### COL 106: Data-structures

### **Course coordinators:**

Parag Singla (parags@cse.iitd.ac.in)
Amit Kumar (amitk@cse.iitd.ac.in)

### Data-structures

### **Teaching assistants:**

Two TAs will be available during lab hours.

# Make use of TAs for resolving any problems regarding the course :

coding, understanding a particular concept, assignments, etc.

### **Evaluations components**

**Quiz: 15%** 

Minor Exam: 25%

Assignments: 25% (5-6 assignments)

Major exam: 35%

# Assignments

You will be expected to program in Python

One programming assignment every 2 weeks

NO late submission (strictly enforced, reasons like illness will not be accepted)

#### NO COPYING FROM ANY SOURCE

(if caught copying, expect an "F" grade)

### Course Information

Make sure you can access the course information from moodle.

Check course web-page for announcements.

Textbook: Data-structures and Algorithms, by Goodrich, Tamassia, Goldwasser.

### **Topics**

**Arrays** 

Lists

Abstract Data Types, object oriented concepts

Stacks, Queues

Trees: Binary trees, Balanced trees, B-trees

Strings: Tries, Matching algorithms

Sorting

Hashing

**Graphs** 

### Data Structures and Algorithms

- Algorithm: Outline, the essence of a computational procedure, step-by-step instructions
- □ Program: an implementation of an algorithm in some programming language
- Data structure: Organization of data needed to solve the problem

### Algorithmic problem

Specification of input

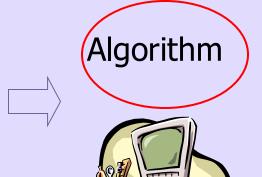


Specification of output as a function of input

- □ Infinite number of input *instances* satisfying the specification. For eg: A sorted, non-decreasing sequence of natural numbers of non-zero, finite length:
  - □ 1, 20, 908, 909, 100000, 100000000.
  - □3.

# Algorithmic Solution

Input instance, adhering to the specification





Output related to the input as required



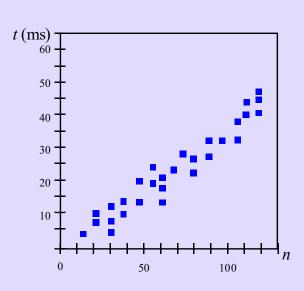
Infinitely many correct algorithms for the same algorithmic problem

### What is a Good Algorithm?

- □ Efficient:
  - □ Running time
  - □ Space used
- □ Efficiency as a function of input size:
  - □ The number of bits in an input number
  - Number of data elements (numbers, points)

# Measuring the Running Time

How should we measure the running time of an algorithm?



### Experimental Study

- □ Write a program that implements the algorithm
- Run the program with data sets of varying size and composition.
- Use a system call to get an accurate measure of the actual running time.

# Limitations of Experimental Studies

- □ It is necessary to implement and test the algorithm in order to determine its running time.
- Experiments can be done only on a limited set of inputs, and may not be indicative of the running time on other inputs not included in the experiment.
- □ In order to compare two algorithms, the same hardware and software environments should be used.

# Beyond Experimental Studies

We will develop a general methodology for analyzing running time of algorithms. This approach

- Uses a high-level description of the algorithm instead of testing one of its implementations.
- □ Takes into account all possible inputs.
- □ Allows one to evaluate the efficiency of any algorithm in a way that is independent of the hardware and software environment.

### Pseudo-Code

- A mixture of natural language and high-level programming concepts that describes the main ideas behind a generic implementation of a data structure or algorithm.
- □ Eg: **Algorithm** arrayMax(A, n):

Input: An array A storing n integers.

Output: The maximum element in A.

currentMax  $\leftarrow$  A[0]

for  $i \leftarrow 1$  to n-1 do

if currentMax < A[i] then currentMax ← A[i]</pre>

return currentMax

### Pseudo-Code

It is more structured than usual prose but less formal than a programming language

- □ Expressions:
  - use standard mathematical symbols to describe numeric and boolean expressions
  - □ use ← for assignment ("=" in Java)
  - □ use = for the equality relationship ("==" in Java)
- Method Declarations:
  - □ **Algorithm** name(param1, param2)

### Pseudo Code

- □ Programming Constructs:
  - decision structures: if ... then ... [else ... ]
  - while-loops: while ... do
  - □ repeat-loops: **repeat ... until ...**
  - □ for-loop: **for ... do**
  - □ array indexing: A[i], A[i,j]
- Methods:
  - □ calls: object method(args)
  - □ returns: return value

### **Analysis of Algorithms**

- Primitive Operation: Low-level operation independent of programming language.
   Can be identified in pseudo-code. For eg:
  - □ Data movement (assign)
  - □ Control (branch, subroutine call, return)
  - □ arithmetic an logical operations (e.g. addition, comparison)
- By inspecting the pseudo-code, we can count the number of primitive operations executed by an algorithm.

# **Example: Sorting**

#### **INPUT**

sequence of numbers

$$a_1, a_2, a_3, \dots, a_n$$
2 5 4 10 7



#### **OUTPUT**

a permutation of the sequence of numbers

$$b_1,b_2,b_3,\ldots,b_n$$

$$2 \quad 4 \quad 5 \quad 7 \quad 10$$

# Correctness (requirements for the output)

For any given input the algorithm halts with the output:

- $b_1 < b_2 < b_3 < \dots < b_n$
- b<sub>1</sub>, b<sub>2</sub>, b<sub>3</sub>, ...., b<sub>n</sub> is a permutation of a<sub>1</sub>, a<sub>2</sub>, a<sub>3</sub>,....,a<sub>n</sub>

#### **Running time**

Depends on

- number of elements (n)
- how (partially) sorted they are
- algorithm

### **Insertion Sort**



#### **Strategy**

- Start "empty handed"
- Insert a card in the right position of the already sorted hand
- Continue until all cards are inserted/sorted

INPUT: A[1..n] – an array of integers OUTPUT: a permutation of A such that  $A[0] \le A[1] \le ... \le A[n-1]$ 

```
for j←0 to n-1 do
    key ← A[j]
    Insert A[j] into the sorted sequence
    A[1..j-1]
    i←j-1
    while i>=0 and A[i]>key
        do A[i+1]←A[i]
        i--
    A[i+1]←key
```

### **Analysis of Insertion Sort**

```
times
                                           cost
                                             C_1
for j\leftarrow 1 to n-1 do
                                             C_2
                                                      n-1
 key←A[j]
                                                      n-1
 Insert A[j] into the sorted
 sequence A[1..j-1]
                                                      n-1
                                             C_3
 i←j-1
                                                     \sum_{j=2}^{n} t_{j}
                                             C_4
 while i \ge 0 and A[i] \ge key
                                             C_5 \qquad \sum_{j=2}^n (t_j - 1)
    do A[i+1] \leftarrow A[i]
                                             C_6 \qquad \sum_{j=2}^n (t_j - 1)
                                                      n-1
                                             C_7
 A[i+1] \leftarrow key
```

Total time = 
$$n(c_1+c_2+c_3+c_7) + \sum_{j=2}^{n} t_j (c_4+c_5+c_6)$$
  
-  $(c_2+c_3+c_5+c_6+c_7)$ 

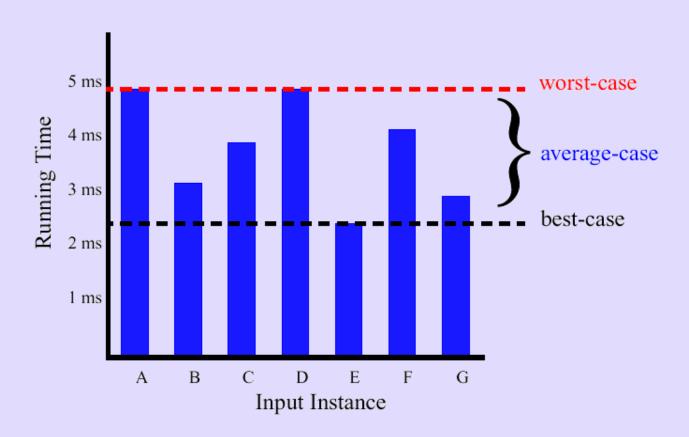
# Best/Worst/Average Case

Total time = 
$$n(c_1+c_2+c_3+c_7) + \sum_{j=1}^{n-1} t_j (c_4+c_5+c_6) - (c_2+c_3+c_5+c_6+c_7)$$

- Best case: elements already sorted; t<sub>j</sub>=1, running time = f(n), i.e., *linear* time.
- Worst case: elements are sorted in inverse order; t<sub>j</sub>=j, running time = f(n²), i.e., quadratic time
- □ **Average case**:  $t_j = j/2$ , running time =  $f(n^2)$ , i.e., *quadratic* time

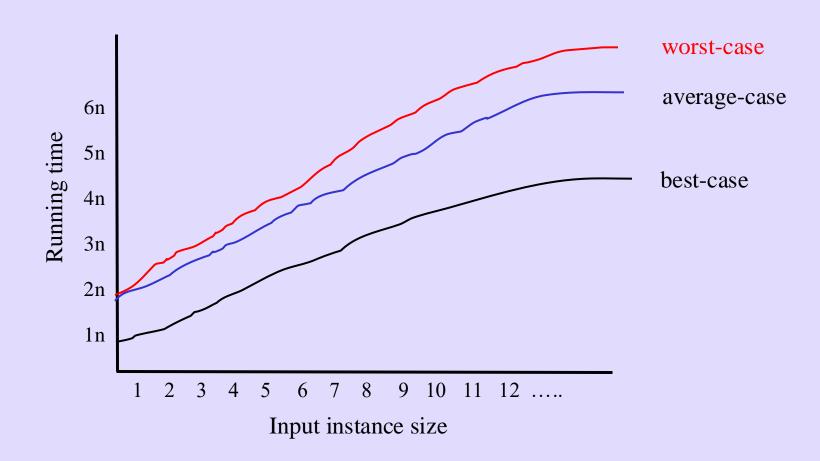
# Best/Worst/Average Case (2)

For a specific size of input n, investigate running times for different input instances:



# Best/Worst/Average Case (3)

### For inputs of all sizes:



# Best/Worst/Average Case (4)

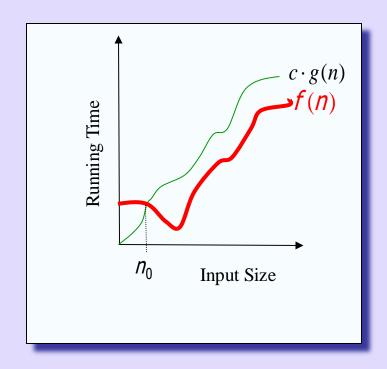
- Worst case is usually used: It is an upperbound and in certain application domains (e.g., air traffic control, surgery) knowing the worstcase time complexity is of crucial importance
- For some algorithms worst case occurs fairly often
- Average case is often as bad as the worst case
- □ Finding average case can be very difficult

### Asymptotic Analysis

- Goal: to simplify analysis of running time by getting rid of "details", which may be affected by specific implementation and hardware
  - □ like "rounding":  $1,000,001 \approx 1,000,000$
  - $\square 3n^2 \approx n^2$
- Capturing the essence: how the running time of an algorithm increases with the size of the input in the limit.
  - Asymptotically more efficient algorithms are best for all but small inputs

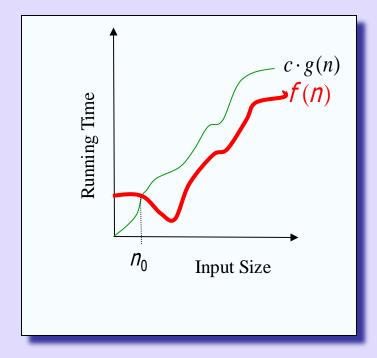
### **Asymptotic Notation**

- □ The "big-Oh" O-Notation
  - asymptotic upper bound
  - $\Box$  f(n) is O(g(n)), if:



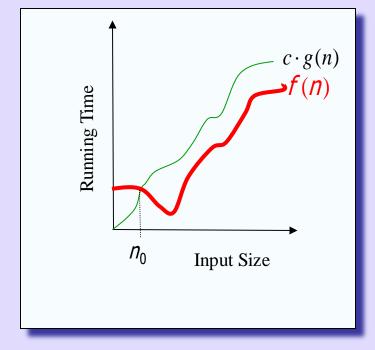
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  - $\square$ f(n) is O(g(n)), if there exists constants c and  $n_0$ , s.t. **f(n)** ≤ **c g(n)** for  $n_0$



### Asymptotic Notation

- □ The "big-Oh" O-Notation
  - □ asymptotic upper bound
  - $\Box$ f(n) is O(g(n)), if there exists constants c and  $n_0$ , s.t. **f(n)** ≤ **c g(n)** for  $n_0$
  - f(n) and g(n) are functions over nonnegative integers
- Used for worst-case analysis



# Asymptotic Notation (terminology)

Special classes of algorithms: □ Logarithmic: Linear: Quadratic: □ Polynomial: **Exponential:** "Relatives" of the Big-Oh  $\square \Omega$  (f(n)): Big Omega -asymptotic *lower* bound  $\square \Theta$  (f(n)): Big Theta -asymptotic *tight* bound

# Asymptotic Notation (terminology)

- Special classes of algorithms:
  - □ Logarithmic: O(log n)
  - ☐ Linear: O(n)
  - □ Quadratic: O(n²)
  - □ Polynomial:  $O(n^k)$ ,  $k \ge 1$
  - $\square$  Exponential: O(a<sup>n</sup>), a > 1

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- "Relatives" of the Big-Oh
  - $\square \Omega$  (f(n)): Big Omega -asymptotic *lower* bound
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# Example

For functions f(n) and g(n) there are positive constants c and  $n_0$  such that:  $f(n) \le c$  g(n) for  $n \ge n_0$ 

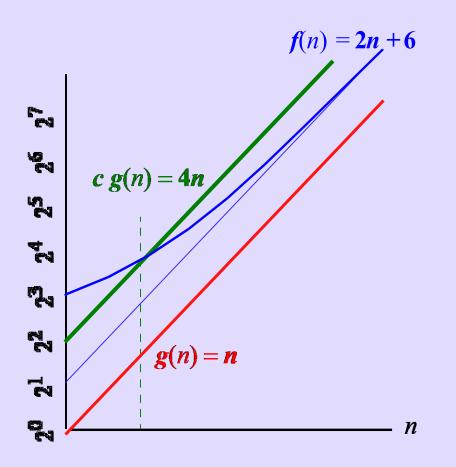
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# Example

For functions f(n) and g(n) there are positive constants c and  $n_0$  such that:  $f(n) \le c$  g(n) for  $n \ge n_0$ 

#### conclusion:

2n+6 is O(n).



### Another Example

```
On the other hand...
n^2 is not O(n) because there is
```

### **Another Example**

```
On the other hand...

n^2 is not O(n) because there is no c and n_0 such that:

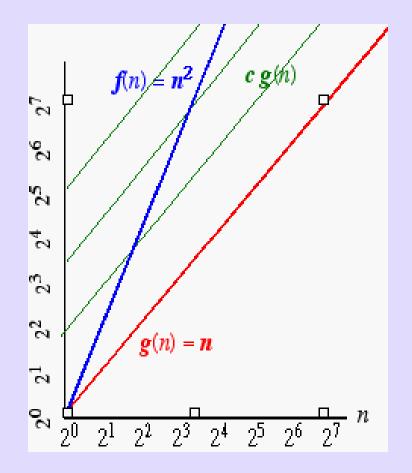
n^2 \le cn for n \ge n_0
```

### **Another Example**

On the other hand...  $n^2$  is not O(n) because there is no c and  $n_0$  such that:

$$n^2 \le cn$$
 for  $n \ge n_0$ 

The graph to the right illustrates that no matter how large a c is chosen there is an n big enough that  $n^2 > cn$ )



- Simple Rule: Drop lower order terms and constant factors.
  - □ 50 *n* log *n* is \_\_\_\_\_
  - □7*n* 3 is \_\_\_\_\_
  - $\square 8n^2 \log n + 5n^2 + n \text{ is } \_\_\_$

- Simple Rule: Drop lower order terms and constant factors.
  - $\square$  50  $n \log n$  is  $O(n \log n)$
  - $\square$ 7*n* 3 is O(*n*)
  - $\square 8n^2 \log n + 5n^2 + n \text{ is } O(n^2 \log n)$
- □ Note: Even though (50 n log n) is O(n5), it is expected that such an approximation be of as small an order as possible

## Asymptotic Analysis of Running Time

- □ Use O-notation to express number of primitive operations executed as function of input size.
- Comparing asymptotic running times
  - $\square$  an algorithm that runs in O(n) time is better than one that runs in  $O(n^2)$  time
  - □ similarly, O(log n) is better than O(n)
  - $\Box$  hierarchy of functions: log n < n < n<sup>2</sup> < n<sup>3</sup> < 2<sup>n</sup>

## Asymptotic Analysis of Running Time

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  - □ similarly, O(log n) is better than O(n)
  - □ hierarchy of functions:  $log n < n < n^2 < n^3 < 2^n$
- □ Caution! Beware of very large constant factors.
   An algorithm running in time 1,000,000 n is still O(n) but might be less efficient than one running in time 2n², which is O(n²)

# Example of Asymptotic Analysis

#### **Algorithm** prefixAverages1(X):

Input: An n-element array X of numbers.

Output: An n-element array A of numbers such that A[i] is the average of elements X[0], ..., X[i].

for 
$$i \leftarrow 0$$
 to n-1 do  $a \leftarrow 0$ 

return array A

#### Example of Asymptotic Analysis

#### **Algorithm** prefixAverages1(X):

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```
for i \leftarrow 0 to n-1 do
a \leftarrow 0
for j \leftarrow 0 to i do
a \leftarrow a + X[j] \longleftarrow 1 \text{ step}
A[i] \leftarrow a/(i+1)
return array A
```

Analysis: running time is O(n<sup>2</sup>)

#### A Better Algorithm?

#### **Algorithm** prefixAverages1(X):

Input: An n-element array X of numbers.

Output: An n-element array A of numbers such that A[i] is the average of elements X[0], ..., X[i].

for 
$$i \leftarrow 0$$
 to n-1 do  $a \leftarrow 0$ 

return array A

#### A Better Algorithm

#### **Algorithm** prefixAverages2(X):

*Input*: An *n*-element array X of numbers.

Output: An n-element array A of numbers such that A[i] is the average of elements X[0], ..., X[i].

$$s \leftarrow 0$$

for  $i \leftarrow 0$  to n do

$$s \leftarrow s + X[i]$$
  
A[i]  $\leftarrow s/(i+1)$ 

return array A

Analysis: Running time is O(n)

# Asymptotic Notation (terminology)

- Special classes of algorithms:
  - □ Logarithmic
  - □ Linear:
  - □ Quadratic:
  - □ Polynomial:
  - □ Exponential:

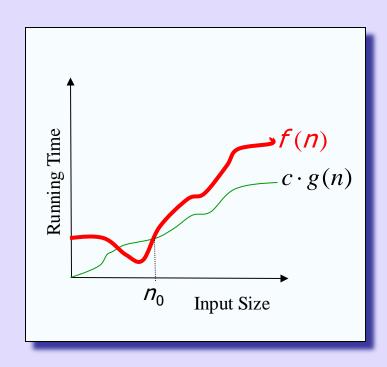
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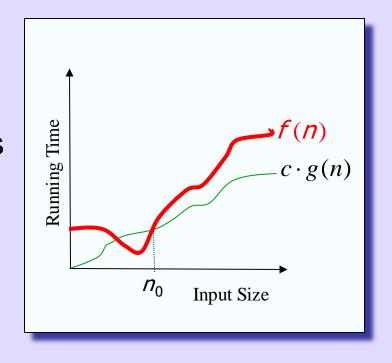
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- "Relatives" of the Big-Oh
  - $\square \Omega$  (f(n)): Big Omega -asymptotic *lower* bound
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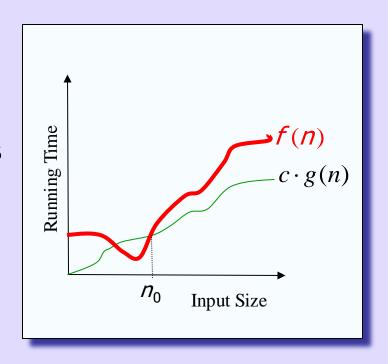
□ The "big-Omega" Ω– Notation



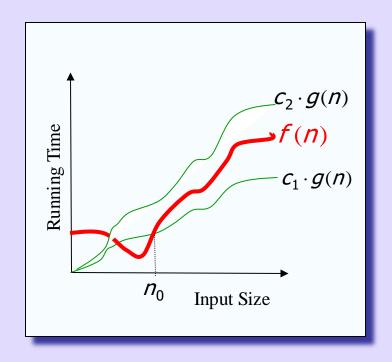
- □ The "big-Omega" Ω– Notation
  - asymptotic lower bound
  - □ f(n) is Ω(g(n)) if there exists constants c and  $n_0$ , s.t. c g(n) ≤ f(n) for  $n ≥ n_0$



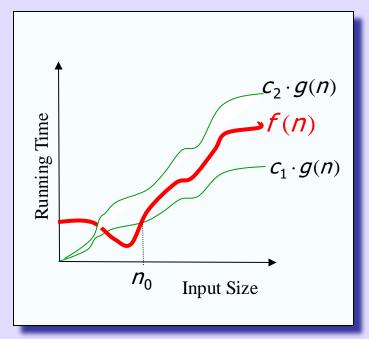
- The "big-Omega" Ω−
   Notation
  - asymptotic lower bound
  - □ f(n) is Ω(g(n)) if there exists constants c and  $n_0$ , s.t. c g(n) ≤ f(n) for  $n ≥ n_0$
- Used to describe bestcase running times or lower bounds for algorithmic problems
  - $\square$  E.g., lower-bound for searching in an unsorted array is  $\Omega(n)$ .



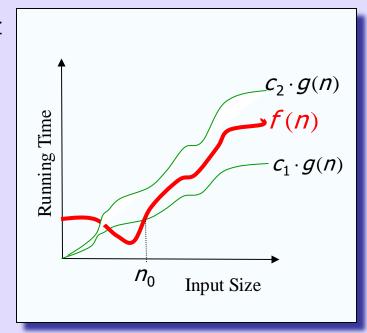
- □ The "big-Theta" Θ–Notation
  - asymptotically tight bound



- □ The "big-Theta" ⊕-Notation
  - asymptotically tight bound
  - □  $f(n) = \Theta(g(n))$  if there exists constants  $c_1$ ,  $c_2$ , and  $n_0$ , s.t.  $c_1$   $g(n) \le f(n) \le c_2$  g(n) for  $n \ge n_0$



- □ The "big-Theta" Θ–Notation
  - asymptotically tight bound
  - □  $f(n) = \Theta(g(n))$  if there exists constants  $c_1$ ,  $c_2$ , and  $n_0$ , s.t.  $c_1$   $g(n) \le f(n) \le c_2$  g(n) for  $n \ge n_0$
- □ f(n) is  $\Theta(g(n))$  if and only if f(n) is O(g(n)) and f(n) is  $\Omega(g(n))$
- $\square$  O(f(n)) is often misused instead of  $\Theta(f(n))$



Two more asymptotic notations

- □ "Little-Oh" notation f(n) is o(g(n)) non-tight analogue of Big-Oh
  - □ For every c, there should exist  $n_0$ , s.t. f(n)  $\leq c g(n)$  for  $n \geq n_0$
  - Used for **comparisons** of running times. If f(n)=o(g(n)), it is said that g(n) dominates f(n).
- □ "Little-omega" notation f(n) is  $\omega(g(n))$  non-tight analogue of Big-Omega

 $\Box$   $f(n) = \omega(g(n))$ 

Analogy with real numbers

```
\Box f(n) = O(g(n)) \qquad \cong \qquad f \leq g

\Box f(n) = \Omega(g(n)) \qquad \cong \qquad f \geq g

\Box f(n) = \Theta(g(n)) \qquad \cong \qquad f = g

\Box f(n) = o(g(n)) \qquad \cong \qquad f < g
```

□ Abuse of notation: f(n) = O(g(n)) actually means  $f(n) \in O(g(n))$ 

 $\cong$ 

f > g

# Comparison of Running Times

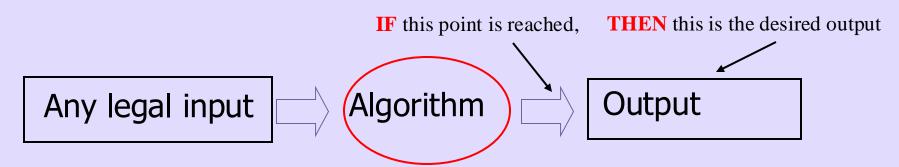
Running Time	Maximum problem size (n)		
	1 second	1 minute	1 hour
400 <i>n</i>	2500	150000	9000000
20 <i>n</i> log <i>n</i>	4096	166666	7826087
2 <i>n</i> <sup>2</sup>	707	5477	42426
n <sup>4</sup>	31	88	244
2 <sup>n</sup>	19	25	31

#### Correctness of Algorithms

- The algorithm is correct if for any legal input it terminates and produces the desired output.
- Automatic proof of correctness is not possible
- But there are practical techniques and rigorous formalisms that help to reason about the correctness of algorithms

#### Partial and Total Correctness

□ Partial correctness



□ Total correctness



# **Loop Invariants**

```
for j ← 1 to length(A)-1
    do

        key ← A[j]
        i ← j-1
        while i>0 and A[i]>key
        do A[i+1] ← A[i]
        i--
        A[i+1] ← key
```

# Example of Loop Invariants (1)

□ Invariant: at the start of each for loop, A[0...j-1] consists of elements originally in A[0...j-1] but in sorted order

```
for j ← 1 to length(A)-1
    do

        key ← A[j]
        i ← j-1
        while i>0 and A[i]>key
        do A[i+1] ← A[i]
        i--
        A[i+1] ← key
```

# Example of Loop Invariants (2)

□ Invariant: at the start of each for loop, A[0...j-1] consists of elements originally in A[1...j-1] but in sorted order

```
for j ← 1 to length(A)-1
  do

  key ← A[j]
  i ← j-1
  while i>0 and A[i]>key
   do A[i+1] ← A[i]
    i--
  A[i+1] ← key
```

□ **Initialization**: j = 1, the invariant trivially holds because A[0] is a sorted array  $\odot$ 

## Example of Loop Invariants (3)

□ Invariant: at the start of each for loop, A[0...j-1] consists of elements originally in A[0...j-1] but in sorted order

```
for j ← 1 to length(A)-1
    do

        key ← A[j]
        i ← j-1
        while i>0 and A[i]>key
        do A[i+1] ← A[i]
        i--
        A[i+1] ← key
```

■ **Maintenance**: the inner **while** loop moves elements A[j-1], A[j-2], ..., A[j-k] one position right without changing their order. Then the former A[j] element is inserted into k-th position so that  $A[k-1] \le A[k] \le A[k+1]$ .

A[0...j-1] sorted +  $A[j] \rightarrow A[0...j]$  sorted

# Example of Loop Invariants (4)

□ **Invariant**: at the start of each **for** loop, A[0...j-1] consists of elements originally in A[0...j-1] but in sorted order

```
for j ← 1 to length(A)-1
    do

        key ← A[j]
        i ← j-1
        while i>0 and A[i]>key
        do A[i+1] ← A[i]
        i--
        A[i+1] ← key
```

□ **Termination**: the loop terminates, when j=n. Then the invariant states: "A[0...n-1] consists of elements originally in A[0...n-1] but in sorted order" ©

#### **Assertions**

- □ To prove correctness we associate a number of assertions (statements about the state of the execution) with specific checkpoints in the algorithm.
  - □ E.g., A[1], ..., A[k] form an increasing sequence
- Preconditions assertions that must be valid before the execution of an algorithm or a subroutine
- Postconditions assertions that must be valid after the execution of an algorithm or a subroutine

#### **Loop Invariants**

- □ Invariants assertions that are valid any time they are reached (many times during the execution of an algorithm, e.g., in loops)
- We must show three things about loop invariants:
  - □ Initialization it is true prior to the first iteration
  - Maintenance if it is true before an iteration, it remains true before the next iteration
  - □ Termination when loop terminates the invariant gives a useful property to show the correctness of the algorithm

#### Math You Need to Review

□ Properties of logarithms:

```
log_b(xy) = log_bx + log_by

log_b(x/y) = log_bx - log_by

log_b x^a = a log_b x

log_b a = log_x a/log_x b
```

□ Properties of exponentials:

```
a^{(b+c)} = a^b a^c; a^{bc} = (a^b)^c
a^b / a^c = a^{(b-c)}; b = a^{log_a b}
```

- □ Floor:  $\lfloor x \rfloor$  = the largest integer  $\leq x$
- □ Ceiling:  $\lceil x \rceil$  = the smallest integer ≥ x

#### Math Review

- □ Geometric progression
  - $\square$  given an integer  $n_0$  and a real number  $0 < a \ne 1$

$$\sum_{i=0}^{n} a^{i} = 1 + a + a^{2} + \dots + a^{n} = \frac{1 - a^{n+1}}{1 - a}$$

- geometric progressions exhibit exponential growth
- Arithmetic progression

$$\sum_{i=0}^{n} i = 1 + 2 + 3 + \dots + n = \frac{n^2 + n}{2}$$

#### **Summations**

The running time of insertion sort is determined by a nested loop

```
for j←1 to length(A)-1
    key←A[j]
    i←j-1
    while i>=0 and A[i]>key
        A[i+1]←A[i]
        i←i-1
        A[i+1]←key
```

■ Nested loops correspond to summations

$$\sum_{j=1}^{n-1} j = O(n^2)$$