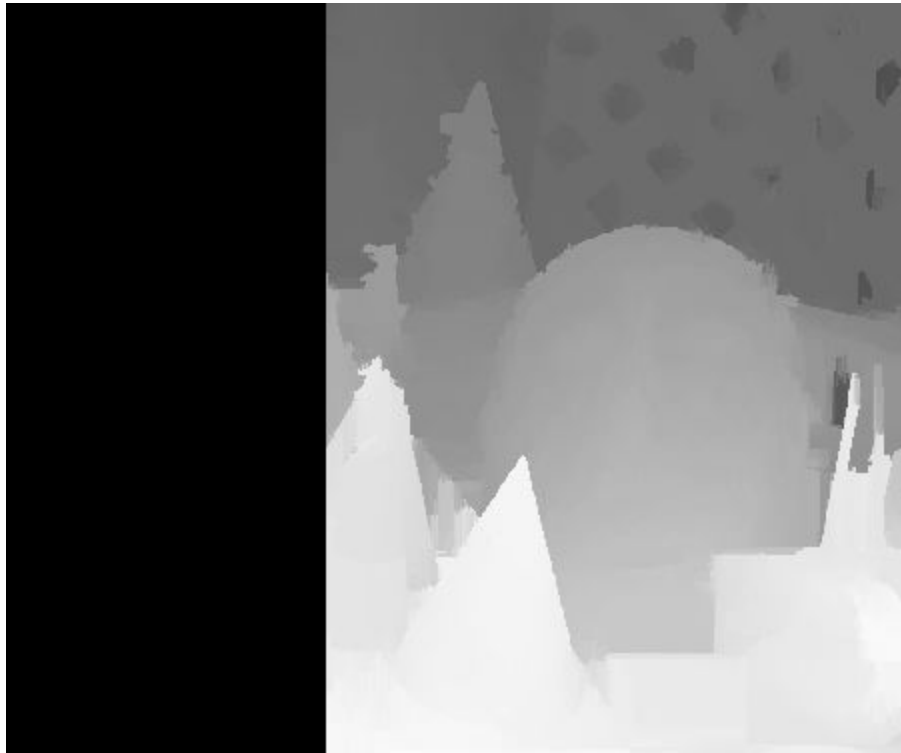# CV: Bonus Assignment

Anubhav Jain

2015129

Output Depth Map

Both of the images are first projected to a parallel plane system. We calculate the essential matrix for the two images. Now stereo is used to find the depth of each point based on the difference between the two cameras, the focal length.