Total No. of Questions: 6	Total No.	of Questions:	6
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Enrollment No.....



## Faculty of Engineering End Sem Examination Dec-2023

EC3CO23 Signals & Systems

Programme: B.Tech. Branch/Specialisation: EC

**Maximum Marks: 60 Duration: 3 Hrs.** 

Note: All questions are compulsory. Internal choices, if any, are indicated. Answers of Q.1 (MCQs) should be written in full instead of only a, b, c or d. Assume suitable data if necessary. Notations and symbols have their usual meaning.

Q.1	i.	A deterministic signal has-		1
		(a) No Uncertainty	(b) Uncertainty	
		(c) Partial uncertainty	(d) None of these	
	ii.	A signal is energy signal if-		1
		(a) $E = 0$ , $P = 0$	(b) $E = infinite$ , $P = finite$	
		(c) $E = finite$ , $P = 0$	(d) $E = finite$ , $P = infinite$	
ii	iii.	An exponential Fourier Serie	es consists of-	1
		(a) A one-sided spectrum		
		(b) A two-sided spectrum		
		(c) Both one-sided and two-	sided spectrum	
		(d) None of these		
	iv.	The Fourier Transform of e	<sup>5t</sup> u(t) will be-	1
		(a) $\frac{1}{j\omega}$ (b) $\frac{1}{5-j\omega}$	$(c) \frac{1}{5+j\omega} \qquad (d) \frac{1}{5^2 - \omega^2}$	
	v.	y(t) = x(-t) is for a-		1

- (a) Non-linear system
  - (b) Linear, causal and time-invariant system
  - (c) Linear, non-causal and time-invariant system
  - (d) Linear, non-causal and time-variant system
- vi. For a system the input and output relation is given by a differential 1 equation  $\frac{dy(t)}{dt} + 2y(t) = x(t)$ . What is the impulse response of the system?
  - (a) u(t)
- (b) 2u(t)
- (c)  $e^{-2t}u(t)$  (d)  $e^{2t}u(t)$

vii.	If two signals $x(n) = {\delta(n) + \delta(n+1)}$ and $h(n) = {\delta(n+1) + \ldots}$
	$\delta(n-1)$ are convolved, then the number of samples in the result of
	convolution are-

(a) 3

(b) 4

(c) 5

viii. Difference equation technique for higher order systems is used in-

(a) Laplace Transform

(b) Fourier Transform

(c) Z-Transform

(d) None of these

ix. The only signal whose ROC is the entire z-plane will be-

(a)  $\delta(n)$ 

(b) u(n)

(c) r(n)

(d)  $a^n$ 

(d) 6

1

1

1

6

The inverse z-transform of  $2 + 3z^{-1} + 4z$  shall be given by-

(a) [2, 3, 4] (b) [3, 4, 2] (c) [4, 2, 3] (d) [3, 2, 4]

Q.2 i. Show that the following signals are orthogonal over an interval [0, 1]:  $x_2(t) = 2$ ;  $x_2(t) = \sqrt{3}(1+2t)$ 

Determine whether the following signals are energy signals or power 6 signals and calculate their energy or power.

(a)  $\left(\frac{1}{2}\right)^n u(n)$ 

(b)  $\cos^2 \omega t$ 

(c)  $2e^{-4t}u(t)$ 

Explain the analogy between vectors and signals.

Q.3 i. Write the Dirichlet's conditions for existence of Fourier Series. What are the types of Fourier Series?

Explain Parseval's and Convolution Fourier Transform theorems with 6 proof.

OR iii. With the help of DTFT and Inverse-DTFT find out the output of a 6 causal discrete LTI system which is characterised by the difference equation-

$$y(n) - \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2) = 2x(n)$$

For input  $x(n) = \left(\frac{1}{4}\right)^n u(n)$ .

Q.4 Attempt any two-

> Draw the direct form-I and direct form-II structures for the differential 5 equation,

$$\frac{dy(t)}{dt} + y(t) = 5x(t)$$

Find the convolution of the following signals:

(a)  $x_1(t) = e^{-3t}u(t)$ ;  $x_2(t) = u(t+3)$ 

(b)  $x_1(t) = tu(t)$ ;

 $x_2(t) = tu(t)$ 

5

6

8

Check and verify the following systems are causal, time invariant and 5 memory less or not?

(a) 
$$y(t) = x(t) - x(t-2)$$

(b) y (t) =
$$x^2(t)$$

Q.5 i. Determine whether the following systems are linear or nonlinear:

$$(a) y(n) = x(n^2)$$

$$(b) y(n) = x^2(n)$$

Find the total response  $\{y^n(n) + y^p(n)\}\$  of the difference equation,

$$y(n) - \frac{2}{5}y(n-1) = 2x(n)$$

Given that the input x(n)=2u(n) and the initial condition y(0)=0.

OR iii. Determine the response of the system characterized by the impulse 6 response  $h(n) = \left(\frac{1}{2}\right)^n u(n)$ to the input signal  $x(n) = (n+1) (1/4^n) u(n).$ 

Explain one-sided and two-sided z-transform with examples. 2 Q.6 i.

Explain following properties of z-transform:

(a) Time shifting (b) Time reversal

(c) Differentiation

(d) Final value theorem

OR iii. An LTI system is described by the equation,

$$y(n) = x(n) + 0.81x(n-1) - 0.81x(n-2) - 0.45y(n-2)$$

Determine the transfer function of the system. Sketch the poles and zeros on the z-plane. Access the stability.

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