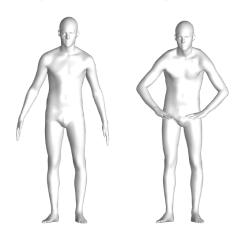
#### Example: Zero-centered functions

If  $f:\to [-1,1]$  but f is not surjective, it can be useful to recenter colors



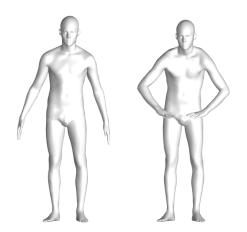
# Visualizing correspondence

How to visualize correspondence between shapes?



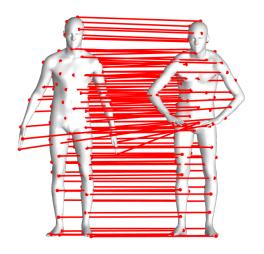
## Visualizing correspondence

How to visualize correspondence between shapes?

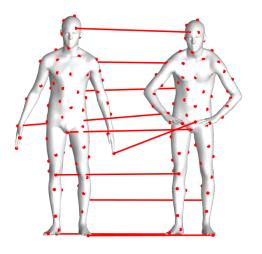


- It might be not one-to-one
- It might be not surjective (formally, not a correspondence)
- It might be sparse

# Visualizing correspondence: Points and lines

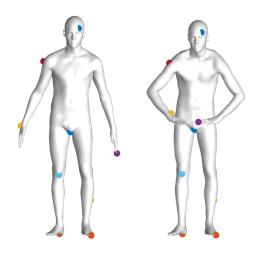


## Visualizing correspondence: Points and lines



Useful for visualizing sparse matches

#### Visualizing correspondence: Points and colors



Useful for visualizing sparse matches (e.g., between landmarks)

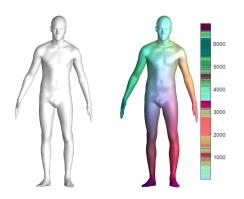
Dense matches (~all points) can be used to color the entire mesh

• Create a colormap with one color for each point  $(n \times 3 \text{ matrix})$ 



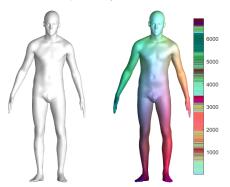
Dense matches (~all points) can be used to color the entire mesh

- Create a colormap with one color for each point  $(n \times 3 \text{ matrix})$
- Plot the vector  $(1, 2, \ldots, n)$



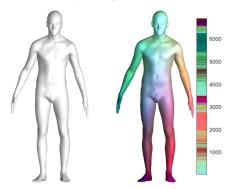
Dense matches ( $\sim$ all points) can be used to color the entire mesh

- Create a colormap with one color for each point  $(n \times 3 \text{ matrix})$
- Plot the vector  $(1, 2, \ldots, n)$
- ullet For smooth colors: interpret x,y,z as R, G, B



Dense matches ( $\sim$ all points) can be used to color the entire mesh

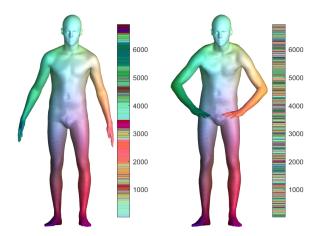
- Create a colormap with one color for each point  $(n \times 3 \text{ matrix})$
- Plot the vector  $(1, 2, \ldots, n)$
- For smooth colors: interpret x, y, z as R, G, B



Warning: New versions of Matlab require shading flat (not interp)

**Case 1:** One match for each source point, surjective (one-to-one map)

Obtain the target colormap by permuting the rows of the source colormap

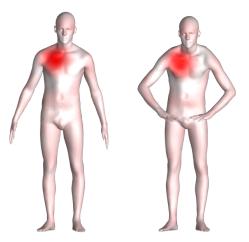


**Case 2:** One match for each source point, not surjective Obtain the source colormap by pulling back the target colormap

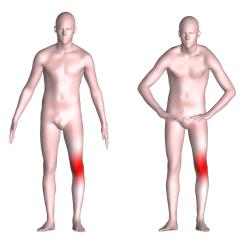


This hides the lack of surjectivity in the correspondence

The correspondence can be used to map functions to functions



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This also works for non-surjective and in general soft maps

## Pov-RAY



## Exercise: Rendering of 1d Euclidean embedding

Replicate in Pov-RAY the rendering from the last exercise of the Oct 04 lecture

- You must use the bluewhitered colormap
- Remember to extend the solution from FPS to entire mesh using the Voronoi regions

Use materials and lights as you like.

Send your renderings in .png format to rodola@di.uniroma1.it, using [FundCG] as the email subject.