
Software Testing and Quality Assurance

Lecture 2

Agenda

- Software Testing from theoretical standpoint
 - Verification Vs Validation
 - Static Vs Dynamic Testing
 - Adequacy
 - Graph Based Testing
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Input and Output Space

- Let \mathbf{U} be the set of numbers and characters that can be represented on some computer system.
 - Let \mathbf{I} be the input space, and \mathbf{O} be the output space.
 - Both \mathbf{I} and \mathbf{O} are equal to the set of finite sequences of \mathbf{U} .
-

Specifications

- A *specification* is a relation $\mathbf{S} \subseteq \mathbf{I} \times \mathbf{O}$
- The *input domain of specification* \mathbf{S} is the set
$$\mathbf{D}^{\mathbf{S}} = \{ i \in \mathbf{I} \mid \exists o \in \mathbf{O}, (i, o) \in \mathbf{S} \}$$
- Ideally, a specification is a *total* function, which describes an intended behavior of the program for every possible input.
- In practice, a specification is a *partial* function, whose domain is the set of all values for which \mathbf{S} is defined.

Programs

- A program defines a partial function
$$\mathbf{P} : \mathbf{I} \rightarrow \mathbf{O}$$
 - The *input domain of program \mathbf{P}* is the set
$$\mathbf{D}^{\mathbf{P}} = \{i \in \mathbf{I} \mid \mathbf{P} \text{ halts on input } i\}$$
$$= \{i \in \mathbf{I} \mid \mathbf{P}(i) \text{ is defined}\}$$
 - Those inputs which cause program \mathbf{P} to crash or go into an infinite loop are not in $\mathbf{D}^{\mathbf{P}}$
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Program Correctness

- Program **P** is correct w.r.t. specification **S**, iff
$$\mathbf{D}^{\mathbf{S}} \subseteq \mathbf{D}^{\mathbf{P}} \text{ and } \forall i \in \mathbf{DS}, (i, \mathbf{P}(i)) \in \mathbf{S}$$
 - That is, **P** is correct w.r.t. **S** iff for each element i on the input domain of **S**, **P** halts on input i , returning a value which is in accordance with the specification.
-

Testing and Correctness

- In order to determine correctness by testing it is necessary to be able to generate a finite set $\mathbf{T} \subset \mathbf{D}$ with the following properties:
 - For each $t \in \mathbf{T}$ there is a computable procedure for determining whether or not \mathbf{P} terminates for t .
 - $\{\forall t \in \mathbf{T}, \mathbf{P}(t) = \mathbf{S}(t)\} \Rightarrow \{\forall t \in \mathbf{D}, \mathbf{P}(t) = \mathbf{S}(t)\}$
-

Verification vs. Validation

- Verification:
 - "Are we building the product right?"
 - The software should conform to its specification.
 - Validation:
 - "Are we building the right product?"
 - The software should do what the user really requires.
-

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Verification and Validation

- **Validation**: *process of evaluating a system or component during or at the end of the development process to determine whether it satisfies specified **requirements***
 - Validation: Are we building the right product?
 - **Verification**: *the process of evaluating a system or component to determine whether the products of a given development phase satisfy the conditions imposed at the start of that phase*
 - Verification: Are we building the product right?
 - **IEEE definitions**
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The V & V Process

- Is a whole life-cycle process - V & V must be applied at each stage in the software process.
 - Example: Peer document reviews
- Has two principal objectives
 - The discovery of defects in a system
 - The assessment of whether or not the system is usable in an operational situation

V & V Goals

- Verification and validation should establish confidence that the software is fit for its purpose.
 - This does NOT mean completely free of defects.
 - Rather, it must be good enough for its intended use. The type of use will determine the degree of confidence that is needed.
- This leads us to definition of testing
 - Software testing is the process of analyzing a software item to detect the differences between existing and required conditions (that is, bugs) and to evaluate the features of the software item

V & V Confidence

- Depends on the system's purpose, user expectations, and marketing environment
 - System purpose
 - The level of confidence depends on how critical the software is to an organization (e.g., safety critical).
 - User expectations
 - Users may have low expectations of certain kinds of software
 - Marketing environment
 - Getting a product to market early may be more important than finding defects in the program

Static vs. Dynamic V & V

- Code and document inspections - Concerned with the analysis of the static system representation to discover problems (*static v & v*)
 - May be supplement by tool-based document and code analysis
 - Software testing - Concerned with exercising and observing product behaviour (*dynamic v & v*)
 - The system is executed with test data and its operational behaviour is observed
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What, when, how and how much...

- What (or what against what) to test?
 - Is it the code, specification, features ...
 - Answer: at different levels, we bear different perspectives
 - This could be code, model against requirements
 - What are requirements?
 - When to test?
 - How and how much?
 - We want to find out when to stop testing
-

Test Selection and Adequacy Criteria

- Attention has focused on two important areas:
 - *Test selection criteria* i.e., conditions that must be fulfilled by a test.

For example, a criterion for a numerical program whose input domain is the integers might specify that each test contain one positive integer, one negative integer, and zero. { 3, 0, -7 }, { 122, 0, -11 }, { 1, 0, -1 } are three of the tests selected by this criterion.
 - *Test adequacy criteria* i.e., the properties of a program that must be exercised to constitute a thorough testing.

For example, we consider that our software has been adequately tested if the test suite causes each method to be executed at least once. This provides a measurable objective for completeness.
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What is adequacy?

- Given a program P written to meet a set of functional requirements $R = \{R_1, R_2, \dots, R_n\}$.
Let T contain k tests for determining whether or not P meets all requirements in R .
- Assume that P produces correct behavior for all tests in T .
We now ask:
Has P been tested thoroughly? or: Is T adequate?

In software testing, the terms “thorough” and “adequate” have the same meaning.

Measurement of adequacy

- **Adequacy** is measured for a given **test set** and a given **criterion**.
 - A test set is considered **adequate** wrt **criterion C** when it **satisfies C**.
-

Example

Program **Sum** must meet the following requirements:

- R1 Input two integers, x and y , from standard input.
 - R2.1 Print to standard output the sum of x and y if $x < y$.
 - R2.2 Print to standard output the Sum of x and y if $x \geq y$.
-

Example (contd.)

Suppose now that the test adequacy criterion C is specified as:

C : A test set T for program (P, R) is considered *adequate* if, for each r in R there is a test case in T that tests the correctness of P with respect to r .

$T = \{t: \langle x=2, y=3 \rangle\}$ is *inadequate* with respect to C for program *Sum*.

The lone test case t in T tests $R1$ and $R2.1$, but not $R2.2$.

Black-box and white-box criteria

Given an adequacy criterion C , we derive a finite set C_e known as the **coverage domain**.

A criterion C is a **white-box** test adequacy criterion if the corresponding **C_e depends solely on the program P under test.**

A criterion C is a **black-box** test adequacy criterion if the corresponding **C_e depends solely on the requirements R for the program P under test.**

Coverage

Measuring adequacy of T:

T covers C_e if, for each e' in C_e , there is a test case in T that tests e' . T is **adequate wrt C** if it covers all elements of C_e .

T is **inadequate with respect to C** if it covers $k < n$ elements of C_e .

k/n is the **coverage** of T wrt C.

Example

Consider criterion:

“A test T for (P, R) is **adequate** if , for each requirement r in R , there is at least one test case in T that tests the correctness of P with respect to r .”

The coverage domain is $C_e = \{R1, R2.1, R2.2\}$.

T covers $R1$ and $R2.1$ but not $R2.2$.

Hence, T is **inadequate** with respect to C .

The coverage of T wrt C is $2/3=0.66$.

Another Example

Consider the following criterion:

“A test T for program (P, R) is considered adequate if each path in P is traversed at least once.”

Assume that P has exactly two paths, p_1 and p_2 , corresponding to condition $x < y$ and condition $x \geq y$, respectively.

For the given adequacy criterion C we obtain the coverage domain C_e to be the set $\{p_1, p_2\}$.

Another Example (contd.)

To measure the adequacy of T of **Sum** against C, we execute P against each test case in T.

As T contains only one test for which $x < y$, only path p1 is executed.

Thus, the coverage of T wrt C is 0.5. T is not adequate with respect to C.

We can also say that p1 is tested and p2 is **not tested**.

Code-based coverage domain

In the previous example, we assumed that P contains two paths. When the coverage domain must contain elements from the **code**, these elements must be derived by **analyzing the code**.

Errors in the program and incomplete/incorrect requirements can cause the coverage domain to be different from the expected.

Question: What if we have 20 paths....

However

An adequate test set might not reveal even the most obvious error in a program.

This does not diminish in any way the need for the measurement of test adequacy, as increasing coverage might reveal an error!

Program Representation

Graph based representation

- We can represent a program as a set of nodes connected with vertices
 - We can define graph coverage criterion
 - We can based our sufficiency measurement or adequacy of testing
 - Program information
 - Control-flow
 - Data-flow
 - Dependence
 - ...
-

Control Flow Graphs

- A Control Flow Graph (CFG) is a *static*, abstract representation of a program.
 - A CFG is a directed graph $\mathcal{G} = (\mathcal{N}, \mathcal{E})$
 - Each node, in the set \mathcal{N} , is either a *statement node* or a *predicate node*.
 - A *statement node* represents a simple statement. Alternatively, a statement node can be used to represent a basic block.
 - A *predicate node* represents a conditional statement.
 - Each *edge*, in the set \mathcal{E} , represents the flow of control between statements.
 - Optionally, we use circles to represent statement nodes, and rectangles to represent predicate nodes.
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Example of a CFG

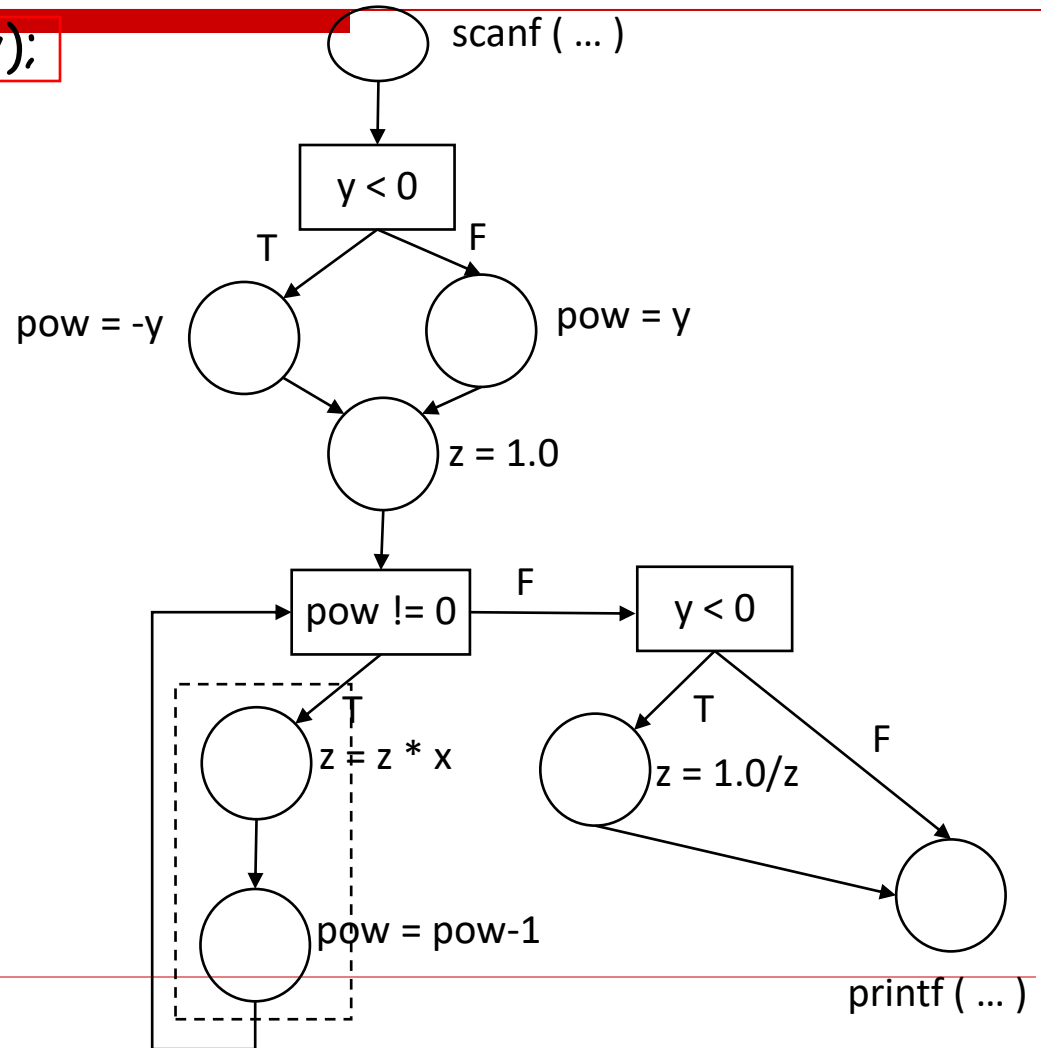
```
scanf ("%d, %d", &x, &y);
```

```
if (y < 0)  
    pow = -y;  
else  
    pow = y;
```

```
z = 1.0;
```

```
while (pow != 0) {  
    z = z * x;  
    pow = pow - 1;  
}
```

```
if (y < 0)  
    z = 1.0 / z;  
printf ("%f", z);
```



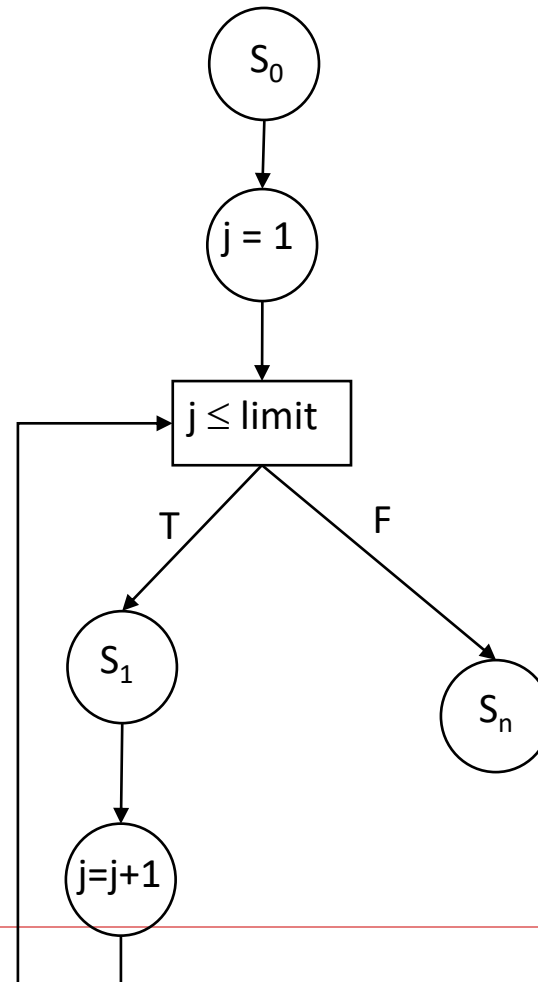
CFG: The **for** Loop

What does the CFG for the following code fragment look like?

```
S0;  
for ( j = 1; j <= limit; j=j+1 )  
{  
    S1;  
}  
Sn;
```

CFG: The **for** Loop

```
S0;  
for ( j = 1; j <= limit; j=j+1 )  
{  
    S1;  
}  
Sn;
```



CFGs: Switch-Case

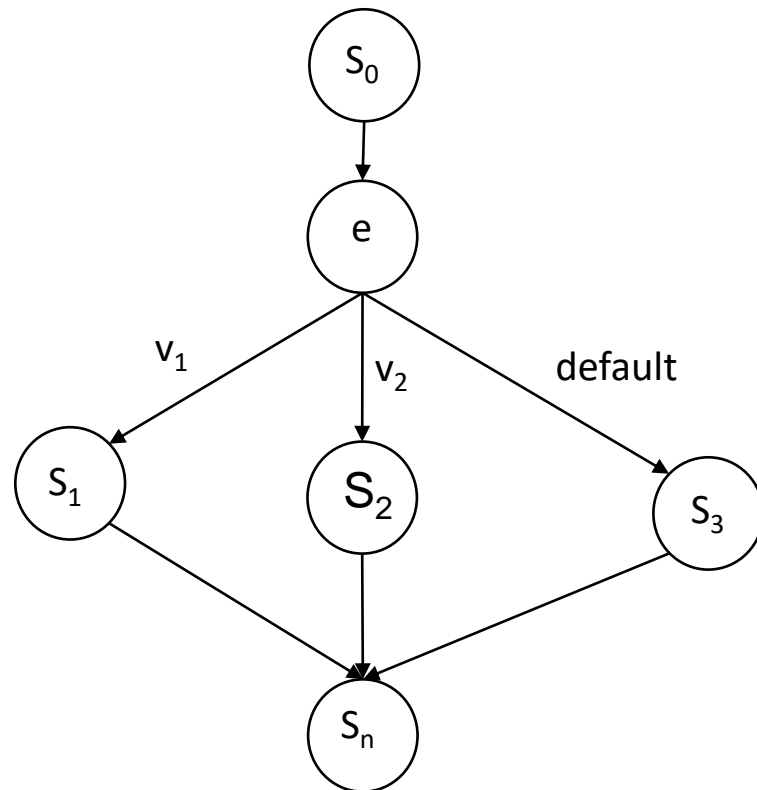
What does the CFG for the following code fragment look like?

```
S0;  
switch ( e )  
{  
    case v1:  
        S1;  
        break;  
    case v2:  
        S2;  
        break;  
    default:  
        S3;  
}  
Sn;
```

CFGs: Switch-Case

Intuitively, the diagram shown on the right...

However, e is not a predicate.



Program Paths

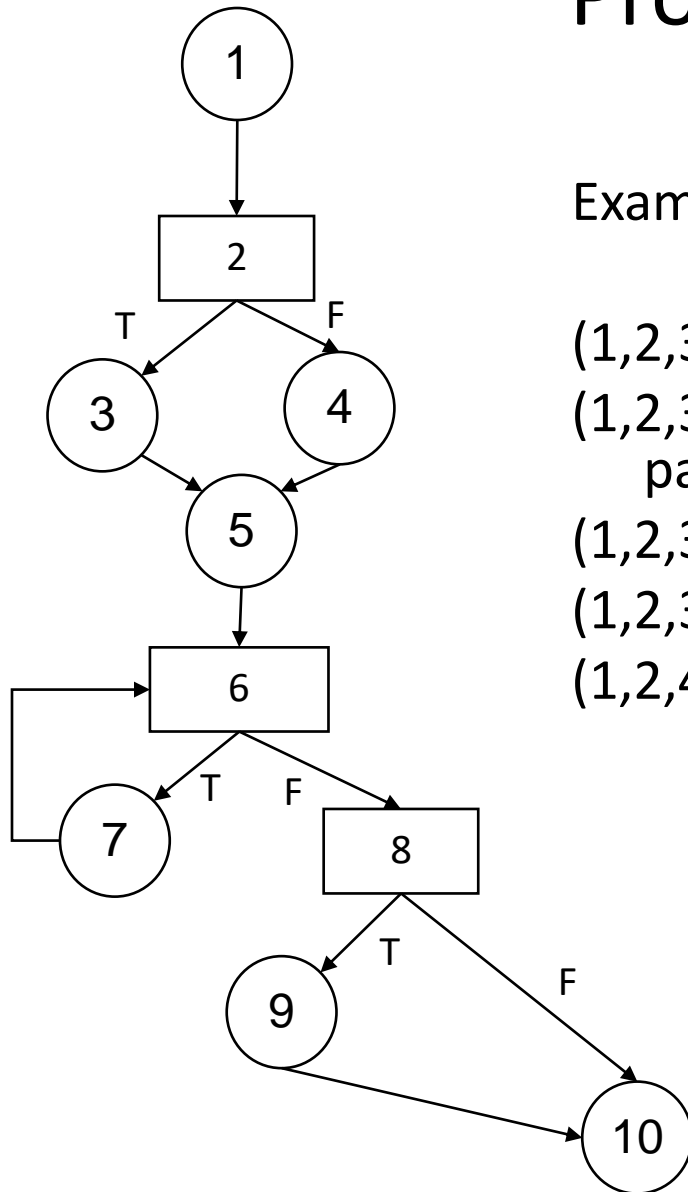
- A *path* is a unique sequence of executable statements from one point of the program to another point.
 - In a graph, a path is a sequence (n_1, n_2, \dots, n_t) of nodes such that $\langle n_i, n_{i+1} \rangle$ is an edge in the graph, $\forall i=1, 2, \dots, t-1$ ($t > 0$).
-

Program Paths

- *Complete path* starts with the first node and ends at the last node of the graph.
 - *Execution path* a complete path that can be exercised by some input data.
 - *Subpath* a subsequence of the sequence, e.g.,
 - n_1, n_2, \dots, n_t
 - *Elementary path* all nodes are unique.
 - *Simple path* all edges are unique
-

Program Paths

Example:



(1,2,3,5,6,7,6,8,10) is a *complete* path

(1,2,3,5,6,7,6,7,6,8,10) is a different *complete* path

(1,2,3,5) is a *subpath*

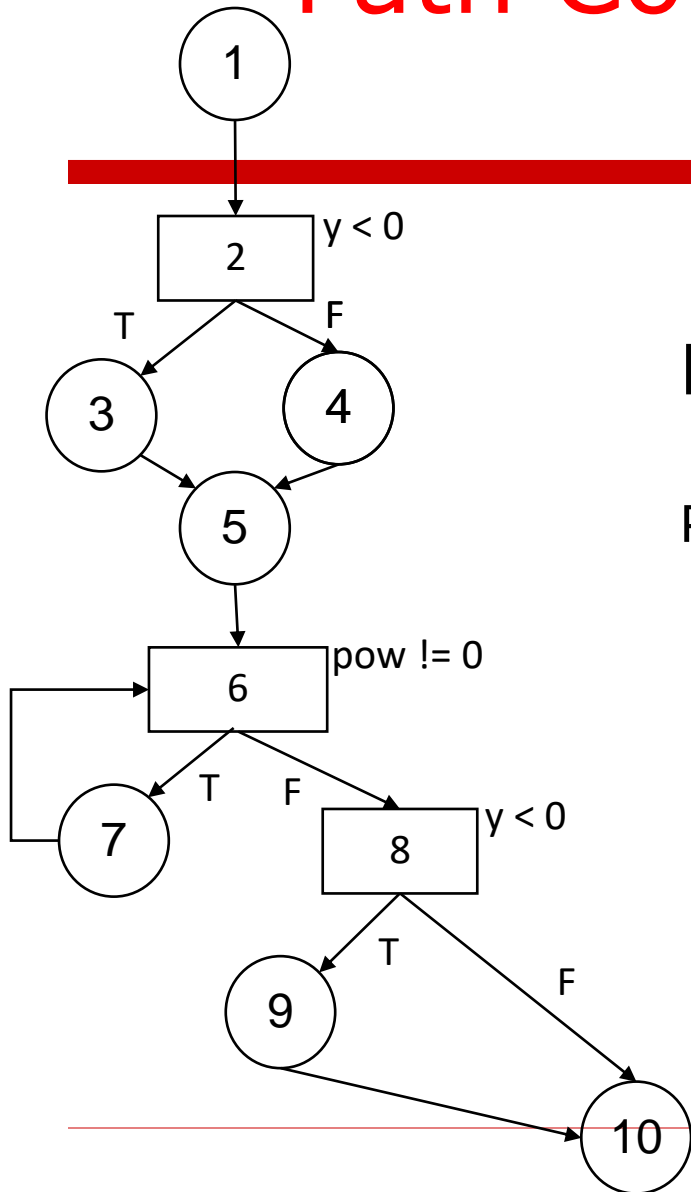
(1,2,3,5,6,8,10) is an *elementary* path

(1,2,4,5,6,7,6,8,10) is a *simple* path

Path Condition

- *Path condition*: the conjunction of the individual predicate conditions that are generated at each branch point along the path.
 - The path condition must be satisfied by the input data in order for the path to be executed.
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Path Condition



Example:

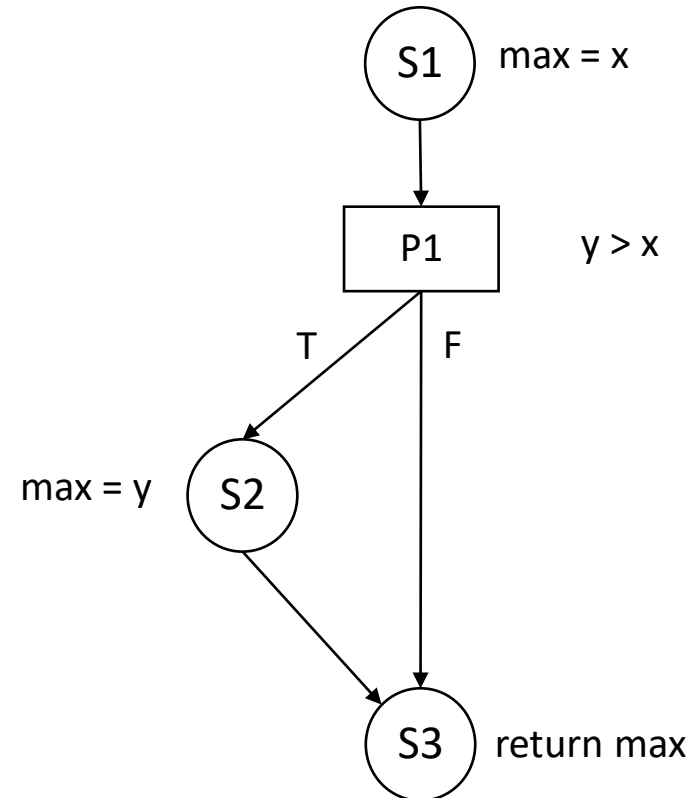
$$\text{PC}(1,2,4,5,6,8,10) = (y \geq 0 \wedge \text{pow} == 0 \wedge y \geq 0)$$

Number of Paths

The simple CFG shown here has 2 different paths:

(S1, P1, S2, S3)

(S1, P1, S3)

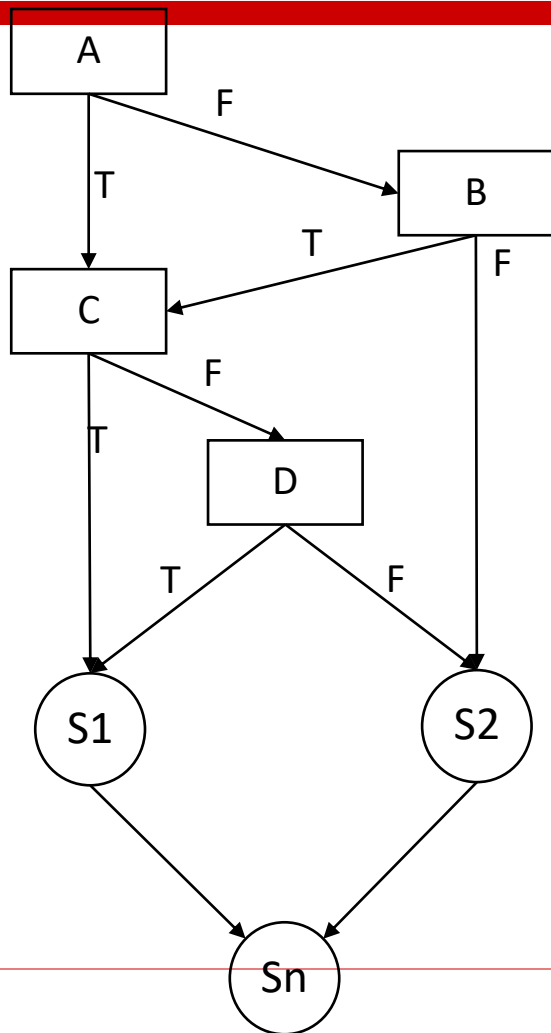


Number of Paths

How many paths?

```
if ((A||B) && (C||D))
{
    S1;
}
else
{
    S2;
}
```

Number of Paths



There are:

2 statements + s_n
4 branches

7 paths (4T + 3 F)

(A, C, S1)

(A, C, D, S1)

(A, C, D, S2)

(A, B, C, S1)

(A, B, C, D, S1)

(A, B, C, D, S2)

(A, B, S2)

Infinite Paths

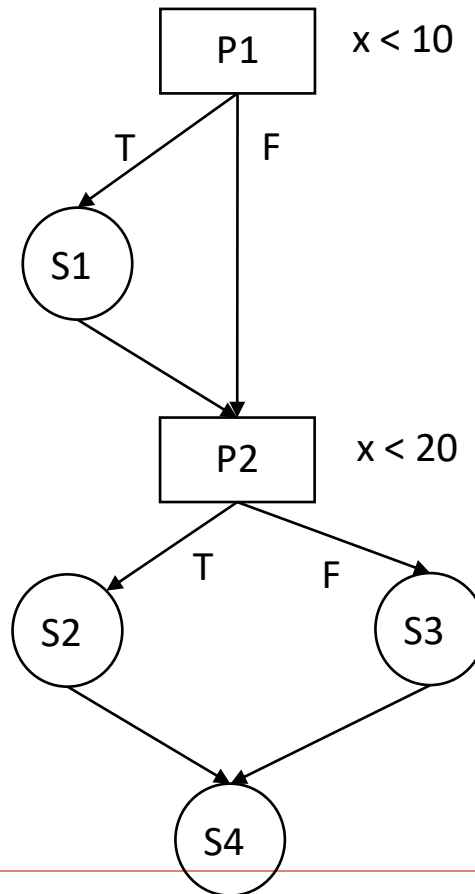
- Since the value for the variable a is entered by the user, we consider this program to have an infinite number of paths.
 - In general, programs that contain loops with control variables whose value is supplied by the user have infinite number of paths.
-

Infeasible Paths

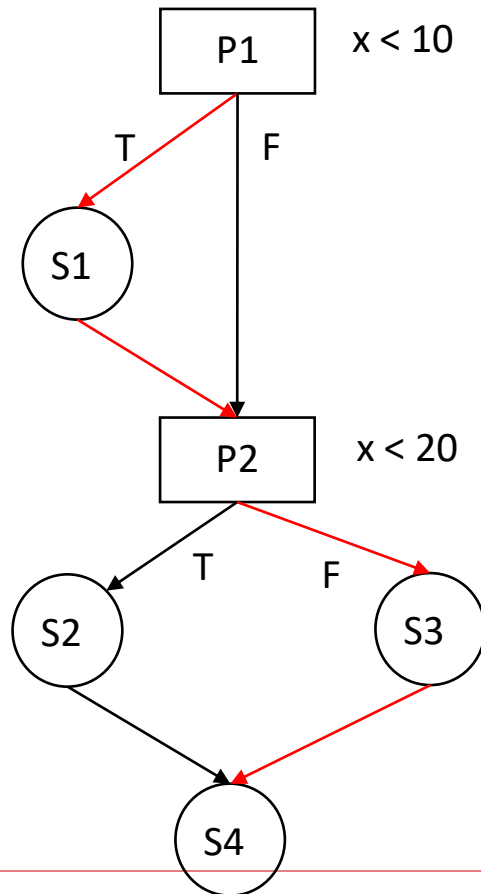
- A path is said to be feasible if it can be exercised by some input data; otherwise the path is said to be infeasible.
 - Infeasible paths are the result of contradictory predicates.
-

Infeasible Paths

Are there any
infeasible paths?
How many?



Infeasible Paths



The path
(P1, S1, P2, S3, S4)
is not feasible.
Unless S1 changes the
value of x ...

Flow graphs Consist of Three Primitives

- A **decision** is a program point at which the control can diverge.
 - (e.g., if and case statements).
- A **junction** is a program point where the control flow can merge.
 - (e.g., end if, end loop, goto label)
- A **process block** is a sequence of program statements uninterrupted by either decisions or junctions. (i.e., straight-line code).
 - A process has one entry and one exit.
 - A program does not jump into or out of a process.

Path Selection Criteria

- There are many paths between the entry and exit points of a typical routine.
 - Even a small routine can have a large number of paths.
 - Examples
 - Exercise every path from entry to exit.
 - Exercise every statement at least once.
 - Exercise every branch (in each direction) at least once.
 - Clearly, 1 implies 2 and 3
 - However, 1 is impractical for most routines.
 - Also, 2 is not equal to 3 in languages with *goto* statements.
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Effectiveness of Control-flow Testing

- Studies show that control-flow testing catches 50% of all bugs caught during unit testing.
 - About 33% of all bugs.
 - Control-flow testing is more effective for unstructured code than for code that follows structured programming.
 - Experienced programmers can bypass drawing flowgraphs by doing path selection on the source.
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Limitations of Control-flow Testing

- Control-flow testing as a sole testing technique is limited:
 - Interface mismatches and mistakes are not caught.
 - Not all initialization mistakes are caught by control-flow testing.
 - Specification mistakes are not caught.
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Path Predicates

- Every path corresponds to a succession of **true** or **false** values for the predicates traversed on that path.
 - A **Path Predicate Expression** is a Boolean expression that characterizes the set of input values that will cause a path to be traversed.
 - **Multiway branches** (*e.g.*, case/switch statements) are treated as equivalent if then else statements.
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Path Predicate Expressions

- Any set of input values that satisfies ALL of the conditions of the path predicate expression will force the routine through that path.
 - If there is no such set of inputs, the path is not achievable.
 - Process of creating path expression:
 - Write down the predicates for the decisions you meet along a path.
 - The result is a set of path predicate expressions.
 - All of these expressions must be satisfied to achieve a selected path.
-

Process (In)dependent and correlated Predicates

- Process independent predicates
 - A predicate whose truth value cannot/can change as a result of the processing is said to be **Process Independent/Dependent**, respectively.
 - If all the variables on which a predicate is based are process independent, the predicate must be process independent.
 - Correlated predicates
 - A pair of predicates whose outcomes depend on one or more variables in common are said to be **Correlated Predicates**.
 - Every path through a routine is achievable only if all predicates in that routine are uncorrelated.
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Path Sensitization

- The act of finding a set of solutions to the path predicate expression is called **path sensitization**.
 - This yields set of values when given as input allow us to traverse that path
 - We manually compute expected outputs
 - Set of inputs together with expected outputs, they form test cases
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Test Outcomes

- The **outcome** of test is what we expect to happen as a result of the test.
- Test outcomes include anything we can observe in the computer's memory that should have (not) changed as a result of the test.
- Since we are not “kiddie testing” we must predict the outcome of the test as part of the test design process.

Testing Process

- run the test
 - observe the actual outcome
 - compare the actual outcome to the expected outcome.
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Summary

- Control flow graphs
 - Path selection criteria
 - Input vector
 - Predicates
 - Path sensitization
 - Test outcomes and process
-