

Parameters

- noLanes: int[]
- dedicatedLane: string/Enum
- dedicatedLaneFlow: int
- pedestrianCrossing: boolean
- crossingTime: int/float
- crossingRPH: int/float
- sequencingPriority: int[]
- + getNoLanes(): int[]
- + getDedicatedLane(): string/Enum
- + getDedicatedLaneFlow(): int
- + hasPedestrianCrossing(): boolean
- + getCrossingTime(): int/float
- + getCrossingRPH: int/float
- + getSequencingPriority: int[]