

## Gaussian Process & Brownian Motion

GP = Stochastic Process

Finite dim dist (SP) = Gaussian random vector

Standard Brownian motion

(i)  $B_0 = 0$  /  $B(t)$  or  $B_t$

(ii)  $B_t - B_s \perp B_r$   $r \leq s$   
Indp. increment  $t \geq s$

(iii) Gaussian increment

$$B_t - B_s \sim N(0, t-s)$$

Brownian motion with drift (i) & (ii)

(iii)  $B_t - B_s \sim N(\mu(t-s), \sigma^2(t-s))$   
Drift parameter:  $\mu$ .

Variance parameter:  $\sigma$

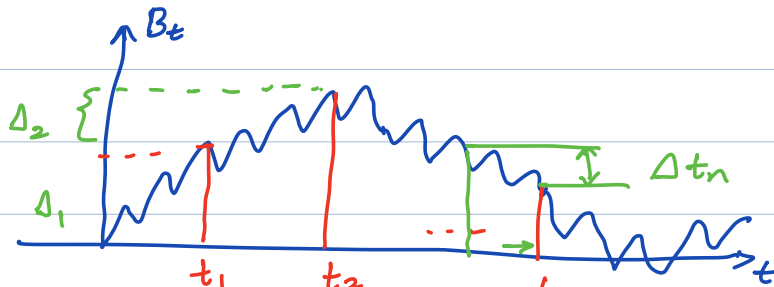
$B_t$  : standard Brownian motion  
( $\mu = 0, \sigma^2 = 1$ )

$W_t$  : Brownian motion with drift  
( $\mu, \sigma$ )

$$W_t = \mu t + \sigma \cdot B_t \quad [\text{Proof as exercise}]$$

## Properties (Standard Brownian Motion)

1. Brownian Motion is a Gaussian Process



$$B = (B(t_1), B(t_2), \dots, B(t_n))$$

↑ Gaussian random vector

Proof

$$\Delta_i = B(t_i) - B(t_{i-1})$$

↑ Diff?

Gaussian distributed  $\sim(0, t_i - t_{i-1})$

$$B(t_1) = \Delta_1$$

$$B(t_2) = \underbrace{B(t_2) - B(t_1)}_{\Delta_2} + \underbrace{B(t_1)}_{\Delta_1}$$

$$= \Delta_2 + \Delta_1$$

$$B(t_3) = \underbrace{B(t_3) - B(t_2)}_{\Delta_3} + \underbrace{B(t_2)}_{\Delta_2 + \Delta_1}$$

$$= \Delta_3 + \Delta_2 + \Delta_1$$

$$\vdots$$

$$B(t_n) = \Delta_n + \Delta_{n-1} + \dots + \Delta_1$$

$$B = \begin{pmatrix} B(t_1) \\ B(t_2) \\ \vdots \\ B(t_n) \end{pmatrix} = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix} \begin{bmatrix} \Delta_1 \\ \vdots \\ \Delta_n \end{bmatrix}$$

↑ Gaussian random vector

Gaussian random vector

$B_t$  is a Gaussian process

Theorem : A stochastic process  $B_t$  is a std. Brownian motion iff

- (i)  $B_t$  is a Gaussian process
- (ii)  $\mathbb{E}[B_t] = 0$
- (iii)  $\text{Cov}(B_t, B_s) = \min(s, t)$
- (iv)  $B$  has continuous sample paths

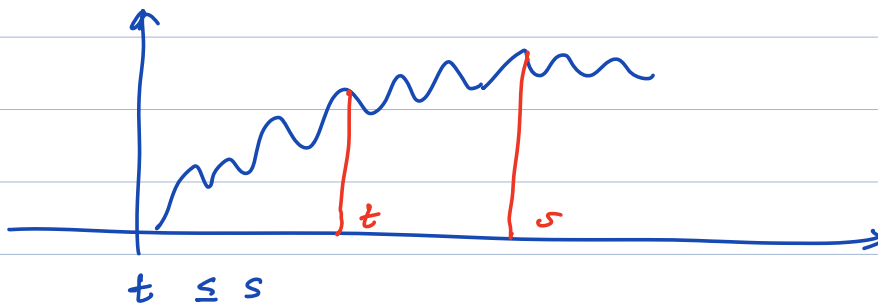
(ii)  $\mathbb{E}[B_t] = 0$

~~$B_t \sim N(0, 1)$  ?~~

$$B_t = B_t - \underbrace{B_0}_0 \sim N(0, t)$$

$$\mathbb{E}[B_t] = 0$$

(iii)  $\text{Cov}(B_t, B_s) = \min(s, t)$



$$\begin{aligned} \text{Cov}(B_t, B_s) &= \mathbb{E}[B_t B_s] - m_s m_t \uparrow 0 \\ &= \mathbb{E}[B_t B_s] \end{aligned}$$

$$B_s = \underbrace{B_s - B_t}_{\sim N(0, s-t)} + \underbrace{B_t - B_0}_{\substack{\text{independent} \\ \sim N(0, t)}}$$

$$\mathbb{E}[B_t B_s] = \mathbb{E}[B_t [B_s - B_t + B_t]]$$

$$= \mathbb{E}[B_t [B_s - B_t]] + \mathbb{E}[B_t^2]$$

$$= \mathbb{E}[B_t] \mathbb{E}[B_s - B_t] + \mathbb{E}[B_t^2]$$

Independent

$\overset{0}{\nearrow}$   $\overset{0}{\nearrow}$

$t$

$$= t$$

$$\text{Cov}(B_t, B_s) = t \quad t \leq s$$

$$\text{Cov}(B_t, B_s) = s \quad t \geq s \text{ [Exercise!]}$$

$$\text{Cov}(B_t, B_s) = \min(s, t)$$

2. Sample paths of Brownian motion are continuous but nowhere differentiable.

(Intuition)

$$\frac{d}{dt} B_t = \lim_{h \rightarrow 0} \frac{(B_{t+h} - B_t)}{h}$$

$$\downarrow \mathcal{N}(0, h)$$

$$\left( \frac{1}{h} \mathcal{N}(0, h) \right)$$

$$\sim \mathcal{N}\left(0, \frac{1}{h}\right)$$

$$= dt \mathcal{N}(0, 1)$$

$h \rightarrow 0$

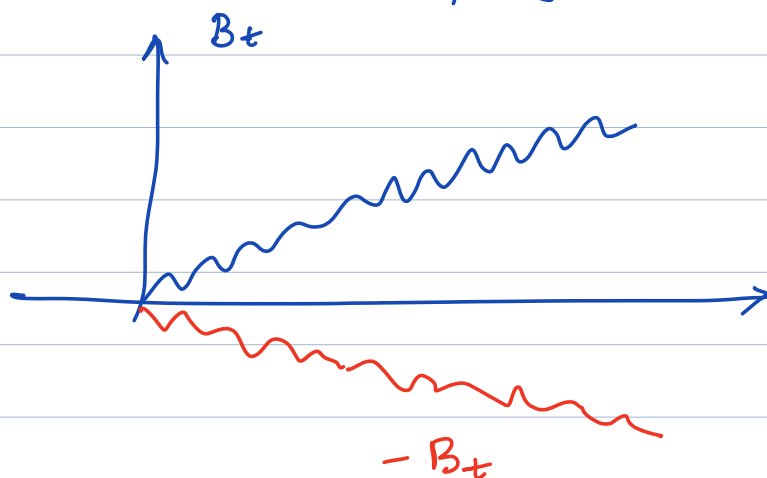
$\frac{B(t+h) - B(t)}{h}$

↓  
infinite variances  
as  $h \rightarrow 0$

$\Rightarrow$  Not differentiable.

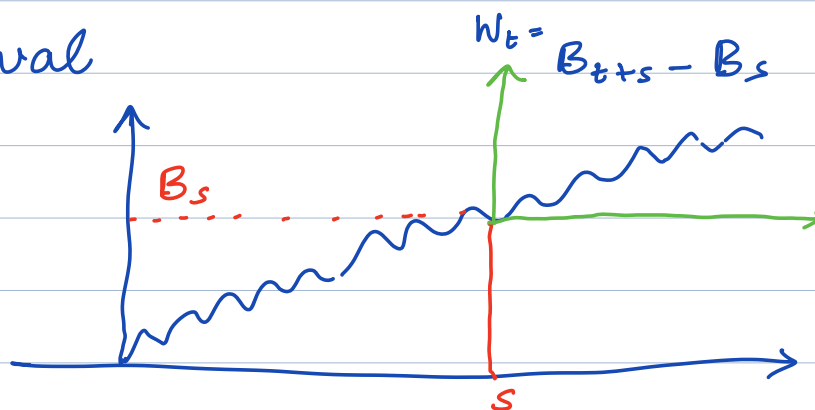
$$B(t+h) - B(t) \sim \mathcal{N}(0, h)$$

### 3. Reflection Property



$B_t$  is a std Brownian motion so is  $\{-B_t\}$   
[Proof as exercise]

### 4. Renewal

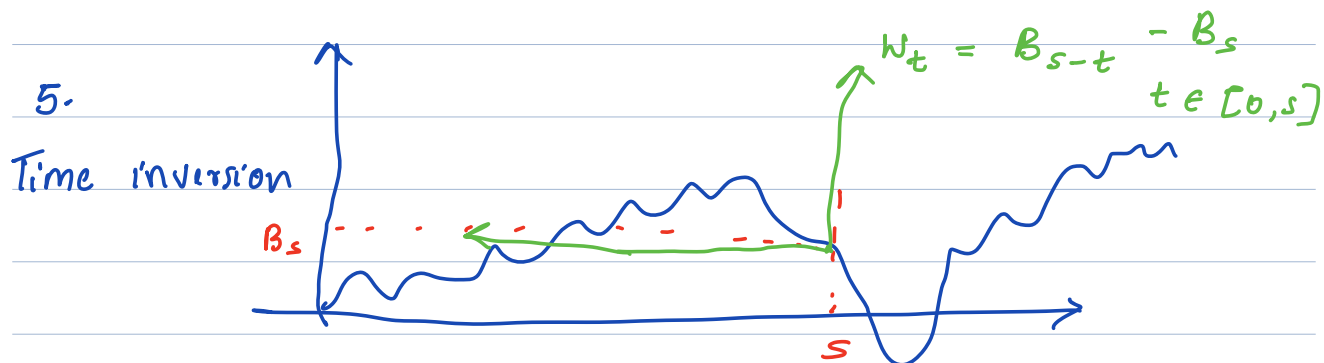


$\nexists$   $B_t$  is a std Brownian motion

D

So is  $W_t$

[Proof - Exercise!]



If  $B_t$  is a std Brownian motion so is

$$W_t = B_{s-t} - B_s ; t \in [0, s]$$

[Proof : Exercise!]

6. Brownian motion is the limit of a simple symmetric random walk.