

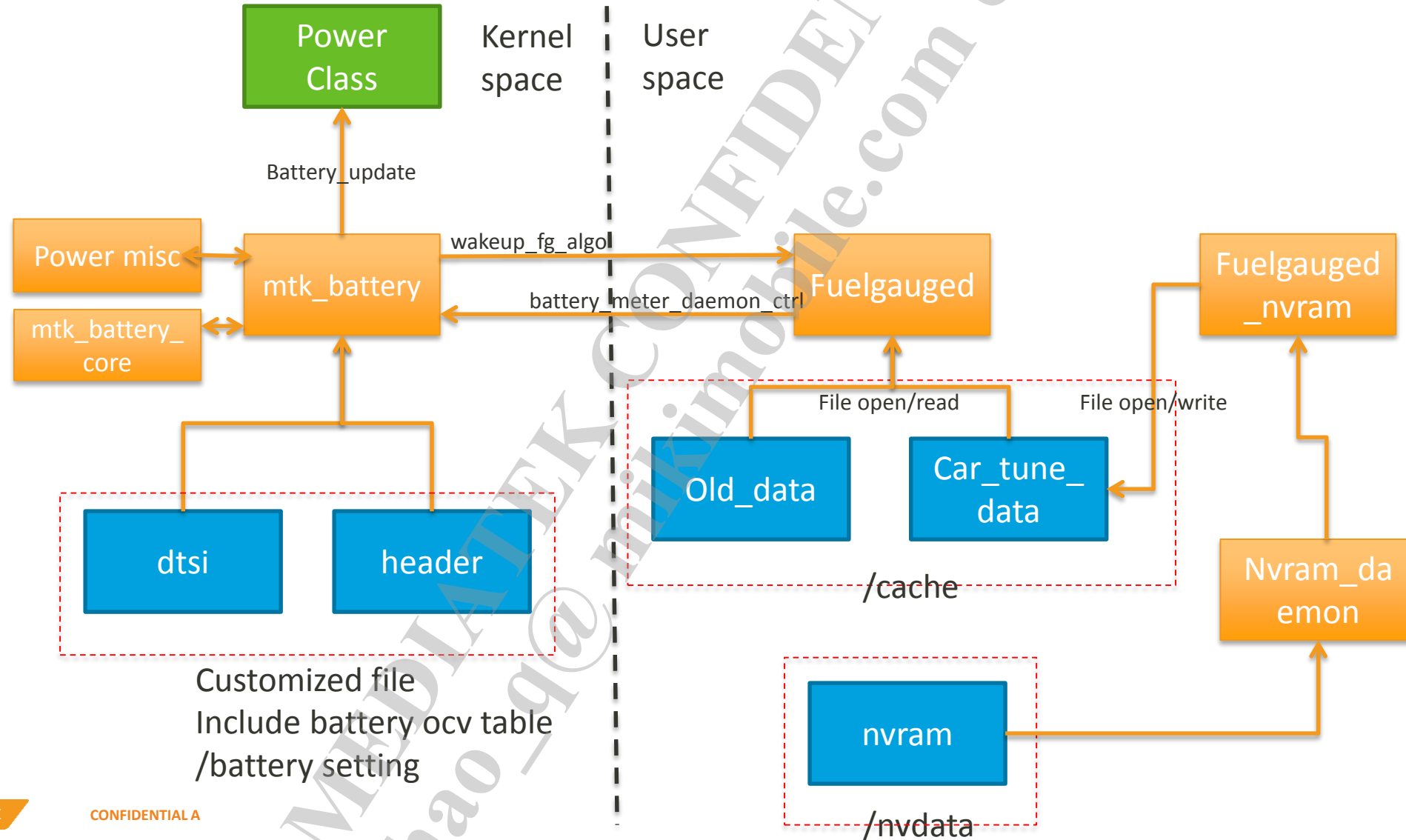


# GM3.0 SW architecture

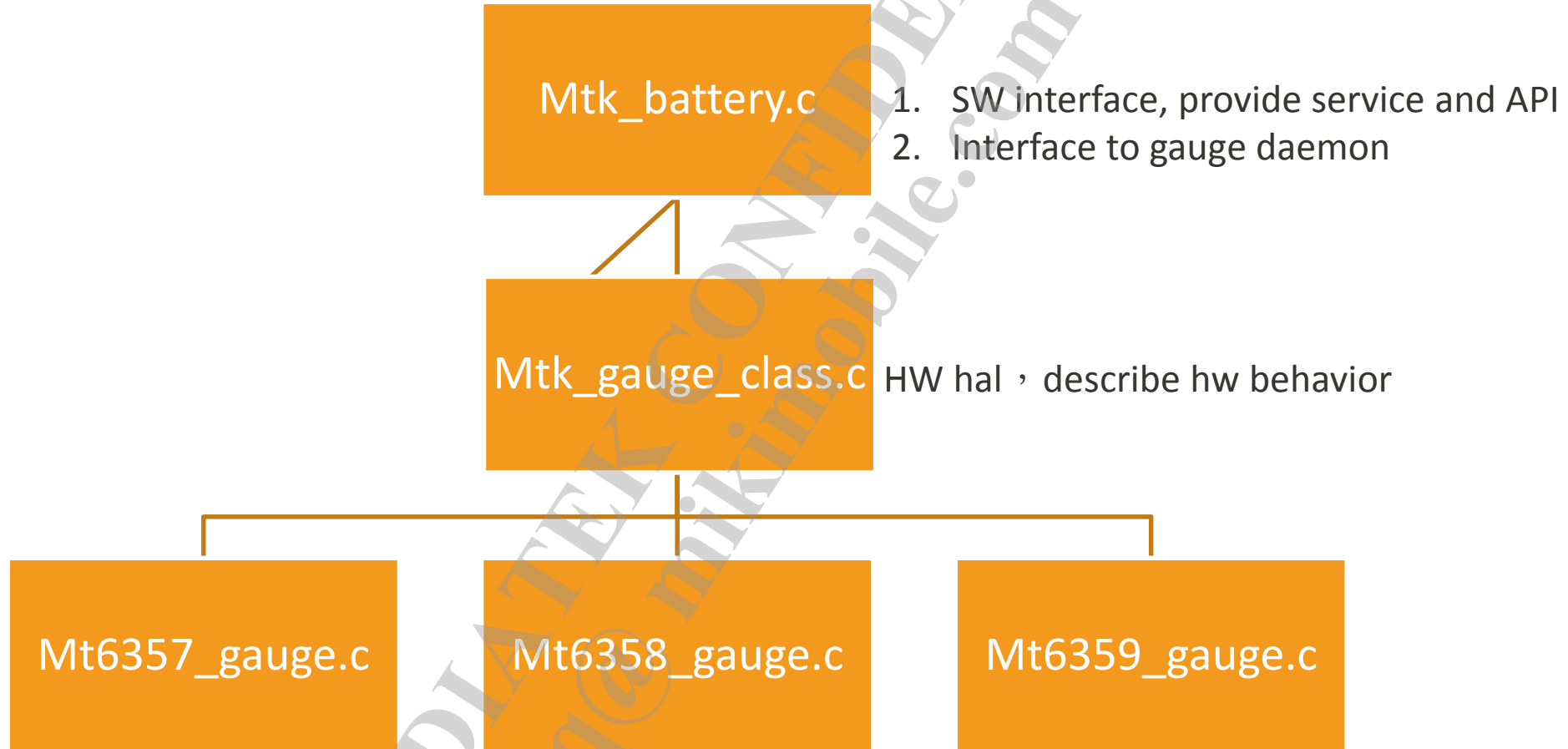
# Timo Liao



# GM30 sw architecture

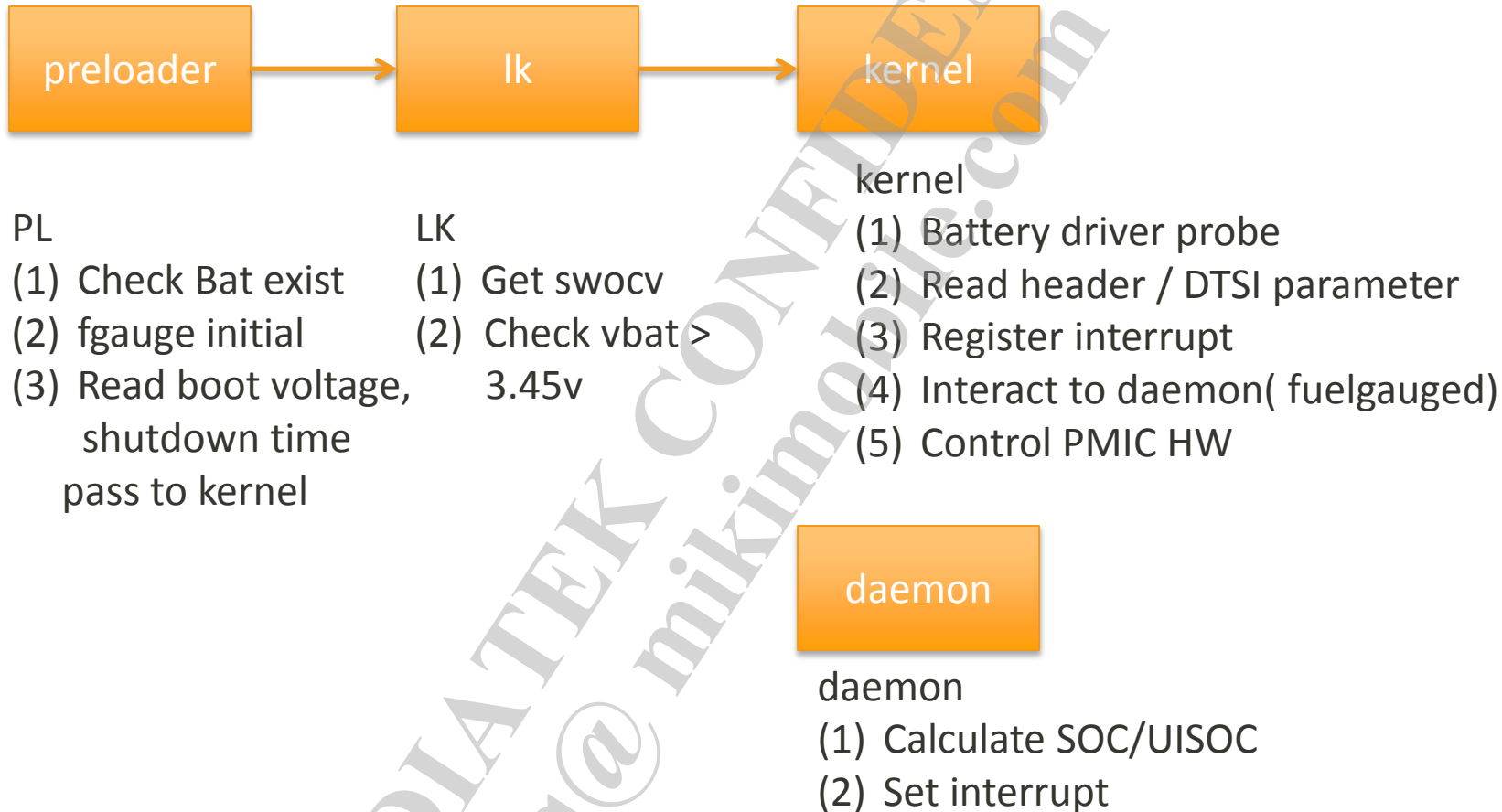


# Kernel describe



Difference PMIC have difference detail, but all operation described in mtk\_gauge\_class

# Initial flow



# Preloader file list

- vendor/mediatek/proprietary/bootable/bootloader/preloader/platform/mt6873/src/drivers/battery.c
- vendor/mediatek/proprietary/bootable/bootloader/preloader/platform/mt6873/src/drivers/charging\_bat.c

# Preloader conclusion

- fuel\_gauge\_init()
  - Check battery exist or not
  - Gauge HW init
  - Check gauge has been reset or not (check bat plugout)
  - read boot\_vbat
  - read shutdowntime
  - Check 2sec reboot or not
- Please do not adjust init flow

# LK file list

- vendor/mediatek/proprietary/bootable/bootloader/lk/platform/common/power
  - mtk\_battery.c
  - mtk\_battery.h
- vendor/mediatek/proprietary/bootable/bootloader/lk/platform/mt6873/mt\_gauge.c
- vendor/mediatek/proprietary/bootable/bootloader/lk/platform/mt6873/platform.c

# LK Conclusion

- LK need to get\_swocv() and check battery voltage is over 3.45v.  
If battery voltage is  $< 3.45\text{v}$ , hold system in LK to charge until vbat is  $> 3.45\text{v}$
- Platform.c
  - Get vbat / check\_sw\_ocv()



**MEDIATEK**

*everyday genius*