[4]

- For each of the following impulse responses, determine whether the corresponding system is (i) memory-less, (ii) causal and (iii) stable. Justify your answer.
 - (a) $h[n] = (2)^n u[-n]$
 - (b) $h[n] = e^{2n}u[n-1]$
 - (c) $h[n] = \left(\frac{1}{2}\right)^n u[n]$
- OR Calculate y[n], n = 0,1,2,3 for the first order recursive system y[n] - (1/2)y[n-1] = x[n] if the input is x[n] = u[n] and initial condition y[-1] = -2.
- Q.6 Attempt any two:
 - Determine the z –transform of the signal $x[n] = \alpha^n u[n]$. Depict the ROC and the locations of the poles and zeros of X(z) in z -plane.
 - Find the inverse z -transform of $X(z) = \frac{1}{1 \frac{1}{2}z^{-1}} + \frac{2}{1 2z^{-1}}$ assuming that signal is causal.
 - Determine whether the LTI system y[n] (6/5)y[n-1] -5 (16/25)y[n-2] = 2x[n] + x[n-1] is clausis or not.

Total No. of Questions: 6

Total No. of Printed Pages:4

Enrollment No.....



Faculty of Engineering

End Sem (Odd) Examination Dec-2017 EC3CO01 / EI3CO01 Signals and Systems

Programme: B.Tech.

Branch/Specialisation: EC/EI

Duration: 3 Hrs.

5

Maximum Marks: 60

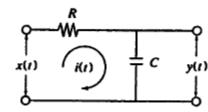
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Note: All questions are compulsory. Internal choices, if any, are indicated. Answers of Q.1 (MCQs) should be written in full instead of only a, b, c or d.

- Q.1 i. Consider the periodic signal $e^{-t/2}$, $0 \le t \le 2$, with period T = 12. What is its power?
 - (a) $\left(1 \frac{1}{e}\right)$ (b) (e 1) (c) $\frac{1}{2}\left(1 \frac{1}{e^2}\right)$ (d) $\frac{1}{2}(e^2 1)$
 - The power of a sinusoidal signal $x(t) = A\cos(2\pi f t)$ is
- (b) 0 (c) $\frac{A^2}{2}$ (d) $\frac{A}{2}$
- Consider the unit-step function u(t) defined as, u(t) = 1 if t > 1 $0, \frac{1}{2}$ at t = 0 and 0 if $t \le 0$. What is its Fourier transform?
- (b) $\delta(f)$
- (c) $\frac{1}{i2\pi f}$ (d) $\frac{1}{2}(\delta(f) + \frac{1}{i2\pi f})$
- Consider the impulse train $(t) = \sum_{n=-\infty}^{\infty} \delta(t nT_s)$. What is its 1 discrete Fourier series representation?
 - (a) $\frac{1}{T_0} \sum_{k=-\infty}^{\infty} \delta(f \frac{k}{T_0})$
- (b) $\delta(f)$
- (c) $\sum_{k=-\infty}^{\infty} \delta(f \frac{k}{T})$ (d) $\sum_{k=-\infty}^{\infty} sinc(kT_s)\delta(f kT_s)$
- Consider a system with input x(t) and output y(t) given by 1 $y(t) = x(t) \sum_{n=-\infty}^{\infty} \delta(t - nT)$. The system is
 - (a) Linear and Time invariant
 - (b) Linear and not-time invariant
 - (c) Non-linear and time invariant
 - (d) Non-linear and not-time invariant

P.T.O.

Consider the RC network shown in the figure below. Find its impulse response h(t).



- (a) $\frac{1}{RC} \left(1 e^{-t/RC} \right) u(t)$
- (b) $sinc(\frac{t}{RC})$
- (c) $\frac{1}{RC} \left(e^{-t/RC} \right) u(t)$ (d) $\frac{1}{\left(1 + \left(\frac{t}{RC}\right)^2\right)}$

vii. The causal sequence defined by $x[n] = 3(-1)^n, n \ge 0$ and 0 for 1 n < 0 has

- (a) Finite energy with zero power
- (b) Infinite energy with finite average power=4.5
- (c) The data is insufficient
- (d) None of these

viii. If the output of the system is $y[n] = \sum_{k=-\infty}^{n} x[k]$ with an input x[n], the system will work as

- (a) Accumulator
- (b) Adder

(c) Subtractor

(d) Multiplier

According to Time shifting property of z-transform, if X(z) is the z-transform of x[n] then what is the z-transform of x[nk]?

- (a) $z^k X(z)$ (b) $z^{-k} X(z)$ (c) X(z-k) (d) X(z+k)

What is the z-transform of the signal defined as x[n] = u[n] -1 u[n-N]?

- (a) $\frac{1+z^N}{1+z^{-1}}$ (b) $\frac{1-z^N}{1+z^{-1}}$ (c) $\frac{1+z^{-N}}{1+z^{-1}}$ (d) $\frac{1-z^{-N}}{1-z^{-1}}$

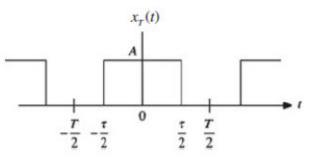
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2 Q.2 i. What is Impulse function? Define sifting property of impulse.

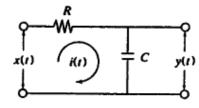
- Differentiate between energy and power signals with examples. 3 ii.
- Compute the energy of the signal $x(t) = \sin(2\pi f_0 t)$. iii.

OR iv. What are orthogonal signals? What is the necessary condition 5 for orthogonality? Give one example.

Q.3 i. Find and plot the complex Fourier series of the pulse sequence shown in following figure.



- Consider the impulse train $(t) = \sum_{n=-\infty}^{\infty} \delta(t nT_s)$. What is its 8 discrete Fourier transform?
- OR If $x_1(t)$ and $x_2(t)$ are periodic signals with period T and their Fourier series expressions are $x_1(t) = \sum_{n=-\infty}^{\infty} d_n e^{j2\pi f_0 t}$ and $x_2(t)=\sum_{n=-\infty}^{\infty}e_ne^{j2\pi f_0t},\;f_0=rac{1}{\tau}\;{
 m show}$ that the signal x(t)= $x_1(t)x_2(t)$ with period T can be expressed as x(t) = $\sum_{n=-\infty}^{\infty} d_k e_{n-k} e^{j2\pi f_0 t}.$
- What are LTI systems? Demonstrate distortion less Q.4 i. 3 transmission.
 - Consider the RC network shown in the figure below. Find its 7 unit step response.



- OR iii. Consider the continues time system described by input output 7 relation y(t) = x(t)x(t-1). Show that this system is non-linear.
- Consider a system with impulse response $h[n] = \left(\frac{3}{4}\right)^n u[n]$. Q.5 i. Determine the output of the system at time n = -5, n = 5 and n = 10 when the input is x[n].

P.T.O.

Medicaps. University

1/5

Erd Sem (odd) Exam Dec 2017 EC3CO01/EI3CO01 signal & system Programme; B Tech. Branch: EC/EI solution/ Marking Scheme

MCP

$$\frac{1}{T_s} \underset{K=-\infty}{\overset{\infty}{\leq}} S \left(f - \frac{K}{T_s} \right)$$

brear and not-time invariant

Infinite Energy with finite ava

Accornulator

Q.2 (1) Impulse defination S(+)=0 + 70

Sifting property
$$\int_{0}^{\infty} a(t) \delta(t) dt = a(t) = a(t)$$

Either for confiberus or discrete.

. <u>Q. 2</u> (ii)

Defre Energy Signal with Exmple - 1.5 M — 11 — Power Signal -11 - 1.5 M

(111) Define Energy Signal + formula - 2 M

Steps + calculation of Energy - 3 M

Ans | Frengy = 00 Tailes

OR

(IV)

orthogonal Signal defination -> 2M

Necessary condition -> IM

Example of cottagonal fun _ 3 2M with Proof

q. 3 (i)

Formula Exponential/Tongonometric

x(+) = \(\frac{20}{x} \) \text{Thwot} \(\frac{20}{x} \) \(\frac{1}{x} \) \(\frac{

calculation ** & plot - >

Xn = + \int \alpha \taut \e \dt

(ii) Attempting the question get
full marks — BM

Proof By Famier series convolution Property 2M fourier series -219 convolution Property ---Proof statement -4 100 (1) LTI System Linear System defination __ 105 M & conditions Thre hvancout -11- - 1.5 M E -11-Distortion less transmission - Out of Syllabus (11) Equation of RC Network 2M & laplace transform IM fredreg I(s) IM finding y(s) Inverse laplace Y(s) i.e 311 1 y(+) = u(+) - = +/RCu(+) (111) 3 W For given problem additivity Proof -3 M homogenity Broof -IM comment on Result

OR (Tii)

3/5

· 9.5 (1) Attempting the question get 4 M full moreks (11) Static/memoryless eausual stable Non-Causal Stable - 2M Data 13 Causual Unstable - 211 Insufficient Cauval Urstable - 2M for memory 1888 check YMJ = Yg(n) + Yp(n) (111) 2M Yg(n) = K. (1/2) Yp(n) = K(生) + X/K1 finding dorki coeff = 2 Solution 4(0) = y(1) = y12) = y(3) =7/4 Attempt any two Z transform finding 0 $x(2) = \frac{1}{1-az^{-1}} = \frac{2}{z-a}$ Roc 12/79 Roc define & Us Plot location Pole/zero

$$X(2) = \frac{1}{1 - 42^{-1}} + \frac{2}{1 - 22^{-1}}$$

Inverse ZTX for causual signal

$$x(m) = (3)^{n}u(m) + 2\cdot(2)^{n}u(m)$$

$$2.5 M + 2.5 M$$

(111) LTI System.

$$y(n) - 615 y(n-1) - 16/25 y(n-2)$$

$$= 2x(n) + x(n-1)$$

causualty proof ____ 4 M

by any method. for given problem

x - * - * - *