

Small Variance Asymptotics for Non-parametric Bayesian Clustering

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Table of contents

- 1 Introduction
- 2 Dirichlet Process
 - Inference
 - Hard clustering
- 3 Hierarchical Dirichlet process Mixture Models
- 4 Extending to Exponential Family
 - Background
 - Bregman Hard clustering
- 5 Evaluation



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- We start with a hard non-parameteric clustering algorithm.
- We then extend this algorithm to a hierarchical structure using Hierarchical Dirichlet process.
- Finally, we generalize the clustering algorithm, to use bregman divergence instead of just euclidean distance.



Dirichlet Process

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Definition

(Ferguson) We say G is Dirichlet Process distributed with base distribution H and concentration parameter α , written as $G \sim DP(\alpha, H)$ if $(G(A_1), \dots, G(A_r)) \sim \text{Dir}(\alpha H(A_1), \dots, \alpha H(A_r))$ for every finite measurable partition A_1, \dots, A_r of Θ which is support of H



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$$V[G(A)] = \frac{H(A)(1-H(A))}{\alpha+1}$$



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- Constructions like Blackwell-MacQueen urn scheme and Stick breaking process ensure existence of DP.



Posterior of DP

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- Simple algebra yields: $G | \theta_1, \dots, \theta_n \sim DP(\alpha + n, \frac{\alpha}{\alpha + n} H + \frac{n}{\alpha + n} \frac{\sum_{i=1}^n \delta_{\theta_i}}{n})$



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- We have seen CRP and stick breaking process in class.



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$$\mu_1, \dots, \mu_k \sim G_0$$

$$\pi \sim \text{Dir}\left(\frac{\alpha}{k}, \frac{\alpha}{k}, \dots, \frac{\alpha}{k}\right)$$

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- Let $k \rightarrow \infty$ to get infinite mixture model



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- After assigning cluster to each point, we compute the means of all clusters using the points assigned to them and the prior.
- Proceed in cyclic manner until convergence.



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- The probabilities become binary(exact form in report) and resulting update turns out to be analogous to $k - means$ where we assign the point to closest mean
- However one subtle difference is that if the distance to closest mean is greater than $\lambda(\alpha)$, then the probabilities corresponding to each of the existing cluster falls to zero and we start a new cluster.



Underlying Objective function

- ① We will show in report that the hard clustering algorithm minimizes the objective function:

$$\min_{\{I_j\}_{j=1}^k} \sum_{c=1}^k \sum_{x \in I_c} \|x - \mu_c\|^2 + \lambda k$$

$$\text{where } \mu_c = \frac{\sum_{x_i \in I_c} x_i}{|I_c|}$$



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- 2 This is similar to the K-means algorithm, only value of k is not fixed and the objective penalizes large k .



- Input: x_1, \dots, x_n, λ : cluster penalty parameter.
 - Output: Clustering of points in l_1, \dots, l_k and no. of cluster k .
- 1 Initialize $k = 1, l_1 = x_1, \dots, x_n, \mu_1 = \frac{\sum x_i}{n}$ and $z_i = 1$ for each point.
 - 2 Repeat until convergence:
 - For each point x_i ,
 - Compute distance from all means i.e. $d_{ic} = ||x_i - \mu_c||^2$ for all c .
 - if $\min_c d_{ic} > \lambda$, set $k = k + 1, z_i = k, \mu_k = x_i$.
 - Else, set $z_i = \min_c d_{ic}$
 - Assign points x_i with $z_i = c$ to the cluster l_c .
 - For each cluster $c, \mu_c = \frac{\sum_{x_i \in l_c} x_i}{|l_c|}$.



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Definition

$$\begin{aligned}
 G_0 | \gamma, H &\sim DP(\gamma, H) & G_j | \alpha, G_0 &\sim DP(\alpha, G_0) \\
 \phi_{ji} | G_j &\sim G_j & x_{ji} | \phi_{ji} &\sim F(\phi_{ji})
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where G_0 is global measure and G_j 's are specific to data-sets. This allows mixture models to share components.



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- There is a metaphor called *Chinese Restaurant Franchise* that gives an alternative view of HDP.



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where k, g is total number of local and global clusters respectively. λ_l, λ_g are regularization parameters, l_p is the set points assigned to cluster p and $\mu_p = \frac{1}{|l_p|} \sum_{x_{ij} \in l_p} x_{ij}$



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Definitions

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Posterior has same form as prior with $\tau = \tau + \mathbf{x}_i$ and $\eta = \eta + 1$



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(Bregman, 1967) Let $\phi : S \rightarrow \mathbb{R}$ be a strictly convex function defined on convex set S such that ϕ is differentiable on interior of S . The bregman divergence is defined as $d_\phi = \phi(\mathbf{x}) - \phi(\mathbf{y}) - \langle \mathbf{x} - \mathbf{y}, \nabla \phi(\mathbf{y}) \rangle$

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(Rockfellar 1970) Let ψ be a **proper, closed**, convex function with $\Theta = \text{interior}(\text{domain}(\psi))$. The pair (Θ, ψ) is called a convex function of legendre type if following are satisfied

- Θ is nonempty
- ψ is strictly convex and differentiable on Θ
- $\forall \theta_b \in bd(\Theta), \lim_{\theta \rightarrow \theta_b} \|\nabla \psi(\theta)\| \rightarrow \infty, \theta \in \Theta$

Legendre Function

Lemma

(Barndoff 1978) Let ψ be the cumulant function of a regular exponential family with natural parameter space $\Theta = \text{dom}(\psi)$. Then (Θ, ψ) is a convex function of legendre type



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Theorem

(Rockfellar) Let ψ be proper, closed strictly convex function with conjugate function ψ^* . Let $\Theta = \text{int}(\text{dom}(\psi))$ and $\Theta^* = \text{int}(\text{dom}(\psi^*))$. If (θ, ψ) is a convex function of legendre type then

Legendre Dual

Theorem (cntd..)

- (θ^*, ψ^*) is a convex function of legendre type.
- (θ^*, ψ^*) and (θ, ψ) are called legendre duals of each other.
- The gradient function $\nabla\psi$ is a one to one function from open convex set Θ onto the open convex set Θ^* .
- $\nabla\psi^* = (\nabla\psi)^{-1}$



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Using theorem and lemma, (Θ, ψ) and $(\text{int}(\text{dom}(\phi)), \phi)$ are legendre dual of each other.



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$$\text{More importantly, } \nabla\psi^{-1}(\mu) = \theta(\mu) = \nabla\phi(\mu) \quad (1)$$

$$\implies \phi(\mu) = \langle \theta(\mu), \mu \rangle - \psi(\theta(\mu)) \quad (2)$$



Relation with Exponential Family

Theorem

Let $p_{\psi,\theta}(\mathbf{x})$ be pdf of regular exponential family distribution. Let ϕ be the conjugate of ψ . Let θ be natural parameter and μ be expectation parameter. Let d_ϕ be the bregman divergence derived from ϕ . Then $p_{\psi,\theta}(\mathbf{x})$ can be uniquely expressed as $p_{\psi,\theta}(\mathbf{x}) = \exp(-d_\phi(\mathbf{x}, \mu))b_\phi(\mathbf{x})$ where $b_\phi(\mathbf{x}) = \exp(\phi(\mathbf{x}))h(\mathbf{x})$

Proof.

$$\begin{aligned}
 p_{\psi,\theta}(\mathbf{x}) &= h(\mathbf{x})\exp(\langle \mathbf{x}, \theta \rangle - \psi(\theta)) \\
 &= h(\mathbf{x})\exp(\phi(\mu) + \langle \mathbf{x} - \mu, \nabla \phi(\mu) \rangle) \\
 &= h(\mathbf{x})\exp(-(\phi(\mathbf{x}) - \phi(\mu) - \langle \mathbf{x} - \mu, \nabla \phi(\mu) \rangle) + \phi(\mathbf{x})) \\
 &= \exp(-d_\phi(\mathbf{x}, \mu))b_\phi(\mathbf{x}) \text{ where } b_\phi(\mathbf{x}) = \exp(\phi(\mathbf{x}))h(\mathbf{x})
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Bijection

Theorem

(Banerjee et al) There is a bijection between regular exponential families and regular bregman divergences

Examples

- For 1-d Gaussian distribution $p(x|\mu) = \frac{1}{\sqrt{2\pi}} \exp(-\frac{(x-\mu)^2}{2})$, the corresponding bregman divergence is $(x - \mu)^2$



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We can use this idea in the previous DP-means and HDP-means to obtain a new algorithm for hard clustering by replacing euclidean distance with above bregman divergence.



Bregman DP means

- **Input** $x_1, x_2, \dots, x_n, \lambda$
- **Initialize** $\mu_1 = \frac{1}{n} \sum_{i=1}^n x_i$
- **Assignment** For each x_i ,
 - Compute bregman divergence of the x_i with current cluster centers.
 - If $\min_c d_\phi(\mathbf{x}, \mu_c) < \lambda$, then assign it to cluster $\underset{c}{\operatorname{argmin}} d_\phi(\mathbf{x}, \mu)$
 - Else, define a new cluster with its mean as x_i and assign x_i to this cluster.
- **Mean Update** For each cluster, set its means $\mu_c = \frac{1}{|I_j|} \sum_{\mathbf{x} \in I_j} \mathbf{x}$ where I_j is the set of points in j^{th} cluster



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The corresponding algorithm for Hierarchical Dirichlet process is similar, where we replace euclidean distance with the above defined bregman divergence



Evaluation metrics

- 1 NMI
- 2 Custom Validation



NMI

$$\text{NMI}(Y, C) = \frac{2 \times \mathbb{I}(Y; C)}{\mathbb{H}(Y) + \mathbb{H}(C)}$$

where:

- ① $Y :=$ class labels
- ② $C :=$ cluster labels
- ③ $\mathbb{H}(\cdot) :=$ Entropy
- ④ $\mathbb{I}(Y; C) :=$ Mutual Information b/w Y and C
 $\mathbb{I}(Y; C) := \mathbb{H}(Y) - \mathbb{H}(Y|C)$

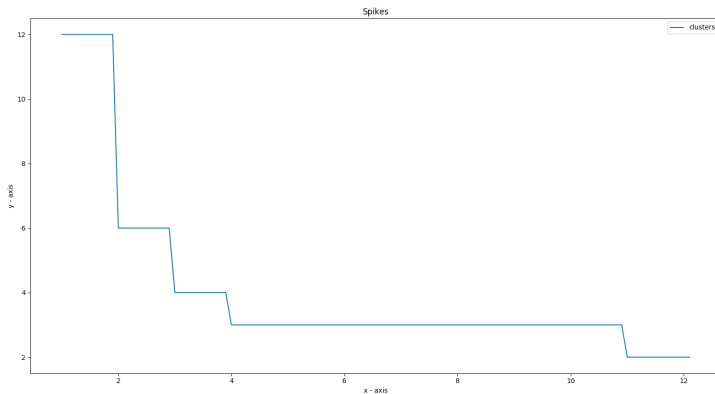


Custom Validation

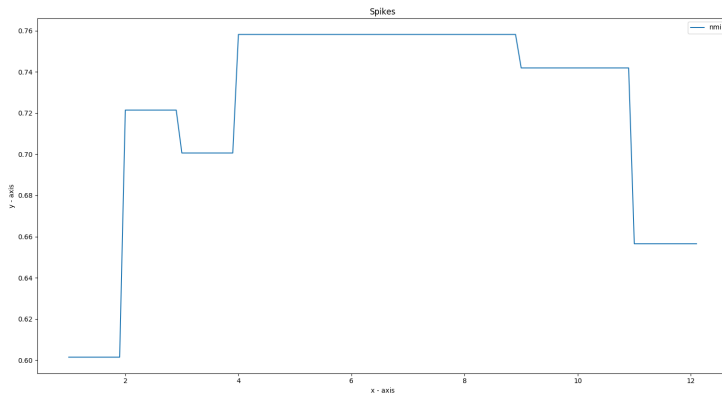
- For each generated cluster label, we find the original cluster label that it maps to.
- We then find the accuracy of this mapping w.r.t. the clustering.



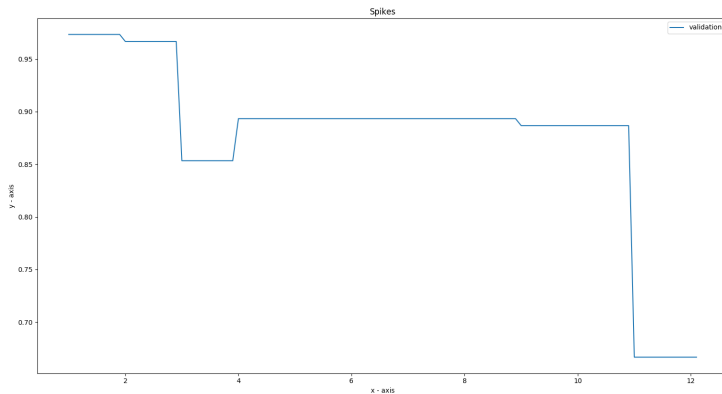
DP Means: No. of Clusters



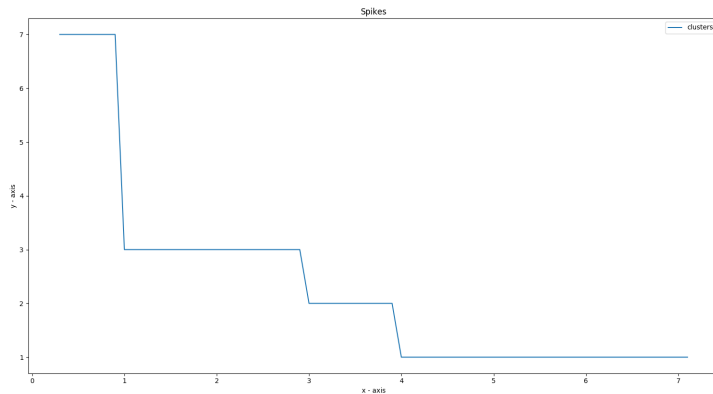
DP Means: NMI



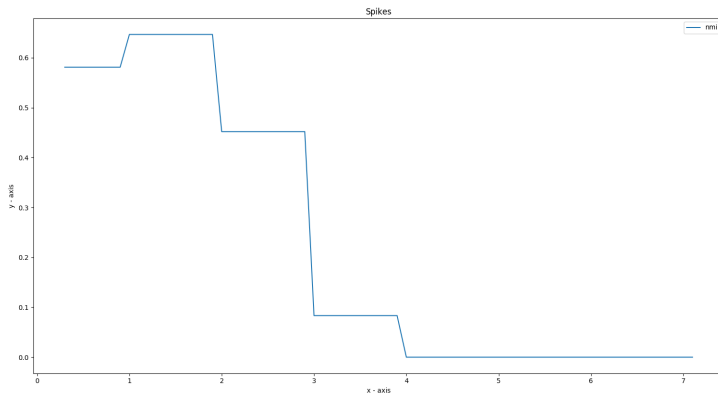
DP Means: Custom Validation



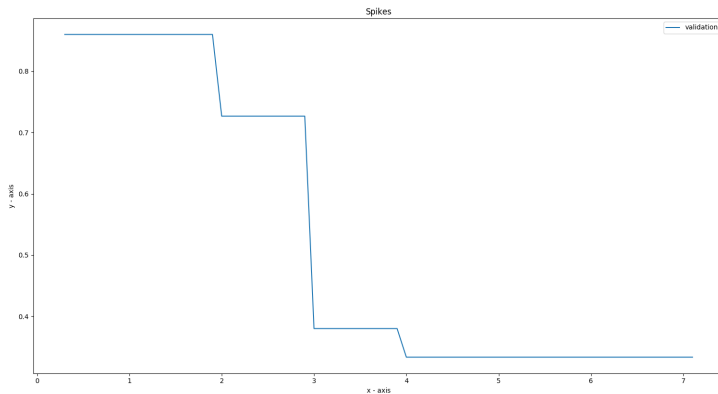
DP Means with Bregman Divergence: No. of Clusters



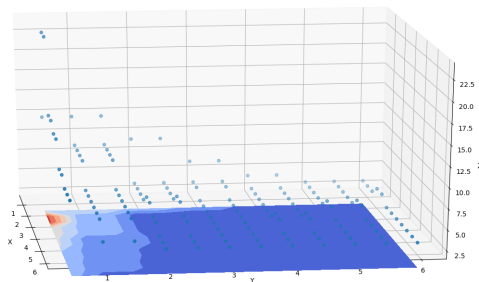
DP Means with Bregman Divergence: NMI



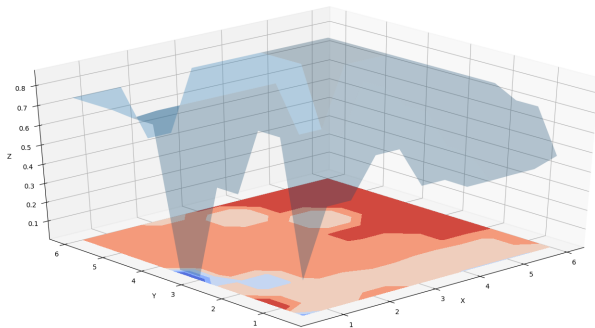
DP Means with Bregman Divergence: Custom Validation



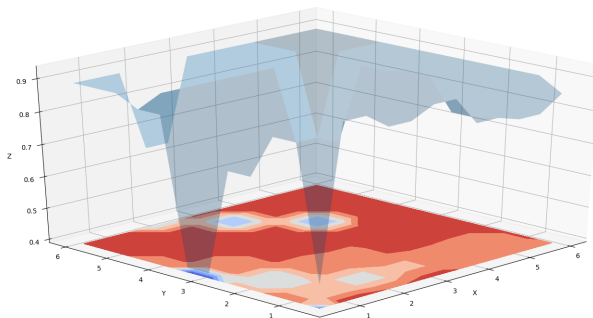
Hierarchical DP: No. of Clusters



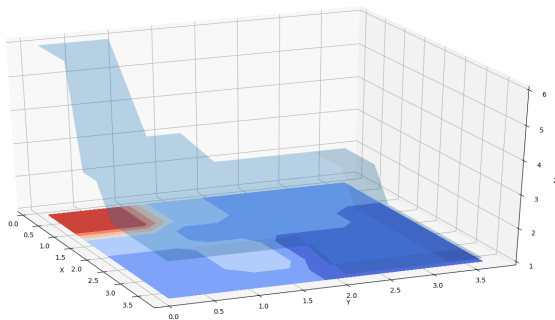
Hierarchical DP: NMI



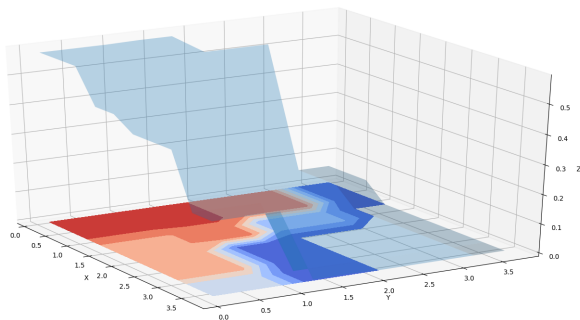
Hierarchical DP: Custom Validation



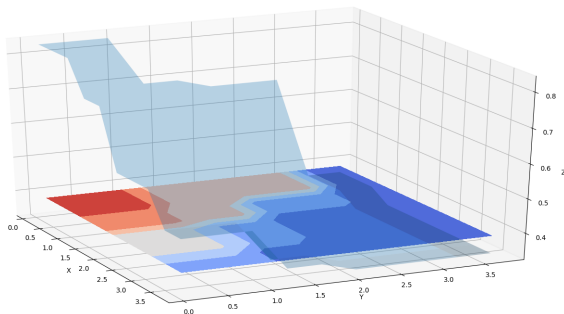
Hierarchical DP with Bregman Divergence: No. of Clusters



Hierarchical DP with Bregman Divergence: NMI



Hierarchical DP with Bregman Divergence: Custom Validation



Things learnt from Project

- Never (ever) code a ML model in C++ (unless absolutely required) :p
- Learnt the concepts of Dirichlet and Hierarchical Dirichlet Prior
- Learnt about Bregman Divergences
- Learnt how small variance asymptotics can be useful



Thank You 😊

