Total No. of Questions: 6

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Enrollment No.....



Faculty of Engineering End Sem Examination May-2023 RA3EL04 Industrial Robotics & Material Handling

Systems Branch/Specialisation: RA Programme: B.Tech.

Duration: 3 Hrs. Maximum Marks: 60

Note: All questions are compulsory. Internal choices, if any, are indicated. Answers of

-) should be written in full inst Notations and symbols have th	ead of only a, b, c or d. Assume suitable data eir usual meaning.	a i
Q.1	i.	Which one of the following (a) Information robots	robots comes under first generation? (b) Autonomous loading	1
		(c) Autonomous harvesting	(d) None of these	
	ii.	The main objective of Indust	rial Robot is to	1
		(a) Increase productivity		
		(b) Minimize the labor requi	rement	
		(c) Enhance the life of produ	action machines	
		(d) All of these		
	iii.	For color monitor & color model is used.	video camera application color	1
		(a) RGB (b) CMY	(c) HIS (d) YIQ	
	iv.	al image processing system-	1	
		(a) Image acquisition	(b) Storage & processing	
		(c) Display	(d) All of these	
	v.	Which type of robot is comn	nonly used for arc welding applications?	1
		(a) Cartesian robots	(b) SCARA robots	
		(c) Articulated robots	(d) Delta Robot	
	vi.	What is the main advantag welding?	e of using robotic welding over manual	1
		(a) Lower initial cost		
		(b) Higher accuracy and con	sistency	
		(c) Ability to weld larger par	rts.	
		(d) Increased safety for hum	an operators	

P.T.O.

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	vii.	What is an end effector?		1
		(a) Type of sensor used in robotics		
		(b) A part of a robot that performs a specific	task	
		(c) A type of motor used in robotics		
(d) A type of software used for programming robots				
	viii.	What is the primary factor to consider when application?	n selecting a robot for an	1
		(a) Price	(b) Payload capacity	
		(c) Operating speed	(d) Power source	
	ix. Which of the following is a type of manual material handline equipment?		nanual material handling	1
		(a) Automated guided vehicles (AGVs)	(b) Robots	
		(c) Conveyor belts	(d) Hand trucks	
	х.	Which of the following is an example of technology?	an application for RFID	1
		(a) Scanning items at a grocery store checko	ut	
		(b) Tracking inventory in a warehouse		
		(c) Printing shipping labels		
		(d) Creating marketing materials		
Q.2	i.	State the general consideration in robotics ma	aterial handling.	2
₹	ii.	What are the benefits of using industrial robo	•	3
	iii.	What are some common challenges associ implementing material transfer systems? How	iated with designing and	5
		addressed?		
OR	iv.	What are some common types of industrial r work Envelope of a robot, also sketch the work	_	5
		and cylindrical coordinate robot.		
Q.3	i.	What are some of the benefits of using robots	s for inspection, compared	2
		to traditional inspection methods?		
	ii.	What are some of the key factors that sho		8
		selecting a robot for inspection tasks? What		
OD		trends and technologies in the field of robots	•	0
OR	iii.	Describe the basic functions of Machine V	vision technique used in	ð
		Robotics, with a neat block diagram.		
Q.4	i.	Write short note on underwater application of	f robot.	3

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OR	ii. iii.	Explain various steps involved in applying a robot in spot welding with advantages and limitations. What are some of the emerging trends and technologies in the field of robots for welding, such as collaborative robots or vision systems? Explain it.	
Q.5	i. ii.	Explain the impact of Robot on industry and society. What are the costs associated with implementing robots in a	4
OR	iii.	manufacturing environment? How can these costs be justified based on expected benefits such as increased productivity or reduced labor costs? Define end effector used in robot. Classify various type of gripers used in industrial robots.	6
Q.6	i. ii.	Attempt any two: Explain any ten principles of material handling used in industries. What types of AGVs are available for material handling operations? What factors to be considered when implementing AGVs in material	5

iii. Explain the role of Bar Code Technology and RFID in material 5

handling operations?

handling operations.

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Marking Scheme

KA	3E)	L04 Industrial Robotics and Material Handling Syste	ems
Q.1	i)	Which one of the following robots comes under first generation?	1
		a. Information robots	
	ii)	The main objective of Industrial Robot is to d. All the above	1
	iii)	If a robot can alter its own trajectory in response to external conditions, it is	1
		a. RBG	
	iv)	Which of the basic parts of a robot unit would include the computer circuitry that could be programmed to determine what the robot would do? b. All of these	1
	v)	Which type of robot is commonly used for arc welding applications? c. Articulated robots	1
	vi)	What is the main advantage of using robotic welding over manual welding? a. Higher accuracy and consistency	1
	vii)	What is an end effector? b. A part of a robot that performs a specific task.	1
	viii	What is the primary factor to consider when selecting a robot for an application? a. Payload capacity	1
	ix)	Which of the following is a type of manual material handling equipment? d. Hand trucks	1
	x)	Which of the following is an example of an application for RFID technology? b. Tracking inventory in a warehouse	1
0.2	i.	The General consideration in maintenance handling	2

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	iii.	What are the benefits of using industrial robots in manufacturing. What are some common challenges associated with designing and implementing material transfer systems, and how can these challenges be addressed?	3+2
OR	iv.	What are some common types of industrial robots? Explain the term work Envelope of a robot, also sketch the work envelope of a cartesian and cylindrical coordinate robot.	2+3
Q.3	i.	What are some of the benefits of using robots for inspection, compared to traditional inspection methods?	2
	ii.	What are some of the key factors that should be considered when selecting a robot for inspection tasks? What are some of the emerging trends and technologies in the field of robots for inspection	4+4
OR	iii.	Describe the basic functions of Machine Vision technique used in Robotics, with a neat block diagram.	8
Q.4	i.	Write short note on underwater application of robot. Explain various steps involved in applying a robot in spot welding	3 7
	11.	with advantages and limitations.	,
OR	iii.	What are some of the emerging trends and technologies in the field of robots for welding, such as collaborative robots or vision systems? Explain	7
Q.5	i.	Explain the impact of Robot on industry and society.	4
	ii.	What are the costs associated with implementing robots in a manufacturing environment, and how can these costs be justified based on expected benefits such as increased productivity or reduced labour costs?	6
OR	iii.	Define end effector used in robot. Classify various type of gripers used in industrial robots.	2+4
Q.6		Attempt any two:	
	i.	Explain the 10 principles of material handling used in industries	5

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- ii. What types of AGVs are available for material handling operations? What factors to be considered when implementing AGVs in material handling operations?
- iii. Explain the role of Bar Code Technology and RFID in material 2.5+2.5 handling operations.
