

# Actuators - IRO6 Introduction

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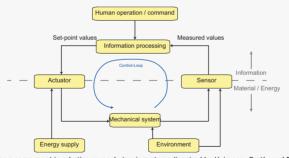
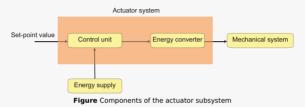
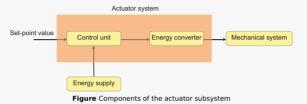


Figure Actuator as a component in robotics or mechatronic systems (inspired by Heimann, Gerth, and Popp, Mechatronik: Komponenten, Methoden, Beispiele)



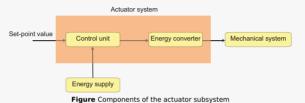






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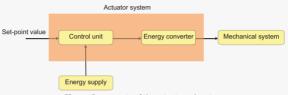
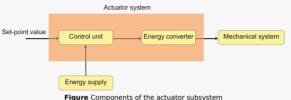


Figure Components of the actuator subsystem

- The control unit: generates the input for the actual energy converter with
  - the supply energy and
  - the set-point value of the control variable

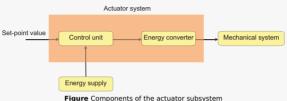




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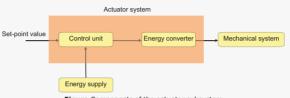
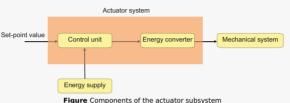


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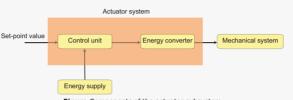


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# Different energy converter technologies

Hydraulic, pneumatic and especially electric drives are used for robots