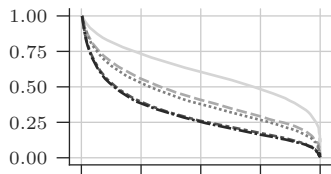


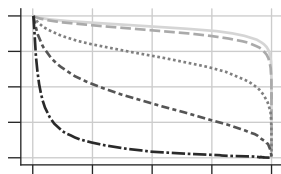
filter = Bilateral filter



filter = Gaussian filter



filter = Gaussian noise



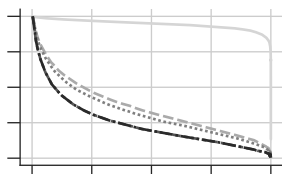
filter = Mean filter



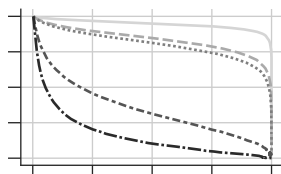
filter = Median filter



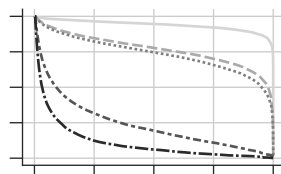
filter = Non-local means



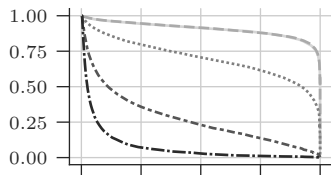
filter = Uniform noise



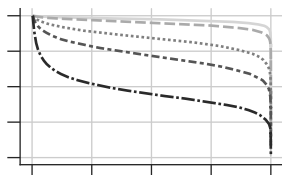
filter = Cauchy noise



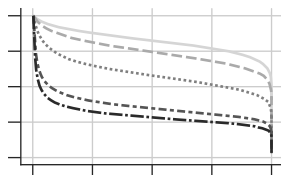
filter = Laplacian noise



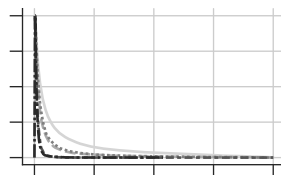
filter = Snow noise



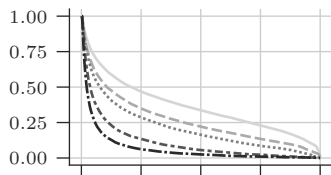
filter = Salt-and-pepper noise



filter = Comb



filter = Comb Reverse



filter = Baseline



— 1xS  
 - - 1.5xS  
 ..... 2xS  
 - . - . 5xS  
 - - - 10xS