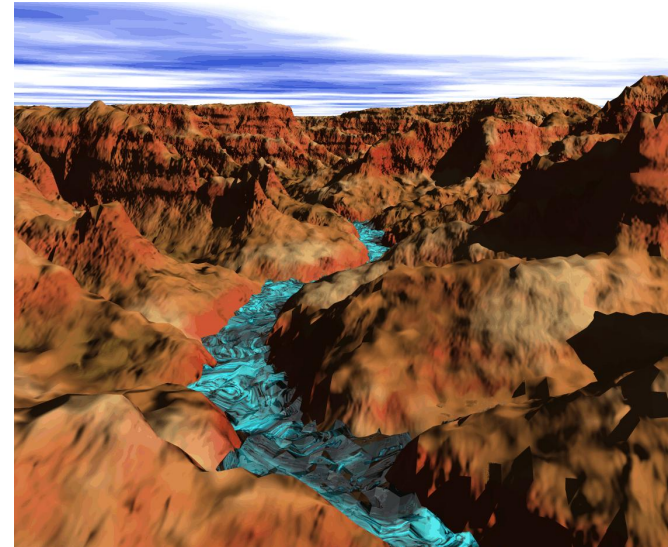
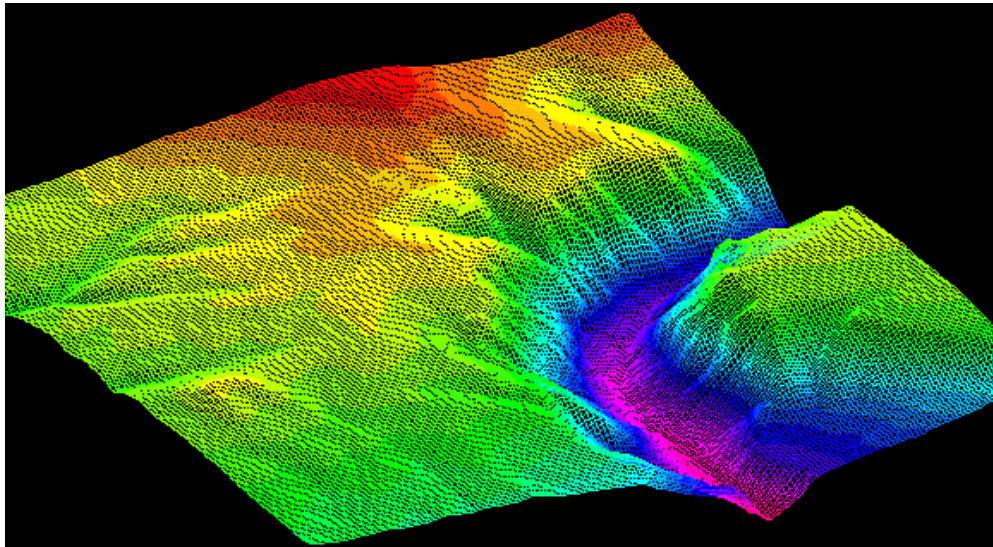


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# Design of Human Interface Game Software

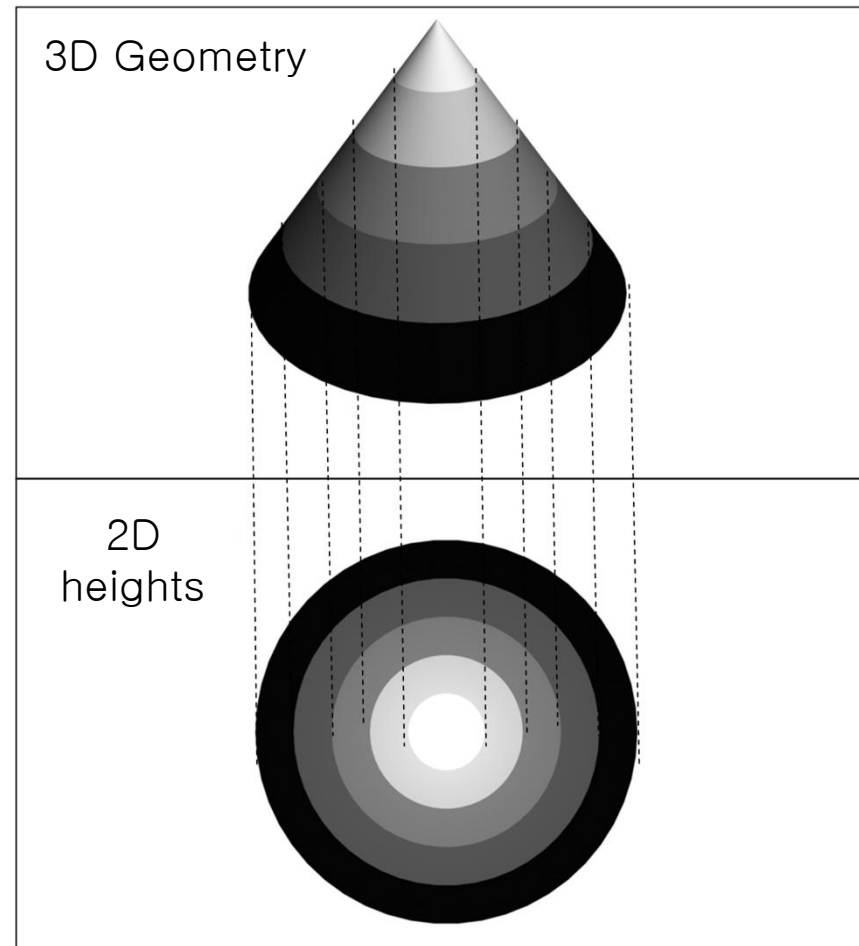
- 
- Modeling: Terrain
  - Modeling: Scene Graph
  - Buffers

# Terrain

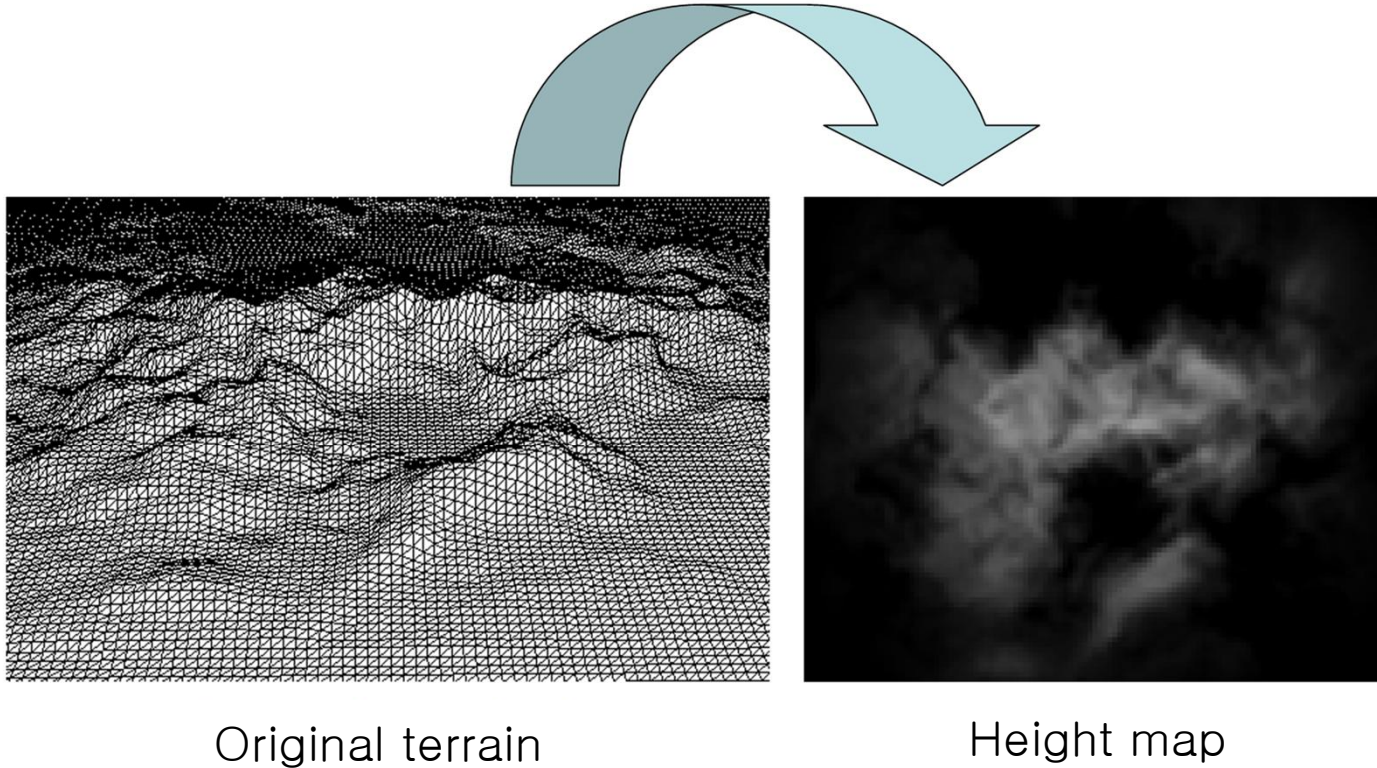


# DEM (Digital Elevation Model)

- A height map is used to represent terrain or ground surface topography
- Height Map
  - A raster image used to store surface elevation data
  - Used in bump mapping, displacement mapping, terrains



# DEM (Digital Elevation Model)

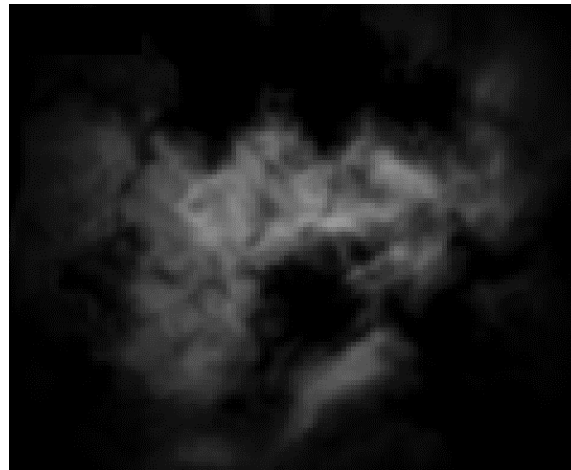


- Build a height map using remote sensing techniques
  - Radar scanning
  - Direct survey of land surface

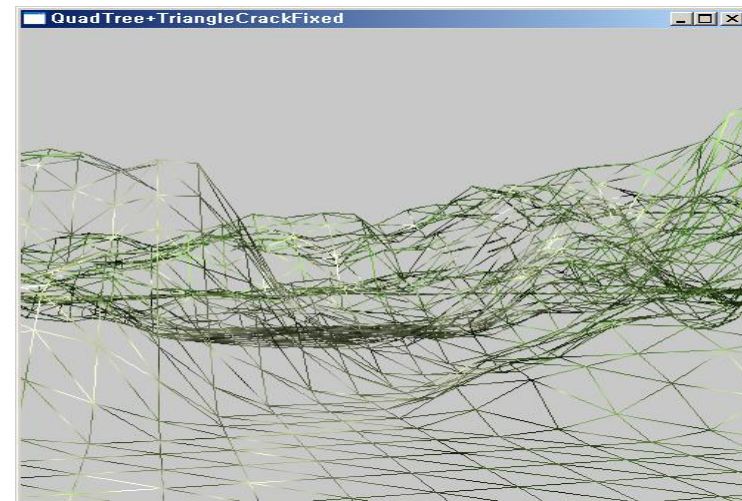
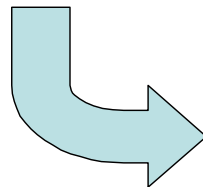
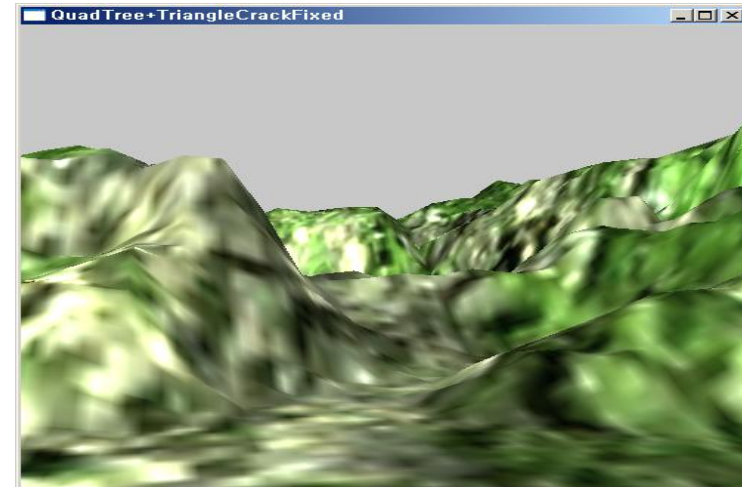
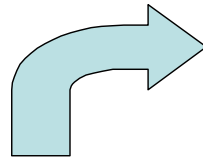


# DEM (Digital Elevation Model)

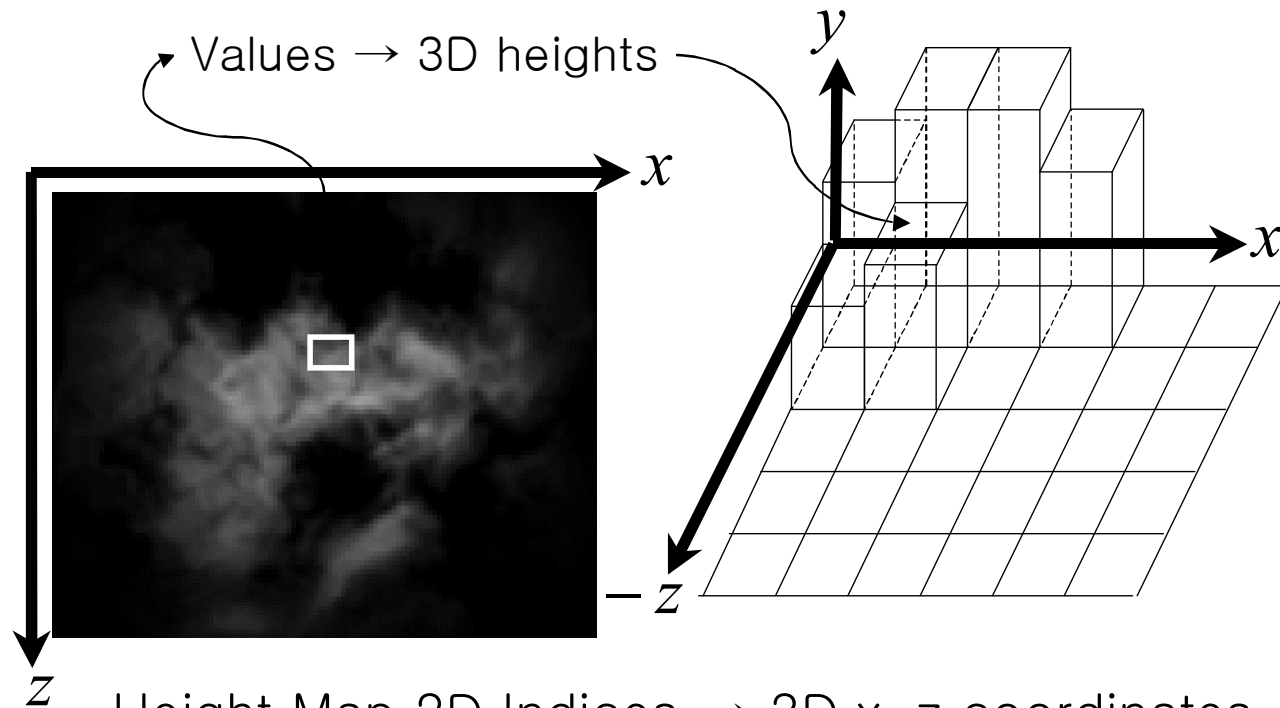
- Construct a triangle mesh from a height map



Height map



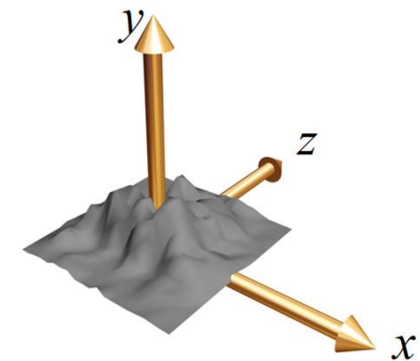
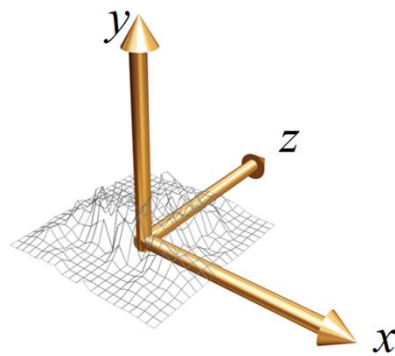
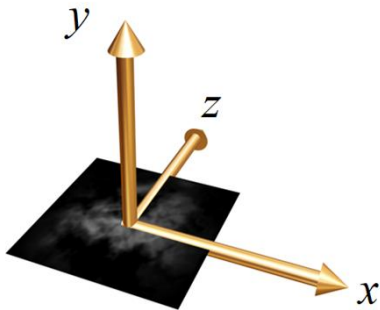
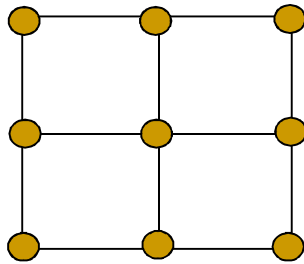
# Constructing Triangle Meshes



Height Map 2D Indices  $\rightarrow$  3D x-z coordinates  
Height Map Values  $\rightarrow$  3D heights (y coordinate)  
\* Each cell generates two triangles

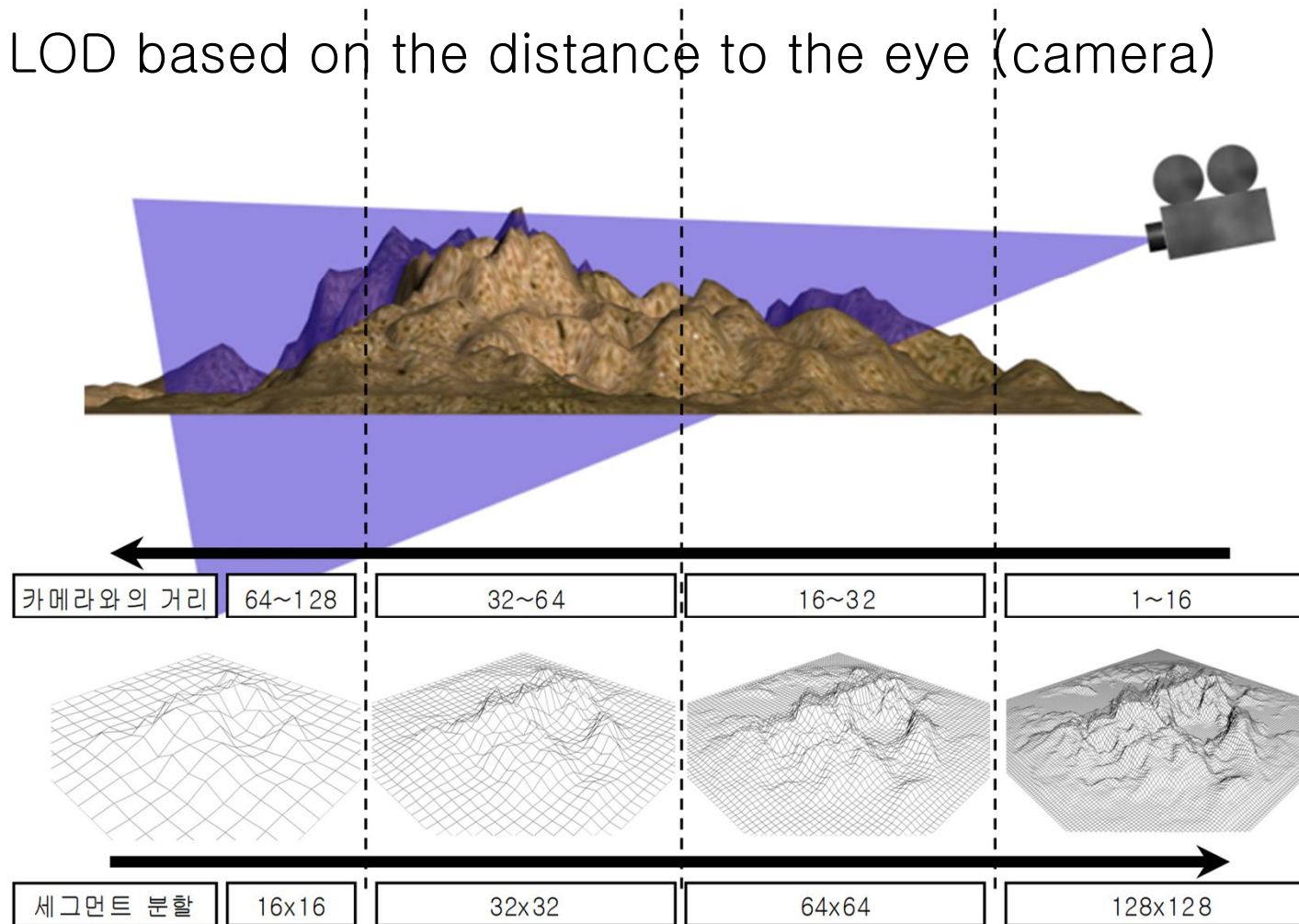
# Constructing Triangle Meshes

- Vertices at the corners of the height map



# LOD(Level Of Detail)

- LOD based on the distance to the eye (camera)





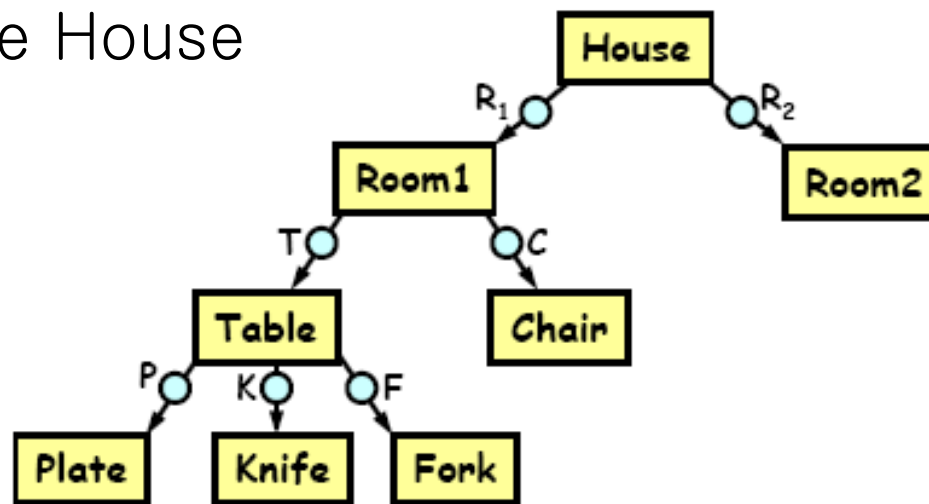
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# Scene Graph

- Scene Management
  - How to store virtual objects for efficient data access and rendering
- Hierarchical Structure
  - Good for culling – we can cull the whole subtree when the bounding box of a node is not visible
  - Apply transformations hierarchically

# Scene Graph

- Local Coordinate System
  - Each object has its own local coordinate system
  - Each node stores the transformation to convert its local coordinates to parent's local coordinate system
- Ex) Transform vertex  $\mathbf{v}$  of the Plate to the coordinates of the House
  - $(R_1TP)\mathbf{v}$



# Scene Graph

- Transformation of a vertex to the world coordinate system

$$v_{world} = M \times v_{local}$$

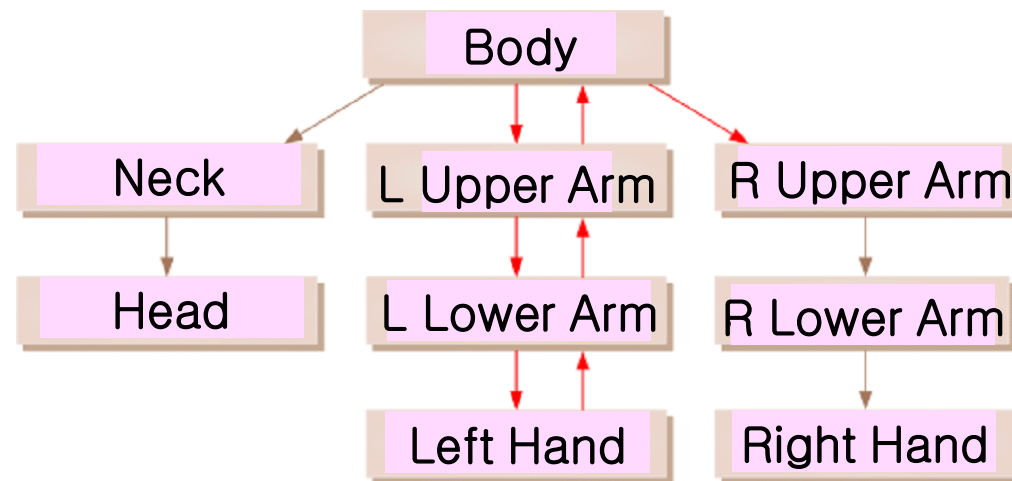
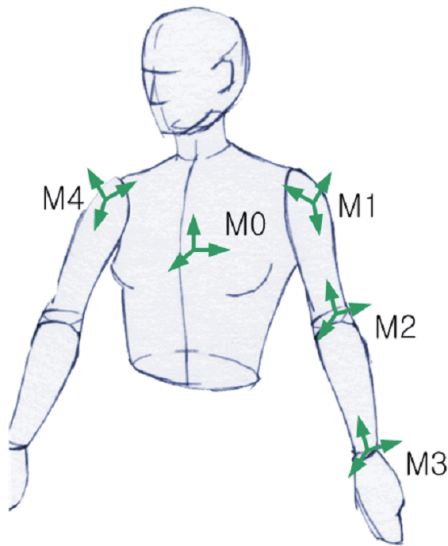
- In the hierarchy,  $v_{world} = M_{parent} \times M_{child} \times v_{local}$
- For n parents.

$$v_{world} = M_{parent(1)} \cdots \times M_{parent(n-1)} \times M_{parent(n)} \times M_{child} \times v_{local}$$

- If the parent is transformed (moved), the children are also transformed (moved)

# Scene Graph

- Traversing Hierarchy
  - **Push** for storing the current coordinate system
  - **Pop** for restoring the previous coordinate system



# Scene Graph

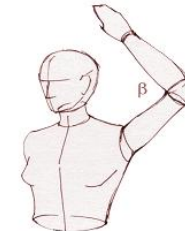
```
void drawArm( ){  
    glMatrixMode(GL_MODELVIEW);  
    glLoadIdentity( );  
    Draw_Body( );  
    glPushMatrix( );  
        GoToShoulderCoordinates( );  
        Draw_UpperArm( );  
        glPushMatrix( );  
            GoToElbowCoordinates( );  
            Draw_LowerArm( );  
            glPushMatrix( );  
                GoToWristCoordinates( );  
                Draw_Hand( );  
            glPopMatrix( );  
        glPopMatrix( );  
    glPopMatrix( );  
}
```



World (Global) coordinate system  
body



Store world coordinate system  
Shoulder local coordinate system  
upper arm



Store Shoulder coordinate system  
Elbow local coordinate system  
lower arm

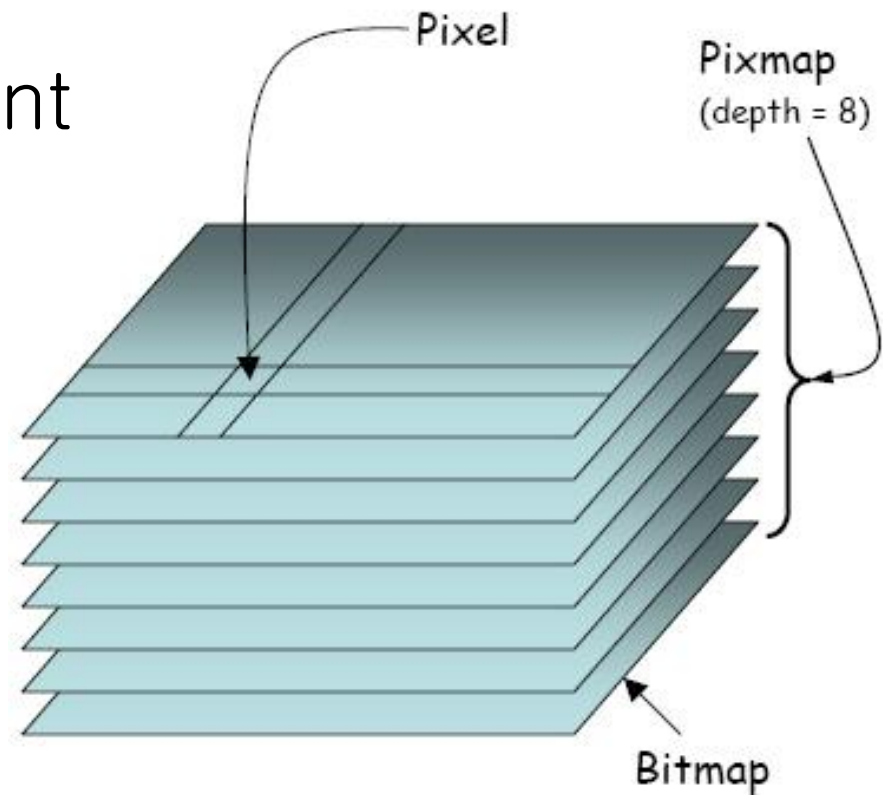


Store Elbow coordinate system  
Wrist local coordinate system  
hand  
restore Elbow coordinate system  
restore Shoulder coordinate system  
restore World coordinate system

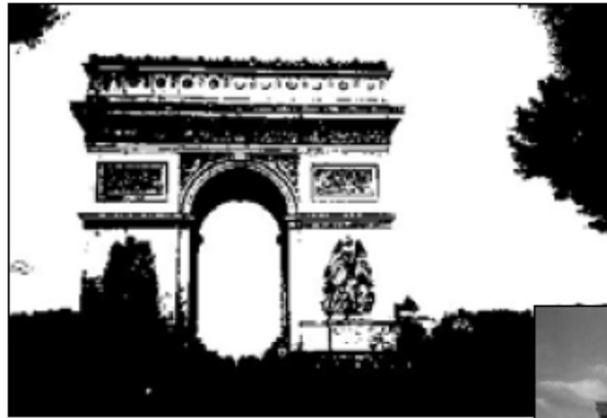


# Bitmaps and Pixmaps

- Pixel: a picture element
- Bitmap
  - ❑ 2D array of single-bit pixels
- Pixmap
  - ❑ Stack of bitmaps
  - ❑ To represent full RGB color, it is sufficient to have 24-bit depth, 8 bits for each color channel



# Bitmaps and Pixmaps



Bitmap (depth = 1)

Pixmap (depth = 8)



Pixmap (depth = 24)



# Multi-Pass Rendering

- The pipeline takes one triangle at a time, so only local information and pre-computed maps are available
- Multi-pass techniques render the scene, or parts of the scene, multiple times
  - Makes use of auxiliary buffers to hold information
  - Make use of tests and logical operations on values in the buffers
  - Really, a set of functionality that can be used to achieve a wide range of effects
    - Mirrors, shadows, bump-maps, anti-aliasing, compositing, ...

# Buffers

- Buffers allow you to store **global information** about the rendered scene
  - ❑ Like scratch work space, or extra screen memory
  - ❑ They are only cleared when you say so
  - ❑ This functionality is fundamentally different from that of vertex or pixel shaders
- Buffers are defined by:
  - ❑ The type of **values** they store
  - ❑ The logical **operations** that they influence
  - ❑ The way they are **accessed** (written and read)

# OpenGL Buffers

- Color buffers: Store RGBA color information for each pixel
  - OpenGL actually defines four or more color buffers: front/back (double buffering), left/right (stereo) and auxiliary color buffers
- Depth buffer: Stores distance to object for each pixel (Z-buffer)
- Stencil buffer: Masking operations
- Accumulation buffer: Composition of images



# Stencil Buffer

- The stencil buffer acts like a paint stencil – it lets some fragments through but not others
- It stores multi-bit values – you have some control of #bits
- You specify two things:
  - The test that controls which fragments get through
  - The operations to perform on the buffer when the test passes or fails
  - **All tests/operation look at the value in the stencil that corresponds to the pixel location of the fragment**
- Typical usage: One rendering pass sets values in the stencil, which control how various parts of the screen are drawn in the second pass

# Stencil Tests

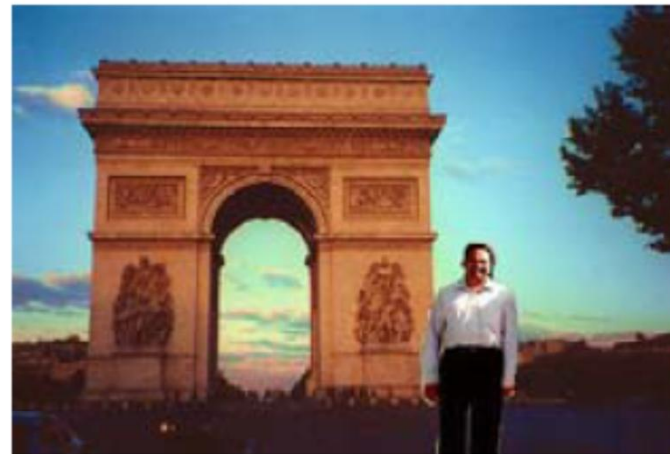
- You give an operation, a reference value, and a mask
- Operations:
  - Always let the fragment through
  - Never let the fragment through
  - Logical operations between the reference value and the value in the buffer:  $<$ ,  $<=$ ,  $=$ ,  $\neq$ ,  $>$ ,  $>=$
- The mask is used to select particular bit-planes for the operation
  - $(\text{reference} \ \& \ \text{mask}) \ \text{op} \ (\text{buffer} \ \& \ \text{mask})$

# Chroma Keying



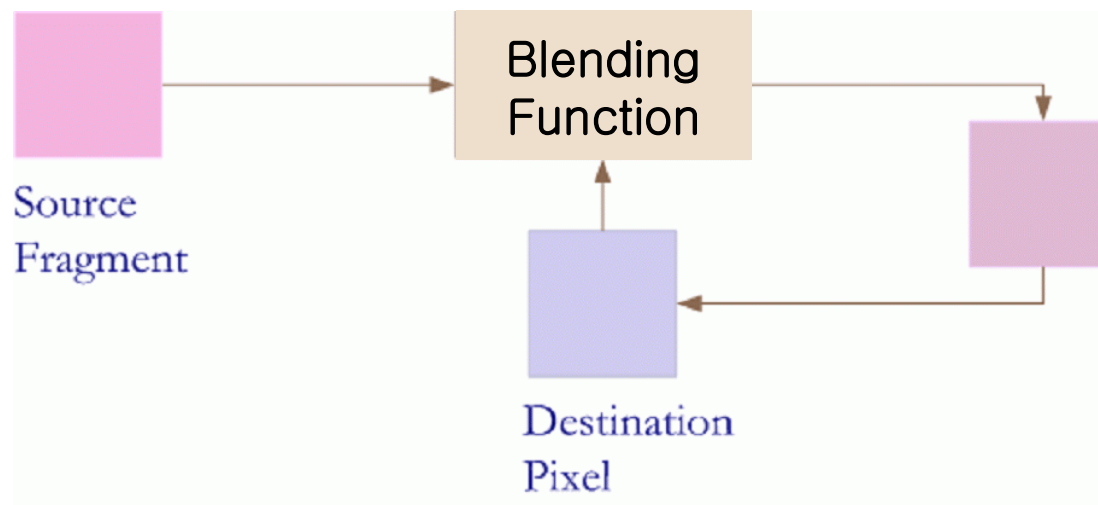
+

=



# Blending

- Blend fragments and the pixels in the frame buffer
  - Input fragment = Source Fragment
  - Pixel in the frame buffer = Destination Pixel
  - Result is stored in the destination pixel.



# Blending

- $(R_s, G_s, B_s, A_s)$  : Source fragment color
- $(R_d, G_d, B_d, A_d)$  : Destination pixel color
- $(S_r, S_g, S_b, S_a)$  : Blending factor for source fragment
- $(D_r, D_g, D_b, D_a)$  : Blending factor for destination pixel

$$(R, G, B, A) = (R_s S_r + R_d D_r, G_s S_g + G_d D_g, B_s S_b + B_d D_b, A_s S_a + A_d D_a)$$

- Various blending factors
  - (GL\_ONE, GL\_ZERO)
  - (GL\_SRC\_ALPHA, GL\_ONE)
  - (GL\_ONE, GL\_DST\_ALPHA)
  - (GL\_SRC\_ALPHA, GL\_DST\_ALPHA)





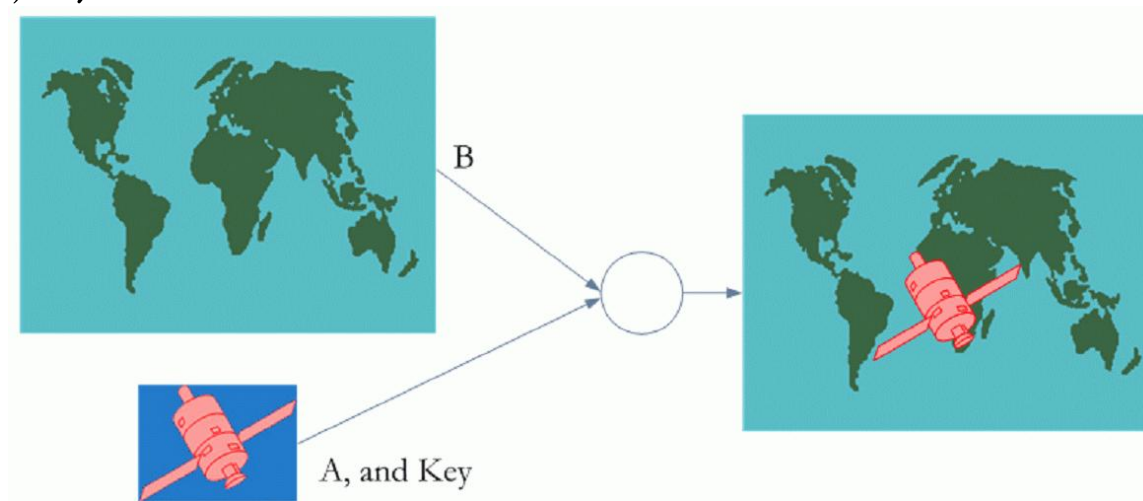
# Blending

- Image Composition

- Blend the image with the background. Make the blue area of the image A transparent

- Image A = source fragment, background B = destination

- Make the alpha value of blue fragment to be 0. Set the source factor as GL\_SRC\_ALPHA. Then the factor for the blue fragment is (0, 0, 0, 0)



# Blending

- Choosing transparent area = Keying, Blue Screening
  - Use specific color: Chroma Keying
  - Use brightness: Luma Keying
  - Select specific shape: Matte, Matting

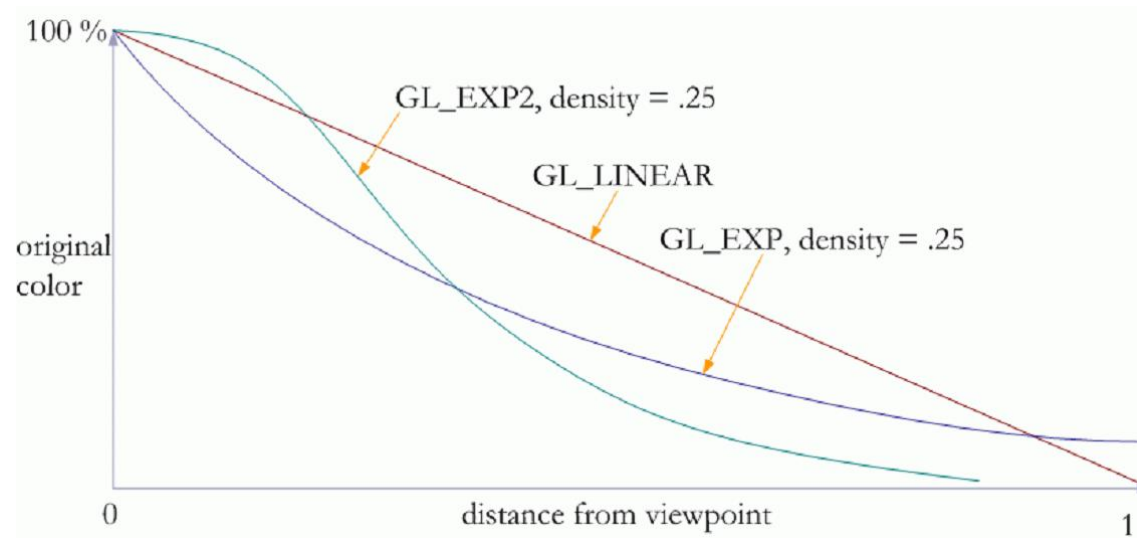
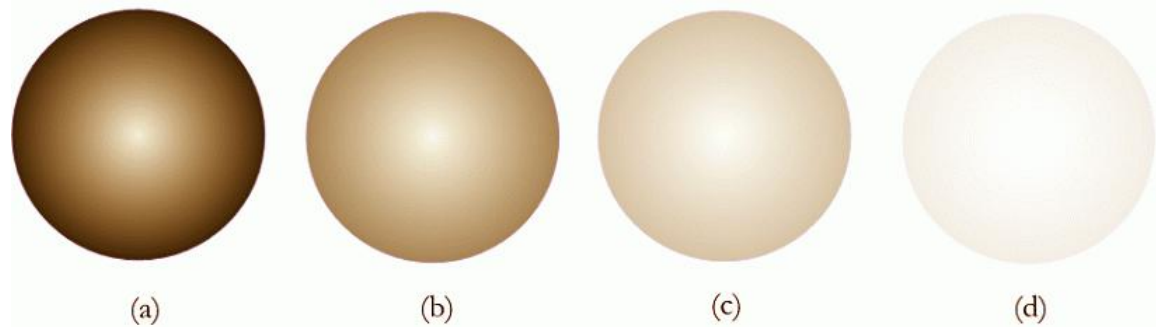
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# Depth Cue

- Perspective projection: objects in a distance are small
- Repeated patterns: more patterns in a distance
- Occlusion
- Shading and shadows

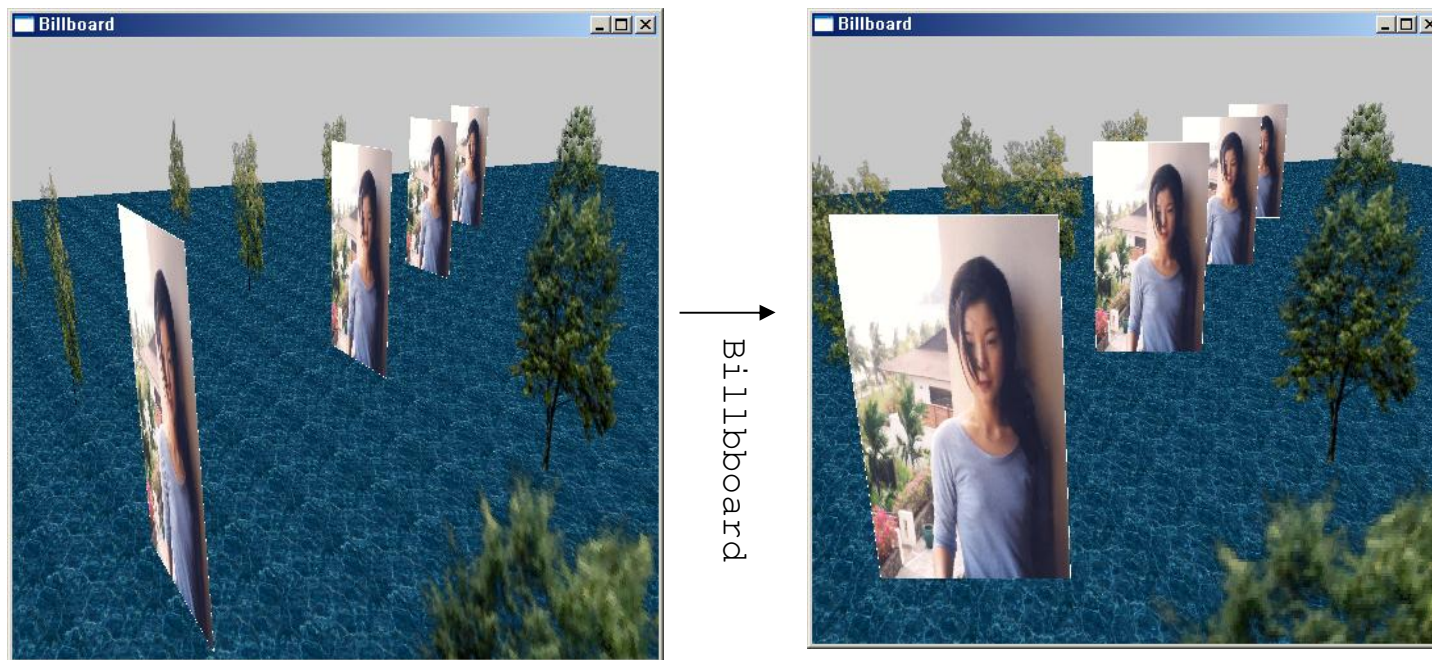
# Fog Effect

- Objects in a distance are diluted.



# Billboard

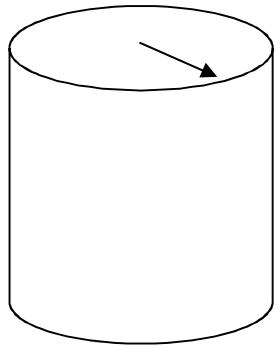
- A billboard is used to represent a complex object with a texture mapping. Billboards are always facing the eye (camera). The texture on the billboard is blended with the background.





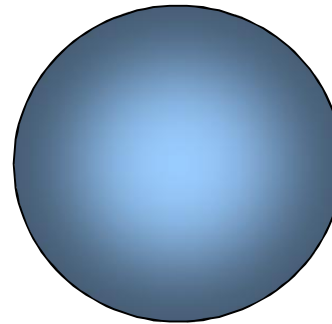
# Billboard

- To make the billboard facing the eye, we need to compute the rotation matrix. The rotation matrix is the inverse matrix of the rotation part of the eye transformation.



- Cylindrical Billboards

Consider the rotations  
around Y axis



- Spherical Billboards

Consider every rotations