

view_frames Result
Recorded at time: 1581414574.753

map

Broadcaster: /slam_gmapping
Average rate: 20.204 Hz
Most recent transform: 1581414574.730 (0.023 sec old)
Buffer length: 4.900 sec

odom

Broadcaster: /am_driver_safe
Average rate: 9.132 Hz
Most recent transform: 1581414574.636 (0.118 sec old)
Buffer length: 4.818 sec

base_link

Broadcaster: /static_transform_publisher
Average rate: 10.194 Hz
Most recent transform: 1581414574.756 (-0.003 sec old)
Buffer length: 4.807 sec

os1_sensor

Broadcaster: /os1_cloud_node
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1581414574.753 sec old)
Buffer length: 0.000 sec

os1_imu

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1581414574.753 sec old)
Buffer length: 0.000 sec

antenna_center

Broadcaster: /os1_cloud_node
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1581414574.753 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1581414574.753 sec old)
Buffer length: 0.000 sec

cutting_disc_center

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

sw_arm_left_1

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

sw_arm_left_2

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

sw_arm_left_3

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

sw_arm_left_4

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

front_left_swivel_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

sw_arm_right_1

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

sw_arm_right_2

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

sw_arm_right_3

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

sw_arm_right_4

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

front_right_swivel_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

back_left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

back_right_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

col_front_chassis

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

col_front_left

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

col_front_right

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

col_rear_left

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

col_rear_right

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

loop_front_center

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

loop_front_right

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

loop_rear_left

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

loop_rear_right

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1581414574.623 (0.130 sec old)
Buffer length: 4.800 sec

loop_rear_right