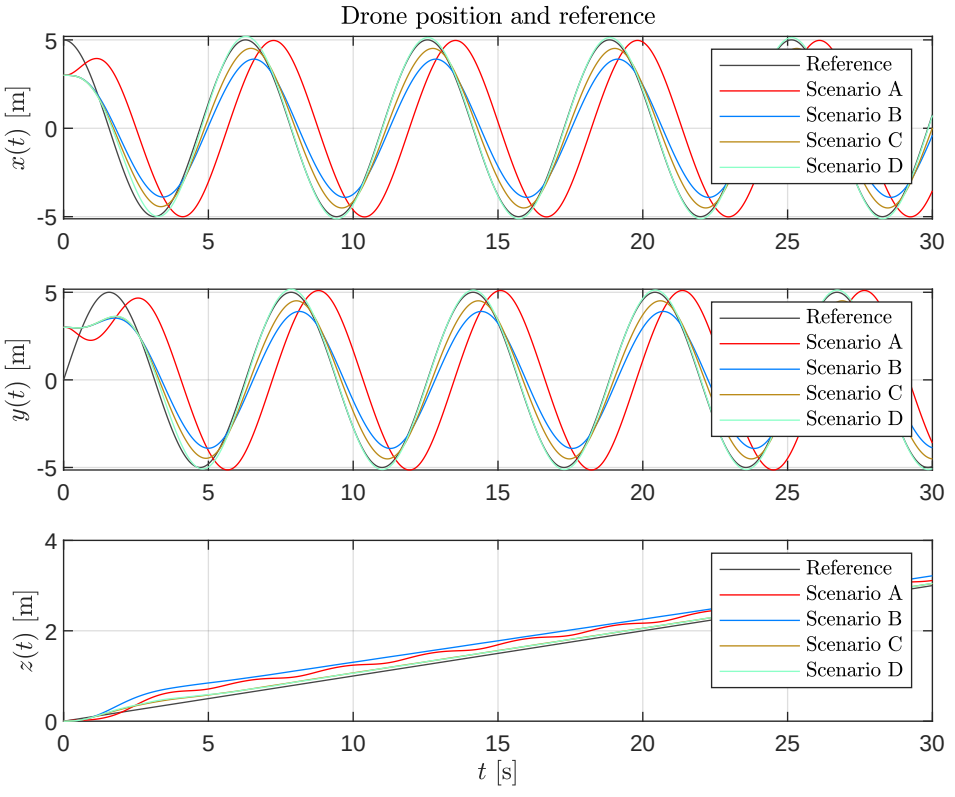
Drone position and reference
$x(t)$ [m]
$y(t)$ [m]
$z(t)$ [m]
t [s]
Reference
Scenario A
Scenario B
Scenario C
Scenario D
5
0
-5
4
2
0
0
5
10
15
20
25
30