Total No. of Questions: 6

Total No. of Printed Pages:3

## Enrollment No.....



## Faculty of Engineering End Sem Examination May-2024 ME3EL23 Fundamentals of AI

Programme: B.Tech. Branch/Specialisation: ME

Duration: 3 Hrs. Maximum Marks: 60

Note: All questions are compulsory. Internal choices, if any, are indicated. Answers of Q.1 (MCQs) should be written in full instead of only a, b, c or d. Assume suitable data if necessary. Notations and symbols have their usual meaning.

- '	_	Notations and symbols have the	ir usual meaning.	a 11
Q.1 i.		Which of the following is the	goal of intelligent agent?	1
		(a) High performance	(b) Optimized results	
		(c) Rational action	(d) All of these	
	ii.	Condition-Action is a charact	eristic feature of	1
		(a) State space search	(b) Production system	
		(c) Both (a) & (b)	(d) None of these	
	iii.	Which of the following is not	a method for finding heuristic value?	1
		(a) Eucladian distance	(b) Manhatton distance	
		(c) Number of misplaced tiles	(d) None of these	
iv	iv.	BFS belongs to which search	technique-	1
		(a) Informed (b) uninformed	d (c) Heuristic (d) All of these	
	v.	'¬' this symbol is used to rep	present-	1
		(a) Conjunction	(b) Disjunction	
		(c) Negation	(d) If and only if rule	
	vi.	Top to bottom approach is fol	lowed by which chaining?	1
		(a) Forward	(b) Backward	
		(c) Both (a) & (b)	(d) None of these	
	vii.	Which of the following is	responsible for resolving conflicts and	1
		creating agreements?		
		(a) Negotiation and bargainin	g	
		(b) Agent architecture		
		(c) Agent communication pro	tocols	
		(d) Trust and reputation mana	gement	

1-1	[2]
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	viii.	The role of 'Trust' in multi agent system is	1
		(a) Ensuring complete autonomy of agents	
		(b) Minimizing communication between agents	
		(c) Facilitating cooperation and collaboration among agents	
		(d) Preventing agents from sharing information	
	ix.	What is the primary objective of robot hardware perception in AI?	1
		(a) Understanding natural language	
		(b) Recognizing human emotions	
		(c) Sensing and interpreting physical environment	
		(d) Strategic decision making	
	Χ.	Which of the following involves conversion of human language to	1
		machine readable format?	
		(a) Information retrieval	
		(b) Machine translation	
		(c) Speech recognition	
		(d) Robot hardware perception	
Q.2	i.	What do you understand from the term artificial intelligence?	2
	ii.	What are the advantages and disadvantages of artificial intelligence?	3
	iii.	What is an intelligent agent? What are its types? Explain any one type	5
		with diagram.	
OR	iv.	Explain the concept of production system in artificial intelligence.	5
Q.3	i.	Write difference between Breadth First Search (BFS) & Depth First	4
		Search (DFS).	
	ii.	Explain the concept of A* algorithm with the help of suitable example.	6
OR	iii.		6
	111.	using suitable example.	v
Q.4	i.	Represent 'Z' sentence as propositional logic-	2
		(a) X: Rohan is doctor, Y: Rohan is engineer	
		Z: Rohan is doctor or engineer	
		(b) X: It is hot, Y: It is humid	
		Z: If it is humid then it is hot	
	ii.	Represent the following sentences as first order predicate logic-	3
		(a) Some boys like football	
		(b) All men drink coffee	

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	iii.	What is knowledge representation? Explain different types of	5
OR	iv	knowledge.  Explain the concept of unification with suitable example.	5
Q.5		Attempt any two:	
	i.	Explain the architecture of intelligent agent. Draw necessary diagram in support of your answer.	5
	ii.	Write an informative note on agent communication covering all important points.	5
	iii.	Describe the term multi agent system.	5
Q.6		Attempt any two:	
	i.	Explain the role of artificial intelligence in robotics and automation.	5
	ii.	Describe the term:	5
		(a) Machine Translation (b) Speech recognition	
	iii.	Explain various applications of artificial intelligence.	5

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## **Marking Scheme**

## Fundamental of AI (T) - ME3EL23 (T)

Q.1	i)	d) All of these		1
	ii)	b) Production system		1
	iii)	d) None of these		1
	iv)	b) uninformed		1
	v)	c) Negation		1
	vi)	b) Backward		1
	vii)	a). Negotiation and bargaining		1
	viii)	c). Facilitating cooperation and collaboration among	g agents	1
	ix)	c) Sensing and interpreting physical environment		1
	x)	B. Machine translation		1
Q.2	i.	Definition	2 Mark	2
	ii.	Advantages	1.5 Mark	3
		Disadvantages	1.5 Mark	
	iii.	Definition	1 Mark	5
		Types	1 Mark	
		Explanation with diagram	3 Mark	
OR	iv.	Definition	1 Mark	5
		Components, Explanation	4 Mark	
Q.3	i.	1 Mark for each difference	4 Mark	4
	ii.	Concept & equation	2 Mark	6
		Diagram	2 Mark	
		Solution	2 Mark	
OR	iii.	Concept & equation	2 Mark	6
		Diagram	2 Mark	
		Solution	2 Mark	
Q.4	i.	1 Mark for each sentence	2 Mark	2
	ii.	1.5 Marks for each sentence	3 Mark	3
	iii.	Definition	1 Mark	5
		Types	1 Mark	
		Explanation	3 Mark	
OR	iv	Unification	3 Mark	5
		Example	2 Mark	
Q.5	i.	Architecture	3 Mark	5
		Diagram	2 Mark	
	ii.	Agent communication	3 Mark	5
		Important components	2 Mark	

OR	iii.	Multi agent system	5 Mark	5
Q.6		Any two		
	i.	Role in robotics	2.5 Mark	5
		Role in automation	2.5 Mark	
	ii.	i) Machine Translation	2.5 Mark	5
		ii) Speech recognition	2.5 Mark	
	iii.	Applications (at least 5)	5 Mark	5

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P.T.O.