7

7

Enrollment No.....

			Jobs				
		A	В	С	D	Е	
	I	5	11	10	12	4	
	II	2	4	6	3	5	
Machines	III	3	12	5	14	6	
	IV	6	14	4	11	7	
	V	7	9	8	12	5	

Five jobs are performed, first on machine X and then on Machine Y. The OR iii. time taken, in hours by each job on each machine is given below:

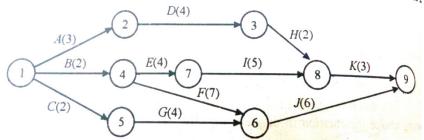
Jobs	1	2	3	4	5
Machine A	5	1	9	3	10
Machine B	2	6	7	8	4

Determine the sequence for 5 jobs that will minimize the total elapsed time and idle time for machine A and B

- Q.6 i. What are the three time estimates used in the context of PERT (Program 3 Evaluation Review Technique)? Define them.
 - Draw the network for the data given below and compute: (a) Critical path (b) Early start and Late start times for each activity and (c) Total project duration.

Activity	A	В	С	D	Е	F	G	Н	I
Predecessor	-	-	-	A	В	С	D, E	В	H, F
Estimated time	3	5	4	2	3	9	8	7	9
(weeks)									

For the following diagram: OR



- (a) Compute earliest event time and latest event time.
- (b) Critical path and total project duration.

Faculty of Management

End Sem (Even) Examination May-2018 MS3CO05 Operations Research

Programme: BBA Branch/Specialisation: Management

Duration: 3 Hrs. Maximum Marks: 60 Note: (a) All questions are compulsory. Internal choices, if any, are indicated. Answers of Q.1 (MCQs) should be written in full instead of only a, b, c or d. (b) Use of simple (non-programmable) calculator is allowed. Operations research is the application of ______methods to arrive Q.1 i. at the optimal solutions to the problems. (a) Economical (b) Scientific (c) Both (a) and (b) (d) Artistic Models are obtained by enlarging or reducing the size of an item. (a) Analogue (b) Symbolic (c) Iconic (d) None of these In graphical method to solve LPP, if there is no feasible region in the 1 plotted graph, then it is case of (a) Unique solution (b) Many solution (c) Bounded solution (d) No solution In linear programming problems, the objective function and objective constraints are: (c) Solved (b) Quadratic (d) Adjacent (a) Linear Transportation model is also known as: (a) Logistics model (b) Distribution model (c) Assignment model (d) None of these The Penalty in Vogel's Approximation Method represents difference 1 between _____cost of respective row / column. (a) Two Largest (b) Largest and smallest (c) Two smallest (d) None of these

Minimum number of lines to cover all the zeroes in an Assignment

(b) Rows

(d) All of these

problem is equal to number of

(a) Assignments

(c) Columns

1

[3]

viii. The time interval between the starting the first job and completing the last job including idle time if any in a particular order by the given set of machines is called _____ time

(a) Processing

(b) Waiting

(c) Total elapsed

(d) Idle

Activity which starts only after finishing other activity is called

(a) Predecessor

(b) Successor (c) Dummy (d) None of these

Network models have advantage in terms of project_

(a) Planning

(b) Controlling

(c) Scheduling

(d) All of these

Q.2 i. Discuss any four limitations of Operations Research.

4

6

6

1

1

1

- Discuss in brief the scope of Operations Research in any three key areas ii. of Business Management.
- What are the three major phases of Scientific Method in Operations iii. OR Research? Explain them in brief.
- A firm manufactures three products A, B and C. The profits are Rs.3, Q.3 i. Rs.2 and Rs.4 respectively. The firm has two machines M_1 and M_2 and below is the required capacity processing time in minutes for each machine on each product.

Machines	Product				
	A	В	С		
M_1	4	3	5		
M_2	2	2	4		

Machines M_1 and M_2 have 2000 and 2500 machine minutes respectively. The firm must manufacture 100 A's, 200 B's and 50 C's but not more than 150 A's. Formulate an LPP to maximize the profit.

Solve the given Linear Programming Problem by Graphical Method.

$$Min z = 6x_1 + 14x_2$$

 $subject to: 5x_1 + 4x_2 \ge 60$
 $3x_1 + 7x_2 \le 84$
 $x_1 + 2x_2 \ge 18$
 and $x_1, x_2 \ge 0$

Solve the given Linear Programming Problem by Simplex Method. OR

$$Max \ z = 4x_1 + 10x_2$$

 $subject \ to: \ 2x_1 + x_2 \le 10$
 $2x_1 + 5x_2 \le 20$
 $2x_1 + 3x_2 \le 18$
 $and \ x_1, x_2 \ge 0$

Define the following terms in a Transportation Model: O.4 i.

(a) Feasible solution (b) Initial basic feasible solution

(c) Optimal solution (d) Non-degenerate solution

Solve the following cost minimizing Transportation problem to get an optimal solution.

		Destinations					
		D1 D2 D3 D4					
	S1	5	2	4	3	22	
Sources	S2	4	8	1	6	15	
	S3	4	6	7	5	8	
Demand		7	12	17	9		

Obtain the initial basic feasible solution of the following Transportation OR iii. problem using North West Corner Rule and Least Cost Method and find the transportation cost associated in both the cases.

		Distrib	oution c	entres		
		Ι	II	III	IV	Supply
	A	2	3	11	7	6
Plants	В	1	0	6	1	1
	С	5	8	15	9	10
Requirement		7	5	3	2	

Q.5 Explain the mathematical model of an Assignment Problem

A company has 5 jobs to be done. The following matrix shows the return in rupees on assigning i^{th} (i = I, II, III, IV, V) machines to the i^{th} job(j = A, B, C, D, E). Assign the five jobs to the five machines so as to maximize the total expected profits.

P.T.O.

	Medi-Caps University	多图
*	Faculty of Management	
*	End Sem (Even) Examination May-2017	
	MS 3 CO05 Operations Research	
	Programme: BBA M.M. 60	
	Solution	
Q.	Li, (b) scientific	
	ii. (c) Iconic	(i)
	iii. (d) No solution	(1)
	iv. (a) linear	(11)
	(v. (b) Distribution model	(1)
	VI. (c) two smallest vii. (d) assignments	(1)
	vin·(c) total elapsed	(1)
	(x. (a) Predecessor	(1)
	X. (d) Oll of the above	(1)
9.2	i 1. Mathematical models, which are essence	
	of Orkado not take into account quali-	(1)
	of Orkado not take into account quali- tative factors or enrotional factors which are quite real.	
	are quite real.	
	2. OR models are applicable to only specific	1+19
	category of problems	~)
	3. OK techniques are usually very expensive	1213
	3. OR techniques are usually very expensive as they require services of specialised	()
	persons and computers.	
	4. Many OR techniques having extremalia	
	4. Many OR techniques having extremely lengthy techniques/computations to	(+1)
	solve any mathematical problem	
	Note: Student may write other limitations	

(ii) some of the areas of night. Where OR tech- 13 (2) niques have been successfully applied any as below: 1. Marketing: a) selection of advertising media planning b.) Sales effort allocation () Optimum policies for marketing. (2)2. Personnel Mgmt.:a) selection of personnel b) Determination of retirement age c) Wages administration d) Scheduling of training pgmis (+2)3. Finance/Accounting: -9.) Capital requirement 6) Cash flow analysis C) Profit plans (+2)a) Capital Budgeting (Note: Student may write other key areas, may explain the key points & also may give examples) (iii) The most important feature en O.R. Q 2 is use of scientific method. There are (OR) three major phases of scientific method on which or practise is based. (2) 1) Judgement Phase: This phase include a) i'dentification of real-life problem 6.) delection of an appropriate objective () formulation of the problem etc. 2) Research phase: - This phase includes (+2) a.) formulation of hypothesis, b) analysis quipo etc. 3.) Action Phase: consist of recomendations for declaranteté (Chidout chould explain the Useon Alasa I man adende

Q. 3	(i) Let x_1, x_2, x_3 be the no. of units of phoduct A, B, C resp. 8. t · these quantities maximizer	Pg 3
×	the profit. .: Decision variables are x_1, x_2, x_3 Required LPP is:- Objective func": Max $z = 3x_1 + 2x_2 + 4x_3$	(1)
	subject to constraints $4x_1 + 3x_2 + 5x_3 \le 2000$ $2x_1 + 2x_2 + 4x_3 \le 2500$	
	$100 \le x_1 \le 150$ $x_2 > 200$	(1.0)
	$x_3 > 50$ & Non-negativity $x_1, x_2, x_3 > 0$.	(+2)
Q-3	(Li) Replacing all inequalities of the constraints	(d1)
	$5x_1 + 4x_2 = 60$ if $x_1 = 0 \Rightarrow x_2 = 15$ i.e. point $(0,15)$ if $x_2 = 0 \Rightarrow x_1 = 12$ i.e. point $(12,0)$ Similarly in $3x_1 + 7x_2 = 84$, points are $(28,0)(0,12)$ 4 in $x_1 + 2x_2 = 18$, points are $(18,0)$, $(0,9)$ Plotting the three lines passing through above points and using the	
	12 B(3.6, 10.4) the fearible region as shown in figure. 6 32 4 6 8 10 12 14 16 18 20 22 24 26 28 2 0,000 2, 4 21,2 21,2 21,3 2 26,000 2, 4 21,2 21,2 21,3 21,3 21,3 21,3 21,3 21,3	(+2) for graph

Pg(4) The feasible region is ABCD Deternine the values of objective function z at the extreme points A, B, C&D. Z= 62+14x2 Extreme point 2 22 118 5 .8 A 168 10.4 3.6 8 148 0 28 108 + Minimum 0 D 18 Since z is to be minimized, .. the min's value of z occurs at D (18,0) Hence the optimal sol to the LPP is $x_1 = 18$, $x_2 = 0$, Z = 108 (min value) (iii) converting the given LPP into standardform Maxz: 4x, + 10x2+0s, +0.52+0.53 sub to 2x, +x2 + S1 = 10 $2x_1 + 5x_2 + S_3 = 20$ $2x_1 + 3x_2 + s_3 = 18$ std form Non-neg. 2,, 22, S1, S2, S3 7,0 $G \rightarrow$ 10 0 Basic Minm non-neg variable 1 CB1 Ratio XB/XI 1 XB ス 53 5,0 10 0 10/1 = 10 Ó S2 0 . 20 5 0 20/5 = (4) 0 53 18 2 3 18/3 = 6 0 Zj = ECBXB -10 -4 Sj=ZCBXj-Cj 0 0 0 S1 0 815 6 0 1 -1/5 0 2 10 4 2/5 0 115 0 53 0 4/5 3/50 0 1 = 2 (x x - y (+3) Zj = ECBXB +2 0 0 0 In 2nd iteration,

New R2 -> Old R2/5 New R1 -> eld R1 - 1. New R2 New R0 -> Old R2 - 7. New R2

0.3

(OR)

-	ve see that in 2nd iteration, all sis are zero or positive, so the optimal sold is	Pg (5)
,	2,=0 & 22=4 & Max Z = 4x0+10x4 = 40 Dus.	(+1)
0.4	(i) 9) Feasible sol" - A feasible sol" to a T.P.	The second section is the second
	is a set of non negative allocations x; that satisfies the rim (now & colm) restrictions	(1)
	b) Initial B. F.S> A feasible sol to a T. P. is	
	said to be I.B.F.S if it contains not more	
=	that (m+n-1) non-negative allocations, where m is no of rows & n is no of columns.	(+1)
	(3) Optimal Sol" - A jeasible sol" (not necessain	9
	basic) that minimizes (maximizes) the	
	transportation cost (profit) ès called an	(+1)
	optimal solution.	
	is said to be non-degenerate it.	
	is said to be non-degenerate it, The total no of non-negative allocations	
	is exactly m+n-1, and	
	-> these m+n-1 allocations are in indepen-	(+1)
0-	alut positions.	edate appropriate to
94	(ii) : total supply = total demand = 45. .: problem is balanced, so, By VAM	D
	Do De Quali Consensities	
	5, 5, 2 4 8 3 22/10/8 1 1 2	
	S ₂ 4 8 1 6 15/0 3 3	-
	S ₂ 4 6 7 5 8 1 1 1 1	
	Demand 7 12/0 17/2/0 9	
Ĭ.	Column 0 4* 3 2	
	Penaltier 0 - 3* 2	
	- 3 [*] 2 - 3 [*]	

Inus, By VAM, initial B.F.S & T.C. = 2 x12 + 4x2 + 3x8 + 1x15 + 4x7+6x1 = 24+8+24+15+28+5 = R1.104. Applying test of optimality by MODI method : no q occupied cells = 6 R m+n-1=6 :. I'B.F.S. is non-degenerate. Thus the test of optimality is non-degenerate. 1.) Set the cost matrix & set the nois 4; & v; (for occupied cells) s.t cij = ui + Vi uj D'2 D3 (i=1,2,3) Dy |4| = 3 (j=1, 2, 3, 4)142=0 (let vy=0) U3 = 5 V; V1=-1 == 1 V3=1 V4=0 2) Compute cij for unoccupied celle 6 4 7 3.) Compute u; +v; for unoccupied cells -1 -1 0 Since all the enteres in 6 Dij are positive or zero 4) Construct Dij = (ij - (4;+ vj) the current IBFS is optimal. Hence IBFS obtained by VAM is 9

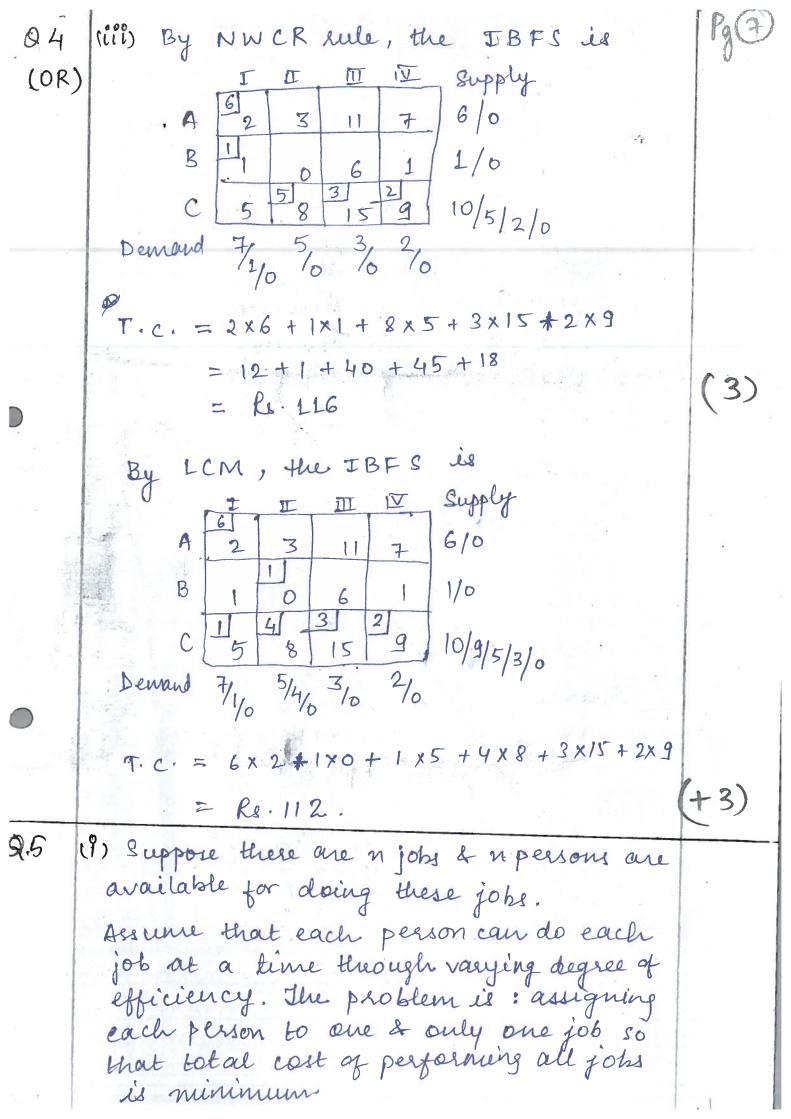
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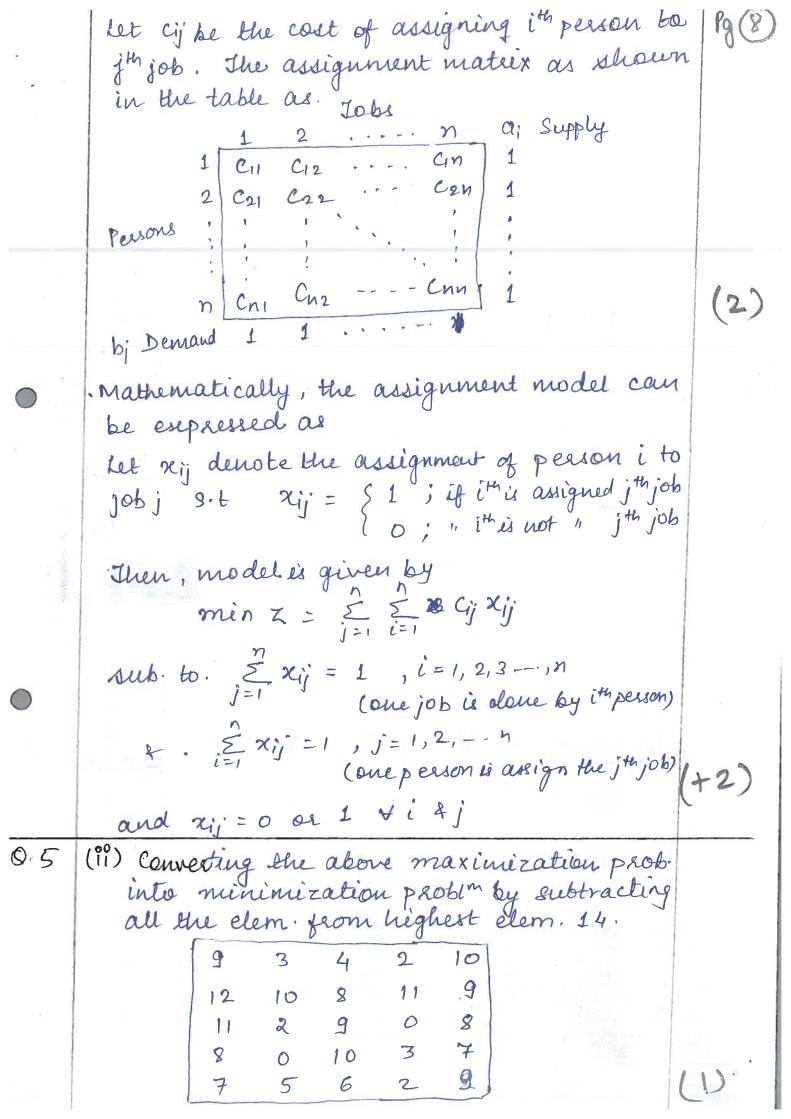
2

DW

optimal of Minm T. C.

û Rs 104





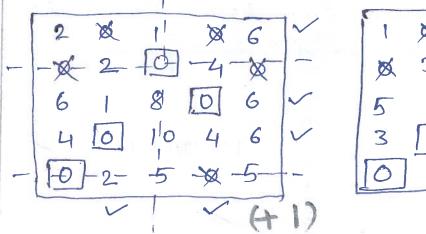
Subtracting the smallest elem. of each sow Pg(9) from all the elem.s of that sow, we have

(+1)

subtracting the smallest elem of each colm from all the elem-s of that colm & them determine an optimal assignment

(+2)

Since 3rd & 5th sow have no assignment, draw min'm no. of lines covering all zeroes (as above) as current sol is not optimal the new revised matrix is constructed by selecting the smallest elem. among all uncovelem. I subteact it from all uncovelem fadd it to the elems at intersection flines a again determine an optimal assign. I repeating the process if necessary.



1 × 0 × 5 × 3 × 50 5 1 7 0 5 3 0 9 4 5 0 3 5 1 5

(+1)

This table gives optimum assignment as 190 $1 \rightarrow C$, $2 \rightarrow E$, $3 \rightarrow D$, $4 \rightarrow B$, $5 \rightarrow A$ and $2 \rightarrow C$, $2 \rightarrow E$, $3 \rightarrow D$, $4 \rightarrow B$, $5 \rightarrow A$ and $2 \rightarrow C$, $2 \rightarrow E$, $3 \rightarrow D$, $4 \rightarrow B$, $5 \rightarrow A$ and $2 \rightarrow C$, $2 \rightarrow E$, $3 \rightarrow D$, $4 \rightarrow B$, $5 \rightarrow A$ and $4 \rightarrow C$, $4 \rightarrow C$,

Q5 (iii) The smallest processing in the given (OR) ploblem is 1 on machine A for job 2 so perform job 2 frist as shown below:

Job

Delete the job 2. 4 reduce list of processing time becomes:

Job	T.	3	4	5
machina	5	9	3	10
Machine B	2	7	8	4

Step-II: Again the smallest processing in the reduced list is 2 on somachine B for job 1. So place job 1 last in the list

Proceeding same way, the optimal job seg. is 1 3 5 4 2 i.e. (2-4-3-5-1)

computation of elapsed time:

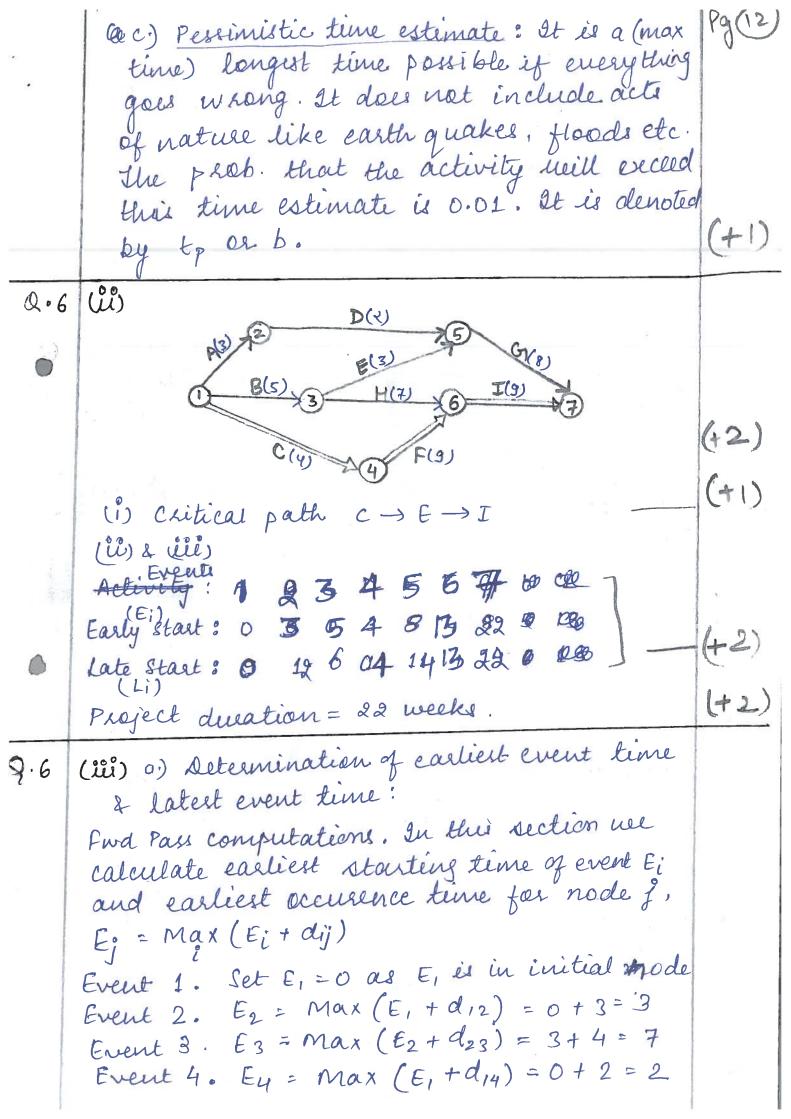
							Idl	etime	10
Jobs	det	Machine A			chine	Machin	Machin	Ī	
2003	IN	OUT		IN	OUT		A	B	I
2	0	1		1	7	(6)	0		-
4	1	4	(1+3)	7	15	(8)	0	0	
3	4	13	(9+4)	15	22	(7)	0	0	
5	13	23	(10)	23	27	(4)	0	1	
1	23	28	(5)	28	30	(2)	30-28	1	7.00
			and the second control of the second control			THE RESERVED AND ADDRESS TO A PERSON TO SERVED AND ADDRESS OF THE PERSON TO SERVED AND ADDRESS OF THE PERSON TO ADDRESS O		-	

(+2)

2 | 3 | 1

Note: A job is assign on a machine A first and after it has been completely process on machine A it is assigned to machine B. If the machine B is not free at the moment for processing the same job, the job has to get win a waiting time for its tuen on machine B i.e. passing le not allowed. Total elapsed time - The min's elaps time is the time from start up job to the ending of (+1) Last job es 30. Ideal time on machine A - It is given by 30-28 = 2 unit. ideal for 3 units (i.e. 0-1, 22-23, 27-28) (+1) (1) The three time estimates used in the context of PERT are :a) optimistic time estimate - It is the minm possible time (ideally). The optimistic time that an activity will take if everything goes well. The prob. that the time activity will take less than this time estimate is 0.01, which is every little chance that activity can be done in time less than optimistic time. It is denoted by to or(a). b) most likely time: It is a subjective estineate of most frequently time. It refers to the estimate of the normal time that conditions). In most likely time, the most realistec time available & assumes normal delays It is denoted by tm or (m). (+1)

0.6



```
Pg [3]
  Event 5 = E5 = Max(E1+d15)=0+2=2
   Event 6. E6 = Max (E4+d46, E5+d56) = Max (2+7,2+4)
                                       = Max(9,6)=9
   Event 7.
             E_7 = Max (E_4 + d_{47}) = 2 + 4 = 6

E_8 + Max (E_3 + d_{38}) = E_7 + d_{78} = Max (9,11) = 11

E_9 = Max (E_8 + d_{89}) = E_6 + d_{69}
   Event 8.
   Event 9
                = Max (11+3, 9+6)
                 = Max (14,15) = 15
                                                     - (2.5)
  Backward Pass Computation: in this section
  we calculate, the latest finish time &
  latest start time. The latest time for an
  event i is given by
          Li = Min (1; -dij)
  Event 9. set Lg = Eg = 15.
  Event 8. Lg = Min (Lg-dgg) = 15-3=12
  Event 7. L7 = min (18-d78) = 12-5=7
  Event 6. 16 = Min (Lg - d69) = 15-6 = 9
  Event 5. Ls = Min (L6 - d56) = 9-4=5
  Event 4. L4 = L4 = Min (L6 - d46, L7 - d47)
                 = Min (9-7, 7-4) = Min (2,3) = 2
 Event 3. L3 = Min (L8 -d38) = 12-2=10
 Event 2. L2 = Min (L3 - d23) = 10-4=6
Event 1. L, = Min (12-d12, 64-d14, 65-d15)
                                                   (2.5)
           E_{2}=3=N \text{Lin} (6-3,2-2,5-2)=0
                             (HO) E8=11
6=9
                                     K(3)
                 GC4)
                         L6=9
```

The critical path shown by double line in the figure is the largest path through the network. The critical path is 1-4-6-9 for which E-v alues are equal to L-v alues i.e. $E_1=L_1$, $E_4=L_4$, $E_6=L_6$, $E_9=L_9$.

(+2)