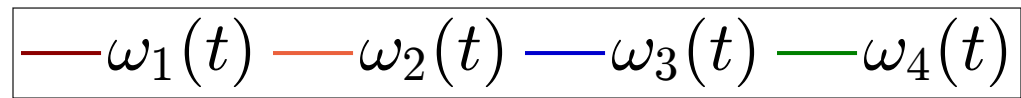
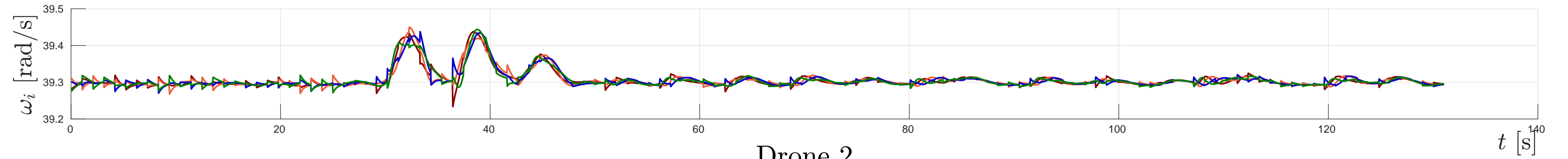


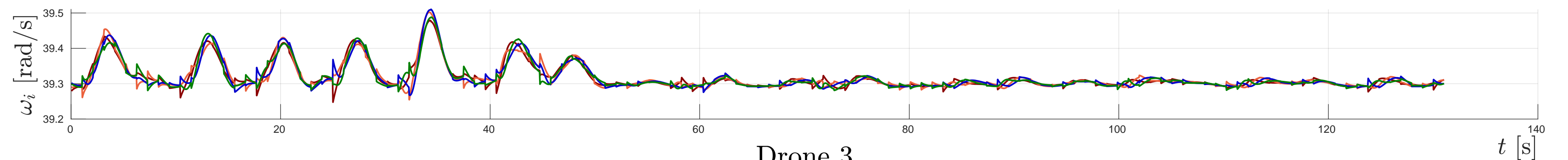
# Control inputs $\omega_i(t)$



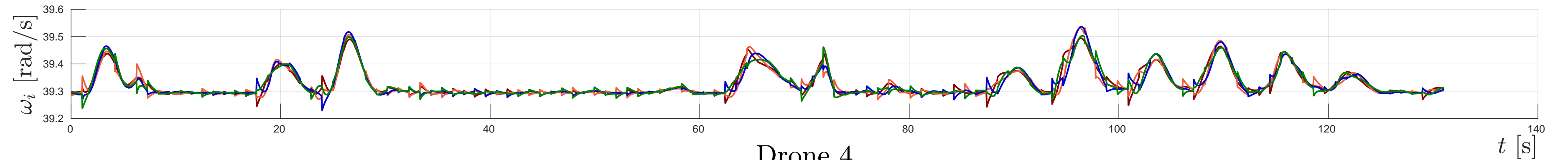
## Drone 1



## Drone 2



## Drone 3



## Drone 4

