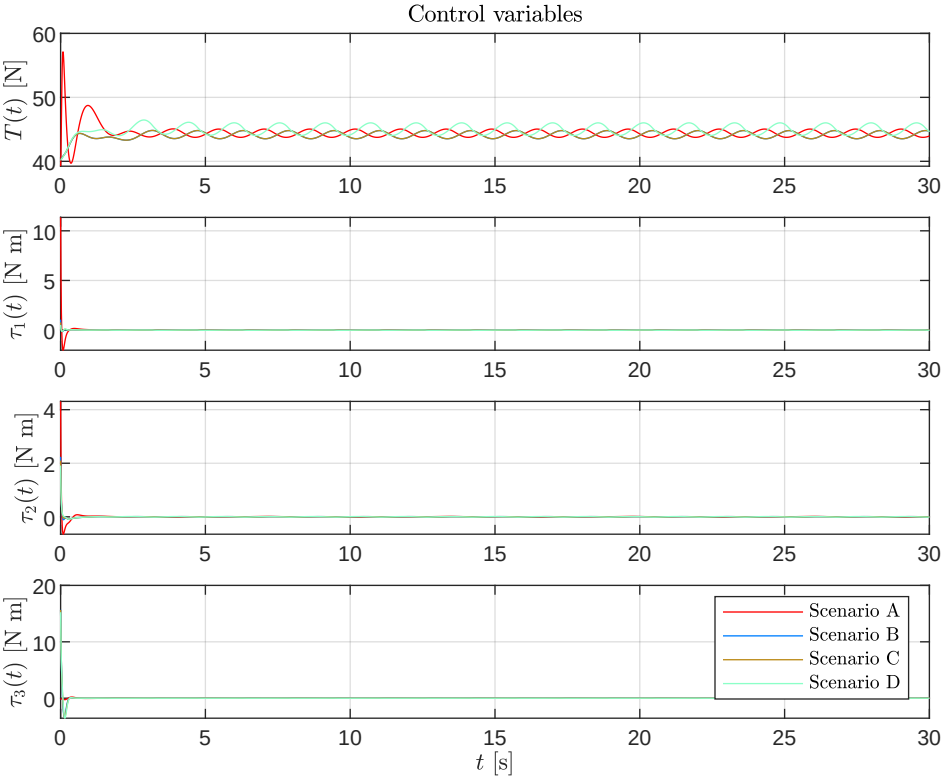
Control variables
$T(t)$ [N]
$\tau_1(t)$ [N m]
$\tau_2(t)$ [N m]
$\tau_3(t)$ [N m]
t [s]
Scenario A
Scenario B
Scenario C
Scenario D