

EE671: VLSI Design Assignment 1

CMOS Inverter Design using Sky130 PDK

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Introduction

In this assignment, a CMOS inverter is designed and simulated using the SkyWater 130nm (Sky130A) PDK in NGSpice. The design objective is to obtain a minimum-size inverter with equal rise and fall times, and then extract its static and dynamic characteristics. The inverter is loaded with another identical inverter to capture realistic behavior.

Q1: Minimum Size CMOS Inverter (INVX1)

Design Parameters

The minimum channel length (L_{min}) is fixed at $0.15\mu\text{m}$. NMOS width is restricted to $0.42\mu\text{m}$, while PMOS width is chosen to balance rise and fall times.

Inverter Design Parameter	Value
PMOS Width (μm)	1.26
PMOS Length (μm)	0.15
NMOS Width (μm)	0.42
NMOS Length (μm)	0.15

Dynamic Characteristics

The input was a rail-to-rail pulse with rise/fall time of 20 ps. The inverter was loaded with another INVX1. The measured rise time, fall time, and propagation delay are:

- **Rise time (t_r):** Defined as the time taken for the output voltage to rise from 20% to 80% of V_{DD} .

$$t_r = t_{80\% V_{DD}} - t_{20\% V_{DD}}$$

- **Fall time (t_f):** Defined as the time taken for the output voltage to fall from 80% to 20% of V_{DD} .

$$t_f = t_{80\% V_{DD}} - t_{20\% V_{DD}}$$

- **Propagation delay (t_p):** Calculated as the average of low-to-high and high-to-low propagation delays:

$$t_p = \frac{t_{PHL} + t_{PLH}}{2}$$

where

$$t_{PHL} = t_{50\% V_{in, rising}} - t_{50\% V_{out, falling}}, \quad t_{PLH} = t_{50\% V_{in, falling}} - t_{50\% V_{out, rising}}$$

$$t_{PHL} = 22.8 \text{ ps}, \quad t_{PLH} = 17.4 \text{ ps}$$

Final $t_p = 20.1 \text{ ps}$

Dynamic Characteristic	Value
Rise time, t_r (ps)	18.5
Fall time, t_f (ps)	18.5
Propagation delay, t_p (ps)	20.1

```

Q1a.cir  Q1b.cir  Q2a.cir  Q2b.cir
File Edit View

*Vout and Vin with time for INVX1 is loaded with INVX1

.lib ~/local/share/pdk/sky130A/libs.tech/ngspice/sky130.lib.spice tt

.param Lmin = 0.15
.param wp = 1.26
.param wn = 0.42

.param ap = 2*wp*Lmin
.param pp = 2*(wp + 2*Lmin)
.param an = 2*wn*Lmin
.param pn = 2*(wn + 2*Lmin)

* The voltage sources:
Vdd vdd gnd DC 1.8
Vi in gnd pulse(0 1.8 0p 20p 10p 1n 2n)

Xnot1 in vdd gnd p not1
Xnot2 p vdd gnd out not1

.subckt not1 a vdd vss z
xm01 z a vdd vdd sky130_fd_pr__pfet_01v8 l=0.15 w={wp} as={ap} ad={ap} ps={pp} pd={pp}
xm02 z a vss vss sky130_fd_pr__nfet_01v8 l=0.15 w={wn} as={an} ad={an} ps={pn} pd={pn}
.ends

* Simulation command:
.tran 1ps 10ns
.measure tran tr TRIG v(p) VAL=0.36 RISE=2 TARG v(p) VAL=1.44 RISE=2
.measure tran tf TRIG v(p) VAL=1.44 FALL=2 TARG v(p) VAL=0.36 FALL=2
.measure tran tphl TRIG v(in) VAL=0.9 RISE=2 TARG v(p) VAL=0.9 FALL=2
.measure tran tplh TRIG v(in) VAL=0.9 FALL=2 TARG v(p) VAL=0.9 RISE=2

.control
run
wdata /mnt/c/Users/anujy/IITB_COURSES/7th_SEMESTER_AUGUST_2025/EE671/Assignment_1/Q1a.txt in p
plot in p
.endc

```

Figure 1: Code snippet for Dynamic Characteristics INVX1

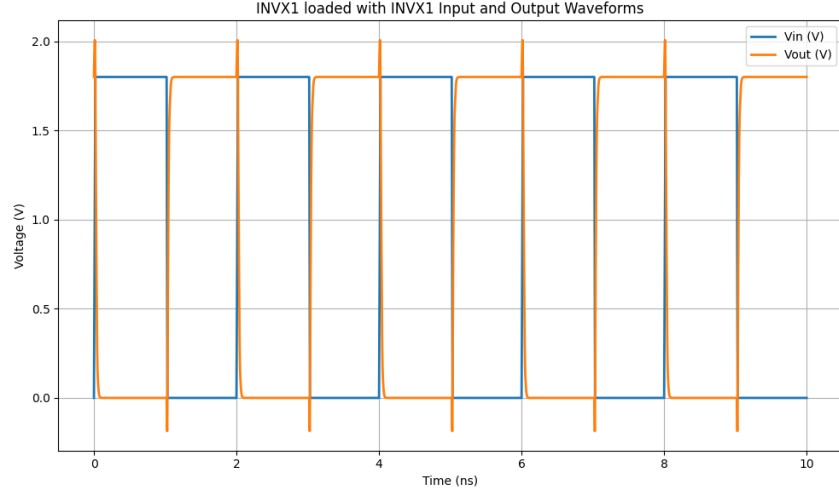


Figure 2: Inversion of the input signal by INVX1.

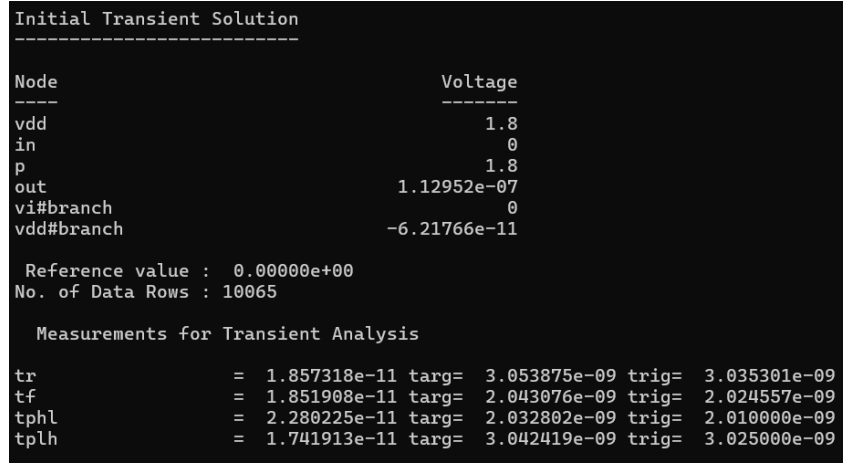


Figure 3: Dynamic Transfer Characteristic of INVX1.

Static Characteristics

Using a DC sweep on the input, the Voltage Transfer Characteristic (VTC) was obtained and parameters were extracted:

- **Switching Threshold (V_M):** The input voltage at which $V_{in} = V_{out}$.

$$V_M = V_{in}$$

Measured value: 0.89 V

- **Noise Margins:** The noise margins are calculated using:

$$N_{ML} = V_{IL} - V_{OL}, \quad N_{MH} = V_{OH} - V_{IH}$$

where $V_{OL} \approx 0$ and $V_{OH} \approx V_{DD}$.

- V_{IL} : Maximum input voltage recognized as logic '0', obtained from the VTC where $\frac{dV_{out}}{dV_{in}} = -1$ (lower transition point). Measured $V_{IL} = 0.77$ V

- V_{IH} : Minimum input voltage recognized as logic '1', obtained from the VTC where $\frac{dV_{out}}{dV_{in}} = -1$ (upper transition point). Measured $V_{IH} = 1.01$ V
- $N_{ML} = 0.77$ V, $N_{MH} = 0.79$ V

Static Characteristic	Value
V_{IH} (V)	1.01
V_{IL} (V)	0.77
N_{MH} (V)	0.79
N_{ML} (V)	0.77
Switching Voltage V_M (V)	0.89

```

Q1a.cir Q1b.cir Q2a.cir Q2b.cir
File Edit View

*Vout vs Vin and their direvative for INVX1 is loaded with INVX1

.lib ~/.local/share/pdk/sky130A/libs.tech/ngspice/sky130.lib.spice tt

.param Lmin = 0.15
.param wp = 1.26
.param wn = 0.42

.param ap = 2*wp*Lmin
.param pp = 2*(wp + 2*Lmin)
.param an = 2*wn*Lmin
.param pn = 2*(wn+ 2*Lmin)

* The voltage sources:
Vdd vdd gnd DC 1.8

Xnot1 in vdd gnd p not1
Xnot2 p vdd gnd out not1

.subckt not1 a vdd vss z
xm01 z a vdd vdd sky130_fd_pr__pfet_01v8 l=0.15 w={wp} as={ap} ad={ap} ps={pp} pd={pp}
xm02 z a vss vss sky130_fd_pr__nfet_01v8 l=0.15 w={wn} as={an} ad={an} ps={pn} pd={pn}
.ends

Vin in gnd 0
* Simulation command:
.dc Vin 0 1.8 0.001

.control
run
wrdata /mnt/c/Users/anujy/IITB_COURSES/7th_SEMESTER_AUGUST_2025/EE671/Assignment_1/Q1b.txt V(p) vs V(in)
plot V(p) vs V(in)
.endc

```

Figure 4: Code snippet for Static Characteristics INVX1

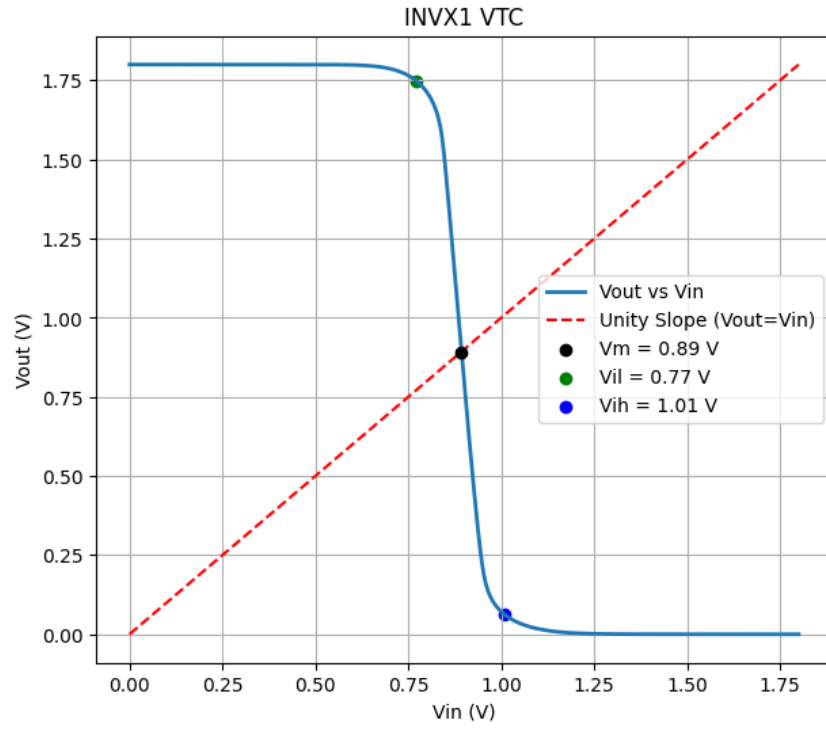


Figure 5: Static Transfer Characteristic of INVX1 with unity slope line and extracted parameters.

Q2: Strength-2 Inverter (INVX2)

The transistor widths were doubled to obtain INVX2. The inverter was loaded with INVX1 and the same set of measurements were repeated.

Design Parameters

Inverter Design Parameter	Value
PMOS Width (μm)	2.58
PMOS Length (μm)	0.15
NMOS Width (μm)	0.84
NMOS Length (μm)	0.15

Dynamic Characteristics

These are the dynamic characteristics calculated with the target of making the rise time equal to the fall time

Dynamic Characteristic	Value
Rise time, t_r (ps)	17.3
Fall time, t_f (ps)	17.3
Propagation delay, t_p (ps)	15.3

```

Q1a.cir  Q1b.cir  Q2a.cir  Q2b.cir
File Edit View

*Vout and Vin with time for INVX2 is loaded with INVX1
.lib ~/local/share/pdk/sky130A/libs.tech/ngspice/sky130.lib.spice tt

.param Lmin1 = 0.15
.param wp1 = 1.29
.param wn1 = 0.42
.param Lmin2 = 0.15
.param wp2 = 2*wp1
.param wn2 = 2*wn1

.param ap1 = 2*wp1*Lmin1
.param pp1 = 2*(wp1 + 2*Lmin1)
.param an1 = 2*wn1*Lmin1
.param pn1 = 2*(wn1 + 2*Lmin1)
.param ap2 = 2*wp2*Lmin2
.param pp2 = 2*(wp2 + 2*Lmin2)
.param an2 = 2*wn2*Lmin2
.param pn2 = 2*(wn2 + 2*Lmin2)

vdd vdd gnd DC 1.8
Vi in gnd pulse(0 1.8 0p 20p 10p 1n 2n)

Xnot1 in vdd gnd p not2
Xnot2 p vdd gnd out not1

.subckt not1 a vdd vss z
xm01 z a vdd vdd sky130_fd_pr__pfet_01v8 l={Lmin1} w={wp1} as={ap1} ad={ap1} ps={pp1} pd={pp1}
xm02 z a vss vss sky130_fd_pr__nfet_01v8 l={Lmin1} w={wn1} as={an1} ad={an1} ps={pn1} pd={pn1}
.ends

.subckt not2 a vdd vss z
xm03 z a vdd vdd sky130_fd_pr__pfet_01v8 l={Lmin2} w={wp2} as={ap2} ad={ap2} ps={pp2} pd={pp2}
xm04 z a vss vss sky130_fd_pr__nfet_01v8 l={Lmin2} w={wn2} as={an2} ad={an2} ps={pn2} pd={pn2}
.ends

.tran 1ps 10ns
.measure tran tr TRIG v(p) VAL=0.36 RISE=2 TARG v(p) VAL=1.44 RISE=2
.measure tran tf TRIG v(p) VAL=1.44 FALL=2 TARG v(p) VAL=0.36 FALL=2
.measure tran tphl TRIG v(in) VAL=0.9 RISE=2 TARG v(p) VAL=0.9 FALL=2

```

Figure 6: Code snippet for Dynamic Characteristics INVX2

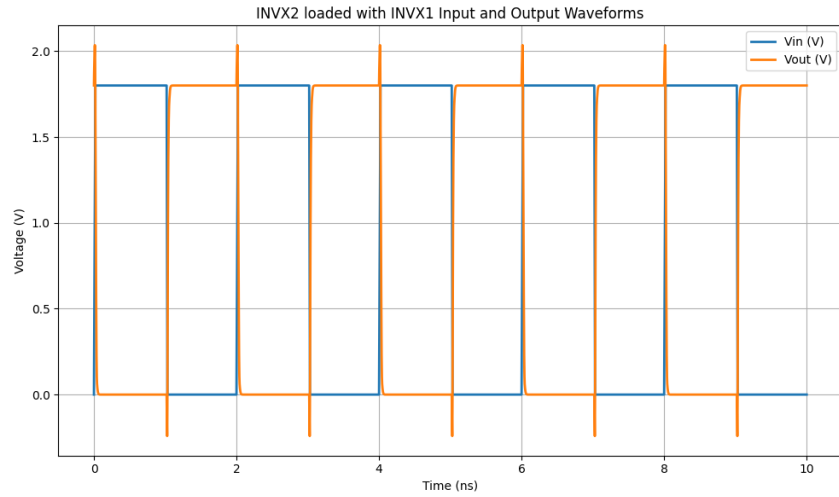


Figure 7: Inversion of the input signal by INVX2

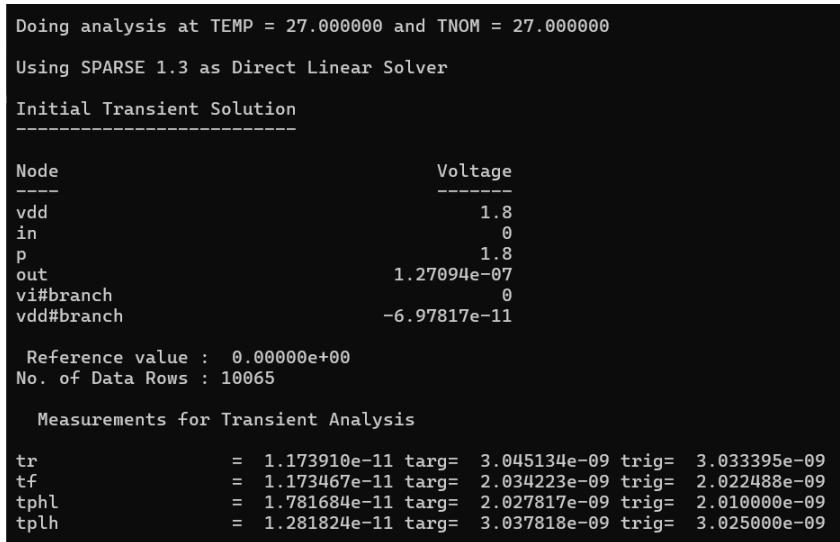


Figure 8: Dynamic Transfer Characteristic of INVX2

Static Characteristics

Using a DC sweep on the input, the Voltage Transfer Characteristics was obtained and parameters extracted:

Static Characteristic	Value
V_{IH} (V)	1.02
V_{IL} (V)	0.77
N_{MH} (V)	0.78
N_{ML} (V)	0.77
Switching Voltage V_M (V)	0.90

```

Q1a.cir      Q1b.cir      Q2a.cir      Q2b.cir
File Edit View

.param ap1 = 2*wp1*Lmin1
.param pp1 = 2*(wp1 + 2*Lmin1)
.param an1 = 2*wn1*Lmin1
.param pn1 = 2*(wn1+ 2*Lmin1)

.param ap2 = 2*wp2*Lmin2
.param pp2 = 2*(wp2 + 2*Lmin2)
.param an2 = 2*wn2*Lmin2
.param pn2 = 2*(wn2+ 2*Lmin2)

* The voltage sources:
Vdd vdd gnd DC 1.8

Xnot1 in vdd gnd p not2
Xnot2 p vdd gnd out not1

.subckt not1 a vdd vss z
xm01 z a vdd vdd sky130_fd_pr__pfet_01v8 l={Lmin1} w={wp1} as={ap1} ad={ap1} ps={pp1} pd={pp1}
xm02 z a vss vss sky130_fd_pr__nfet_01v8 l={Lmin1} w={wn1} as={an1} ad={an1} ps={pn1} pd={pn1}
.ends

.subckt not2 a vdd vss z
xm03 z a vdd vdd sky130_fd_pr__pfet_01v8 l={Lmin2} w={wp2} as={ap2} ad={ap2} ps={pp2} pd={pp2}
xm04 z a vss vss sky130_fd_pr__nfet_01v8 l={Lmin2} w={wn2} as={an2} ad={an2} ps={pn2} pd={pn2}
.ends

Vin in gnd 0
* Simulation command:
.dc Vin 0 1.8 0.001

.control
run
wrdata /mnt/c/Users/anujy/IITB_COURSES/7th_SEMESTER_AUGUST_2025/EE671/Assignment_1/Q2b.txt V(p) vs V(in)
plot V(p) vs V(in)
.endc

```

Figure 9: Code snippet for Static Characteristics INVX2

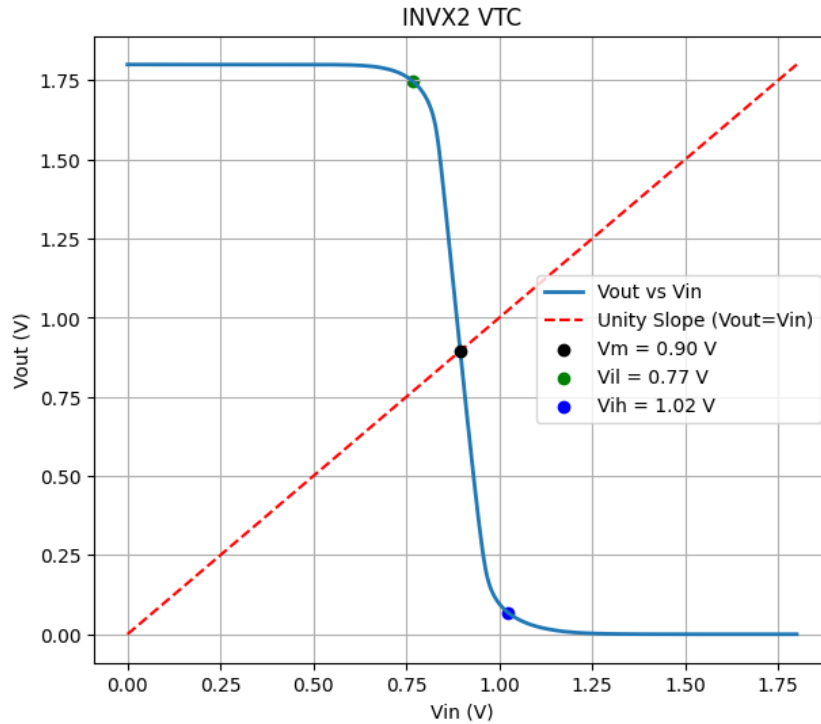


Figure 10: Static Transfer Characteristic of INVX2 with unity slope line and extracted parameters.

Results and Comparison

Parameter	INVX1	INVX2
t_r (ps)	18.5	17.3
t_f (ps)	18.5	17.3
t_p (ps)	20.1	15.3
V_M (V)	0.89	0.90
N_{MH} (V)	0.79	0.78
N_{ML} (V)	0.77	0.77

Observation

INVX2 shows improved drive strength compared to INVX1, leading to reduced rise/fall times and propagation delay. The switching voltage V_M remains approximately unchanged, but dynamic performance improves.