

## Course „Control Systems 2 “

## Solution to Exercise Sheet 5

### Task 15

a) The transformation is regular if the transformation matrix

$$\underline{T} = \begin{bmatrix} 1 & 0 & 1 \\ \alpha & \beta & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

is regular, i.e. if  $\det(\underline{T}) \neq 0$ . Since it is easy to show that  $\det(\underline{T}) = 2\beta$ , the transformation is regular for arbitrary values of  $\alpha$  and for all values of the parameter  $\beta$  except for  $\beta = 0$ .

b) By applying the transformation formulas we obtain the equivalent system description

$$\begin{aligned} \dot{\tilde{x}} &= \begin{bmatrix} 0 & 1 & \frac{1}{2} \\ -3 & 3 & 2 \\ 2 & 0 & 0 \end{bmatrix} \tilde{x} + \begin{bmatrix} 3 \\ 7 \\ 4 \end{bmatrix} u \\ y &= \begin{bmatrix} 0 & 2 & \frac{1}{2} \end{bmatrix} \tilde{x} + 3u \end{aligned}$$

### Task 16

The system descriptions are equivalent if there exists a regular state transformation

$$\tilde{x} = \underline{T}x$$

which transforms the first system into the second and vice versa. The corresponding transformation matrix must be regular and it must satisfy the following equations

$$\tilde{A} = \underline{T}A\underline{T}^{-1} \Rightarrow \tilde{A}\underline{T} = \underline{T}A$$

$$\tilde{b} = \underline{T}b$$

$$\tilde{c}^T = \underline{c}^T \underline{T}^{-1} \Rightarrow \tilde{c}^T \underline{T} = \underline{c}^T$$

Substituting the given system matrices/vectors we obtain

$$\begin{aligned} \Rightarrow \begin{bmatrix} 4 & 1 \\ 6 & 1 \end{bmatrix} \begin{bmatrix} t_{11} & t_{12} \\ t_{21} & t_{22} \end{bmatrix} &= \begin{bmatrix} t_{11} & t_{12} \\ t_{21} & t_{22} \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \\ \begin{bmatrix} 2 \\ 2 \end{bmatrix} &= \begin{bmatrix} t_{11} & t_{12} \\ t_{21} & t_{22} \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ \begin{bmatrix} 2 & -0.5 \end{bmatrix} \begin{bmatrix} t_{11} & t_{12} \\ t_{21} & t_{22} \end{bmatrix} &= \begin{bmatrix} 2 & 1 \end{bmatrix} \end{aligned}$$

In total we get a linear system of eight equations for the four unknown entries of the transformation matrix  $\underline{T}$ . Solving this system of equations using e.g. the Gauss algorithm we find the solution

$$\underline{T} = \begin{bmatrix} 1 & 1 \\ 0 & 2 \end{bmatrix}$$

Since  $\det(\underline{T}) = 2 \neq 0$  this transformation matrix is regular. Thus, the two system descriptions are equivalent.