

## *Quick Sort*


- Another method which is different from Merge Sort in which, the divided sub files are not need to be merged later.
- This method uses a procedure known as “PARTITION” (C.A.R. Hoare).

# Partitioning

- To partition data is to divide it into two groups, so that all the items with a key value higher than a **specified value** are in one group, and all the item with a lower key value are in another.
  - Data could be partitioned more than 2-ways
- The value used to determine in which of two groups an item is placed is called a **pivot value**

- Basically the quicksort algorithm operates by partitioning an array into two subarrays, and then calling itself to quicksort each of these subarrays.

- **Algorithm**

- Partition the array into left and right subarrays
  - Call itself to sort left subarray
  - Call itself to sort right subarray
    - If array has only one element it is sorted
- How is the pivot selected 

Global n: integer;

A: array [1..n] of items;

procedure PARTITION(m: integer {index}, var  
p: integer {index+1});

{within A[m], A[m+1], ..., A[p-1] the elements are  
rearranged in such a way that if initially  $t = A[m]$ , then after  
completion  $A[q] = t$ , for some q between m and p-1,  $A[k] \leq t$ ,  
 $m \leq k \leq q$ ,  $A[k] \geq t$ ,  $q < k < p$ , final value of p is q}

var i: integer; v: item;

begin

$v \leftarrow A[m]$ ;  $i \leftarrow m$ ; {A[m] is a partition element}

while (i < p) do

begin

$i \leftarrow i+1;$

while( $A[i] < v$ ) do  $i \leftarrow i+1;$  { $i$  moves left to right}

$p \leftarrow p-1;$

while( $A[p] > v$ ) do  $p \leftarrow p-1;$  { $p$  moves right to left}

if ( $i < p$ ) then swap( $A[i], A[p]$ );

end

$A[m] \leftarrow A[p]; A[p] \leftarrow v;$       {the partition element  
belongs at  $p$ }

end.

Global n: integer; A:array [1..n] of items;

**procedure QUICKSORT(p, q:integer);**

{sort elements A[p]..A[q] which resides in the A[1..n], in ascending order. A[n+1] >= all elements in A[p..q], and set to infinity}

begin

if (p < q) then

begin

j ← q+1;

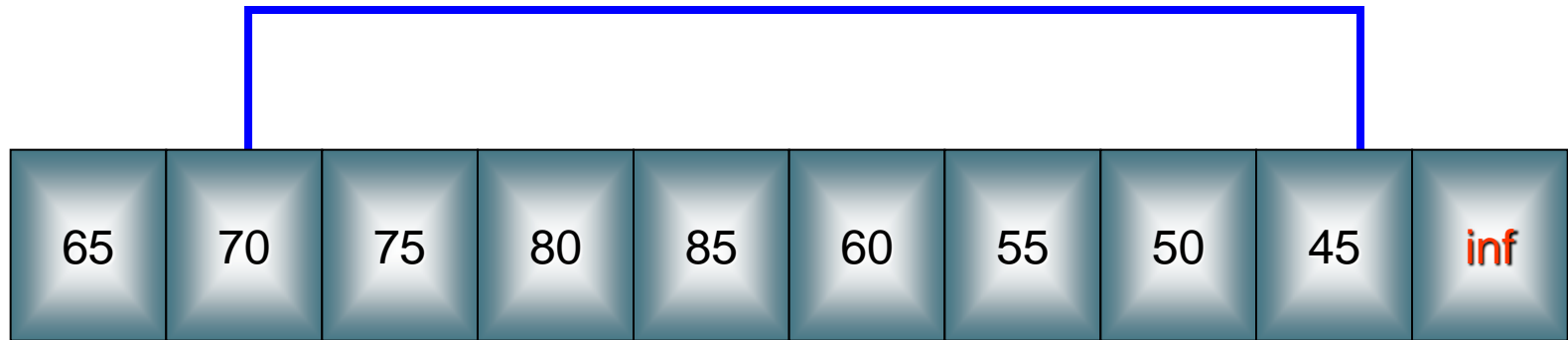
PARTITION(p,j);

QUICKSORT(p, j-1);

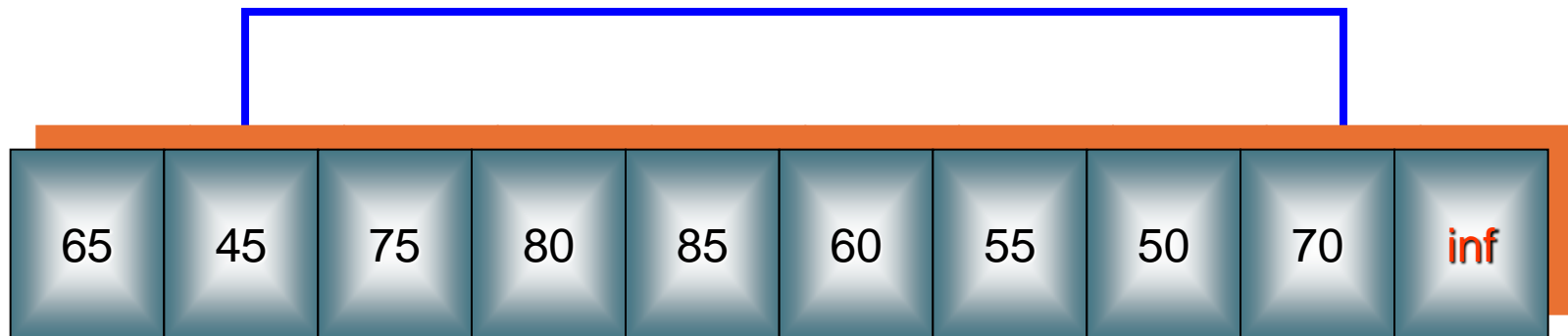
QUICKSORT(j+1, q);

end

end.

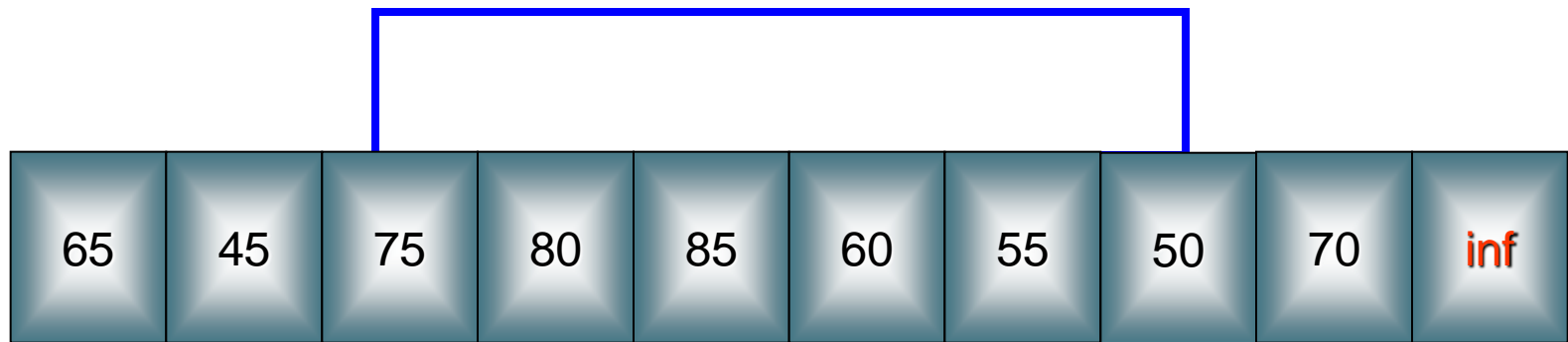


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|-----|-----|-----|-----|-----|-----|-----|-----|-----|----------|---|---|
| (1) | (2) | (3) | (4) | (5) | (6) | (7) | (8) | (9) | (10)     | i | p |
| 65  | 70  | 75  | 80  | 85  | 60  | 55  | 50  | 45  | $\infty$ | 2 | 9 |

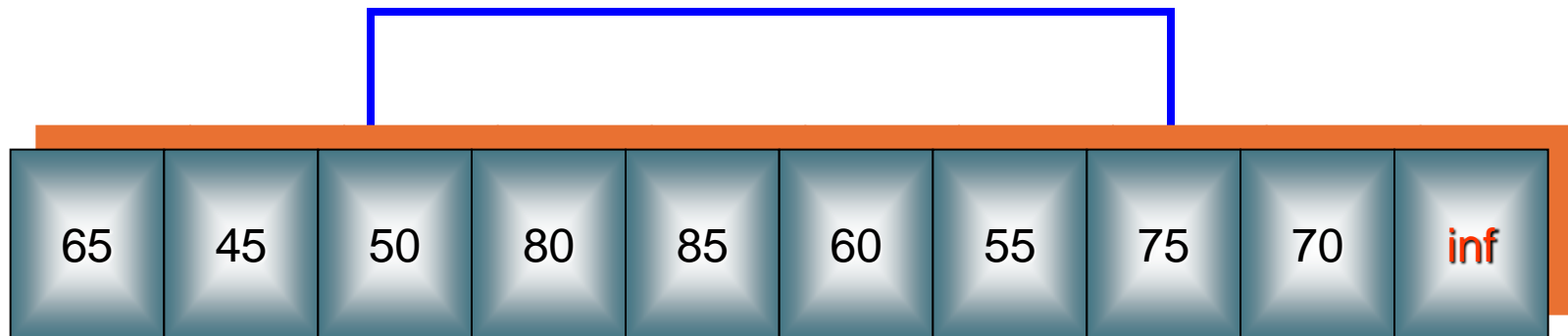


| (1) | (2) | (3) | (4) | (5) | (6) | (7) | (8) | (9) | (10)     | i | p |
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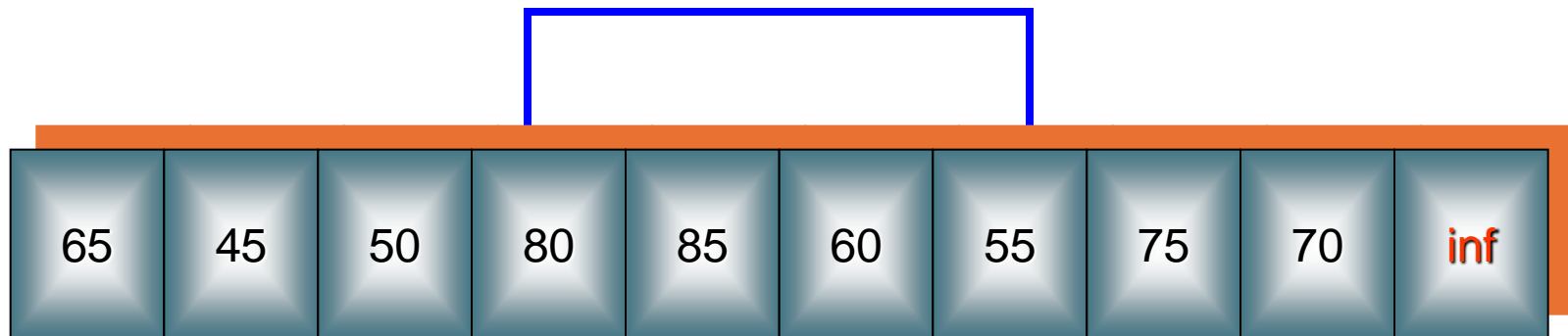




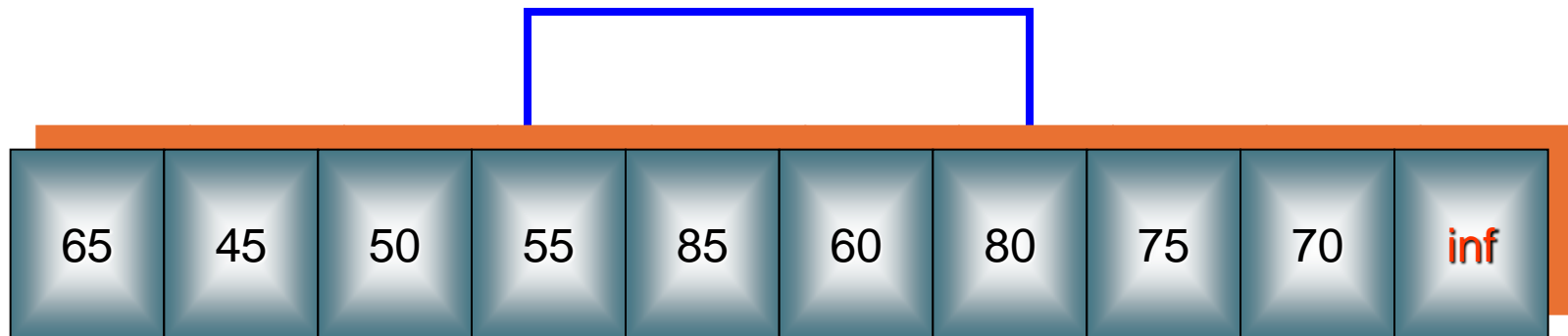
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| (1) | (2) | (3) | (4) | (5) | (6) | (7) | (8) | (9) | (10)     | i | p |
| 65  | 45  | 75  | 80  | 85  | 60  | 55  | 50  | 70  | $\infty$ | 3 | 8 |



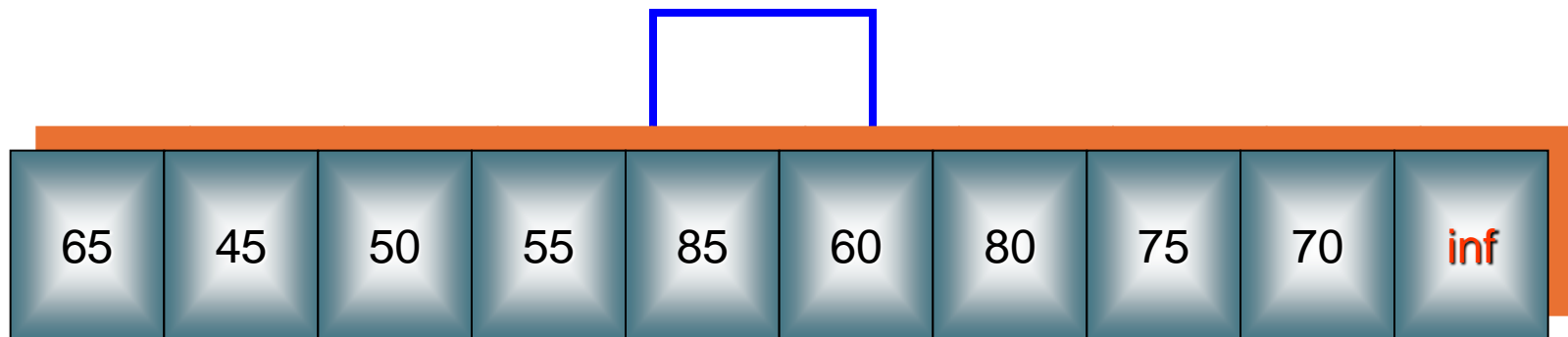
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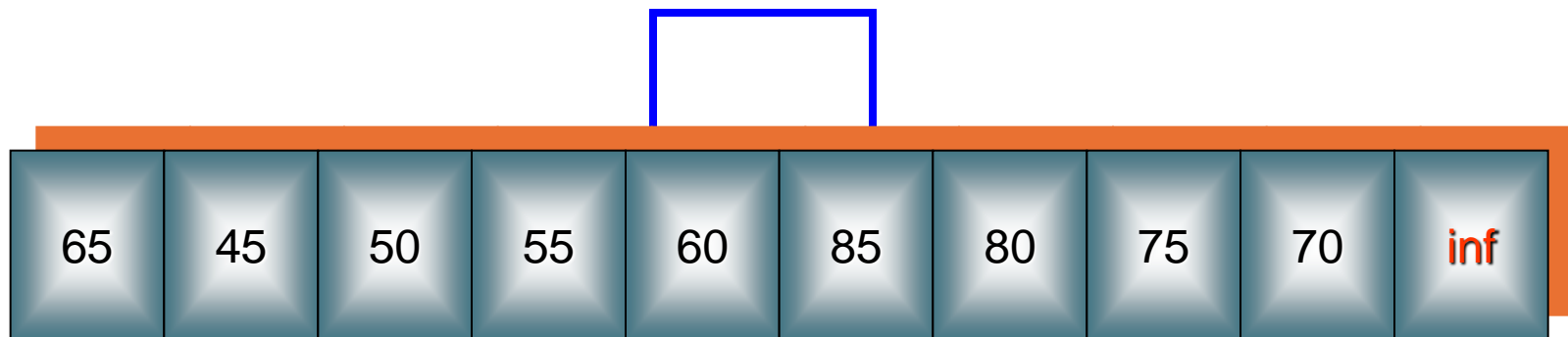
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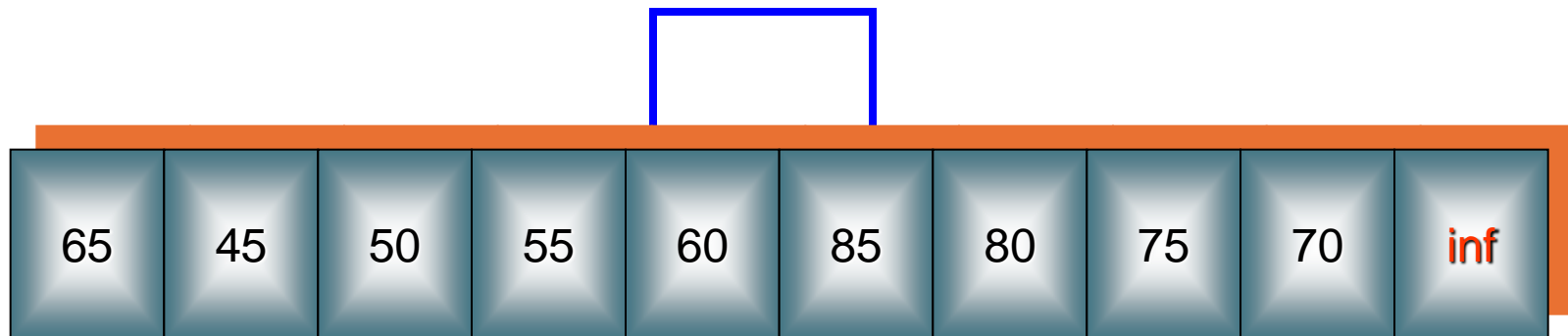
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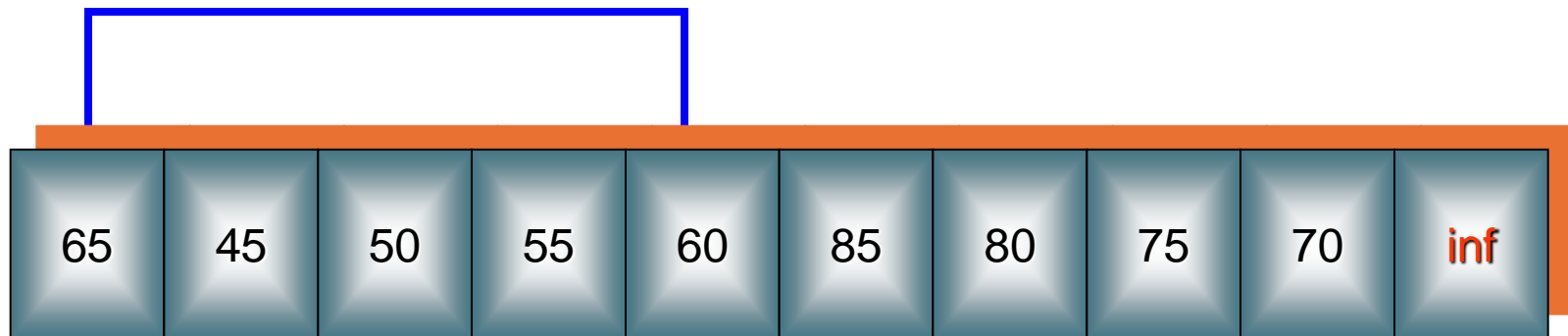
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| (1) | (2) | (3) | (4) | (5) | (6) | (7) | (8) | (9) | (10)     | i | p |
| 65  | 45  | 50  | 55  | 85  | 60  | 80  | 75  | 70  | $\infty$ | 5 | 6 |



|     |     |     |     |     |     |     |     |     |          |   |   |
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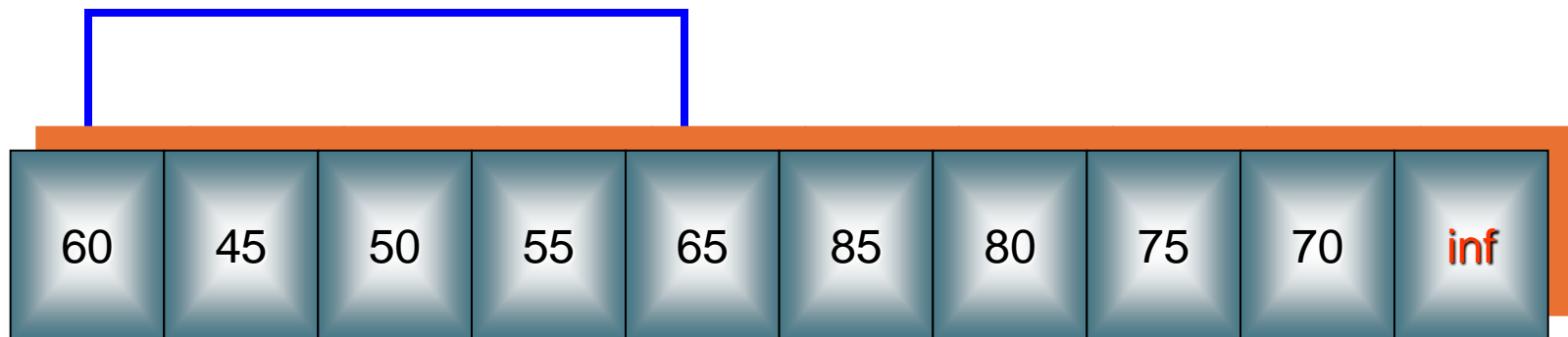


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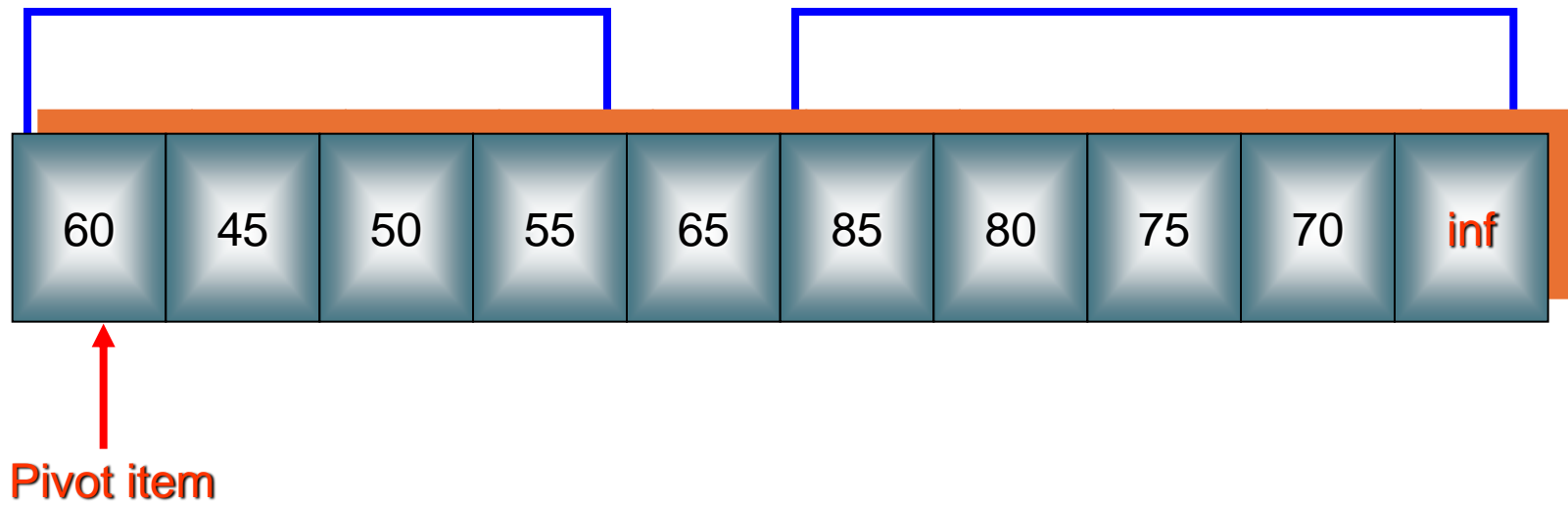


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| 65  | 45  | 50  | 55  | 85  | 60  | 80  | 75  | 70  | $\infty$ |   |   |





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| 60  | 45  | 50  | 55  | 85  | 65  | 80  | 75  | 70  | <b>∞</b> |   |   |



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|-----|-----|-----|-----|-----|-----|-----|-----|-----|----------|---|---|
| 65  | 70  | 75  | 80  | 85  | 60  | 55  | 50  | 45  | $\infty$ | 2 | 9 |
| 65  | 45  | 75  | 80  | 85  | 60  | 55  | 50  | 70  | $\infty$ | 3 | 8 |
| 65  | 45  | 50  | 80  | 85  | 60  | 55  | 75  | 70  | $\infty$ | 4 | 7 |
| 65  | 45  | 50  | 55  | 85  | 60  | 80  | 75  | 70  | $\infty$ | 5 | 6 |
| 65  | 45  | 50  | 55  | 60  | 85  | 80  | 75  | 70  | $\infty$ | 6 | 5 |
| 60  | 45  | 50  | 55  | 65  | 85  | 80  | 75  | 70  |          |   |   |

- Selection of the pivot

- Ideally the pivot should be the **median** of the items being sorted. That is, half the items should be greater than the pivot, and half smaller.
- The worst situation results when a subarray with  $n$  elements is divided into one subarray with 1 element and the other with  $n-1$  elements.
- There are two problems with it
  - Performance of algorithm  $\Theta(n^2)$
  - Recursive function calls take space on the machine stack

# *Worst case analysis of QUICKSORT*

- Assumptions:

1. The  $n$  elements to be sorted are distinct
2. The partitioning element in PARTITION is chosen with some random selection procedure.

The number of element comparisons in each call of “PARTITION” is

$p-m+1$  (distinct elements)

$p-m+2$  (repeated elements)

Let  $r$  be the total number of elements comparisons required at any level of recursion-

- At level one, one call PARTITION(1, n+1);  $r = n$ ;
- At level two, at most two calls are made and  $r = n-1$ ;
- At each level of recursion  $O(r)$  elements comparisons are made so-

$$C_w(n) = \sum_{r=2}^n O(r) = O(n^2)$$

or  $\Omega(n^2)$

## *Average case analysis of QUICKSORT*

Average case value  $C_A(n)$  is much less than its worst case, under the assumptions made earlier.

The partitioning element  $\underline{v}$  in the call of PARTITION( $m, p$ ) has equal probability of being the  $i^{\text{th}}$ ,  $1 \leq i \leq p - m$ , smallest element, in  $A[m, p-1]$ , hence two files remaining to be sorted will be  $A[m:j]$  and  $A[j+1:p-1]$  with probability  $1/(p-m)$ , for all  $m \leq j < p$ .

From this we obtain the recurrence relation

$$C_A(n) = n + 1 + \frac{1}{n} \left( \sum_{1 \leq k \leq n} (C_A(k-1) + C_A(n-k)) \right) \quad \dots(1)$$

$n+1$  is the number of comparisons required by PARTITION on its first call

$$nC_A(n) = n(n+1) + 2(C_A(0) + C_A(1) + \dots + C_A(n-1)) \quad \dots(2)$$

replacing  $n$  by  $n-1$  we get

$$(n-1)C_A(n-1) = n(n-1) + 2(C_A(0) + C_A(1) + \dots + C_A(n-2)) \quad \dots(3)$$



subtracting (3) from (2) we get

$$nC_A(n) - (n-1)C_A(n-1) = 2n + 2(C_A(n-1)) \quad \text{or}$$

$$C_A(n)/(n+1) = \frac{C_A(n-1)}{n} + \frac{2}{n+1}$$

repeatedly using this equation to substitute for  $C_A(n-1)$ ,  $C_A(n-2)$ ,... we get

$$C_A(n)/(n+1) = \frac{C_A(n-2)}{n-1} + \frac{2}{n} + \frac{2}{n+1}$$

$$= \frac{C_A(n-3)}{n-2} + \frac{2}{n-1} + \frac{2}{n} + \frac{2}{n+1}$$

$$= \frac{C_A(1)}{2} + 2 \sum_{3 \leq k \leq n+1} \frac{1}{k}$$

$$\sum_{3 \leq k \leq n+1} \frac{1}{k} \leq \int_2^{n+1} \frac{1}{x} dx = \log_e(n+1) - \log_e 2$$

$$C_A(n) \leq 2(n+1)[\log_e(n+1) - \log_e 2]$$

$$= O(n \log n)$$

$$= \frac{C_A(n-3)}{n-2} + \frac{2}{n-1} + \frac{2}{n} + \frac{2}{n+1}$$

$$= \frac{C_A(1)}{2} + 2 \sum_{3 \leq k \leq n+1} \frac{1}{k}$$

$$= \log_e(n+1) + \lambda - 3/2, \text{ where } \lambda \approx 0.577$$

is known as Euler's constant

$$= O(n \log n)$$

## Matrix Multiplication

Let A and B are two  $n \times n$  matrices, the product  $C = AB$  is also a  $n \times n$  matrix defined as-

$$C_{i,j} = \sum_{k=1}^n A_{i,k} B_{k,j}$$

As a divide and conquer solution of this problem ( $n = 2^k$ ), for  $n = 2$  the solution needs *8 multiplications and 4 additions* and complexity of it is  $O(n^3)$ .

## *Strassen Matrix Multiplication*

Strassen discovered a way to compute  $C_{ij}$  using 7 multiplications and 18 additions.

7 multiplication of size are computed as-

$$P = (A_{11} + A_{22}) (B_{11} + B_{22})$$

$$T = (A_{11} + A_{12}) B_{22}$$

$$Q = (A_{21} + A_{22}) B_{11}$$

$$U = (A_{21} - A_{11}) (B_{11} + B_{12})$$

$$R = A_{11} (B_{12} - B_{22})$$

$$V = (A_{12} - A_{22}) (B_{21} + B_{22})$$

$$S = A_{22} (B_{21} - B_{11})$$

and then

$$C_{11} = P+S-T+V$$

$$C_{12} = R+T$$

$$C_{21} = Q+S$$

$$C_{22} = P+R-Q+U$$

required time  $T(n)$  is given by

$$T(n) = \begin{cases} 7T(n/2) + an^2, & n > 2 \\ b, & n \leq 2 \end{cases}$$

$$T(n) = 7T(n/2) + an^2$$

$$= 7[7T(n/4) + an^2/4] + an^2$$

⋮

$$= 7^k T(1) + an^2((7/4)^0 + (7/4)^1 + \dots + (7/4)^{k-1})$$

$$= 7^{\log n} + an^2 \left[ \frac{(7/4)^k - 1}{(7/4) - 1} \right]$$

$$\leq 7^{\log n} + cn^2[(7/4)^k]$$

$$= cn^{\log 4} (7/4)^{\log n} + 7^{\log n}$$

$$= cn^{\log 4} [n^{\log(7/4)}] + n^{\log 7}$$

$$= cn^{\log 4} n^{\log 7 - \log 4} + n^{\log 7}$$

$$= cn^{\log 4 + \log 7 - \log 4} + n^{\log 7}$$

$$= O(n^{\log 7}) = O(n^{2.81})$$

Victor Pan improved time to  $O(n^{2.681})$  & then  $O(n^{2.496})$



End of Chapter 3