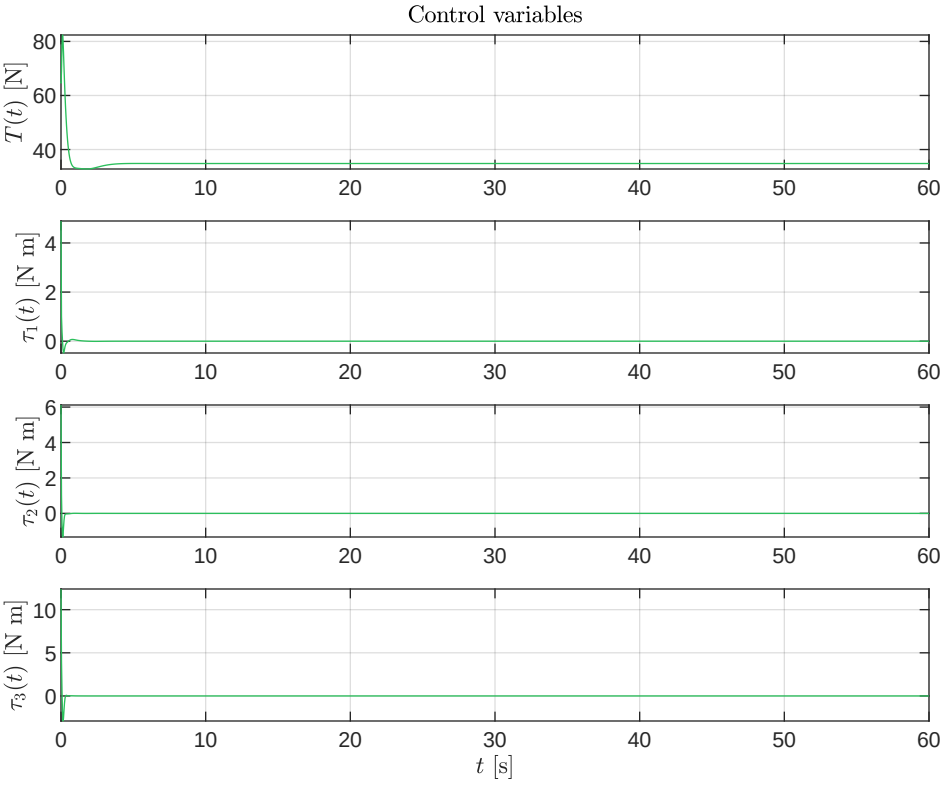
Control variables
$T(t)$ [N]
80
60
40
$\tau_1(t)$ [N m]
4
2
0
$\tau_2(t)$ [N m]
6
4
2
0
$\tau_3(t)$ [N m]
10
5
0
0
10
20
30
40
50
60
t [s]