
Special Lecture

— Dimensionality Reduction, PCA, —
EigenFaces

Higher Dimensional Visualisation



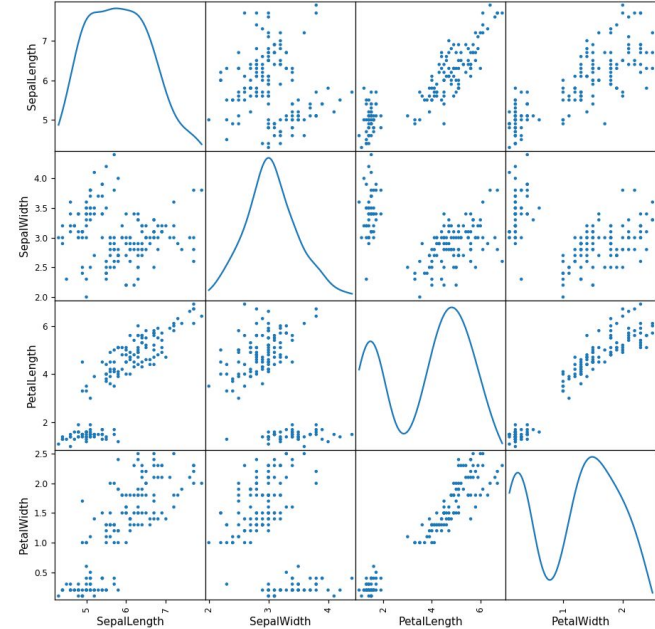
Visualisation

- Select effective *visual encodings* to map data values to graphical features
- Features such as position, size, shape, and color.
- Challenge :
 - for any given data set the number of visual encodings is extremely large

Higher Dimensional Visualization Techniques

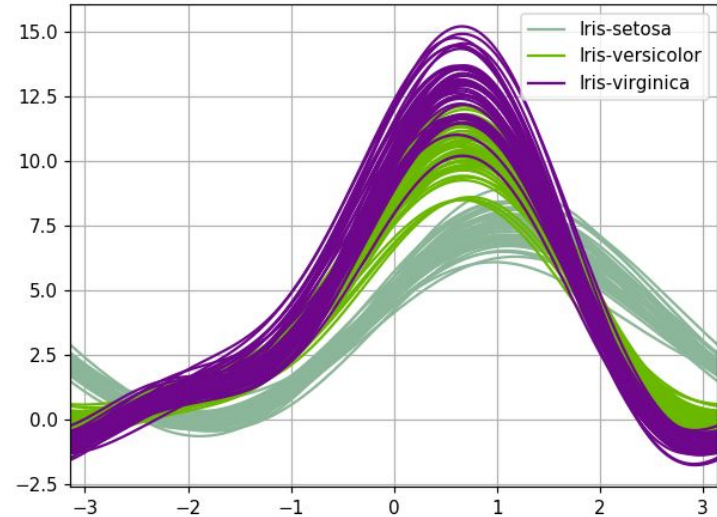
Scatter Plot

- A Scatter plot displays the correlation between a pair of variables
- These scatter plots (nC_2 pairs) can be organized into a matrix, making it easy to look at all pairwise correlations in one place



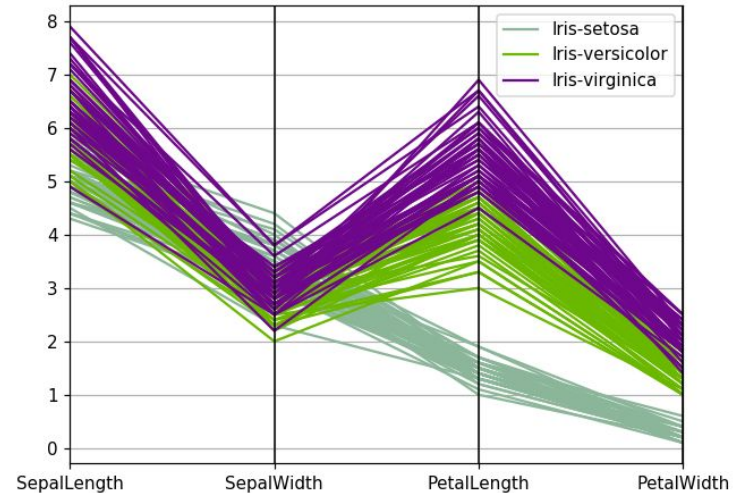
Andrew Plot

- An Andrews plot is a graphical data analysis technique for plotting multivariate data.
- An Andrews curve applies the following transformation to a set of data
 - $F(t) = X_1/\sqrt{2} + X_2\sin(t) + X_3\cos(t) + X_4\sin(2t) + X_5\cos(2t) + \dots$
 - Where $-\pi < t < \pi$



Parallel coordinates Plot

- Parallel coordinates is a visualization technique used to plot individual data elements across many dimensions
- Each of the dimensions corresponds to a vertical axis
- Each data element is displayed as a series of connected points along the dimensions/axes



Reducing Dimensions to visualize

- Feature Selection :
 - Choose the "best" features from your data, which you then visualize
- Feature Extraction :
 - Initial set of measured data and builds derived features intended to be informative and non-redundant, facilitating

Selecting Features as Matrix Multiplication

- Selecting first and third feature
- Selecting first and fourth feature

$$\begin{bmatrix} x_1 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$
$$\begin{bmatrix} x_1 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

$$X' = AX$$

Selecting Features as Matrix Multiplication

- A “new” set of features are selected/extracted from original one by a matrix multiplication.
- Rows of **A** decide what the new features are. (They need not be 0 and 1)
- Often rows of **A** is smaller than column of **A**. This is also called **dimensionality reduction**.

Feature Selection and Extraction

- Selection:
 - Select some features out of a pool
 - (Simple A with 0/1)
- Extraction:
 - Extract a set of new features
 - (elements of A need not be 0/1)

Feature Selection and Extraction

Extraction is often required:

- To visualize in 2D/3D.
- To remove some “useless” or “less useful” features.
- Make computations efficient

(Note: original data could be 1000s of dimension!!)

Principal Component Analysis

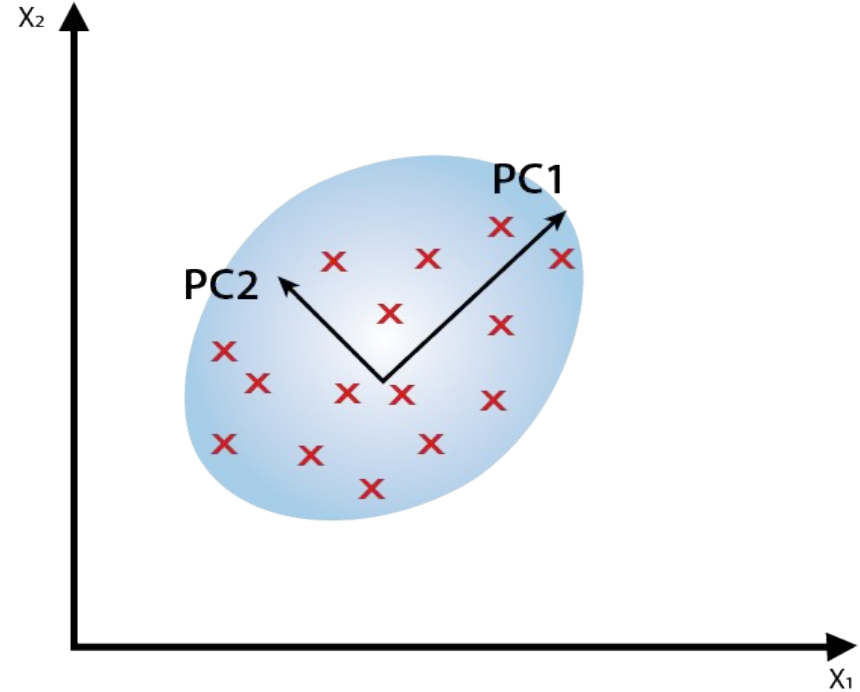
— Simplifying Representations —

Outline

- What is Principal Component Analysis
- PCA based feature extraction
- Projection of point to a line
- PCA and Covariance Matrix

Principal Component Analysis

- PCA is used to reduce the dimensionality of data



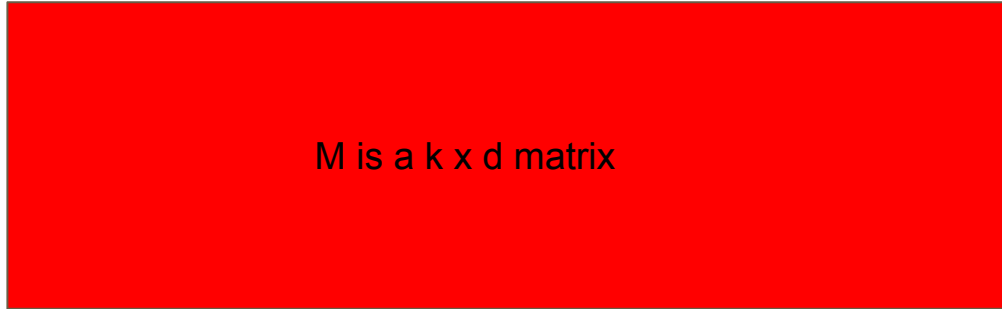
PCA based Feature Extraction

$K \times 1$



=

M is a $k \times d$ matrix



$d \times 1$

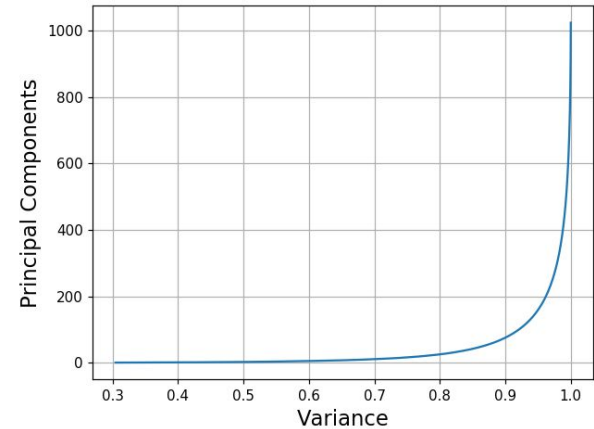


PCA based Feature Extraction

- Let \mathbf{X}_i be an image represented as column vector
- Let $\mathbf{X} = [x_1, x_2, \dots, x_N]$ be a zero mean matrix of size $d \times N$
- Let $A = \mathbf{X}\mathbf{X}^T$ be a $d \times d$ Matrix. It also has d eigen vectors each of d dimensions.
- Row of matrix " \mathbf{M} " are the selected K Eigenvectors of the matrix \mathbf{A} .

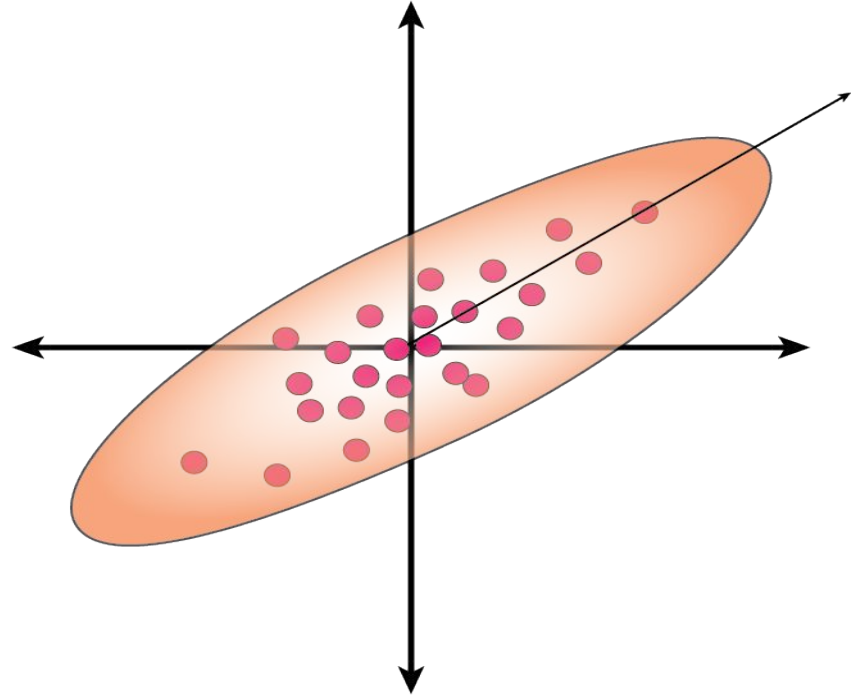
PCA based Feature Extraction

- Plot Principal components vs Variance retained
- Usually a small number of Principal components are enough to retain the variance considerably
- Most of them are near zero or even zero
 - Eg: $K = 500$ $r = 0.9$



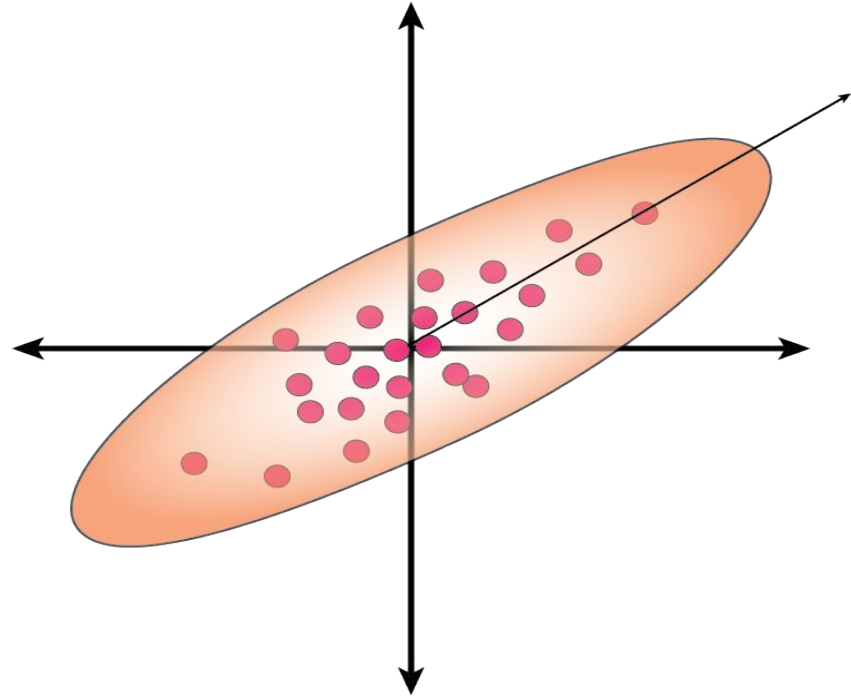
Projection of Point to a Line

- Consider a line through origin
 - Vector along the line
- What does dot product mean?
- Dot product with which vector?



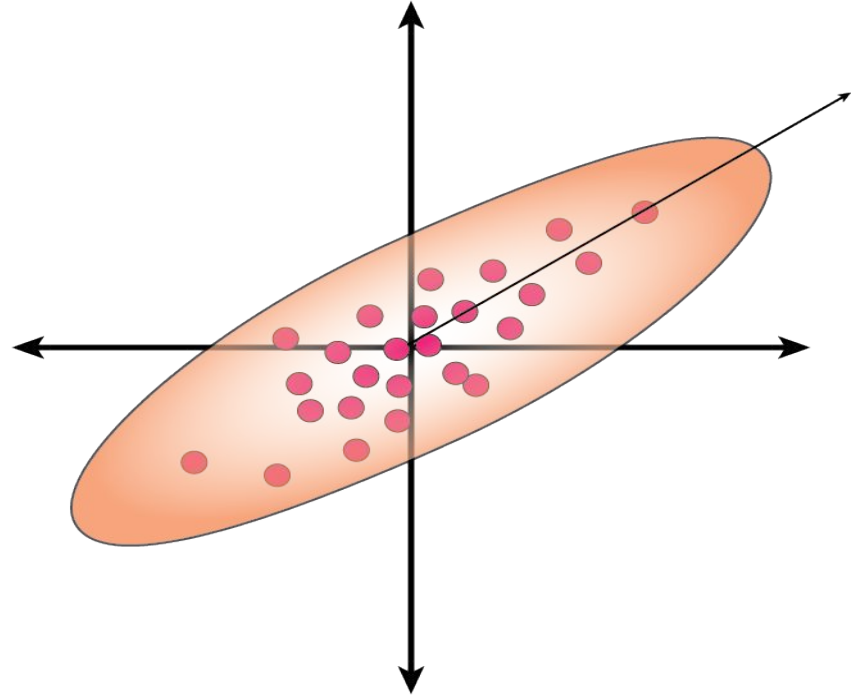
Projection of Point to a Line

- Vector along the line or line coefficients?
 - We consider dot product with vector along the line here
 - We talked about dot product with coefficients



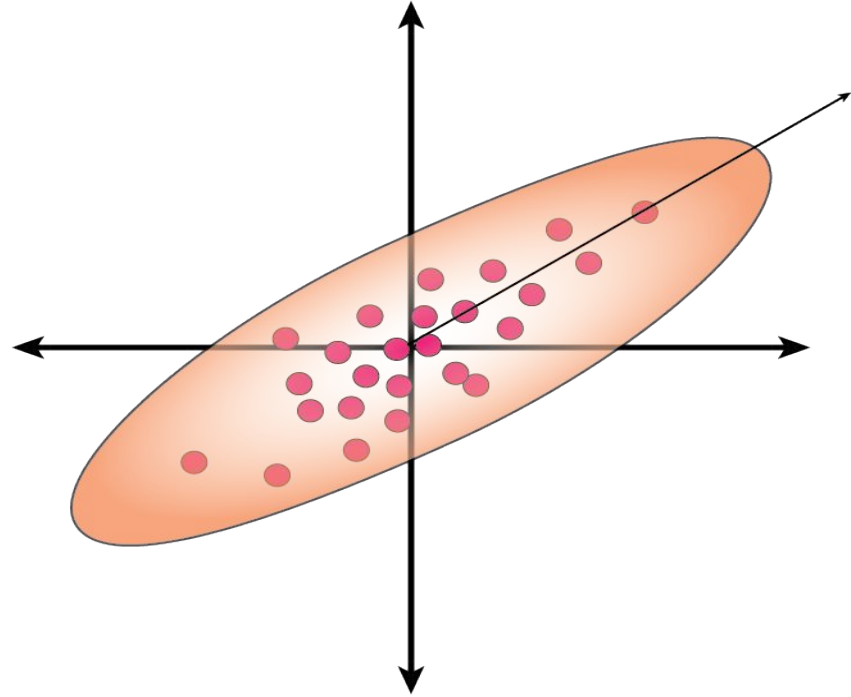
PCA and Covariance Matrix

- Going to 2D to 1D
- Which feature to select ?
 - This may be any feature(or vector in any direction)



PCA and Covariance Matrix

- Two viewpoints:
 - Maximize variance
 - Minimize error



PCA and Covariance Matrix

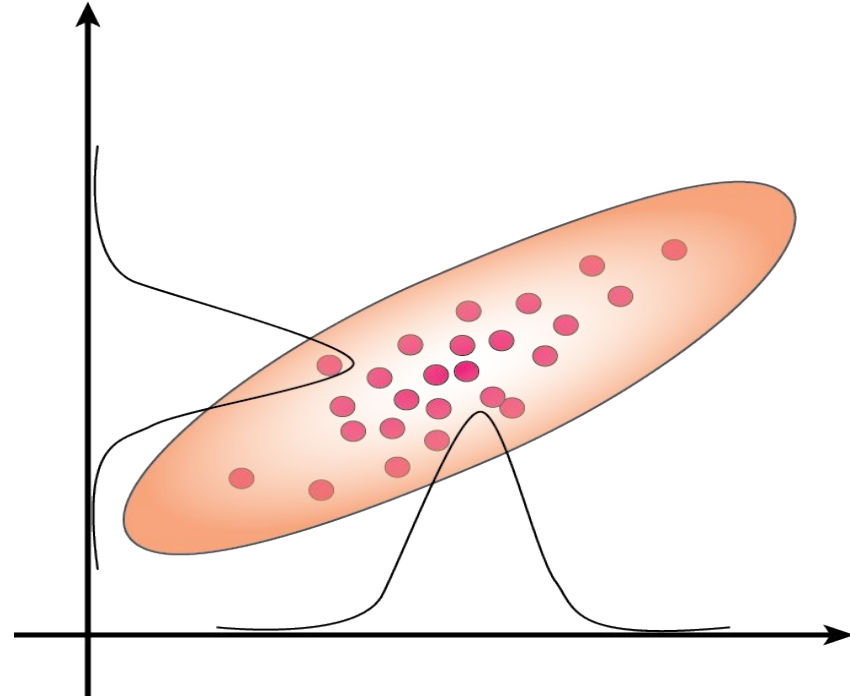
- Solution to both happens to be :

$$Ax = \lambda x$$

- What is A? How do we solve this?

PCA and Covariance Matrix

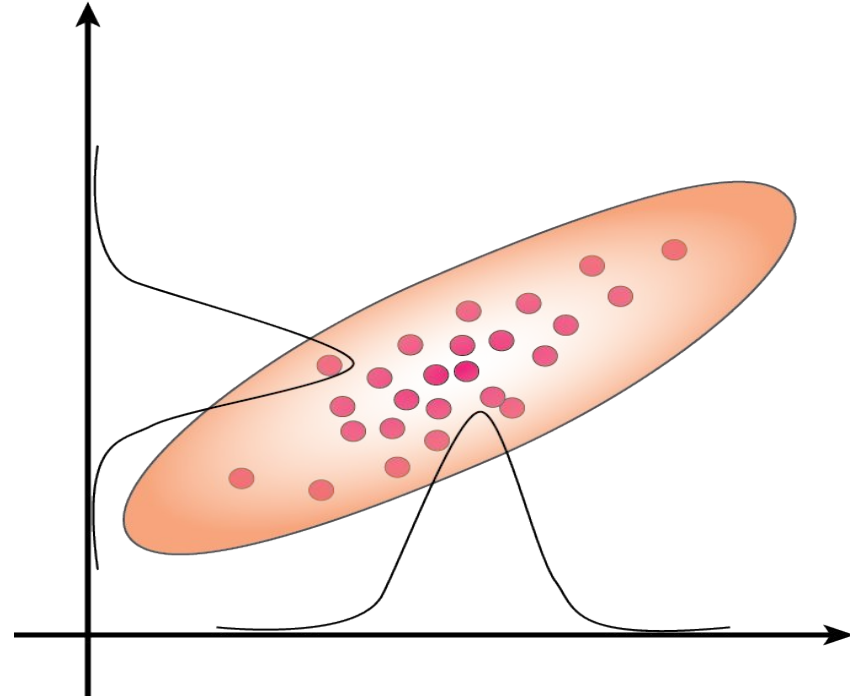
- We have variances along each dimension
- The samples also co-vary.
i.e, features are not independent



PCA and Covariance Matrix

- Captured using a covariance matrix

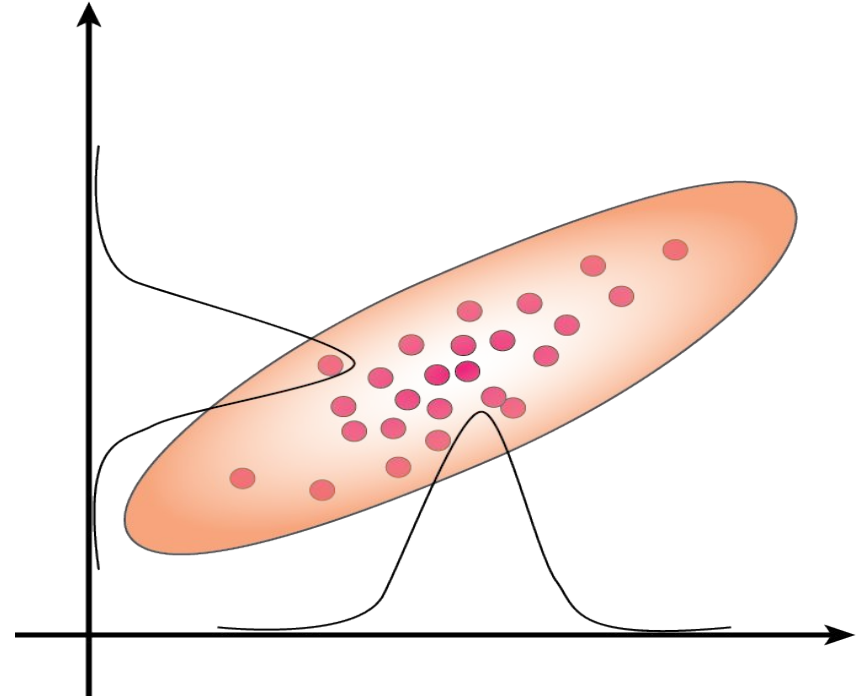
$$\begin{bmatrix} V_a & C_{a,b} & C_{a,c} & C_{a,d} & C_{a,e} \\ C_{a,b} & V_b & C_{b,c} & C_{b,d} & C_{b,e} \\ C_{a,c} & C_{b,c} & V_c & C_{c,d} & C_{c,e} \\ C_{a,d} & C_{b,d} & C_{c,d} & V_d & C_{d,e} \\ C_{a,e} & C_{b,e} & C_{c,e} & C_{d,e} & V_e \end{bmatrix}$$



PCA and Covariance Matrix

$$\hat{\mu} = \frac{1}{N} \sum_{i=1}^N x_i$$

$$\hat{\Sigma} = \frac{1}{N} \sum_{i=1}^N (x_i - \hat{\mu})(x_i - \hat{\mu})^T$$



Likelihood Function

$$N(x, \mu, \sigma) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

Becomes

$$N\left(x, \mu, \Sigma\right) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} e^{-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)}$$

Challenge of Data

$$\begin{bmatrix} V_a & C_{a,b} & C_{a,c} & C_{a,d} & C_{a,e} \\ C_{a,b} & V_b & C_{b,c} & C_{b,d} & C_{b,e} \\ C_{a,c} & C_{b,c} & V_c & C_{c,d} & C_{c,e} \\ C_{a,d} & C_{b,d} & C_{c,d} & V_d & C_{d,e} \\ C_{a,e} & C_{b,e} & C_{c,e} & C_{d,e} & V_e \end{bmatrix}$$

- 1-dim had 2 parameters to estimate
- d-dim will have not just 2d, but over $d^2/2$ parameters.

Thanks!

Questions?

EigenFaces

Face Recognition

Problem Statement

Step 0: Preprocess to

224 X 224 or 50716 X 1

Recognize Indian celebrities

- 10 Classes
- 20 Example each(15 for training and 5 for testing;No colour)



Representations

- Eigen faces(classic)
- VGG Deep Net Features(Modern)

Eigen Face : Visualisation

Mean of all faces



Top 20
EigenVectors(EigenFaces)



EigenFace Feature



X

- Any face in the database can be accurately represented as a linear combination of these 20 eigen faces.



$$x = a_1e_1 + a_2e_2 + \dots + a_{20}e_{20}$$

Thanks!

Questions?