

Advanced Unix Programming
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Assignment-9

Q1. Catch the SIGTERM signal, ignore SIGINT and accept the default action for SIGSEGV. Later let the program be suspended until it is interrupted by a signal. Implement using signal and sigaction.

CODE:

```
#include<stdio.h>
#include<signal.h>
#include<signal.h>
#include<stdlib.h>
#include<string.h>
static void sig_usr(int signo){
    if(signo == SIGTERM)
        printf("SIGTERM signal caught\n");
}
void quitproc(){
    printf("ctrl-\\ pressed to quit\n");
    exit(0); /* normal exit status */
}

int main(){
    if(signal(SIGINT,SIG_IGN) == SIG_ERR)
        printf("can't Ignore SIGINT");
    if(signal(SIGTERM,sig_usr) == SIG_ERR)
        printf("can't catch SIGTERM");
    if(signal(SIGSEGV,SIG_DFL) == SIG_ERR)
        printf("can't catch SIGSEGV");
    if(signal(SIGQUIT,quitproc) == SIG_ERR)
        printf("can't catch SIGQUIT");
    for(;;)
        pause();
}
```

Output:

```

nik@nik-Lenovo-G50-70: ~/aup/AUP/Lab9
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ ./a.out &
[1] 4832
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ ps
  PID TTY          TIME CMD
 3945 pts/11    00:00:00 bash
 4832 pts/11    00:00:00 a.out
 4834 pts/11    00:00:00 ps
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ kill -l
 1) SIGHUP       2) SIGINT      3) SIGQUIT     4) SIGILL       5) SIGTRAP
 6) SIGABRT      7) SIGBUS     8) SIGFPE     9) SIGKILL      10) SIGUSR1
11) SIGSEGV     12) SIGUSR2   13) SIGPIPE   14) SIGALRM     15) SIGTERM
16) SIGSTKFLT   17) SIGCHLD   18) SIGCONT    19) SIGSTOP     20) SIGTSTP;
21) SIGTTIN     22) SIGTTOU   23) SIGURG    24) SIGXCPU     25) SIGXFSZ
26) SIGVTALRM   27) SIGPROF   28) SIGWINCH   29) SIGIO        30) SIGPWR
31) SIGSYS      34) SIGRTMIN  35) SIGRTMIN+1 36) SIGRTMIN+2 37) SIGRTMIN+3
38) SIGRTMIN+4 39) SIGRTMIN+5 40) SIGRTMIN+6 41) SIGRTMIN+7 42) SIGRTMIN+8
43) SIGRTMIN+9 44) SIGRTMIN+10 45) SIGRTMIN+11 46) SIGRTMIN+12 47) SIGRTMIN+13
48) SIGRTMIN+14 49) SIGRTMIN+15 50) SIGRTMAX-14 51) SIGRTMAX-13 52) SIGRTMAX-12
53) SIGRTMAX-11 54) SIGRTMAX-10 55) SIGRTMAX-9  56) SIGRTMAX-8  57) SIGRTMAX-7
58) SIGRTMAX-6  59) SIGRTMAX-5 60) SIGRTMAX-4 61) SIGRTMAX-3  62) SIGRTMAX-2
63) SIGRTMAX-1  64) SIGRTMAX
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ #sending sigint to ignore SIGINT");
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ kill -2 4832
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ ps
  PID TTY          TIME CMD
 3945 pts/11    00:00:00 bash
 4832 pts/11    00:00:00 a.out
 4838 pts/11    00:00:00 ps
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ kill -15 4832,SIG_DFL) == SIG_ERR)
SIGTERM signal caught
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ kill -11 4832
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ ps
  PID TTY          TIME CMD
 3945 pts/11    00:00:00 bash
 4868 pts/11    00:00:00 ps
[1]+  Segmentation fault: (core dumped) ./a.out
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ ps
  PID TTY          TIME CMD
 3945 pts/11    00:00:00 bash
 4897 pts/11    00:00:00 ps
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ ./a.out &
[1] 4898
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$

```

```

nik@nik-Lenovo-G50-70: ~/aup/AUP/Lab9
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ ps
  PID TTY          TIME CMD
 3945 pts/11    00:00:00 bash
 4898 pts/11    00:00:00 a.out
 4919 pts/11    00:00:00 ps
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ fg %1
./a.out
^\\ctrl-\\ pressed to quit
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$

```

Q2. Create a child process. Let the parent sleeps of 5 seconds and exits. Can the child send SIGINT to its parent if exists and kill it? Verify with a sample program.

CODE:

```

#include<stdio.h>
#include<signal.h>
#include<unistd.h>
#include<stdlib.h>
void sig_usr(int signo){
    if(signo == SIGINT)
        printf("\nSignal caught!");
    return;
}
int main(void){
    pid_t pid, ppid;
    if((pid = fork()) == 0){
        ppid = getpid();
        printf("ppid = %d\n", ppid);
        printf("Press ^c to kill parent..\n");
        kill(ppid, SIGINT);
        printf("After killing parent...\n");
    }
    else{
        printf("ppid-> %d pid-> %d ", ppid, pid);
        if(signal(SIGINT, sig_usr) == SIG_ERR)
            printf("Signal processed ");
        int time = sleep(5);
        printf("\nParent exiting with %d seconds left\n", time);
    }
    return 0;
}

```

OUTPUT:



```

nik@nik-Lenovo-G50-70: ~/aup/AUP/Lab9
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ cc a9q2.c
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ ./a.out
ppid-> 0, pid-> 5078
Parent ID = 5078
Press ^c to kill parent..
Parent exiting with 0 seconds left
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$ ./a.out
ppid-> 0, pid-> 5080
Parent ID = 5080
Press ^c to kill parent..
^C
Signal caught!
Parent exiting with 3 seconds left
nik@nik-Lenovo-G50-70:~/aup/AUP/Lab9$

```

Q3. Implement sleep using signal function which takes care of the following:

- a. If the caller has already an alarm set, that alarm is not erased by the call to alarm inside sleep implementation.**
- b. If sleep modifies the current disposition of SIGALRM, restore it**
- c. Avoid race condition between first call to alarm and pause inside sleep implementation using setjmp.**

CODE:

```
#include<setjmp.h>
#include<stdio.h>
#include<stdlib.h>
#include<unistd.h>
#include<signal.h>

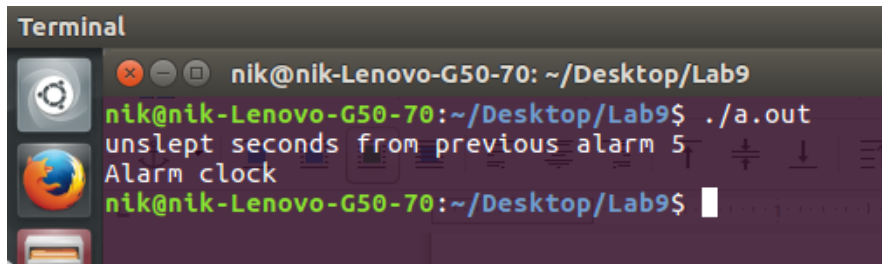
static jmp_buf jb;

int sig_alm(int signo){
    longjmp(jb, 1);
}

unsigned int sleep2(unsigned int secs){
    int time_left;
    time_left = alarm(0);          /* unslept seconds left from previous alarm */
    printf("unslept seconds from previous alarm %d\n", time_left);
    if(setjmp(jb) == 0){
        alarm(secs - time_left);    /* adding that time for user set value */
        pause();
    }
}

int main(){
    alarm(5);
    sleep2(7);
}
```

OUTPUT:



```
Terminal
nik@nik-Lenovo-G50-70: ~/Desktop/Lab9
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$ ./a.out
unslept seconds from previous alarm 5
Alarm clock
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$
```

Q4. “Child inherit parent’s signal mask when it is created, but pending signals for the parent process are not passed on”. Write appropriate program and test with suitable inputs to verify this.

CODE:

```
#include <stdio.h>
#include <stdlib.h>
#include <signal.h>
void err_sys(const char* x){
    perror(x);
    exit(1);
}
static void sig_quit(int signo){
    printf("caught SIGQUIT\n");
    if (signal(SIGQUIT, SIG_DFL) == SIG_ERR)
        err_sys("can't reset SIGQUIT");
}
void check_sigset(sigset_t sigset){
    int i;
    for(i = 0; i < 31; i++){
        if(sigismember(&sigset, i)){
            printf("SIGNAL %d present\n", i);
        }
    }
}
int main(void){
    sigset_t newmask, oldmask, pendmask, sigset;
    pid_t pid;

    if (signal(SIGQUIT, sig_quit) == SIG_ERR)
        err_sys("can't catch SIGQUIT");
    sigemptyset(&newmask);
    sigaddset(&newmask, SIGQUIT); // adding SIGQUIT to newmask

    if (sigprocmask(SIG_BLOCK, &newmask, &oldmask) < 0) // added SIGQUIT to BLOCK
        err_sys("SIG_BLOCK error");

    printf("Send SIGQUIT signals\n");
```

```

sleep(5);
/* SIGQUIT here will remain pending */
if((pid = fork()) == -1){
    err_sys("Fork Error");
}
if(pid){
    printf("IN PARENT:\n");
    if (sigprocmask(0, NULL, &sigset) < 0) {
        err_sys("Error getting signal mask");
    }
    else {
        check_sigset(sigset);
    }

    if (sigpending(&pendmask) < 0)
        err_sys("signal pending error");

    if (sigismember(&pendmask, SIGQUIT))
        printf("IN PARENT: SIGQUIT pending\n");

    wait();
}
else {
    sigset_t childsigset;
    printf("IN CHILD:\n");
    if (sigprocmask(0, NULL, &childsigset) < 0) {
        err_sys("Error getting signal mask");
    }
    else {
        check_sigset(childsigset);
    }

    if (sigpending(&pendmask) < 0){
        err_sys("sigpending error");
    }

    if (sigismember(&pendmask, SIGQUIT)){
        printf("IN CHILD: SIGQUIT pending\n");
    }
    else {
        printf("IN CHILD: SIGQUIT not pending in CHILD\n");
    }
}
}
}

```

OUTPUT:

```
Terminal
nik@nik-Lenovo-G50-70: ~/Desktop/Lab9
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$ ./a.out &
[1] 4124
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$ Send SIGQUIT signals
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$ kill -3 4124
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$ IN PARENT:
SIGNAL 0 present
SIGNAL 3 present
IN CHILD:
IN PARENT: SIGQUIT pending
SIGNAL 0 present
SIGNAL 3 present
IN CHILD: SIGQUIT not pending in CHILD
[1]+  Done                  ./a.out
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$
```

```
Terminal
nik@nik-Lenovo-G50-70: ~/Desktop/Lab9
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$ ./a.out &
[1] 4171
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$ Send SIGQUIT signals
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$ IN PARENT:
SIGNAL 0 present
IN CHILD:
SIGNAL 3 present
SIGNAL 0 present
SIGNAL 3 present
IN CHILD: SIGQUIT not pending in CHILD
[1]+  Done                  ./a.out
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$
```

```
Terminal
nik@nik-Lenovo-G50-70: ~/Desktop/Lab9
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$ ./a.out
Send SIGQUIT signals
^\\IN PARENT:
SIGNAL 0 present
SIGNAL 3 present
IN CHILD:
IN PARENT: SIGQUIT pending
SIGNAL 0 present
SIGNAL 3 present
IN CHILD: SIGQUIT not pending in CHILD
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$ ./a.out
Send SIGQUIT signals
IN PARENT:
SIGNAL 0 present
SIGNAL 3 present
IN CHILD:
SIGNAL 0 present
SIGNAL 3 present
IN CHILD: SIGQUIT not pending in CHILD
nik@nik-Lenovo-G50-70:~/Desktop/Lab9$
```