

Actuation systems for Human-Robot Interaction

Active impedance by control

Stiff actuators
+
Position/Force/Torque
sensor

Impedance-
based

Admittance-
based

Inherent impedance

Inherent compliance

Serial Elastic
Actuators - SEA

Variable Stiffness
Actuators - VSA

Inherent damping

Controlled friction

Controlled rheology

Eddy currents

Fluid dynamic