IDP - Mechanical documentation

Team L212: The Seven Deadly Trins

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1 Material Choice

- 6mm thick MDF wood
- PLA
- 0.7mm thick sheet metal

2 Material Justification

- Main goal was to create a simple and easy to manufacture robot
- Wood used for the main body of the robot since it is easy to laser cut and put together
- Comb joints are used here to increase the strength of the robot and are put together with wood glue. 6mm thick wood used to further increase the structural stability of the robot as it is the thickest material available
- Sheet metal used for the brackets as it is easier to work with the bends
- Use of PLA and 3D printing for parts which cannot be manufactured as easily with either wood or sheet metal

3 Manufacturing

- Robot is laser cut via the dxf files (end of handout) on 6mm thick MDF wood and 0.7mm sheet metal
- Wood glue used for the main body of the robot
- Additional holes which need to be drilled are marked on the drawings
- Sensors and other components are bolted to the robot in the positions shown in the drawings / renders
- Holes in the 3D printed drawing are threaded















































