

# Exercise Image Processing

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Sheet 6

In this exercise we cover the chapters *Nonlinear Filters*, *Geometric Transformations*, and *Structure*. The questions are small-part and can be seen as examples of potential exam problems. Also use the formulary for the exam to work through the problems.

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## Task 6.1: Nonlinear Filters

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6.1a)

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Apply non-maximum suppression to the following 3x3 neighborhood without considering orientation:

0	3	9
3	8	3
9	3	0

Draw the direction of the steepest descent. What value results from the non-maximum suppression according to Canny?

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6.1b)

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What class does the anchor point of the following Canny classification into weak (1) and strong (2) edges receive when a hysteresis filter is applied?

1	2	1
0	1	0
0	0	0

What result do you get if the anchor point was not classified as an edge?

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## Task 6.2: Geometric Transformations & Interpolation

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6.2a)

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Which coordinate transformations can be realized with an affine 2D mapping?

- ☐ Translation
- ☐ Point reflection
- ☐ Bilinear mapping
- ☐ Shear
- ☐ Axis mirroring
- ☐ Destilation

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6.2b)

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given is the following geometric transformation:

$$\begin{aligned}x' &= 1 + 2x \\ y' &= 4 - 2y\end{aligned}$$

Is the inverse mapping existent? if yes, what does the inverse mapping look like?

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6.2c)

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The table shows different types of interpolation and their properties are given. Decide which properties belong to which interpolation types.

	Nearest-Neighbor Interpolation	Bilinear Interpolation	Bikubic Interpolation
light smoothing, few artifacts			
false high frequencies are created, lots of artefacts			
high frequencies are dampened, strong smoothing			

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6.2d)

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Perform bilinear interpolation for the gray value at location  $G(6.5, 8.5)$  when the gray values  $G(6, 8)$ ,  $G(6, 9)$ ,  $G(7, 8)$ ,  $G(7, 9)$  are given as follows:

What value would you get from a nearest neighbor interpolation?

	6	7
8	6	8
9	2	4

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### Task 6.3: Gradient & Structure

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6.3a)

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Which scalar derived quantity of the Hessian matrix is invariant to rotations?

6.3b)

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Show by a short calculation that the magnitude of the 2D gradient is invariant to rotations of the coordinate system.

**Hint:** A 2D rotation by the angle  $\phi$  is given by the rotation matrix  $\mathbf{R} = \begin{bmatrix} \cos(\phi) & \sin(\phi) \\ -\sin(\phi) & \cos(\phi) \end{bmatrix}$ .