List-No.:	

Exam System Theory

Bachelor Robotics at THWS

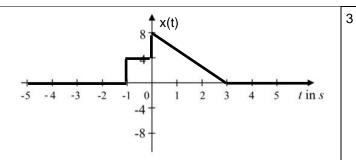
WS 2022/23

		Prof. Dr. R. Hirn
Duration:	90 minute	s
Tools: only legim		nitate calculators and the distributed formulary
Max. points:	90 pts.	(12 + 16 + 15 + 17 + 17 + 13)
Tasks:	6	(on 7 pages)
Last Name, Fi	rst Name:	
Matriculation-	No.:	
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Grade:		
First examiner:	:	
Second examin	ner:	

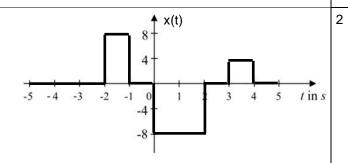
I wish you success!

Points: 12 Task 1

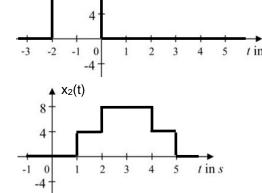
Write x(t) as a sum of elementary functions.



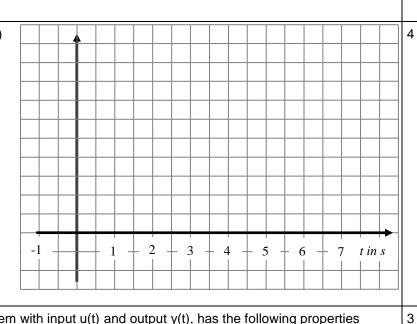
Determine the energy E_x of the signal x(t)



Sketch the convolution product of the two signals $x_1(t)$ and $x_2(t)$ (incl. correct axis labeling!).



x1(t)



Indicate with "Yes" or "No" whether the following system with input u(t) and output y(t), has the following properties (no further explainations are required).

$$y(t) = \left(u(t+2)\right)^2 + u(t)$$

Linearity:

Stability:

Causality:

if v(t-2) x it is causal

Task 2

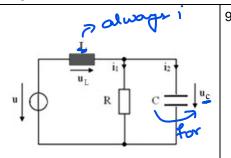
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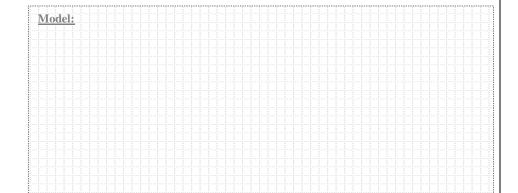
Points: 1

Required steps of modelling: 1) Determination of input variable u, state variables x_i and output variable y. 2) Determination of the coordinate systems. 3) Establishing the balance equations. 4) Isolating the derivatives of all state variables. 5) Drawing a block diagram.

The voltage source u(t) is ideal, the output shall be the voltage uc(t)!

Creat a simulationsmodel following the required steps of modelling 1 to 5.





Determine the Laplace transform X(s) of the signal: $x(t) = (t-2) \cdot e^{-(t-2)} \cdot \varepsilon(t-2)$

common shift of all so consider to

Solve this inital value problem by the tool Laplace tansform.

$$\ddot{\mathbf{x}}(t) + \mathbf{x}(t) = \delta(t)$$

$$x(0_{-}) = 3$$
 und

$$\dot{\mathbf{x}}(\mathbf{0}_{-})=1$$

Points: 15 Task 3

A non-causal system has the shown

Find the transfer function G(s) which describes this system.

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wearing policy

and the service of the service

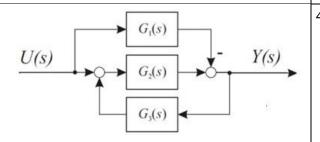
il 12200, Lovel. exter (00 (nov causal)

40 30 20 10 0 -10 -20 -30 -40 -50 -60 90 60 30 -60 90 120 -150 -180 0.01 10 1000 0.1 100 ω [1/s]

Give the transfer function of an all-pass filter with a pole at s = -2 and a pole at s = -3 and sketch its amplitude response.

(als) = 5-2 5.3 (a) 5+3

Determine the transfer function $G(s) = \frac{Y(s)}{U(s)}$ of this system.



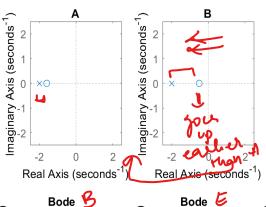
Task 4

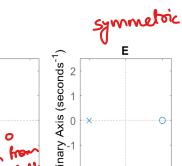


Points: 17

Above you see PZ-diagrams of five systems A to E, below five amplitude responses.

Find the pairs and fill in the correct letters below.

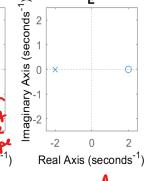




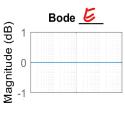


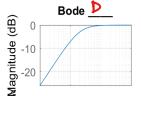
Real Axis (seconds-1) Real Axis (seconds

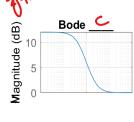
nary Axis (seconds⁻¹)

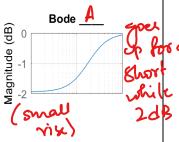


Bode 🔥 Magnitude (dB) -5

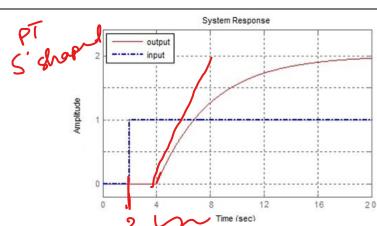








An unknown system was tested with a unit-jump. Give a transfer function, which describes this system. (Pay attention also on the dead time!).



Determine the Fourier transform of the following signal: $x(t) = \frac{3}{t^2}$

Hint: it applies: $\frac{1}{t^2} = -\frac{d}{dt} \left(\frac{1}{t}\right)$

A system with the frequency response $G(j\omega) = \frac{Y(j\omega)}{U(j\omega)} = \frac{j\omega}{j\omega+1}$ is stimulated with the following signal $u(t) = 5\sin(5t)$. Calculate and determine the expected steady-state output signal y(t).

 $A = 5\frac{5}{54} = \frac{5}{154}$

A sin (57+0)

Task 5 Points: 17

An unstable PT₁-System besitzt has the following transfer function: $G(s) = \frac{1}{s-1}$

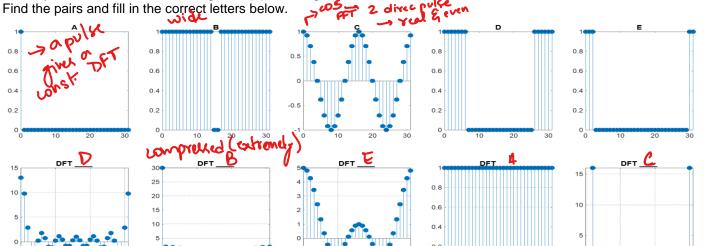
8

Using the jump invariant transformation, calculate the corresponding z-transfer function $G_{HS}(z)$ for a sampling time T = 1s.

Dustity will very small in the other

BDE - even rect. signals epectrum -, not purely but

Above you see five time discrete signals x[k] with length N = 32 labeled as A to E, below five DFTs.



Given is the following z-transfer function G(z) of time-discrete system:

 $G(z) = \frac{Y(z)}{U(z)} = \frac{2z^2+4}{z^2-2}$ - if on in the

Is this system stable?

Give the corresponding difference equation to calculate the output y[k].

(i.e. y[k] should be explicitly calculable, i.e. y[k] shall be be alone on the left side of your equation!)

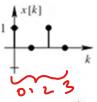
Here HUZZ

Points: 13 Task 6

A time-discrete systems has the following z-transfer function $G(z) = \frac{z+1}{z-0}$	<u>-</u> .
Give the frequency response of this system.	5

2

Above you see a signal x[k], below the definition of the DFT. Determine the second value of the corresponding DFT for the length N = 4. Hint: requested is X[1], i.e. n = 1.



What is the long form of the abbreviation FIR? Give an arbitrary transfer function that has FIR behavior.

2

2

discrete es periodic

Complete the following sentence with at least one correct mathematical statement: "The spectrum of a

non-periodic, analog and odd time signal is _

The steps 1-4 of the modelling of an electric system resulted in the following equations:

1) Input: $u = u_E$, Output: $y = u_C$, State variables: $x_1 = u_C$ and $x_2 = i_L$

$$4) \ \dot{x} = f(x, u, p):$$

4)
$$\dot{x} = f(x, u, p)$$
: $\dot{x}_1 = \frac{du_C}{dt} = \frac{1}{RC}(u_E - u_C)$ $\dot{x}_2 = \frac{di_L}{dt} = \frac{u_E}{L}$

$$\dot{x}_2 = \frac{di_L}{dt} = \frac{u_E}{L}$$

Give the state space representation (matrix-form) of this systems, i.e.:

$$\dot{x} = Ax + Bu$$

$$y = Cx + Du$$

The state space vector is predefined and shall be: $x = \begin{bmatrix} u_c \\ i \end{bmatrix}$