Practical no 1 Code

BFS:-checked working

```
# Python3 Program to print BFS traversal
# from a given source vertex. BFS(int s)
# traverses vertices reachable from s.
from collections import defaultdict
# This class represents a directed graph
# using adjacency list representation
class Graph:
 # Constructor
def___init (self):
    # default dictionary to store graph
    self.graph = defaultdict(list)
 # function to add an edge to graph
 def addEdge(self,u,v):
    11 11 11
    :rtype: object
    self.graph[u].append(v)
 # Function to print a BFS of graph
 def BFS(self, s):
    # Mark all the vertices as not visited
    visited = [False] * (max(self.graph) + 1)
    # Create a queue for BFS
    queue = []
    # Mark the source node as
    # visited and enqueue it
    queue.append(s)
   visited[s] = True
    while queue:
       # Dequeue a vertex from
```

```
# queue and print it
           s = queue.pop(0)
           print (s, end = " ")
           # Get all adjacent vertices of the
            # dequeued vertex s. If a adjacent
            # has not been visited, then mark it
            # visited and enqueue it
           for i in self.graph[s]:
                if visited[i] == False:
                     queue.append(i)
                     visited[i] = True
# Driver code
# Create a graph given in
# the above diagram
g = Graph();
n=int(input("Enter total no of edges in graph"))
for i in range (0,n):
 u=int(input("Enter starting vertex: "))
 v=int(input("Enter ending vertex: "))
 g.addEdge(u, v)
s=int(input("Enter Starting point for traversing in the graph: "))
g.BFS(s)
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      # Python3 Program to print BFS traversal
                                                                                                             A1 A50 ×1 ^ v
       # traverses vertices reachable from s.
      from collections import defaultdict
      # This class represents a directed graph
        # using adjacency list representation
       class Graph:
                                                                                                                        def __init__(self):
          # default dictionary to store graph
  14
           self.graph = defaultdict(list)
  Run: 😎 main
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  Enter total no of edges in graph4
Enter starting vertex: 0
Enter ending vertex: 1
  Enter starting vertex: 1
 Enter starting vertex: 2
        Enter ending vertex: 6
        Enter starting vertex: 2
        Enter ending vertex: 3
        Enter Starting point for traversing in the graph: \theta
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DFS:-

```
# Python3 program to print DFS traversal
# from a given given graph
from collections import defaultdict
# This class represents a directed graph using
# adjacency list representation
class Graph:
# Constructor
def init (self):
# default dictionary to store graph
self.graph = defaultdict(list)
# function to add an edge to graph
def addEdge(self, u, v):
self.graph[u].append(v)
# A function used by DFS
def DFSUtil(self, v, visited):
# Mark the current node as visited
# and print it
print(v, end=' ')
# Recur for all the vertices
# adjacent to this vertex
for neighbour in self.graph[v]:
if neighbour not in visited:
self.DFSUtil(neighbour, visited)
# The function to do DFS traversal. It uses
# recursive DFSUtil()
def DFS(self, v):
# Create a set to store visited vertices
visited = set()
```

```
# Call the recursive helper function
# to print DFS traversal
self.DFSUtil(v, visited)

# Driver code

g = Graph()

n = int(input("Enter total no of edges"))
for i in range(0, n):
    u = int(input("Enter start vertex: "))
    v = int(input("Enter end vertex: "))
    g.addEdge(u, v)
    g.addEdge(v, u)

g.DFS(int(input("Enter the starting vertex: ")))
```

```
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Enter end vertex: 2
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```

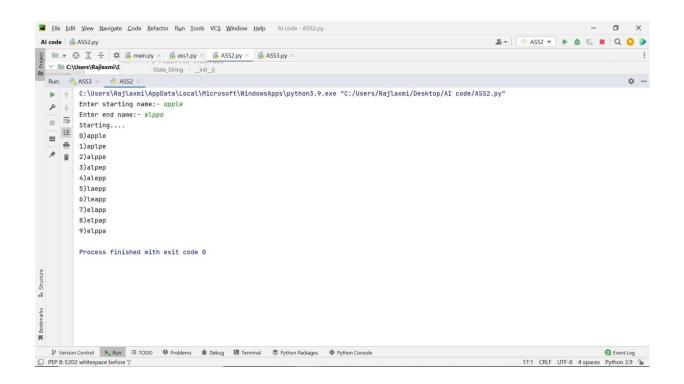
Practical no 2 Code

A-Star Algorithm Python Tutorial - An Introduction To A* Algorithm In Python (simplifiedpython.net)

A* algorithm:-

```
from queue import PriorityQueue
#Creating Base Class
class State(object):
   def init (self, value, parent, start = 0, goal = 0):
      self.children = []
      self.parent = parent
      self.value = value
      self.dist = 0
      if parent:
           self.start = parent.start
           self.goal = parent.goal
           self.path = parent.path[:]
           self.path.append(value)
      else:
          self.path = [value]
          self.start = start
          self.goal = goal
  def GetDistance(self):
      pass
  def CreateChildren(self):
      pass
# Creating subclass
class State String(State):
  def init (self, value, parent, start = 0, goal = 0 ):
      super(State String, self). init (value, parent, start, goal)
      self.dist = self.GetDistance()
  def GetDistance(self):
           if self.value == self.goal:
               return 0
           dist = 0
           for i in range(len(self.goal)):
               letter = self.goal[i]
               dist += abs(i - self.value.index(letter))
           return dist
  def CreateChildren(self):
           if not self.children:
               for i in range(len(self.goal)-1):
```

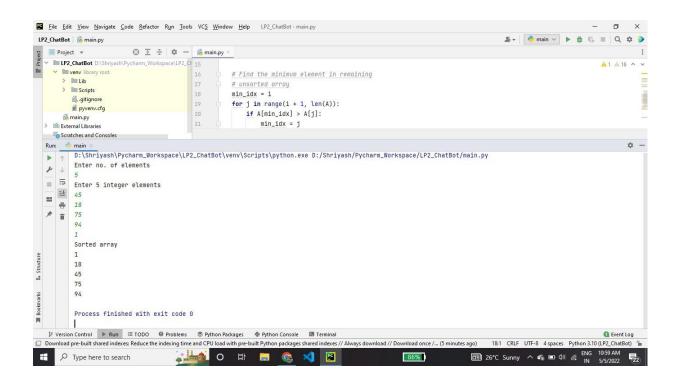
```
val = self.value
                   val = val[:i] + val[i+1] + val[i] + val[i+2:]
                   child = State String(val, self)
                   self.children.append(child)
# Creating a class that hold the final magic
class A_Star Solver:
   def___init__(self, start, goal):
       self.path = []
       self.vistedQueue =[]
       self.priorityQueue = PriorityQueue()
       self.start = start
       self.goal = goal
  def Solve(self):
       startState = State String(self.start, 0, self.start, self.goal)
       count = 0
       self.priorityQueue.put((0,count, startState))
       while(not self.path and self.priorityQueue.qsize()):
              closesetChild = self.priorityQueue.get()[2]
              closesetChild.CreateChildren()
              self.vistedQueue.append(closesetChild.value)
              for child in closesetChild.children:
                  if child.value not in self.vistedQueue:
                   count += 1
                   if not child.dist:
                      self.path = child.path
                      break
                   self.priorityQueue.put((child.dist,count,child))
       if not self.path:
           print("Goal Of is not possible !" + self.goal )
       return self.path
# Calling all the existing stuffs
if name__== " main ":
  start1 = str(input("Enter starting name:- "))
  goal1 = str(input("Enter end name:- "))
  print("Starting.....")
  a = A Star Solver(start1,goal1)
  a.Solve()
  for i in range(len(a.path)):
       print("{0}) {1}".format(i,a.path[i]))
```



Practical No 3 Code

1. Selection sort:-

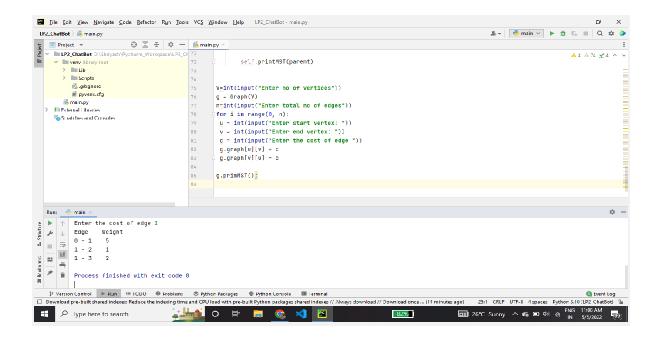
```
# Python program for implementation of Selection
# Sort
import sys
print("Enter no. of elements")
a=int(input())
print("Enter",a,"integer elements")
array=[]
for i in range(a):
  array.append(int(input()))
A=array
# Traverse through all array elements
for i in range(len(A)):
   # Find the minimum element in remaining
   # unsorted array
   min idx = i
   for j in range(i + 1, len(A)):
       if A[min_idx] > A[j]:
           min idx = j
   # Swap the found minimum element with
   # the first element
   A[i], A[min idx] = A[min idx], A[i]
# Driver code to test above
print("Sorted array")
for i in range(len(A)):
   print("%d" % A[i]),
```



2. Minimum Spanning Tree

```
# A Python program for Prim's Minimum Spanning Tree (MST) algorithm.
# The program is for adjacency matrix representation of the graph
import sys # Library for INT MAX
class Graph():
def__init__(self, vertices):
self.V = vertices
self.graph = [[0 for column in range(vertices)]
          for row in range(vertices)]
# A utility function to print the constructed MST stored in parent[]
def printMST(self, parent):
print("Edge \tWeight")
for i in range(1, self.V):
 print(parent[i], "-", i, "\t", self.graph[i][parent[i]])
# A utility function to find the vertex with
# minimum distance value, from the set of vertices
# not yet included in shortest path tree
def minKey(self, key, mstSet):
# Initialize min value
  min = sys.maxsize
for v in range(self.V):
if key[v] < min and mstSet[v] == False:</pre>
min = key[v]
     min index = v
return min index
# Function to construct and print MST for a graph
# represented using adjacency matrix representation
def primMST(self):
     # Key values used to pick minimum weight edge in cut
key = [sys.maxsize] * self.V
parent = [None] * self.V # Array to store constructed MST
# Make key 0 so that this vertex is picked as first vertex
key[0] = 0
   mstSet = [False] * self.V
  parent[0] = -1 # First node is always the root of
for cout in range(self.V):
```

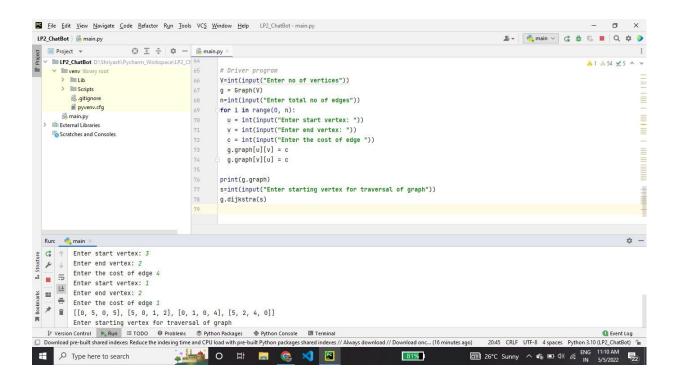
```
# Pick the minimum distance vertex from
   # the set of vertices not yet processed.
   # u is always equal to src in first iteration
      u = self.minKey(key, mstSet)
    # Put the minimum distance vertex in
      # the shortest path tree
        mstSet[u] = True
        # Update dist value of the adjacent vertices
    # of the picked vertex only if the current
      # distance is greater than new distance and
     # the vertex in not in the shortest path tree
          for v in range(self.V):
              # graph[u][v] is non zero only for adjacent vertices of m
              # mstSet[v] is false for vertices not yet included in MST
              # Update the key only if graph[u][v] is smaller than
key[v]
              if self.graph[u][v] > 0 and mstSet[v] == False and key[v]
> self.graph[u][v]:
         key[v] = self.graph[u][v]
          parent[v] = u
self.printMST(parent)
V=int(input("Enter no of vertices"))
g = Graph(V)
n=int(input("Enter total no of edges"))
for i in range(0, n):
u = int(input("Enter start vertex: "))
v = int(input("Enter end vertex: "))
c = int(input("Enter the cost of edge "))
g.graph[u][v] = c
g.graph[v][u] = c
g.primMST();
```



3. Single-Source shortest path problem

```
# Python program for Dijkstra's single
# source shortest path algorithm. The program is
# for adjacency matrix representation of the graph
class Graph():
def___init__(self, vertices):
 self.V = vertices
self.graph = [[0 for column in range(vertices)]
    for row in range(vertices)]
def printSolution(self, dist):
print("Vertex \t Distance from Source: ")
for node in range(self.V):
      print(node, "\t\t", dist[node])
# A utility function to find the vertex with
# minimum distance value, from the set of vertices
# not yet included in shortest path tree
def minDistance(self, dist, sptSet):
  # Initialize minimum distance for next node
min = 1e7
 # Search not nearest vertex not in the
# shortest path tree
for v in range(self.V):
if dist[v] < min and sptSet[v] == False:</pre>
min = dist[v]
   min index = v
   return min index
# Function that implements Dijkstra's single source
# shortest path algorithm for a graph represented
# using adjacency matrix representation
def dijkstra(self, src):
dist = [1e7] * self.V
dist[src] = 0
sptSet = [False] * self.V
for cout in range(self.V):
  # Pick the minimum distance vertex from
# the set of vertices not yet processed.
# u is always equal to src in first iteration
u = self.minDistance(dist, sptSet)
```

```
# Put the minimum distance vertex in the
# shortest path tree
sptSet[u] = True
# Update dist value of the adjacent vertices
# of the picked vertex only if the current
# distance is greater than new distance and
# the vertex in not in the shortest path tree
for v in range(self.V):
if (self.graph[u][v] > 0 and
sptSet[v] == False and
dist[v] > dist[u] + self.graph[u][v]):
   dist[v] = dist[u] + self.graph[u][v]
self.printSolution(dist)
# Driver program
V=int(input("Enter no of vertices"))
g = Graph(V)
n=int(input("Enter total no of edges"))
for i in range(0, n):
u = int(input("Enter start vertex: "))
v = int(input("Enter end vertex: "))
c = int(input("Enter the cost of edge "))
g.graph[u][v] = c
g.graph[v][u] = c
print(g.graph)
s=int(input("Enter starting vertex for traversal of graph"))
g.dijkstra(s)
```

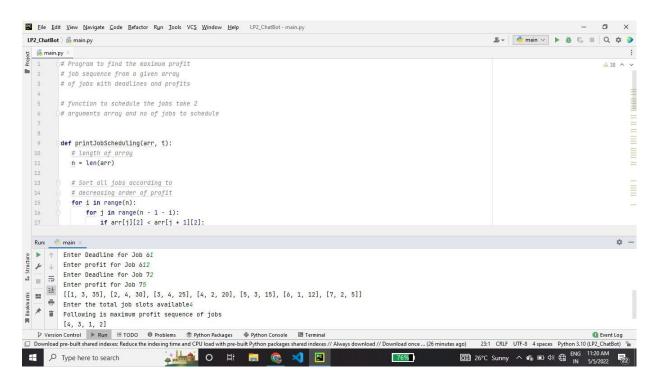


4. Job Scheduling Problems

```
# Program to find the maximum profit
# job sequence from a given array
# of jobs with deadlines and profits
# function to schedule the jobs take 2
# arguments array and no of jobs to schedule
def printJobScheduling(arr, t):
 # length of array
n = len(arr)
# Sort all jobs according to
# decreasing order of profit
for i in range(n):
for j in range (n - 1 - i):
if arr[j][2] < arr[j + 1][2]:</pre>
             arr[j], arr[j + 1] = arr[j + 1], arr[j]
# To keep track of free time slots
result = [False] * t
# To store result (Sequence of jobs)
job = ['-1'] * t
# Iterate through all given jobs
for i in range(len(arr)):
  # Find a free slot for this job
# (Note that we start from the
   # last possible slot)
   for j in range (min(t - 1, arr[i][1] - 1), -1, -1):
   # Free slot found
   if result[j] is False:
    result[j] = True
   job[j] = arr[i][0]
   break
# print the sequence
print(job)
# Driver Code
t = int(input("Enter the total no of jobs"))
arr=[]
```

```
for i in range(t):
    col = []
    col.append(i+1)
    col.append(int(input("Enter Deadline for Job "+str(i+1))))
    col.append(int(input("Enter profit for Job "+str(i+1))))
    arr.append(col)
print(arr)

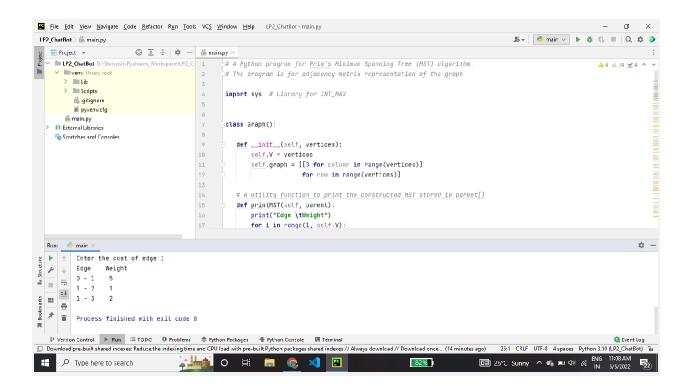
# Function Call
s=int(input("Enter the total job slots available"))
print("Following is maximum profit sequence of jobs")
printJobScheduling(arr, s)
```



5. Prim's minimal Spanning Tree Algorithm

```
# A Python program for Prim's Minimum Spanning Tree (MST) algorithm.
# The program is for adjacency matrix representation of the graph
import sys # Library for INT MAX
class Graph():
def__init__(self, vertices):
self.V = vertices
self.graph = [[0 for column in range(vertices)]
          for row in range(vertices)]
# A utility function to print the constructed MST stored in parent[]
def printMST(self, parent):
print("Edge \tWeight")
for i in range(1, self.V):
         print(parent[i], "-", i, "\t", self.graph[i][parent[i]])
# A utility function to find the vertex with
# minimum distance value, from the set of vertices
# not yet included in shortest path tree
def minKey(self, key, mstSet):
# Initialize min value
  min = sys.maxsize
for v in range(self.V):
if key[v] < min and mstSet[v] == False:</pre>
min = key[v]
     min index = v
return min index
# Function to construct and print MST for a graph
# represented using adjacency matrix representation
def primMST(self):
     # Key values used to pick minimum weight edge in cut
key = [sys.maxsize] * self.V
parent = [None] * self.V # Array to store constructed MST
# Make key 0 so that this vertex is picked as first vertex
key[0] = 0
   mstSet = [False] * self.V
  parent[0] = -1 # First node is always the root of
for cout in range(self.V):
```

```
# Pick the minimum distance vertex from
   # the set of vertices not yet processed.
   # u is always equal to src in first iteration
      u = self.minKey(key, mstSet)
    # Put the minimum distance vertex in
      # the shortest path tree
        mstSet[u] = True
        # Update dist value of the adjacent vertices
    # of the picked vertex only if the current
      # distance is greater than new distance and
     # the vertex in not in the shortest path tree
          for v in range(self.V):
              # graph[u][v] is non zero only for adjacent vertices of m
              # mstSet[v] is false for vertices not yet included in MST
              # Update the key only if graph[u][v] is smaller than
key[v]
              if self.graph[u][v] > 0 and mstSet[v] == False and key[v]
> self.graph[u][v]:
         key[v] = self.graph[u][v]
          parent[v] = u
self.printMST(parent)
V=int(input("Enter no of vertices"))
g = Graph(V)
n=int(input("Enter total no of edges"))
for i in range(0, n):
u = int(input("Enter start vertex: "))
v = int(input("Enter end vertex: "))
c = int(input("Enter the cost of edge "))
g.graph[u][v] = c
g.graph[v][u] = c
g.primMST();
```



6. Kruskal's Minimal Spanning Tree algorithm

```
# Python program for Kruskal's algorithm to find
# Minimum Spanning Tree of a given connected,
# undirected and weighted graph
from collections import defaultdict
# Class to represent a graph
class Graph:
def __init__(self, vertices):
self.V = vertices # No. of vertices
self.graph = [] # default dictionary
# to store graph
# function to add an edge to graph
def addEdge(self, u, v, w):
self.graph.append([u, v, w])
# A utility function to find set of an element i
# (uses path compression technique)
def find(self, parent, i):
if parent[i] == i:
        return i
return self.find(parent, parent[i])
# A function that does union of two sets of x and y
# (uses union by rank)
def union(self, parent, rank, x, y):
xroot = self.find(parent, x)
yroot = self.find(parent, y)
# Attach smaller rank tree under root of
# high rank tree (Union by Rank)
if rank[xroot] < rank[yroot]:</pre>
parent[xroot] = yroot
elif rank[xroot] > rank[yroot]:
  parent[yroot] = xroot
  # If ranks are same, then make one as root
# and increment its rank by one
else:
parent[yroot] = xroot
rank[xroot] += 1
```

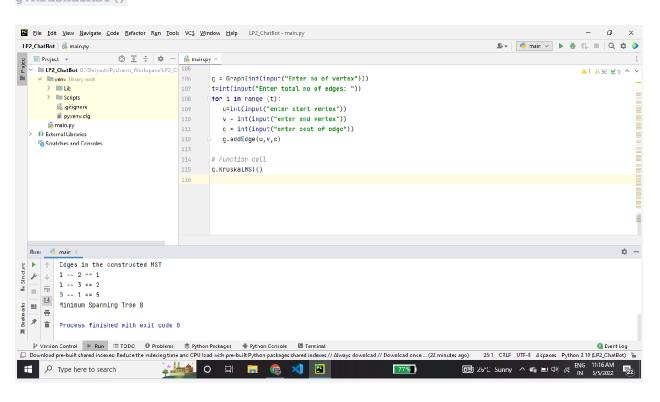
```
# The main function to construct MST using Kruskal's
# algorithm
def KruskalMST(self):
result = [] # This will store the resultant MST
# An index variable, used for sorted edges
  i = 0
# An index variable, used for result[]
  e = 0
# Step 1: Sort all the edges in
# non-decreasing order of their
# weight. If we are not allowed to change the
# given graph, we can create a copy of graph
self.graph = sorted(self.graph,
                      key=lambda item: item[2])
 parent = []
  rank = []
# Create V subsets with single elements
for node in range(self.V):
parent.append(node)
  rank.append(0)
  # Number of edges to be taken is equal to V-1
   while e < self.V - 1:</pre>
    # Step 2: Pick the smallest edge and increment
   # the index for next iteration
   u, v, w = self.graph[i]
   i = i + 1
   x = self.find(parent, u)
   y = self.find(parent, v)
    # If including this edge does't
   # cause cycle, include it in result
   # and increment the indexof result
   # for next edge
   if x != y:
    e = e + 1
   result.append([u, v, w])
   self.union(parent, rank, x, y)
  # Else discard the edge
minimumCost = 0
```

```
print("Edges in the constructed MST")
    for u, v, weight in result:
        minimumCost += weight
        print("%d -- %d == %d" % (u, v, weight))
    print("Minimum Spanning Tree", minimumCost)

# Driver code

g = Graph(int(input("Enter no of vertex")))
t=int(input("Enter total no of edges: "))
for i in range (t):
    u=int(input("enter start vertex"))
    v = int(input("enter end vertex"))
    c = int(input("enter cost of edge"))
    g.addEdge(u,v,c)

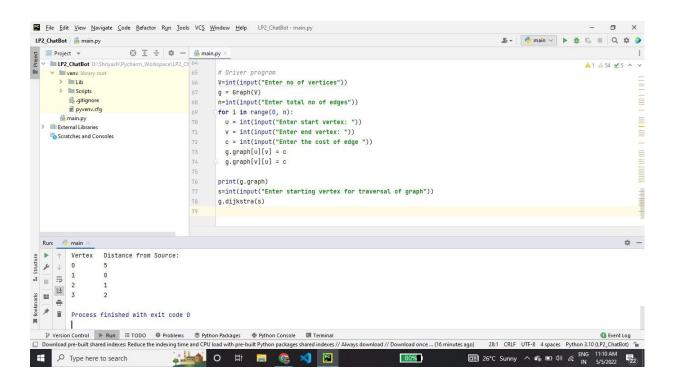
# Function call
g.KruskalMST()
```



7. Dijkstra's Shortest Path Algorithm

```
# Python program for Dijkstra's single
# source shortest path algorithm. The program is
# for adjacency matrix representation of the graph
class Graph():
def __init__(self, vertices):
self.V = vertices
self.graph = [[0 for column in range(vertices)]
    for row in range(vertices)]
def printSolution(self, dist):
print("Vertex \t Distance from Source: ")
for node in range(self.V):
      print(node, "\t\t", dist[node])
# A utility function to find the vertex with
# minimum distance value, from the set of vertices
# not yet included in shortest path tree
def minDistance(self, dist, sptSet):
  # Initialize minimum distance for next node
min = 1e7
  # Search not nearest vertex not in the
# shortest path tree
for v in range(self.V):
if dist[v] < min and sptSet[v] == False:</pre>
min = dist[v]
   min index = v
 return min index
# Function that implements Dijkstra's single source
# shortest path algorithm for a graph represented
# using adjacency matrix representation
def dijkstra(self, src):
dist = [1e7] * self.V
dist[src] = 0
sptSet = [False] * self.V
for cout in range(self.V):
  # Pick the minimum distance vertex from
# the set of vertices not yet processed.
# u is always equal to src in first iteration
u = self.minDistance(dist, sptSet)
```

```
# Put the minimum distance vertex in the
# shortest path tree
sptSet[u] = True
 # Update dist value of the adjacent vertices
# of the picked vertex only if the current
# distance is greater than new distance and
# the vertex in not in the shortest path tree
for v in range(self.V):
if (self.graph[u][v] > 0 and
sptSet[v] == False and
dist[v] > dist[u] + self.graph[u][v]):
    dist[v] = dist[u] + self.graph[u][v]
self.printSolution(dist)
# Driver program
V=int(input("Enter no of vertices"))
g = Graph(V)
n=int(input("Enter total no of edges"))
for i in range(0, n):
u = int(input("Enter start vertex: "))
v = int(input("Enter end vertex: "))
c = int(input("Enter the cost of edge "))
g.graph[u][v] = c
g.graph[v][u] = c
print(g.graph)
s=int(input("Enter starting vertex for traversal of graph"))
g.dijkstra(s)
```

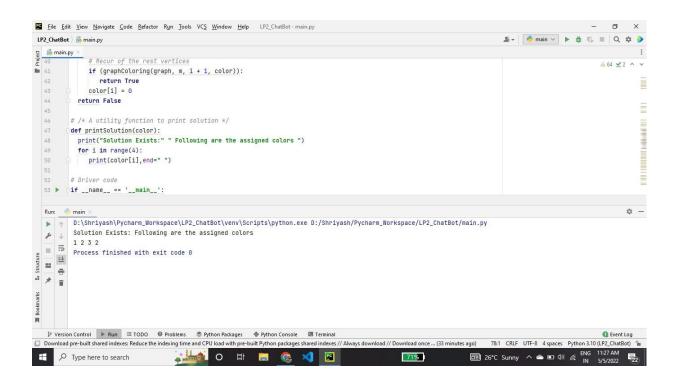


Practical No 4 Code

1. M Coloring Problem

```
# Number of vertices in the graph
# define 4 4
# check if the colored
# graph is safe or not
def isSafe(graph, color):
  # check for every edge
  for i in range(4):
     for j in range(i + 1, 4):
        if (graph[i][j] and color[j] == color[i]):
           return False
  return True
# /* This function solves the m Coloring
# problem using recursion. It returns
# false if the m colours cannot be assigned,
# otherwise, return true and prints
# assignments of colours to all vertices.
# Please note that there may be more than
# one solutions, this function prints one
# of the feasible solutions.*/
def graphColoring(graph, m, i, color):
  # if current index reached end
 if (i == 4):
     # if coloring is safe
     if (isSafe(graph, color)):
        # Print the solution
        printSolution(color)
        return True
     return False
  # Assign each color from 1 to m
  for j in range (1, m + 1):
     color[i] = j
     # Recur of the rest vertices
     if (graphColoring(graph, m, i + 1, color)):
        return True
```

```
color[i] = 0
 return False
# /* A utility function to print solution */
def printSolution(color):
 print("Solution Exists:" " Following are the assigned colors ")
  for i in range(4):
     print(color[i],end=" ")
# Driver code
if __name__ == '__main__':
  # /* Create following graph and
  # test whether it is 3 colorable
  # (3) --- (2)
  # | / |
  # | / |
  # | / |
  # (0) --- (1)
  # */
  graph = [
     [ 0, 1, 1, 1 ],
     [ 1, 0, 1, 0 ],
    [ 1, 1, 0, 1 ],
     [ 1, 0, 1, 0 ],
 m = 3 # Number of colors
  # Initialize all color values as 0.
  # This initialization is needed
  # correct functioning of isSafe()
 color = [0 for i in range(4)]
 if (not graphColoring(graph, m, 0, color)):
     print ("Solution does not exist")
```



2. N Queen Problem

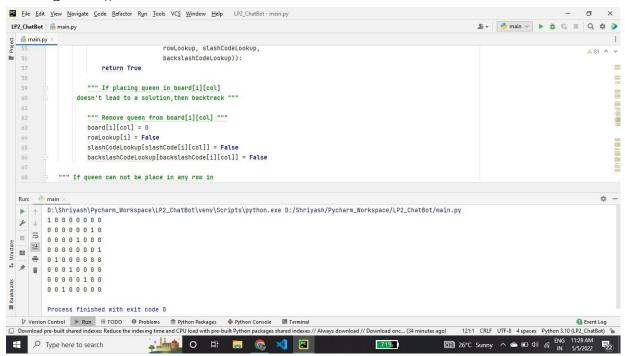
```
""" Python3 program to solve N Queen Problem
using Branch or Bound """
N = 8
""" A utility function to print solution """
def printSolution(board):
   for i in range(N):
       for j in range(N):
           print(board[i][j], end=" ")
       print()
""" A Optimized function to check if
a queen can be placed on board[row][col] """
def isSafe(row, col, slashCode, backslashCode,
          rowLookup, slashCodeLookup,
          backslashCodeLookup):
   if (slashCodeLookup[slashCode[row][col]] or
           backslashCodeLookup[backslashCode[row][col]] or
           rowLookup[row]):
       return False
   return True
""" A recursive utility function
to solve N Queen problem """
def solveNQueensUtil(board, col, slashCode, backslashCode,
                    rowLookup, slashCodeLookup,
                    backslashCodeLookup):
   """ base case: If all queens are
  placed then return True """
   if (col >= N):
       return True
   for i in range(N):
       if (isSafe(i, col, slashCode, backslashCode,
                  rowLookup, slashCodeLookup,
                  backslashCodeLookup)):
           """ Place this queen in board[i][col] """
           board[i][col] = 1
           rowLookup[i] = True
```

```
slashCodeLookup[slashCode[i][col]] = True
           backslashCodeLookup[backslashCode[i][col]] = True
           """ recur to place rest of the queens """
           if (solveNQueensUtil(board, col + 1,
                                slashCode, backslashCode,
                                rowLookup, slashCodeLookup,
                                backslashCodeLookup)):
               return True
           """ If placing queen in board[i][col]
        doesn't lead to a solution, then backtrack """
           """ Remove queen from board[i][col] """
           board[i][col] = 0
           rowLookup[i] = False
           slashCodeLookup[slashCode[i][col]] = False
           backslashCodeLookup[backslashCode[i][col]] = False
   """ If queen can not be place in any row in
  this column col then return False """
   return False
""" This function solves the N Queen problem using
Branch or Bound. It mainly uses solveNQueensUtil() to
solve the problem. It returns False if queens
cannot be placed, otherwise return True or
prints placement of queens in the form of 1s.
Please note that there may be more than one
solutions, this function prints one of the
feasible solutions."""
def solveNQueens():
  board = [[0 for i in range(N)]
            for j in range(N)]
   # helper matrices
   slashCode = [[0 for i in range(N)]
                for j in range(N)]
  backslashCode = [[0 for i in range(N)]
                    for j in range(N)]
   # arrays to tell us which rows are occupied
  rowLookup = [False] * N
   # keep two arrays to tell us
   # which diagonals are occupied
```

```
x = 2 * N - 1
slashCodeLookup = [False] * x
backslashCodeLookup = [False] * x
# initialize helper matrices
for rr in range(N):
    for cc in range(N):
        slashCode[rr][cc] = rr + cc
        backslashCode[rr][cc] = rr - cc + 7
if (solveNQueensUtil(board, 0, slashCode, backslashCode,
                     rowLookup, slashCodeLookup,
                     backslashCodeLookup) == False):
    print("Solution does not exist")
    return False
# solution found
printSolution(board)
return True
```

Driver Cde

solveNQueens()



Practical no 5 Code

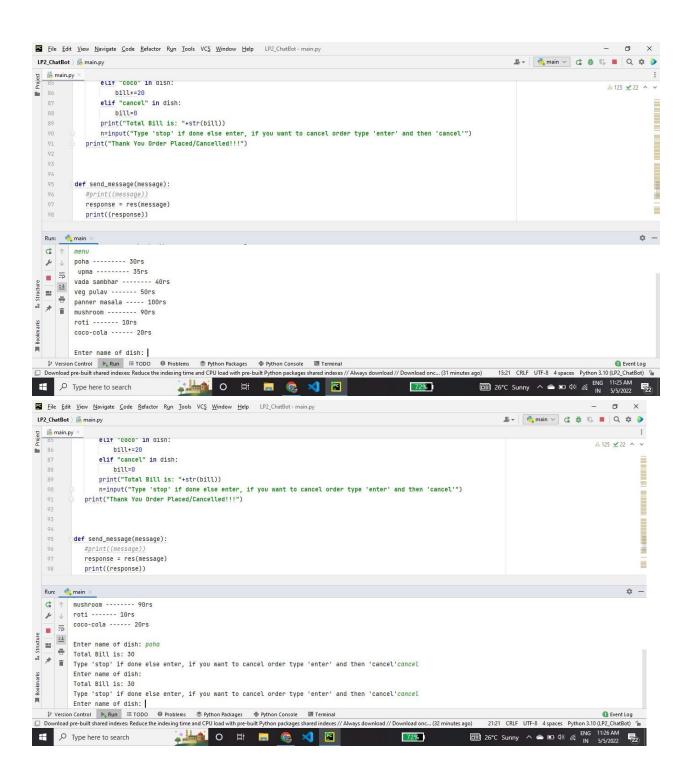
ChatBot

Simple Python chatbot

```
import random
name = "Bot 6282"
resp = {
"name": ["My name is {0}".format(name)],
"deliver": [
"Currently due to covid-19 we only provide parcel delivery services
through zomato/swiggy.",
"Yeah we are soon looking to open an outlet nearest to you, but for now
we only have parcel service. ",
"Sorry only parcel service is available.",
"Our kitchen is situated near aissms college, pune , only parcel service
available."],
"safety": [
"Don't worry our food is 100% safe.",
"We are currently ranked A+ in food safety.",
"Don't worry, Your food is prepared with all safety measures.", ],
"menu":[
"poha ----- 30rs\n "
"upma ----- 35rs\n"
"vada sambhar -----40rs\n"
"veg pulav-----50rs\n"
"panner masala ----- 100rs\n"
"mushroom -----90rs\n"
"roti -----10rs\n"
"coco-cola-----20rs\n",
],
шш: Г
"I'm Sorry i didn't understand can u please enter valid keywords.",
"What do you mean by these?, please enter valid keywords.",
"OOps!! can u please enter valid keywords."],
"default": ["This is a default message"] }
```

```
def res(message):
if message in resp:
bot286 message = random.choice(resp[message])
bot286 message = random.choice(resp["default"])
return bot286 message
def real(xtext):
if "safety" in xtext:
ytext = "safety"
elif "secure" in xtext:
ytext ="safety"
elif "kitchen" in xtext:
ytext ="safety"
elif "deliver" in xtext:
ytext = "deliver"
elif "address" in xtext:
ytext = "deliver"
elif "name" in xtext:
ytext = "name"
elif "menu" in xtext:
ytext ="menu"
else:
ytext = ""
return ytext
def calculatebill():
n="start"
bill=0
while (n!="stop") :
dish= input("Enter name of dish: ").lower()
if "poha" in dish:
bill+=30
elif "upma" in dish:
bill+=35
elif "vada" in dish:
bill+=40
elif "veg" in dish:
bil1+=50
elif "panner" in dish:
bil1+=100
elif "mushroom" in dish:
bil1+=90
elif "roti" in dish:
bill+=10
elif "coco" in dish:
 bill+=20
```

```
elif "cancel" in dish:
bill=0
print("Total Bill is: "+str(bill))
n=input("Type 'stop' if done else enter, if you want to cancel
order type 'enter' and then 'cancel'")
print("Thank You Order Placed/Cancelled!!!")
def send message(message):
#print((message))
response = res(message)
print((response))
if (message=="menu"):
calculatebill()
print("Hi there, My name is {0} \n "
"Welcome to Dhawalikar Pure Veg Restaurant \n"
"How may i assist you, type 'menu' for referring our Menu-Card
".format(name))
while 1:
my input = input()
my_input = my_input.lower()
related text = real(my input)
send message(related text)
if my_input == "exit" or my_input == "stop":
print("BOT: GoodBye!!!")
break
```



Practical No 6 Code

```
go:-
hypothesis(Disease),
write('I believe that the patient have'),
write(Disease),
nl,
write('TAKE CARE'),
undo.
/*Hypothesis that should be tested*/
hypothesis(cold):-cold,!.
hypothesis(flu) :- flu, !.
hypothesis(typhoid) :- typhoid, !.
hypothesis(measles):- measles,!.
hypothesis(malaria):- malaria,!.
hypothesis(unknown). /* no diagnosis*/
/*Hypothesis Identification Rules*/
cold:-
verify(headache),
verify(runny_nose),
verify(sneezing),
verify(sore throat),
write('Advices and Sugestions:'),
nI,
write('1: Tylenol/tab'),
nI,
write('2: panadol/tab'),
write('3: Nasal spray'),
write('Please weare warm cloths Because'),
nl.
flu:-
verify(fever),
verify(headache),
verify(chills),
verify(body ache),
write('Advices and Sugestions:'),
nl,
write('1: Tamiflu/tab'),
nl,
write('2: panadol/tab'),
nI,
write('3: Zanamivir/tab'),
nl,
write('Please take a warm bath and do salt gargling Because'),
nl.
typhoid:-
verify(headache),
verify(abdominal_pain),
verify(poor_appetite),
verify(fever),
write('Advices and Sugestions:'),
```

```
nl,
write('1: Chloramphenicol/tab'),
write('2: Amoxicillin/tab'),
nI,
write('3: Ciprofloxacin/tab'),
write('4: Azithromycin/tab'),
nI,
write('Please do complete bed rest and take soft Diet Because'),
nl.
measles:-
verify(fever),
verify(runny_nose),
verify(rash),
verify(conjunctivitis),
write('Advices and Sugestions:'),
write('1: Tylenol/tab'),
nl,
write('2: Aleve/tab'),
write('3: Advil/tab'),
nl,
write('4: Vitamin A'),
write('Please Get rest and use more liquid Because'),
nl.
malaria:-
verify(fever),
verify(sweating),
verify(headache),
verify(nausea),
verify(vomiting),
verify(diarrhea),
write('Advices and Sugestions:'),
nl,
write('1: Aralen/tab'),
nl,
write('2: Qualaquin/tab'),
nl,
write('3: Plaquenil/tab'),
nI,
write('4: Mefloquine'),
write('Please do not sleep in open air and cover your full skin Because'),
/* how to ask questions */
ask(Question):-
write('Does the patient have following symptom:'),
write(Question),
write('?'),
```

```
read(Response),
nI,
((Response == yes; Response == y)
assert(yes(Question));
assert(no(Question)), fail).
:- dynamic yes/1,no/1.
/*How to verify something */
verify(S):-
(yes(S)
true;
(no(S)
->
fail;
ask(S))).
/* undo all yes/no assertions*/
undo :- retract(yes(_)),fail.
undo :- retract(no(_)),fail.
undo.
/*Output*/
```

