

Matlab Image Processing Results

Multiplying 2 matrices

```
>> A = [1 2 3 4 5;2 3 4 5 2;1 2 4 5 3;1 2 3 4 2;1 3 4 5 2]
```

A =

```
1  2  3  4  5
```

```
2  3  4  5  2
```

```
1  2  4  5  3
```

```
1  2  3  4  2
```

```
1  3  4  5  2
```

```
>> B = [0 0 0 0 1;0 0 0 1 0;0 0 1 0 0;0 1 0 0 0;1 0 0 0 0]
```

B =

```
0  0  0  0  1
```

```
0  0  0  1  0
```

```
0  0  1  0  0
```

```
0  1  0  0  0
```

```
1  0  0  0  0
```

```
>> C = A*B
```

C =

```
5  4  3  2  1
```

```
2  5  4  3  2
```

```
3  5  4  2  1
```

```
2  4  3  2  1
```

```
2  5  4  3  1
```

Multiplying two matrices element wise

```
>> D = A.*B
```

D =

```
0 0 0 0 5
0 0 0 5 0
0 0 4 0 0
0 2 0 0 0
1 0 0 0 0
```

Loading an image and displaying it

```
>> Image = imread('image.jpg');
```

```
>> imshow(Image);
```



Using size function to get the dimensions

```
>> size(Image)
```

```
ans =
```

```
527 518 3
```

Displaying RGB layers separately

```
>> R = Image(:,:,1);
```

```
>> G = Image(:,:,2);
```

```
>> B = Image(:,:,3);
```

```
>> imread(R);
```



```
>> imshow(G);
```



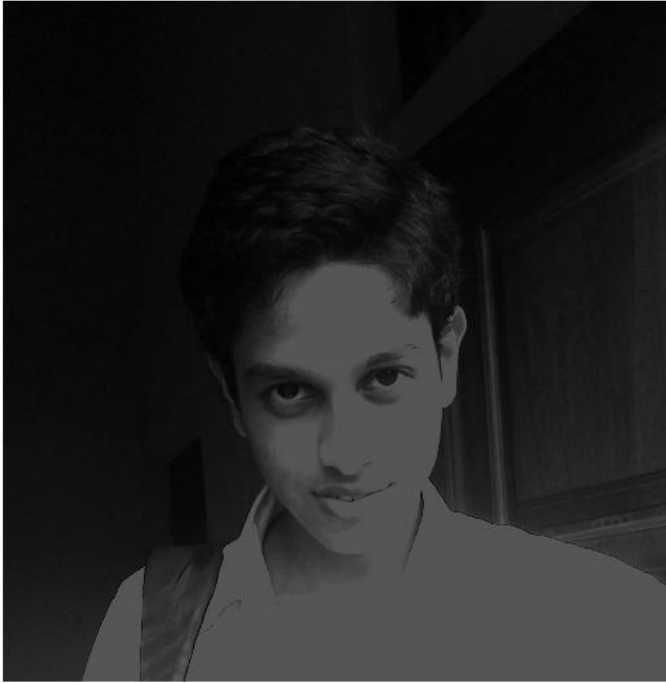
```
>> imshow(B);
```



Converting the colored image to gray scale

```
>> GrayScale = (R + G + B) / 3;
```

```
>> imshow(GrayScale);
```



```
>> GrayScale2 = rgb2gray(Image);
```

```
>> imshow(GrayScale2);
```



Image convolution using my own function

>>edit convert

```
function [Output] = convert(Image,Kernel)
```

```
Output = zeros(size(Image,1),size(Image,2));
```

```
Rows = int32(size(Image,1));
```

```
Cols = int32(size(Image,2));
```

```
K_Size = int32(size(Kernel,1));
```

```
for i=(K_Size/2):(Rows -(K_Size/2) + 1),
```

```
    for j=(K_Size/2):(Cols -(K_Size/2) + 1),
```

```
        Tot=0;
```

```
        a = i+1-(K_Size/2);
```

```
        b = i-1+(K_Size/2);
```

```
        c = j+1-(K_Size/2);
```

```
        d = j-1+(K_Size/2);
```

```
        Reduced_Matrix = Image(a:b,c:d);
```

```
        Reduced_Matrix = Reduced_Matrix.*Kernel;
```

```
        Tot = sum(Reduced_Matrix(:));
```

```
        Output(i,j) = Tot;
```

```
    end
```

```
end
```

```
>> Image = im2double(Image);
```

```
>> R = Image(:, :, 1);
```

```
>> G = Image(:, :, 2);
```

```
>> B = Image(:, :, 3);
```

```
>> Kernel = [1 1 1;1 1 1;1 1 1]
```

Kernel =

```
1  1  1
1  1  1
1  1  1
```

```
>> Converted_R = convert(R,Kernel);  
>> imshow(Converted_R);
```



```
>> Converted_G = convert(G,Kernel);  
>> imshow(Converted_G);
```



```
>> Converted_B = convert(B,Kernel);
```

```
>> imshow(Converted_B);
```



```
>> Converted_Image = cat(3,Converted_R,Converted_G,Converted_B);
```

```
>> imshow(Converted_Image);
```



Using 'conv2' function

```
>> Converted_R2 = conv2(R,Kernel);
```

```
>> Converted_G2 = conv2(G,Kernel);
```

```
>> Converted_B2 = conv2(B,Kernel);
```

```
>> Converted_Image2 = cat(3,Converted_R2,Converted_G2,Converted_B2);
```

```
>> imshow(Converted_Image2);
```



Image Convolutions

1. Image blurring

a. Simple Box Blur

```
>> Kernel = [1/9 1/9 1/9;1/9 1/9 1/9;1/9 1/9 1/9]
```

Kernel =

```
0.1111  0.1111  0.1111
```

```
0.1111  0.1111  0.1111
```

```
0.1111  0.1111  0.1111
```

```
>> Converted_R = convert(R,Kernel);
```

```
>> Converted_G = convert(G,Kernel);
```

```
>> Converted_B = convert(B,Kernel);
```

```
>> Converted_Image = cat(3,Converted_R,Converted_G,Converted_B);
```

```
>> imshow(Converted_Image);
```



b. Gaussian Blur

Kernel =

0	0	0	5	0	0	0
0	5	18	32	18	5	0
0	18	64	100	64	18	0
5	32	100	100	100	32	5
0	18	64	100	64	18	0
0	5	18	32	18	5	0
0	0	0	5	0	0	0

```
>> tot = sum(Kernel (:))
```

tot =

1068

```
>> Kernel = Kernel / tot
```

Kernel =

0	0	0	0.0047	0	0	0
0	0.0047	0.0169	0.0300	0.0169	0.0047	0
0	0.0169	0.0599	0.0936	0.0599	0.0169	0
0.0047	0.0300	0.0936	0.0936	0.0936	0.0300	0.0047
0	0.0169	0.0599	0.0936	0.0599	0.0169	0
0	0.0047	0.0169	0.0300	0.0169	0.0047	0
0	0	0	0.0047	0	0	0

Implementation using my function



Using conv2 function



2. Edge detection

Kernel =

-1 -1 -1

-1 8 -1

-1 -1 -1



Edge detection with Sobel Edge Operator

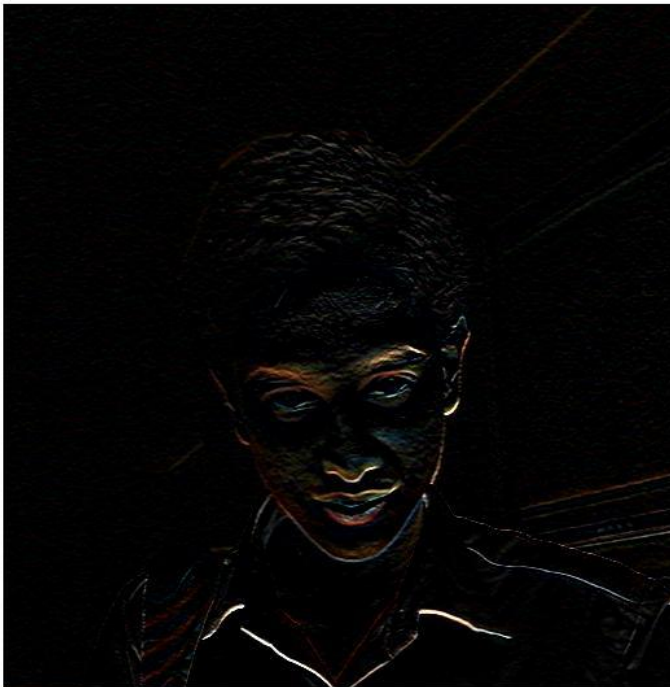
a. Horizontal

Kernel =

-1 -2 -1

0 0 0

1 2 1



b. Vertical

Kernel =

-1 0 1

-2 0 2

-1 0 1



c. With both convolutions applied



3. Sharpening

Kernel =

0 -1 0

-1 5 -1

0 -1 0



Other Convolutions

1. Line detection

a. Horizontal Lines

Kernel =

-1 -1 -1

2 2 2

-1 -1 -1



b. Vertical lines

Kernel =

-1 2 -1

-1 2 -1

-1 2 -1



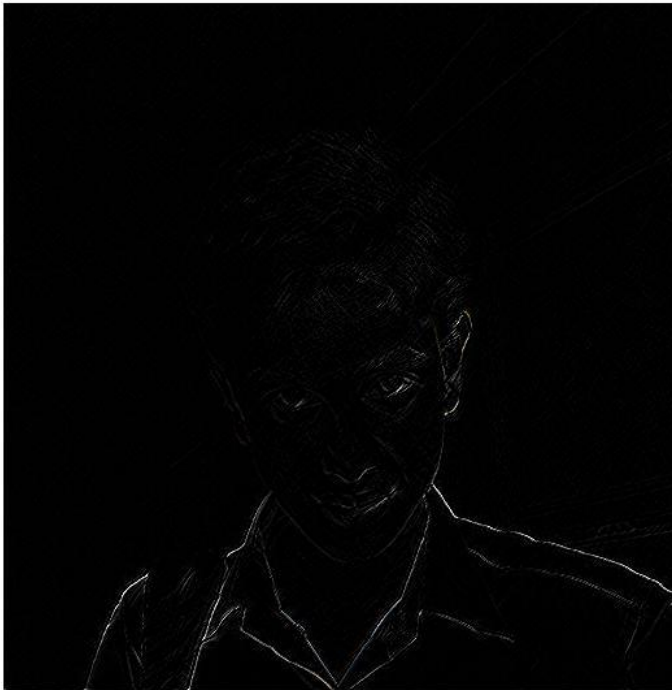
c. 45° lines

Kernel =

-1 -1 2

-1 2 -1

2 -1 -1



d. 135° lines

Kernel =

2 -1 -1

-1 2 -1

-1 -1 2

