

Karki Anurag

Cincinnati, Ohio, USA

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Summary

- Strong foundation in Finite Element Analysis (FEA) for structural, modal, and thermal simulations
- Skilled in Python, MATLAB, ROS2, and microcontroller integration for intelligent system design
- Experienced in collaborative projects applying neural networks, SOMs, and regression models
- Proficient in 3D modeling, simulation workflows, and CAD-to-physical prototyping

Education

University of Cincinnati

Cincinnati, Ohio

MS in Mechanical Engineering

Aug 2024 - Apr 2026

- Fall 2024 student
- Courses taken: Decision Engineering, Industrial AI, Intelligent System, Robot Control and design

Tribhuvan University

Lalitpur, Nepal

Bachelor in Mechanical Engineering

Nov 2017 - July 2022

- Elective Courses taken: Advance Mechanical Design, Mechanical Design & Simulation, Operation Research

Work Experience

National Innovation Center Nepal

Kathmandu, Nepal

Mechanical Engineer

Nov 2022 - Jan 2024

- Designing 3D CAD models and assemblies of VTOL drones using SolidWorks
- Performing Finite Element Analysis (FEA) using ANSYS to evaluate structural integrity of UAV frames
- Conducting modal and thermal simulations to assess in-flight vibration and thermal management performance
- Leading end-to-end UAV prototyping using 3D printing, laser cutting, and carbon-fiber layups for functional testing
- Collaborating with electronics and AI teams to integrate sensors, avionics, and battery modules into airframes

Incubation, Innovation, and Entrepreneurship Center (IIEC)

Lalitpur, Nepal

Mechanical Engineer

Jul 2022 - Nov 2022

- Designing modular UAV components for rapid prototyping and iteration
- Modeling UAV frame structures and sensor payload mounts in SolidWorks for use in Software-in-the-Loop (SITL) and Hardware-in-the-Loop (HITL) environments
- Assisting with ROS-based test flights for navigation stack validation in simulated and physical environments

Design Projects

Shape Optimization of Blended Wing Body Vehicle

Lalitpur, Nepal

Pulchowk campus, Tribhuvan University

Jan 2021 - Feb 2022

- Conducted both aerodynamic and stability analysis of a blended-wing body (BWB) vehicle
- Optimized the shape of the planform with 23% increase in aerodynamic efficiency

Shape Optimization of Convergent-divergent Nozzle for Maximum Thrust Using SU2

Lalitpur, Nepal

Pulchowk campus, Tribhuvan University

May 2021 - Jul 2021

- Performed CFD analysis on 2D nozzle using SU2 software
- Thrust of a supersonic converging-diverging nozzle was optimized by using SU2 software

Design and fabrication of Long endurance Unmanned aerial vehicle (UAV)

Pulchowk campus, Tribhuvan University

Lalitpur, Nepal

Jul 2020 - Nov 2020

- Implemented iterative design process to come to a final design selection
- CAD modeled the entire vehicle
- Fabricated parts using 3D-printer, laser-cutter

Robotics and Automation Projects

Industrial Spray-Painting Robot Workcell Design

University of Cincinnati

Cincinnati, USA

Oct 2024 - Dec 2024

- Designed and simulated a robotic cell using ABB RobotStudio for automated spray painting of car doors
- Achieved 300% improvement in productivity with a 30-second painting cycle vs. 2 minutes manual time
- Developed AHP-based robot selection matrix and conducted cost-benefit analysis yielding <3 year ROI
- Integrated safety (light curtains), motion sensors, and real-time flow control for paint uniformity

Genetic Algorithm-based UAV Path Planning for Wildlife Monitoring

University of Cincinnati

Cincinnati, USA

Oct 2024 - Mar 2025

- Developed an automated path planning system for UAVs using a Genetic Algorithm approach
- Optimized flight paths to maximize the probability of wildlife detection
- Achieved improved performance compared to existing path planning methods

Design and Testing of Decision Support Mechanism

Pulchowk campus, Tribhuvan University

Lalitpur, Nepal

Jan 2021 - Feb 2022

- Designed a data acquisition system using Arduino and sensors
- DAS was attached to UAV and communicated using telemetry to ground station
- Decision support mechanism was built using DAS

Skills

Design skills Solidworks, XFLR5, OpenVSP

Programming skills Python, MATLAB, ROS2

Computational skills ANSYS, SU2, SIMULINK

Miscellaneous skills Linux, Latex, MS Office.

Publications

RESEARCH PAPERS

A Genetic Algorithm Approach to Persistent UAV Surveillance in Probability-Guided Wildlife Monitoring

Anurag Karki, Hem Raj Pandeya, Niraj Prasad Bhatta

An International Journal of Computing and Informatics, 2025

Aerodynamic Shape Optimization of Blended Wing Body Planform

Anurag Karki, Hem P Pandeya, Sudip Bhattra, Abhishek Karn, Aakash Sarraf

14th IOE Graduate Conference, 2023, Lalitpur, Nepal