CS261 Group 29 Planning and Design

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1 Team Planning

1.1 Time Management

In our meetings we have discussed how we are going to manage our time and have agreed to the following deadlines:

Below is a Gantt chart of our planned work schedule.

1.2 Risk Assessment and Management

We have identified the following risks and have agreed on the following mitigation strategies:

1.2.1 Technology Limitations

- Risk description: Team/Team members may be unfamiliar to some tool, libraries, or frameworks, which may cause delays or reduced performance.
- Risk Level: Tolerable
- Risk Likelihood: Moderate

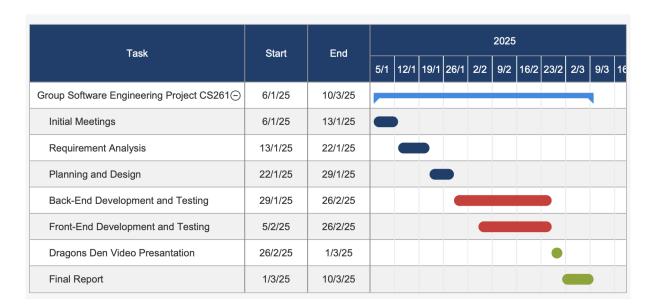


Figure 1: Gantt Chart of Planned Work Schedule

• Mitigation Strategy: Assign tasks to team members based on their expertise in relevant technologies while ensuring everyone is involved in meaningful roles to maintain prductivity and foster teamwork.

1.2.2 Rollback Challenges

- Risk description: Lack of a version control system could prevent from rolling back to the software's last stable state in case of errors
- Risk Level: Catastrophic
- Risk Likelihood: Low
- Mitigation Strategy: Utilise github to always maintain a stable version of the software and updating it when being sure that the changes will not affect its usability.

1.2.3 Testing Risks

- Risk description: Insufficient testing may reduce confidence in the software
- Risk Level: Serious
- Risk Likelihood: Moderate
- Mitigation Strategy: Unit tests will be designed to test the software to make sure that it is working properly.

1.2.4 Time Management

- Risk description: Underestimating task duration or improper prioritization might result in delayed work.
- Risk Level: Serious
- Risk Likelihood: Low
- Mitigation Strategy: The team is meeting in regular intervals to ensure work efficiency and mitigate time related risks.

1.2.5 Requirement Misalignment

• Risk description: During the development of the software, the end product might not be the same as the one describe in the deliverables due to unforeseen circumstances

• Risk Level: Catastrophic

• Risk Likelihood: Low

• Mitigation Strategy: Ensure constant internal communication between the team.

1.2.6 Organisational Risks

 Risk description: Uneven distribution of workload or miscommunication may lead to an incomplete project and delayed work.

• Risk Level: Serious

• Risk Likelihood: Low

 Mitigation Strategy: The team is meeting in regular intervals to ensure work efficiency and mitigate time related risks.

1.2.7 Team Member MIA

• Risk description: Team member is not able to complete their amount of work due to unforeseen circumstances, thus delaying work.

• Risk Level: Serious

• Risk Likelihood: Moderate

• Mitigation Strategy: Team analyses the remaining work from missing member and prioritises and reallocates tasks based on the analysis.

2 Design Pattern

We have decided to adopt the MVC (Model-View-Controller) design pattern for the software. This pattern consists of thre main components: the Model, the View and the Controller. The Model is responsible for the data and the logic of the software, thus it will be our back-end. The View is responsible for the user interface and will be our front-end. The Controller is responsible for the communication between the Model and the View, thus it will be the API that we will use to interface between the front-end and back-end. The image beloww shows the MVC design pattern:

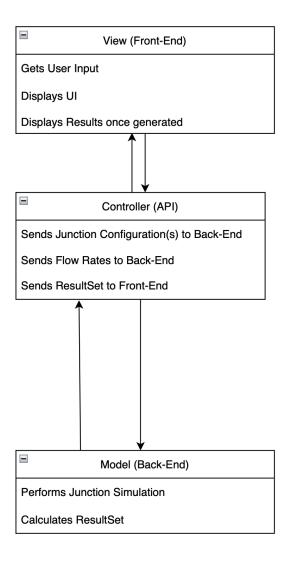


Figure 2: MVC Pattern

Using the MVC pattern will aid us in separating concerns, making the software more modular and easier to maintain. It will also help us separate the development responsibilities between the team members, with some working on the front-end, some on the back-end and some on the API.

3 Front-End

For the front-end, we have decided to use Python and the PyQT toolkit to create the user interface. This is because the whole group is familiar with the frameworks, and it is a powerful and flexible toolkit that will allow us to create a user-friendly interface.

3.1 User Interface

The user interface will be designed to be simple and intuitive, with the user able to input the parameters of the junction configuration. The picture below shows a mock-up of the user interface:

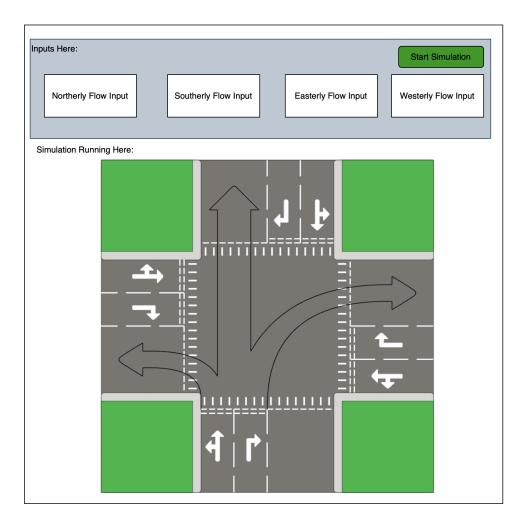


Figure 3: Mock-up of the User Interface

The user will be able to input the number of lanes on each road, the flow rates from each direction to the other directions and specific lanes such as the bus lane, left-turn lane or right-turn lane. The simulation can start by clicking the "Start Simulation" button. The simulation will then run and the results will be displayed on the screen on a tabular format. The figure below shows a mock-up of the results table:

Input Junction Configuration									
Results	■ Northerly Flow	■ Southerly Flow	Easterly Flow	Westerly Flow Westerly Flow	▼				
MaxLength									
MaxWait									
AvgWait									
Overall									
Comparable Junction Configuration									
Results	■ Northerly Flow	Southerly Flow	Easterly Flow	Westerly Flow	▼				
MaxLength									
MaxWait									
AvgWait									
Overall									

Figure 4: Mock-up of the Results Table

3.2 Interfacing with Back-End

Before accepting any user input, the front-end will validate the input to ensure that it is within the required range and that there are no conflicts between certain parameters. The front-end will then pass the input to the back-end using an API. The back-end will run the simulation when the "Start Simulation" button is clicked and return the results to the front-end when the simulation finishes, which will display them on the screen as described above.

3.3 Error Handling

Throughout the whole process of the software, from inputting the parameters to displaying the results, the front-end will have error handling to ensure that the software is robust and reliable. Friendly error messages will be displayed to the user if they input invalid parameters or if there is an error in the simulation. The following pictures show examples of error messages that will be displayed:

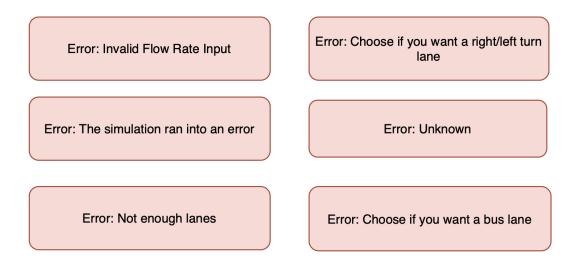


Figure 5: Examples of Error Messages

4 Back-End

For the back-end, we have decided to implement it in Python due to the whole group being familiar with the language, and to make interfacing between the front-end and back-end simple.

4.1 Simulation

We plan to use objects to simulate the junction configurations and calculate the junction efficiency metrics and overall scores, with the structure of classes being as follows:

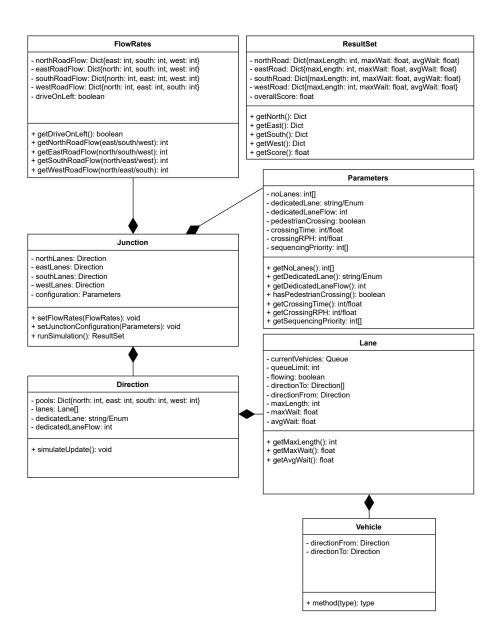


Figure 6: Junction Simulation Class Diagram

The Junction class contains Lane objects representing each lane of a road entering the junction, grouped together in arrays based on the direction they are arriving at the junction from. Two functions will be called by the front-end to set up the simulation: 'setFlowRates' to set the flow rates from each direction to the other directions, passed in the form of a 'FlowRates' object, and 'setJunctionConfiguration' to set the specific settings of the junction (e.g. is there a left turn lane, how many lanes there are on each incoming road) passed in the form of a Parameters object. For each junction configuration generated by the user, a Junction object will be created and be passed a Parameters object corresponding to those configuration settings. We decided to use objects for passing the data instead of passing each setting as an individual parameter ('setJunctionConfiguration') or passing the flow rates as a 2D-array ('setFlowRates') since objects would be easier to work with (for example, no scope for miscommunication about what the indices represent) and make it easier to extend the capabilities of the software in the future.

Each Lane object contains a queue of Vehicle objects, representing the vehicles in that lane waiting to transit the junction. Each Lane will calculate its own maximum wait time ('maxWait'), average wait time ('avgWait') and maximum queue length ('maxLength'), which will be compared with the same values of the other Lanes in its direction by the Junction object, in order to get the three values for the direction.

4.2 Interfacing with Frontend

Even though the frontend and backend portions of the application will be written in Python we will make sure to have a quasi API between the two different components, encapsulating all logic and intefacing between the frontend and backend into functions that would be a 1:1 translation into what an API would be capable of. For example simulating a junction's performance would only require a single call similar to how it would require a single call to an endpoint if this was to expand to use an API.

Separation in this manner will allow for us to keep development efficient, allowing those on the frontend to focus on their tasks and those on the backend to focus on theirs by keeping a well defined method of interaction between the two sides.

If the system was to expand in the future it would be simple to split these functions into an API controller and split the front and backend into a server and client architecture.

4.3 Validation and Error handling

There are a large variety of parameters that can be inputted into the system, it is important that they are properly validated, this will be achieved through functions that check each of the parameters is in the required range and that there are no conflicts between certain parameters. For example the sum of each direction's output flows must be equal to the inflow as well as the requirement for each flow to be greater than or equal to 0.

We will use automated testing to check that the system validates sets of input parameters correctly on each build, any changes to the validation code will be then checked automatically that they produce the correct result.

As we are using python for parts of the project and they are going to live in the same project we will be able to reuse the validation logic between both sections, guaranteeing consistent behaviour.

5 Deployment

5.1 Modularity

Separation of the frontend and backend into separate services will allow us to more easily expand the system in the future. The backend simulation is connected to an API which can then be accessed using different applications, the frontend and backend can be developed independently and can be swapped in and out as long as they maintain the API used to communicate between each other.

Docker/Podman is an open standard and will allow for these containers to be ran on any platform with a container engine.

5.2 Scalability and Fault tolerance

Usage of containerisation in this manner would allow us to scale the system as the needs of it grow, if for example we have multiple applications taking data from the backend at a time we can run multiple instances of the backend and use a load balancer to distribute client calls between each instance. If the client requires a higher level of uptime than a single instance allows, If they need fault tolerance than a single geographic location and instance allows then this would be simple to achieve using a set of containers in a distributed network.

Developing inside a container allows for a consistent build and deployment environment every time, if a client has an installation of docker/podman then they would be able to run the software just as they would any other container. Containers are largely similar to bare metal performance so in small use cases (start of the program lifecycle) there is no significant impact by using containers.