

DISTRIBUTED COMPUTING IN SENSOR NETWORKS

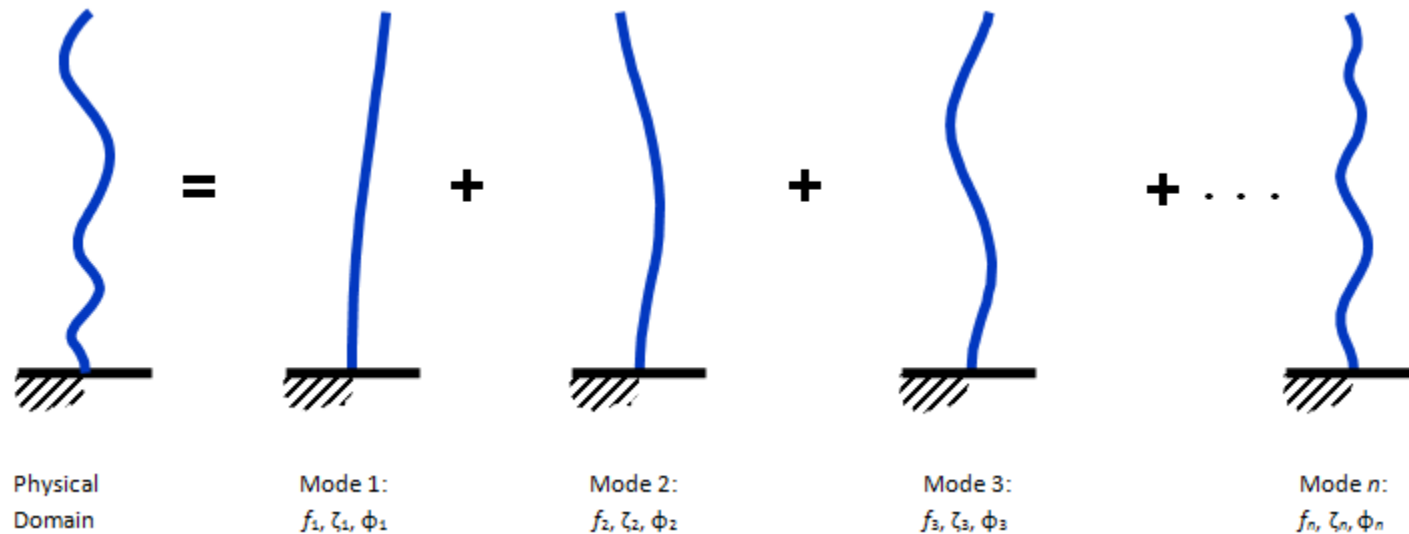
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BACKGROUND



- Mode shapes describe the dynamic response of mechanical systems to their environment
- Material properties (mass, stiffness, damping), can be inferred from these responses
- Changes in modal responses may indicate defects

COMPUTATION

Given time series $x(t)$ from n sensor locations:

Compute $X_n(\omega)$ for each of the n locations

For a specific ω_i form $G_{n \times n}(\omega_i)$ where:

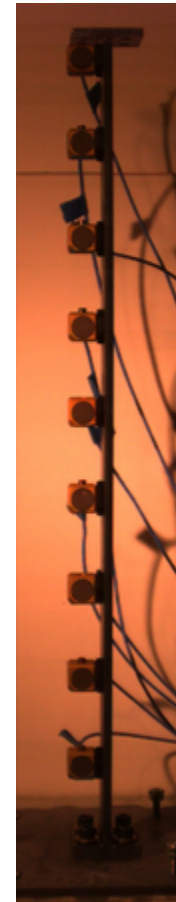
$$G_{jk}(\omega_i) = X_j(\omega_i) \times X_k(\omega_i)^*$$

Then decompose $G_{n \times n} = U_{n \times n} \Sigma_{n \times n} V_{n \times n}^*$

The first singular vector (column) of U is the mode shape estimate

MOTIVATION: TECHNOLOGY CAN OVERWHELM TRADITIONAL ALGORITHMS

Example 1: high-res cameras can produce huge data sets
(e.g one time series per pixel)



MOTIVATION: TECHNOLOGY CAN OVERWHELM TRADITIONAL ALGORITHMS

Example 2: Networks of wirelessly connected sensor devices

- Devices have built in accelerometers and microcontrollers
- Very low cost enables large scale, dense deployment
- Communication out of the network drains battery, and we are forced to perform computation on slow (100MHz), memory constrained (128kB RAM) devices

APPROACH & SECRET WEAPON

- Recall that we use only the first singular vector as an estimate of the mode shape
- Because our matrix is normal, we can use a power method to estimate the largest eigenvector (PageRank!)

Algorithm:

$$i = 0; \text{ init } v_0$$

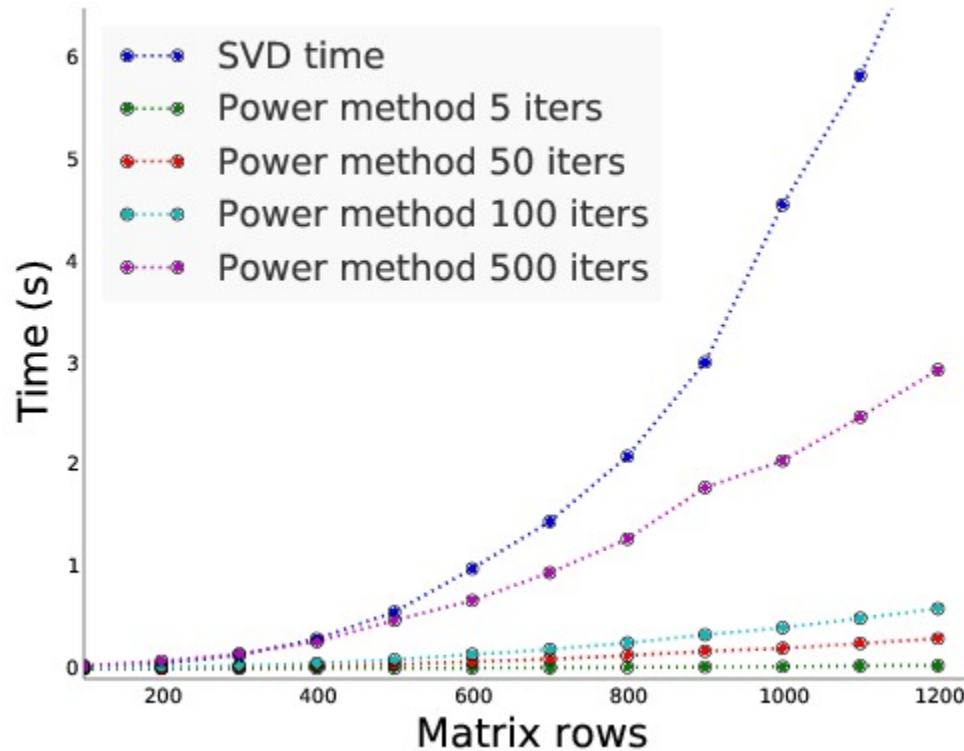
while ($i < N$) :

$$v_{i+1} = Gv_i$$

$$v_{i+1} = \frac{v_{i+1}}{\|v_{i+1}\|}$$

$$i = i + 1$$

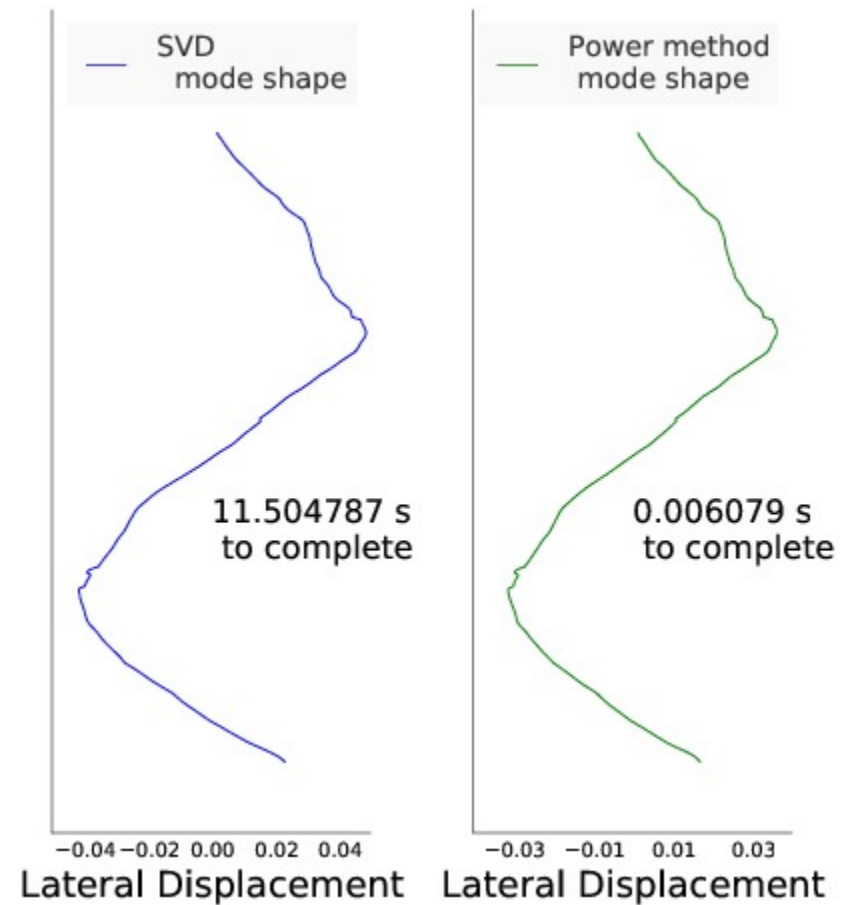
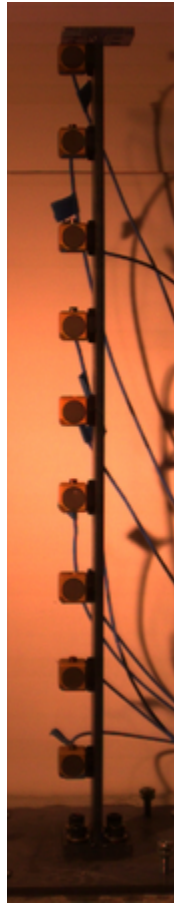
APPROACH & SECRET WEAPON



Rate of convergence: $\frac{\lambda_1}{\lambda_2}$

λ_1 is the largest eigenvalue, λ_2 the next largest

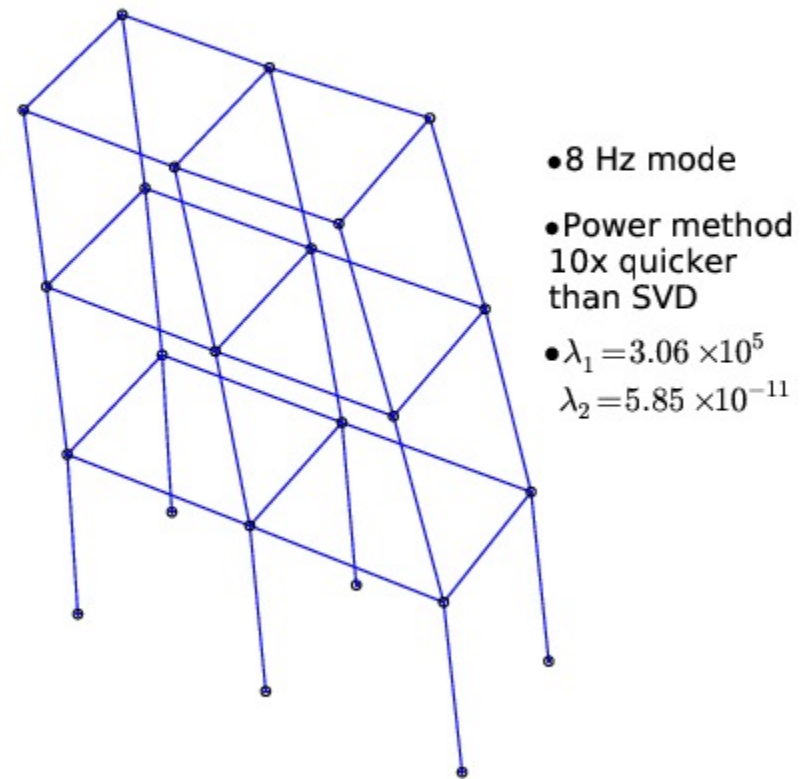
RESULTS: SERIAL COMPARISON



1217 individual time series of
length 1000

$$\lambda_1 = 3.9 \times 10^5;$$
$$\lambda_2 = 1.2 \times 10^{-9}$$

RESULTS: SERIAL COMPARISON



54 individual time series of
length 180000

RESULTS: PARALLELISATION IN MPI

EVALUATION

MAIN LESSON