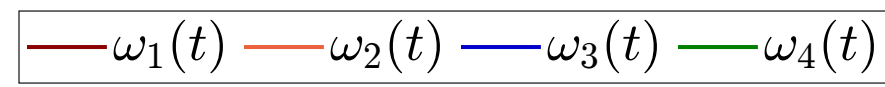
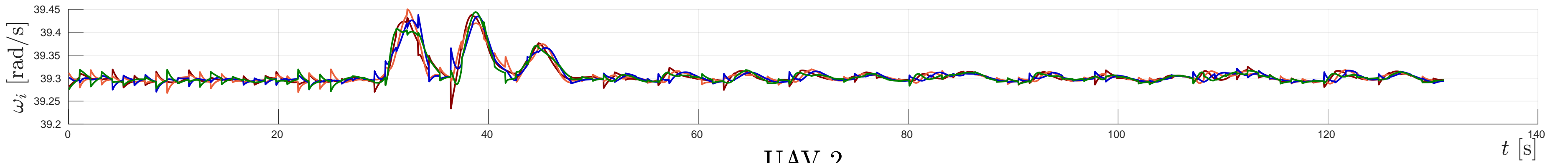


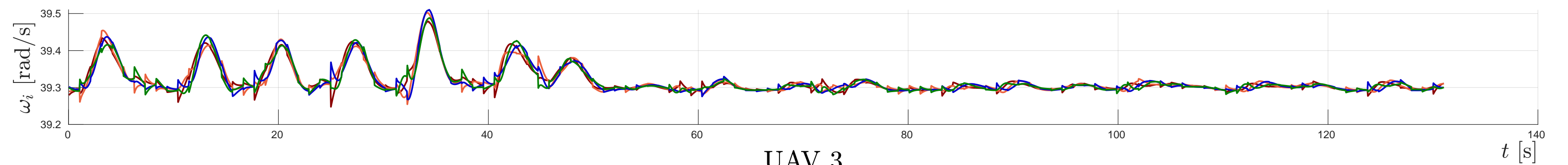
Control inputs $\omega_i(t)$



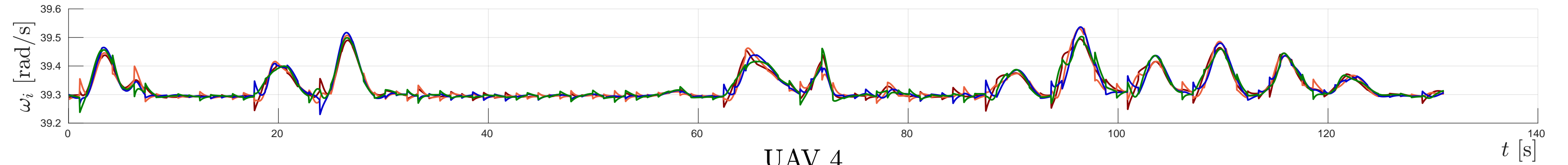
UAV 1



UAV 2



UAV 3



UAV 4

