

Dr. Domenico Chiaradia, Prof. Antonio Frisoli

PERCRO lab

Scuola Superiore Sant'Anna

Pisa, Italy

✉ *d.chiaradia@santannapisa.it,*

a.frisoli@santannapisa.it

🌐 *<https://www.santannapisa.it/en/institute/tecip/human-robot-interaction>*

Prof. Kevin Lynch, Prof. I-Ming Chen

Editor in Chief, Editor, IEEE Transaction on Robotics

August 15, 2019

Subject: Paper IEEE T-RO 18-0568

Dear Editor in Chief, dear Editor,

it is our great pleasure to submit for revision a revised version of our original paper entitled "*Modeling, Design and Control of the Rehab-Exos, a Joint Torque Controlled Upper-Limb Exoskeleton*" by Domenico Chiaradia, Massimiliano Solazzi, Rocco Vertechy, and Antonio Frisoli already submitted for possible publication to IEEE Transactions on Robotics as IEEE T-RO 18-0568.

Following first decision and invitation from Editor to "resubmit as new", we have completely revised the paper and addressed all the reviewers concerns and suggestion. We are now submitting this new revised version for evaluation, wuth the hope that can be revised by the same reviewers again.

Yours faithfully,

Dr. Domenico Chiaradia, Prof. Antonio Frisoli

Attached: Revised manuscript + reply to reviewers