

Segmentation of Indian Traffic

```
In [52]: import math
from PIL import Image, ImageDraw
from PIL import ImagePath
import pandas as pd
import os
from os import path
from tqdm import tqdm
import json
import cv2
import numpy as np
import matplotlib.pyplot as plt
import urllib
```

1. You can download the data from this link, and extract it
2. All your data will be in the folder "data"
3. Inside the data you will be having two folders

```
|--- data
|----| ---- images
|----| ----- Scene 1
|----| -----| ----- Frame 1 (image 1)
|----| -----| ----- Frame 2 (image 2)
|----| -----| ----- ...
|----| ----- Scene 2
|----| -----| ----- Frame 1 (image 1)
|----| -----| ----- Frame 2 (image 2)
|----| -----| ----- ...
|----| -----| -----
|----| ----- masks
|----| ----- Scene 1
|----| -----| ----- json 1 (labeled objects in image 1)
|----| -----| ----- json 2 (labeled objects in image 1)
|----| -----| ----- ...
|----| ----- Scene 2
|----| -----| ----- json 1 (labeled objects in image 1)
|----| -----| ----- json 2 (labeled objects in image 1)
|----| -----| ----- ...
|----| -----| ----- ...
```

Task 1: Preprocessing

1. Get all the file name and corresponding json files

```
In [75]: path = 'data'
G = []
for i in os.listdir(path):
    lst = []
    path1 = os.path.join(path, i)
    print(path1)
    for j in os.listdir(path1):
        path2 = os.path.join(path1, j)
        for k in os.listdir(path2):
            path3 = os.path.join(path2, k)
            lst.append(path3)
    G.append(lst)
```

```
data\images
data\mask
```

```
In [76]: data = pd.DataFrame(list(zip(G[0], G[1])), columns = ['images', 'json'])
data.head()
```

Out[76]:

	images	json
0	data\images\201\frame0029_left\img8bit.jpg	data\mask\201\frame0029_gtFine_polygons.json
1	data\images\201\frame0299_left\img8bit.jpg	data\mask\201\frame0299_gtFine_polygons.json
2	data\images\201\frame0779_left\img8bit.jpg	data\mask\201\frame0779_gtFine_polygons.json
3	data\images\201\frame1019_left\img8bit.jpg	data\mask\201\frame1019_gtFine_polygons.json
4	data\images\201\frame1469_left\img8bit.jpg	data\mask\201\frame1469_gtFine_polygons.json

```
In [77]: import os.path as path
import os
import pandas as pd

def return_file_names_df(root_dir):
    pathlist=[]
    for d in os.listdir(root_dir):
        lst = []
        pa1 = os.path.join(root_dir, d)
        print(pa1)
        for j in os.listdir(pa1):
            pa2 = os.path.join(pa1, j)
            for k in os.listdir(pa2):
                pa3 = os.path.join(pa2, k)
                lst.append(pa3)
        pathlist.append(lst)
    data_df = pd.DataFrame(list(zip(pathlist[0], pathlist[1])), columns = ['images', 'json'])
    data_df['images'] = data_df['images'].replace(r'\\', '/', regex=True)
    data_df['json'] = data_df['json'].replace(r'\\', '/', regex=True)

    return data_df
```

```
In [ ]: data_df = return_file_names_df('data')
```

If you observe the dataframe, we can consider each row as single data point, where first feature is image and the second feature is corresponding json file

```
In [8]: def grader_1(data_df):
    for i in data_df.values:
        if not (path.isfile(i[0]) and path.isfile(i[1]) and i[0][12:i[0].find('_')] == i[1][10:i[1].find('_')]):
            return False
    return True
```

```
In [9]: grader_1(data_df)
```

```
Out[9]: True
```

```
In [10]: data_df.shape
```

```
Out[10]: (4008, 2)
```

2. Structure of sample Json file



- Each File will have 3 attributes
 - imgHeight: which tells the height of the image
 - imgWidth: which tells the width of the image
 - objects: it is a list of objects, each object will have multiple attributes,
 - label: the type of the object
 - polygon: a list of two element lists, representing the coordinates of the polygon

Compute the unique labels

Let's see how many unique objects are there in the json file. to see how to get the object from the json file please check [this blog](#) (<https://www.geeksforgeeks.org/read-json-file-using-python/>)

```
In [22]: import json
def return_unique_labels(data_df):
    unique_labels = set()
    for json_file in data_df['json']:
        with open(json_file) as f:
            json_data = json.load(f)
            objects = json_data['objects']
            for obj in objects:
                unique_labels.add(obj['label'])
    # for each file in the column json
    #      read and store all the objects present in that file
    # compute the unique objects and retrun them
    # if open any json file using any editor you will get better sense of it
    return unique_labels
```

```
In [23]: unique_labels = return_unique_labels(data_df)
```

```
In [24]: len(unique_labels)
```

```
Out[24]: 40
```

```
In [ ]: unique_labels = return_unique_labels(data_df)
```



```
In [25]: label_clr = {'road':10, 'parking':20, 'drivable fallback':20,'sidewalk':30,'non-
-drivable fallback':40,'rail track':40,
                    'person':50, 'animal':50, 'rider':60, 'motorcycle':70,
'bicycle':70, 'autorickshaw':80,\n                    'car':80, 'truck':90, 'bus':90, 'vehicle fallback':90,
'trailer':90, 'caravan':90,\n                    'curb':100, 'wall':100, 'fence':110,'guard rail':110,
'billboard':120,'traffic sign':120,\n                    'traffic light':120, 'pole':130, 'polegroup':130, 'obs-
-str-bar-fallback':130,'building':140,\n                    'bridge':140,'tunnel':140, 'vegetation':150, 'sky':160,
'fallback background':160,'unlabeled':0,\n                    'out of roi':0, 'ego vehicle':170, 'ground':180,'rectif-
ication border':190,\n                    'train':200}
```

```
In [26]: def grader_2(unique_labels):
    if (not (set(label_clr.keys())-set(unique_labels))) and len(unique_labels)
== 40:
        print("True")
    else:
        print("Flase")

grader_2(unique_labels)
```

```
True
```

*here we have given a number for each of object types, if you see we are having 21 different set of objects
*Note that we have multiplies each object's number with 10, that is just to make different objects look differently in the segmentation map
*Before you pass it to the models, you might need to devide the image array /10.

3. Extracting the polygons from the json files

```
In [30]: import json
        # this function will take a file name as argument

        # it will process all the objects in that file and returns

        # label: a list of labels for all the objects label[i] will have the corresponding vertices in vertexlist[i]
        # len(label) == number of objects in the image

        # vertexlist: it should be list of list of vertices in tuple formate
        # ex: [[(x11,y11), (x12,y12), (x13,y13) .. (x1n,y1n)]
        #      [(x21,y21), (x22,y12), (x23,y23) .. (x2n,y2n)]
        #      ....
        #      [(xm1,ym1), (xm2,ym2), (xm3,ym3) .. (xm,ymn)]]
        # len(vertexlist) == number of objects in the image

        # * note that label[i] and vertexlist[i] are corresponds to the same object, one represents the type of the object
        # the other represents the location

        # width of the image
        # height of the image
def get_poly(file):
    with open(file) as f:
        data = json.load(f)

    w, h = data['imgWidth'], data['imgHeight']

    labels = []
    vertexlist = []

    for obj in data['objects']:
        # get the label of the object
        label = obj['label']

        # get the vertices of the polygon
        polygon = obj['polygon']
        vertices_list1 = [(p[0], p[1]) for p in polygon]

        # append the label and vertices to the lists
        labels.append(label)
        vertexlist.append(vertices_list1)

    return w, h, labels, vertexlist
```

```
In [31]: def grader_3(file):
    w, h, labels, vertexlist = get_poly(file)
    print(len((set(labels)))==18 and len(vertexlist)==227 and w==1920 and h==10
80 \
          and isinstance(vertexlist,list) and isinstance(vertexlist[0],list) an
d isinstance(vertexlist[0][0],tuple) )

grader_3('data/mask/201/frame0029_gtFine_polygons.json')
```

True

4. Creating Image segmentations by drawing set of polygons

```
In [27]: import numpy as np
```

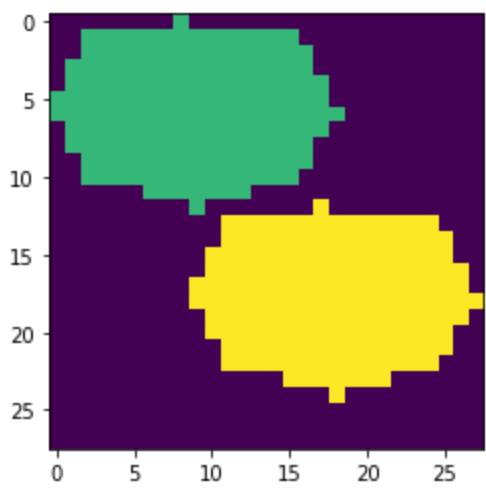
Example

```
In [ ]: import math
from PIL import Image, ImageDraw
from PIL import ImagePath
side=8
x1 = [ ((math.cos(th) + 1) *9, (math.sin(th) + 1) * 6) for th in [i * (2 * math.pi) / side for i in range(side)] ]
x2 = [ ((math.cos(th) + 2) *9, (math.sin(th) + 3) *6) for th in [i * (2 * math.pi) / side for i in range(side)] ]

img = Image.new("RGB", (28,28))
img1 = ImageDraw.Draw(img)
# please play with the fill value
# writing the first polygon
img1.polygon(x1, fill =20)
# writing the second polygon
img1.polygon(x2, fill =30)

img=np.array(img)
# note that the filling of the values happens at the channel 1, so we are considering only the first channel here
plt.imshow(img[:, :, 0])
print(img.shape)
print(img[:, :, 0]//10)
im = Image.fromarray(img[:, :, 0])
im.save("test_image.png")
```

(28, 28, 3)



```
In [34]: def compute_masks(data_df):
    # after you have computed the vertexlist plot that polygon in the image like this
    for ii, row in data_df.iterrows():
        w, h, label, vertexlist = get_poly(row['json'])
        img = Image.new("RGB", (w, h))
        img1 = ImageDraw.Draw(img)
        for i in range(len(label)):
            if len(vertexlist[i]) >= 1:
                img1.polygon(vertexlist[i], fill = label_clr[label[i]])

    # after drawing all the polygons that we collected from json file,
    # you need to store that image in the folder like this "data/output/scene/framenumber_gtFine_polygons.png"
    filename = os.path.basename(row['json'])
    frame_number = filename.split("_")[0][:]

    output_dir = "data/output/scene"
    if not os.path.exists(output_dir):
        os.makedirs(output_dir)

    mask_path = os.path.join(output_dir, "{}_gtFine_polygons.png".format(frame_number))
    img.save(mask_path)
    data_df.at[ii, 'mask'] = mask_path
    # after saving the image into disk, store the path in a list
    # after storing all the paths, add a column to the data_df['mask'] ex: data_df['mask'] = mask_paths

    return data_df
```

```
In [ ]: data_df['mask'] = ""
data_df = compute_masks(data_df)
data_df.head()
```

```
In [47]: data_df['mask'] = data_df['mask'].apply(lambda x: x.replace('\\\\', '/'))
pd.set_option('display.max_rows', None)
pd.set_option('display.max_columns', None)
data_df
```

Out[47] :

	images	json
0	data/images/201/frame0029_leftImg8bit.jpg	data/mask/201/frame0029_gtFine_polygons.json
1	data/images/201/frame0299_leftImg8bit.jpg	data/mask/201/frame0299_gtFine_polygons.json
2	data/images/201/frame0779_leftImg8bit.jpg	data/mask/201/frame0779_gtFine_polygons.json
3	data/images/201/frame1019_leftImg8bit.jpg	data/mask/201/frame1019_gtFine_polygons.json
4	data/images/201/frame1469_leftImg8bit.jpg	data/mask/201/frame1469_gtFine_polygons.json
5	data/images/201/frame1979_leftImg8bit.jpg	data/mask/201/frame1979_gtFine_polygons.json
6	data/images/201/frame2519_leftImg8bit.jpg	data/mask/201/frame2519_gtFine_polygons.json
7	data/images/201/frame2819_leftImg8bit.jpg	data/mask/201/frame2819_gtFine_polygons.json
8	data/images/201/frame3179_leftImg8bit.jpg	data/mask/201/frame3179_gtFine_polygons.json
9	data/images/201/frame3749_leftImg8bit.jpg	data/mask/201/frame3749_gtFine_polygons.json
10	data/images/201/frame4079_leftImg8bit.jpg	data/mask/201/frame4079_gtFine_polygons.json
11	data/images/202/frame0018_leftImg8bit.jpg	data/mask/202/frame0018_gtFine_polygons.json
12	data/images/202/frame0389_leftImg8bit.jpg	data/mask/202/frame0389_gtFine_polygons.json
13	data/images/203/frame0165_leftImg8bit.jpg	data/mask/203/frame0165_gtFine_polygons.json
14	data/images/203/frame0435_leftImg8bit.jpg	data/mask/203/frame0435_gtFine_polygons.json
15	data/images/203/frame0525_leftImg8bit.jpg	data/mask/203/frame0525_gtFine_polygons.json
16	data/images/203/frame0630_leftImg8bit.jpg	data/mask/203/frame0630_gtFine_polygons.json
17	data/images/203/frame0675_leftImg8bit.jpg	data/mask/203/frame0675_gtFine_polygons.json
18	data/images/203/frame0945_leftImg8bit.jpg	data/mask/203/frame0945_gtFine_polygons.json
19	data/images/203/frame1012_leftImg8bit.jpg	data/mask/203/frame1012_gtFine_polygons.json
20	data/images/203/frame1185_leftImg8bit.jpg	data/mask/203/frame1185_gtFine_polygons.json
21	data/images/203/frame1222_leftImg8bit.jpg	data/mask/203/frame1222_gtFine_polygons.json
22	data/images/203/frame1252_leftImg8bit.jpg	data/mask/203/frame1252_gtFine_polygons.json
23	data/images/203/frame1394_leftImg8bit.jpg	data/mask/203/frame1394_gtFine_polygons.json
24	data/images/203/frame1517_leftImg8bit.jpg	data/mask/203/frame1517_gtFine_polygons.json
25	data/images/203/frame1777_leftImg8bit.jpg	data/mask/203/frame1777_gtFine_polygons.json
26	data/images/203/frame1885_leftImg8bit.jpg	data/mask/203/frame1885_gtFine_polygons.json
27	data/images/203/frame1975_leftImg8bit.jpg	data/mask/203/frame1975_gtFine_polygons.json
28	data/images/203/frame2230_leftImg8bit.jpg	data/mask/203/frame2230_gtFine_polygons.json
29	data/images/203/frame2305_leftImg8bit.jpg	data/mask/203/frame2305_gtFine_polygons.json
30	data/images/203/frame2410_leftImg8bit.jpg	data/mask/203/frame2410_gtFine_polygons.json
31	data/images/203/frame2530_leftImg8bit.jpg	data/mask/203/frame2530_gtFine_polygons.json
32	data/images/203/frame2605_leftImg8bit.jpg	data/mask/203/frame2605_gtFine_polygons.json
33	data/images/203/frame2680_leftImg8bit.jpg	data/mask/203/frame2680_gtFine_polygons.json

	images	json
34	data/images/203/frame2909_leftImg8bit.jpg	data/mask/203/frame2909_gtFine_polygons.json
35	data/images/203/frame3239_leftImg8bit.jpg	data/mask/203/frame3239_gtFine_polygons.json
36	data/images/203/frame3299_leftImg8bit.jpg	data/mask/203/frame3299_gtFine_polygons.json
37	data/images/204/frame0066_leftImg8bit.jpg	data/mask/204/frame0066_gtFine_polygons.json
38	data/images/204/frame0221_leftImg8bit.jpg	data/mask/204/frame0221_gtFine_polygons.json
39	data/images/204/frame0397_leftImg8bit.jpg	data/mask/204/frame0397_gtFine_polygons.json
40	data/images/204/frame0611_leftImg8bit.jpg	data/mask/204/frame0611_gtFine_polygons.json
41	data/images/204/frame0791_leftImg8bit.jpg	data/mask/204/frame0791_gtFine_polygons.json
42	data/images/204/frame1011_leftImg8bit.jpg	data/mask/204/frame1011_gtFine_polygons.json
43	data/images/204/frame10164_leftImg8bit.jpg	data/mask/204/frame10164_gtFine_polygons.json
44	data/images/204/frame10355_leftImg8bit.jpg	data/mask/204/frame10355_gtFine_polygons.json
45	data/images/204/frame10437_leftImg8bit.jpg	data/mask/204/frame10437_gtFine_polygons.json
46	data/images/204/frame10573_leftImg8bit.jpg	data/mask/204/frame10573_gtFine_polygons.json
47	data/images/204/frame10764_leftImg8bit.jpg	data/mask/204/frame10764_gtFine_polygons.json
48	data/images/204/frame10873_leftImg8bit.jpg	data/mask/204/frame10873_gtFine_polygons.json
49	data/images/204/frame10982_leftImg8bit.jpg	data/mask/204/frame10982_gtFine_polygons.json
50	data/images/204/frame11119_leftImg8bit.jpg	data/mask/204/frame11119_gtFine_polygons.json
51	data/images/204/frame11282_leftImg8bit.jpg	data/mask/204/frame11282_gtFine_polygons.json
52	data/images/204/frame11419_leftImg8bit.jpg	data/mask/204/frame11419_gtFine_polygons.json
53	data/images/204/frame11528_leftImg8bit.jpg	data/mask/204/frame11528_gtFine_polygons.json
54	data/images/204/frame11637_leftImg8bit.jpg	data/mask/204/frame11637_gtFine_polygons.json
55	data/images/204/frame11800_leftImg8bit.jpg	data/mask/204/frame11800_gtFine_polygons.json
56	data/images/204/frame11964_leftImg8bit.jpg	data/mask/204/frame11964_gtFine_polygons.json
57	data/images/204/frame12073_leftImg8bit.jpg	data/mask/204/frame12073_gtFine_polygons.json
58	data/images/204/frame12182_leftImg8bit.jpg	data/mask/204/frame12182_gtFine_polygons.json
59	data/images/204/frame1221_leftImg8bit.jpg	data/mask/204/frame1221_gtFine_polygons.json
60	data/images/204/frame12428_leftImg8bit.jpg	data/mask/204/frame12428_gtFine_polygons.json
61	data/images/204/frame12591_leftImg8bit.jpg	data/mask/204/frame12591_gtFine_polygons.json
62	data/images/204/frame12891_leftImg8bit.jpg	data/mask/204/frame12891_gtFine_polygons.json
63	data/images/204/frame13191_leftImg8bit.jpg	data/mask/204/frame13191_gtFine_polygons.json
64	data/images/204/frame13437_leftImg8bit.jpg	data/mask/204/frame13437_gtFine_polygons.json
65	data/images/204/frame13600_leftImg8bit.jpg	data/mask/204/frame13600_gtFine_polygons.json
66	data/images/204/frame13819_leftImg8bit.jpg	data/mask/204/frame13819_gtFine_polygons.json
67	data/images/204/frame13900_leftImg8bit.jpg	data/mask/204/frame13900_gtFine_polygons.json
68	data/images/204/frame14173_leftImg8bit.jpg	data/mask/204/frame14173_gtFine_polygons.json

	images	json
69	data/images/204/frame14337_leftImg8bit.jpg	data/mask/204/frame14337_gtFine_polygons.json
70	data/images/204/frame14473_leftImg8bit.jpg	data/mask/204/frame14473_gtFine_polygons.json
71	data/images/204/frame14582_leftImg8bit.jpg	data/mask/204/frame14582_gtFine_polygons.json
72	data/images/204/frame14746_leftImg8bit.jpg	data/mask/204/frame14746_gtFine_polygons.json
73	data/images/204/frame14828_leftImg8bit.jpg	data/mask/204/frame14828_gtFine_polygons.json
74	data/images/204/frame1491_leftImg8bit.jpg	data/mask/204/frame1491_gtFine_polygons.json
75	data/images/204/frame15019_leftImg8bit.jpg	data/mask/204/frame15019_gtFine_polygons.json
76	data/images/204/frame15155_leftImg8bit.jpg	data/mask/204/frame15155_gtFine_polygons.json
77	data/images/204/frame15400_leftImg8bit.jpg	data/mask/204/frame15400_gtFine_polygons.json
78	data/images/204/frame15700_leftImg8bit.jpg	data/mask/204/frame15700_gtFine_polygons.json
79	data/images/204/frame15891_leftImg8bit.jpg	data/mask/204/frame15891_gtFine_polygons.json
80	data/images/204/frame1787_leftImg8bit.jpg	data/mask/204/frame1787_gtFine_polygons.json
81	data/images/204/frame1997_leftImg8bit.jpg	data/mask/204/frame1997_gtFine_polygons.json
82	data/images/204/frame2297_leftImg8bit.jpg	data/mask/204/frame2297_gtFine_polygons.json
83	data/images/204/frame2567_leftImg8bit.jpg	data/mask/204/frame2567_gtFine_polygons.json
84	data/images/204/frame2867_leftImg8bit.jpg	data/mask/204/frame2867_gtFine_polygons.json
85	data/images/204/frame3167_leftImg8bit.jpg	data/mask/204/frame3167_gtFine_polygons.json
86	data/images/204/frame3377_leftImg8bit.jpg	data/mask/204/frame3377_gtFine_polygons.json
87	data/images/204/frame3617_leftImg8bit.jpg	data/mask/204/frame3617_gtFine_polygons.json
88	data/images/204/frame3887_leftImg8bit.jpg	data/mask/204/frame3887_gtFine_polygons.json
89	data/images/204/frame4067_leftImg8bit.jpg	data/mask/204/frame4067_gtFine_polygons.json
90	data/images/204/frame4397_leftImg8bit.jpg	data/mask/204/frame4397_gtFine_polygons.json
91	data/images/204/frame4817_leftImg8bit.jpg	data/mask/204/frame4817_gtFine_polygons.json
92	data/images/204/frame5027_leftImg8bit.jpg	data/mask/204/frame5027_gtFine_polygons.json
93	data/images/204/frame5237_leftImg8bit.jpg	data/mask/204/frame5237_gtFine_polygons.json
94	data/images/204/frame5507_leftImg8bit.jpg	data/mask/204/frame5507_gtFine_polygons.json
95	data/images/204/frame5777_leftImg8bit.jpg	data/mask/204/frame5777_gtFine_polygons.json
96	data/images/204/frame6227_leftImg8bit.jpg	data/mask/204/frame6227_gtFine_polygons.json
97	data/images/204/frame6797_leftImg8bit.jpg	data/mask/204/frame6797_gtFine_polygons.json
98	data/images/204/frame7487_leftImg8bit.jpg	data/mask/204/frame7487_gtFine_polygons.json
99	data/images/204/frame7697_leftImg8bit.jpg	data/mask/204/frame7697_gtFine_polygons.json
100	data/images/204/frame8297_leftImg8bit.jpg	data/mask/204/frame8297_gtFine_polygons.json
101	data/images/204/frame8657_leftImg8bit.jpg	data/mask/204/frame8657_gtFine_polygons.json
102	data/images/204/frame8927_leftImg8bit.jpg	data/mask/204/frame8927_gtFine_polygons.json
103	data/images/204/frame9257_leftImg8bit.jpg	data/mask/204/frame9257_gtFine_polygons.json

	images	json
104	data/images/204/frame9497_leftImg8bit.jpg	data/mask/204/frame9497_gtFine_polygons.json
105	data/images/204/frame9707_leftImg8bit.jpg	data/mask/204/frame9707_gtFine_polygons.json
106	data/images/204/frame9887_leftImg8bit.jpg	data/mask/204/frame9887_gtFine_polygons.json
107	data/images/206/frame0008_leftImg8bit.jpg	data/mask/206/frame0008_gtFine_polygons.json
108	data/images/206/frame0659_leftImg8bit.jpg	data/mask/206/frame0659_gtFine_polygons.json
109	data/images/206/frame0839_leftImg8bit.jpg	data/mask/206/frame0839_gtFine_polygons.json
110	data/images/206/frame1349_leftImg8bit.jpg	data/mask/206/frame1349_gtFine_polygons.json
111	data/images/206/frame1539_leftImg8bit.jpg	data/mask/206/frame1539_gtFine_polygons.json
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3971	data/images/423/frame7987_leftImg8bit.jpg	data/mask/423/frame7987_gtFine_polygons.json
3972	data/images/423/frame8397_leftImg8bit.jpg	data/mask/423/frame8397_gtFine_polygons.json
3973	data/images/423/frame8847_leftImg8bit.jpg	data/mask/423/frame8847_gtFine_polygons.json
3974	data/images/423/frame9927_leftImg8bit.jpg	data/mask/423/frame9927_gtFine_polygons.json
3975	data/images/424/frame0349_leftImg8bit.jpg	data/mask/424/frame0349_gtFine_polygons.json
3976	data/images/424/frame0499_leftImg8bit.jpg	data/mask/424/frame0499_gtFine_polygons.json
3977	data/images/424/frame0799_leftImg8bit.jpg	data/mask/424/frame0799_gtFine_polygons.json
3978	data/images/424/frame0924_leftImg8bit.jpg	data/mask/424/frame0924_gtFine_polygons.json
3979	data/images/424/frame1149_leftImg8bit.jpg	data/mask/424/frame1149_gtFine_polygons.json
3980	data/images/426/0000000_leftImg8bit.jpg	data/mask/426/0000000_gtFine_polygons.json
3981	data/images/426/0000343_leftImg8bit.jpg	data/mask/426/0000343_gtFine_polygons.json
3982	data/images/426/0000454_leftImg8bit.jpg	data/mask/426/0000454_gtFine_polygons.json
3983	data/images/426/0000639_leftImg8bit.jpg	data/mask/426/0000639_gtFine_polygons.json
3984	data/images/428/frame0359_leftImg8bit.jpg	data/mask/428/frame0359_gtFine_polygons.json
3985	data/images/428/frame0839_leftImg8bit.jpg	data/mask/428/frame0839_gtFine_polygons.json
3986	data/images/428/frame0959_leftImg8bit.jpg	data/mask/428/frame0959_gtFine_polygons.json
3987	data/images/428/frame1079_leftImg8bit.jpg	data/mask/428/frame1079_gtFine_polygons.json
3988	data/images/428/frame1199_leftImg8bit.jpg	data/mask/428/frame1199_gtFine_polygons.json

	images	json
3989	data/images/428/frame1319_leftImg8bit.jpg	data/mask/428/frame1319_gtFine_polygons.json
3990	data/images/428/frame1439_leftImg8bit.jpg	data/mask/428/frame1439_gtFine_polygons.json
3991	data/images/428/frame1559_leftImg8bit.jpg	data/mask/428/frame1559_gtFine_polygons.json
3992	data/images/428/frame1679_leftImg8bit.jpg	data/mask/428/frame1679_gtFine_polygons.json
3993	data/images/428/frame1799_leftImg8bit.jpg	data/mask/428/frame1799_gtFine_polygons.json
3994	data/images/428/frame2039_leftImg8bit.jpg	data/mask/428/frame2039_gtFine_polygons.json
3995	data/images/428/frame3119_leftImg8bit.jpg	data/mask/428/frame3119_gtFine_polygons.json
3996	data/images/428/frame3359_leftImg8bit.jpg	data/mask/428/frame3359_gtFine_polygons.json
3997	data/images/428/frame3479_leftImg8bit.jpg	data/mask/428/frame3479_gtFine_polygons.json
3998	data/images/428/frame3599_leftImg8bit.jpg	data/mask/428/frame3599_gtFine_polygons.json
3999	data/images/428/frame3719_leftImg8bit.jpg	data/mask/428/frame3719_gtFine_polygons.json
4000	data/images/428/frame3839_leftImg8bit.jpg	data/mask/428/frame3839_gtFine_polygons.json
4001	data/images/428/frame3959_leftImg8bit.jpg	data/mask/428/frame3959_gtFine_polygons.json
4002	data/images/429/frame10303_leftImg8bit.jpg	data/mask/429/frame10303_gtFine_polygons.json
4003	data/images/429/frame13262_leftImg8bit.jpg	data/mask/429/frame13262_gtFine_polygons.json
4004	data/images/429/frame13699_leftImg8bit.jpg	data/mask/429/frame13699_gtFine_polygons.json
4005	data/images/429/frame15812_leftImg8bit.jpg	data/mask/429/frame15812_gtFine_polygons.json
4006	data/images/429/frame18062_leftImg8bit.jpg	data/mask/429/frame18062_gtFine_polygons.json
4007	data/images/429/frame18403_leftImg8bit.jpg	data/mask/429/frame18403_gtFine_polygons.json

```
In [47]: data_df.to_csv('preprocessed_data.csv', index=False)
```

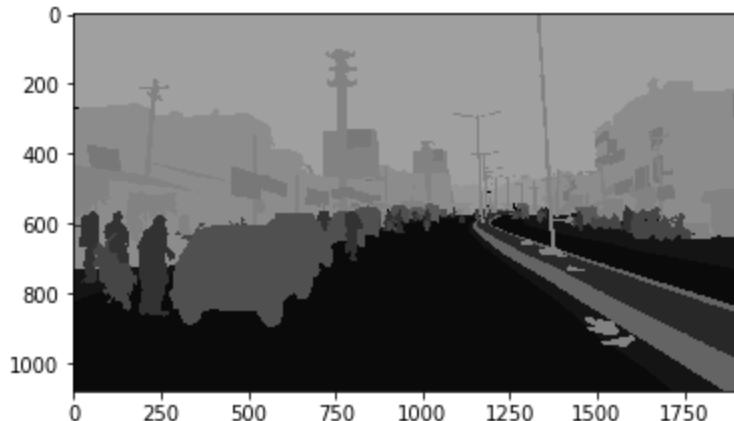
```
In [3]: import pandas as pd
data_df=pd.read_csv('preprocessed_data.csv')
```

```
In [2]: from google.colab import drive
drive.mount('/content/drive')
```

Mounted at /content/drive

```
In [51]: my_img = cv2.imread('data/output/scene/frame0029_gtFine_polygons.png')
plt.imshow(my_img)
```

```
Out[51]: <matplotlib.image.AxesImage at 0x1c8595f5278>
```



```
In [4]: %cd "/content/drive/My Drive/COMPUTER VISION SEGMENTATION/"
/content/drive/My Drive/COMPUTER VISION SEGMENTATION
```

```
In [ ]: !ls
```

```
'Copy of Reference_Pipelines.ipynb'  Reference_Pretrained_Unet.ipynb
data                                     'Segmentation_Assignment (1).ipynb'
data.zip                                Segmentation_Assignment.ipynb
preprocessed_data.csv
```

```
In [56]: import tensorflow as tf
# tf.enable_eager_execution()
import os
import numpy as np
import pandas as pd
import cv2
import matplotlib.pyplot as plt
# from hilbert import hilbertCurve
import imgaug.augmenters as iaa
import numpy as np
# import albumentations as A
os.environ['TF_FORCE_GPU_ALLOW_GROWTH'] = 'true'
```

```
In [66]: # import tensorflow as tf
# we are importing the pretrained unet from the segmentation models
# https://github.com/qubvel/segmentation_models
import segmentation_models as sm
from segmentation_models import Unet
# sm.set_framework('tf.keras')
tf.keras.backend.set_image_data_format('channels_last')
```

```
In [61]: from tensorflow.keras import layers
from tensorflow.keras.layers import Dense, Input, Conv2D, MaxPool2D, Activation, Dropout, Flatten, LSTM, BatchNormalization, ReLU, Reshape
from tensorflow.keras.models import Model
import random as rn
```

```
In [62]: from tensorflow.keras.layers import Flatten
```

```
In [ ]: import cv2
from google.colab.patches import cv2_imshow

# Load image
image = cv2.imread("data/images/201/frame0299_leftImg8bit.jpg")

# Check if image is not None
if image is not None:
    # Print shape
    print(image.shape)

    # Display image
    cv2_imshow(image)
else:
    print('Error: could not read image file')
```

Output hidden; open in <https://colab.research.google.com> to view.

```
In [63]: %env SM_FRAMEWORK=tf.keras
# we are importing the pretrained unet from the segmentation models
# https://github.com/qubvel/segmentation_models
import segmentation_models as sm
from segmentation_models import Unet
# sm.set_framework('tf.keras')
tf.keras.backend.set_image_data_format('channels_last')
```

env: SM_FRAMEWORK=tf.keras

```
C:\Anaconda3\lib\site-packages\classification_models\resnext\__init__.py:4: User
Warning: Current ResNext models are deprecated, use keras.applications.ResNeXt m
odels
    warnings.warn('Current ResNext models are deprecated, '
```

```
In [65]: # We are importing the pretrained unet from the segmentation models.
# https://github.com/qubvel/segmentation_models
tf.keras.backend.clear_session()
os.environ["SM_FRAMEWORK"] = "tf.keras"
import segmentation_models as sm
from segmentation_models import Unet
from segmentation_models.metrics import iou_score
#sm.set_framework('tf.keras')
tf.keras.backend.set_image_data_format('channels_last')
#from tensorflow.keras.applications.resnet import preprocess_input

# loading the unet model and using the resnet 50 and initialized weights with I
magenet weights.
# "classes" :different types of classes in the dataset.
#backbone = 'resnet50'
#preprocess_input = sm.get_preprocessing(backbone)
```

Task 2: Applying Unet to segment the images

* please check the paper: <https://arxiv.org/abs/1505.04597>

*



* As a part of this assignment we won't writingt this whole architecture, rather we will be doing transfer learning

* please check the library https://github.com/qubvel/segmentation_models

* You can install it like this "pip install -U segmentation-models==0.2.1", even in g oogle colab you can install the same with "!pip install -U segmentation-models==0.2.1"

* Check the reference notebook in which we have solved one end to end case study of i mage forgery detection using same unet

* The number of channels in the output will depend on the number of classes in your d ata, since we know that we are having 21 classes, the number of channels in the outpu t will also be 21

*** This is where we want you to explore, how do you featurize your created segmentatio n map note that the original map will be of (w, h, 1) and the output will be (w, h, 2 1) how will you calculate the loss, you can check the examples in segmentation github**

* please use the loss function that is used in the refence notebooks

Task 2.1: Dice loss

* Explain the Dice loss

* 1. Write the formualtion

* 2. Range of the loss function

* 3. Interpretation of loss function

* 4. Write your understanding of the loss function, how does it helps in segmentation

Dice loss:

Dice loss is a loss function used in image segmentation task. It measures the similarity between the predicted segmentation mask and the ground truth mask. Dice loss measure the overlap between two sets and the range of dice loss is 0 to 1.

Formula:

$$\text{Dice coefficient} = \frac{2 * \text{intersection}}{\text{union} + \text{intersection}} = \frac{2 \cdot \text{TP}}{2 \cdot \text{TP} + \text{FN} + \text{FP}}$$

$$\text{Dice Loss} = 1 - \text{Dice Coefficient}$$

Range:

The range of the Dice loss function is between 0 and 1. When the predicted msk perfectly matches the ground truth mask, then loss is 0. If the predicted mask has no overlap with the ground truth mask, the Dice loss is 1.

Interpretation:

When the Predicted mask does match the ground truth mask the intersection is large and the union is small it means low dice loss and when the predicted mask does not match the ground truth mask, the intersection is small and union is large, resulting in a high dice loss.

Understanding:

The main goal of Image segmentaion is to create the object mask and mask should be very similar to object for better image segmentaion but if mask is not completly overlap with object then with help of dice loss we can find an error.

Dice loss match the ground truth with predicted mask to calculate the loss and Dice loss is more robust to class imbalance and can help the model focus on accurately segmenting the object of interest.

Task 2.2: Training Unet

- * Split the data into 80:20.
- * Train the UNET on the given dataset and plot the train and validation loss.
- * As shown in the reference notebook plot 20 images from the test data along with its segmentation map, predicted map.

```
In [41]: backbone = 'vgg16'  
preprocess_input = sm.get_preprocessing(backbone)
```

```
In [67]: # import imgaug.augmenters as iaa
# For the assignment choose any 4 augmentation techniques
# check the imgaug documentations for more augmentations
aug2 = iaa.Fliplr(1)
aug3 = iaa.Flipud(1)
aug4 = iaa.Emboss(alpha=(1), strength=1)
aug5 = iaa.DirectedEdgeDetect(alpha=(0.8), direction=(1.0))
aug6 = iaa.Sharpen(alpha=(1.0), lightness=(1.5))
```

```

In [68]: def visualize(**images):
    n = len(images)
    plt.figure(figsize=(16, 5))
    for i, (name, image) in enumerate(images.items()):
        plt.subplot(1, n, i + 1)
        plt.xticks([])
        plt.yticks([])
        plt.title(' '.join(name.split('_')).title())
        if i==1:
            plt.imshow(image, cmap='gray', vmax=1, vmin=0)
        else:
            plt.imshow(image)
    plt.show()

'''def normalize_image(mask):
    mask = mask/255
    return mask'''

class Dataset:
    # we will be modifying this CLASSES according to your data/problems
    CLASSES =[0,1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19,20]

    # the parameters needs to changed based on your requirements
    # here we are collecting the file_names because in our dataset, both our images and maks will have same file name
    # ex: fil_name.jpg    file_name.mask.jpg
    def __init__(self, file_names, classes = None):

        self.ids = file_names
        # the paths of images
        self.images_fps = [image_id for image_id in self.ids['images']]
        # the paths of segmentation images
        self.masks_fps = [image_id for image_id in self.ids['mask']]
        # giving labels for each class
        self.class_values = [self.CLASSES.index(cls) for cls in classes]

    def __getitem__(self, i):

        # read data
        image = cv2.imread(self.images_fps[i], cv2.IMREAD_UNCHANGED)
        image = cv2.resize(image, (256, 256), interpolation = cv2.INTER_AREA)
        image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
        image = preprocess_input(image)

        mask = cv2.imread(self.masks_fps[i], cv2.IMREAD_UNCHANGED)
        mask = cv2.resize(mask, (256,256), interpolation = cv2.INTER_NEAREST)
#AREA
        mask = mask / 10
#        print(mask.shape)
#        mask = mask[..., 0]

        #image_mask = normalize_image(mask)

        image_masks = [(mask == v) for v in self.class_values]
        image_mask = np.stack(image_masks, axis=-1).astype('float')
#        print(image_mask.shape)

#        print(image_mask.shape)

```

```

a = np.random.uniform()
if a<0.2:
    image = aug2.augment_image(image)
    image_mask = aug2.augment_image(image_mask)
elif a<0.4:
    image = aug3.augment_image(image)
    image_mask = aug3.augment_image(image_mask)
elif a<0.6:
    image = aug4.augment_image(image)
    image_mask = aug4.augment_image(image_mask)
elif a<0.8:
    image = aug5.augment_image(image)
    image_mask = image_mask
else:
    image = aug6.augment_image(image)
    image_mask = aug6.augment_image(image_mask)
#print(image.shape)
#print(image_mask.shape)

return image, image_mask

def __len__(self):
    return len(self.ids)

class Dataloder(tf.keras.utils.Sequence):
    def __init__(self, dataset, batch_size=1, shuffle=False):
        self.dataset = dataset
        self.batch_size = batch_size
        self.shuffle = shuffle
        self.indexes = np.arange(len(dataset))

    def __getitem__(self, i):

        # collect batch data
        start = i * self.batch_size
        stop = (i + 1) * self.batch_size
        data = []
        for j in range(start, stop):
            data.append(self.dataset[j])

        batch = [np.stack(samples, axis=0) for samples in zip(*data)]

        return tuple(batch)

    def __len__(self):
        return len(self.indexes) // self.batch_size

    def on_epoch_end(self):
        if self.shuffle:
            self.indexes = np.random.permutation(self.indexes)

```

In [69]: CLASSES=[0,1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19,20]
n_cl=len(CLASSES)
BATCH_SIZE = 16
IMAGE_SHAPE = (256, 256, 3)

```
In [79]: from sklearn.model_selection import train_test_split  
X_train, X_test = train_test_split(data_df, test_size=0.11, random_state=42)  
X_train.shape
```

```
Out[79]: (3567, 3)
```

```
In [ ]: import os  
  
# Get current working directory  
print(os.getcwd())
```

```
/content/drive/My Drive/COMPUTER VISION SEGMENTATION
```

```
In [58]: # Dataset for train images  
#CLASSES = ['edited']  
train_dataset = Dataset(X_train, classes=CLASSES)  
test_dataset = Dataset(X_test, classes=CLASSES)  
  
train_dataloader = Dataloder(train_dataset, batch_size=BATCH_SIZE, shuffle=True)  
  
test_dataloader = Dataloder(test_dataset, batch_size=BATCH_SIZE, shuffle=True)
```

```
In [31]: print(test_dataloader[0][0].shape)  
  
(16, 256, 256, 3)
```

```
In [32]: print(train_dataloader[0][0].shape)  
  
(16, 256, 256, 3)
```

```
In [62]: assert train_dataloader[0][0].shape == (BATCH_SIZE, 256, 256, 3)  
assert train_dataloader[0][1].shape == (BATCH_SIZE, 256, 256, n_cl)  
#min  
# define callbacks for learning rate scheduling and best checkpoints saving  
callbacks = [  
    tf.keras.callbacks.ModelCheckpoint('./best_model.h5', save_weights_only=True,  
    save_best_only=True, \  
        mode='max', monitor='val_iou_score'),  
    tf.keras.callbacks.ReduceLROnPlateau(monitor='val_iou_score', min_lr=0.0000  
01, patience=2),  
]
```

```
In [ ]: # loading the unet model and using the resnet 34 and initialized weights with im  
agenet weights  
# "classes" :different types of classes in the dataset  
model = Unet('vgg16', encoder_weights='imagenet', classes=n_cl, activation='sof  
tmax', input_shape =IMAGE_SHAPE)
```

```
In [11]: model.summary()
```

Model: "u-vgg16"

Layer (type)	Output Shape	Param #	Connected to
input_1 (InputLayer)	(None, 256, 256, 3)	0	
block1_conv1 (Conv2D)	(None, 256, 256, 64)	1792	input_1[0][0]
block1_conv2 (Conv2D) [0]	(None, 256, 256, 64)	36928	block1_conv1[0]
block1_pool (MaxPooling2D) [0]	(None, 128, 128, 64)	0	block1_conv2[0]
block2_conv1 (Conv2D) [0]	(None, 128, 128, 128)	73856	block1_pool[0]
block2_conv2 (Conv2D) [0]	(None, 128, 128, 128)	147584	block2_conv1[0]
block2_pool (MaxPooling2D) [0]	(None, 64, 64, 128)	0	block2_conv2[0]
block3_conv1 (Conv2D) [0]	(None, 64, 64, 256)	295168	block2_pool[0]
block3_conv2 (Conv2D) [0]	(None, 64, 64, 256)	590080	block3_conv1[0]
block3_conv3 (Conv2D) [0]	(None, 64, 64, 256)	590080	block3_conv2[0]
block3_pool (MaxPooling2D) [0]	(None, 32, 32, 256)	0	block3_conv3[0]
block4_conv1 (Conv2D) [0]	(None, 32, 32, 512)	1180160	block3_pool[0]
block4_conv2 (Conv2D) [0]	(None, 32, 32, 512)	2359808	block4_conv1[0]
block4_conv3 (Conv2D) [0]	(None, 32, 32, 512)	2359808	block4_conv2[0]

block4_pool (MaxPooling2D) [0]	(None, 16, 16, 512) 0	block4_conv3[0]
block5_conv1 (Conv2D) [0]	(None, 16, 16, 512) 2359808	block4_pool[0]
block5_conv2 (Conv2D) [0]	(None, 16, 16, 512) 2359808	block5_conv1[0]
block5_conv3 (Conv2D) [0]	(None, 16, 16, 512) 2359808	block5_conv2[0]
block5_pool (MaxPooling2D) [0]	(None, 8, 8, 512) 0	block5_conv3[0]
decoder_stage0_upsample (UpSamp [0]	(None, 16, 16, 512) 0	block5_pool[0]
concatenate_1 (Concatenate) upsample[0][0]	(None, 16, 16, 1024) 0	decoder_stage0_
[0]		block5_conv3[0]
decoder_stage0_conv1 (Conv2D) [0][0]	(None, 16, 16, 256) 2359296	concatenate_1
decoder_stage0_bn1 (BatchNormal conv1[0][0]	(None, 16, 16, 256) 1024	decoder_stage0_
decoder_stage0_relu1 (Activatio bn1[0][0]	(None, 16, 16, 256) 0	decoder_stage0_
decoder_stage0_conv2 (Conv2D) relu1[0][0]	(None, 16, 16, 256) 589824	decoder_stage0_
decoder_stage0_bn2 (BatchNormal conv2[0][0]	(None, 16, 16, 256) 1024	decoder_stage0_
decoder_stage0_relu2 (Activatio bn2[0][0]	(None, 16, 16, 256) 0	decoder_stage0_
decoder_stage1_upsample (UpSamp relu2[0][0]	(None, 32, 32, 256) 0	decoder_stage0_
concatenate_2 (Concatenate) upsample[0][0]	(None, 32, 32, 768) 0	decoder_stage1_

[0]			block4_conv3[0]
decoder_stage1_conv1 (Conv2D) [0][0]	(None, 32, 32, 128)	884736	concatenate_2
decoder_stage1_bn1 (BatchNormal [0][0]	(None, 32, 32, 128)	512	decoder_stage1_
decoder_stage1_relu1 (Activatio [0][0]	(None, 32, 32, 128)	0	decoder_stage1_
decoder_stage1_conv2 (Conv2D) [0][0]	(None, 32, 32, 128)	147456	decoder_stage1_
decoder_stage1_bn2 (BatchNormal [0][0]	(None, 32, 32, 128)	512	decoder_stage1_
decoder_stage1_relu2 (Activatio [0][0]	(None, 32, 32, 128)	0	decoder_stage1_
decoder_stage2_upsample (UpSamp [0][0]	(None, 64, 64, 128)	0	decoder_stage1_
concatenate_3 (Concatenate) [0][0]	(None, 64, 64, 384)	0	decoder_stage2_
			block3_conv3[0]
decoder_stage2_conv1 (Conv2D) [0][0]	(None, 64, 64, 64)	221184	concatenate_3
decoder_stage2_bn1 (BatchNormal [0][0]	(None, 64, 64, 64)	256	decoder_stage2_
decoder_stage2_relu1 (Activatio [0][0]	(None, 64, 64, 64)	0	decoder_stage2_
decoder_stage2_conv2 (Conv2D) [0][0]	(None, 64, 64, 64)	36864	decoder_stage2_
decoder_stage2_bn2 (BatchNormal [0][0]	(None, 64, 64, 64)	256	decoder_stage2_
decoder_stage2_relu2 (Activatio [0][0]	(None, 64, 64, 64)	0	decoder_stage2_

decoder_stage3_upsample (UpSamp (None, 128, 128, 64) 0 relu2[0][0]		decoder_stage2_
concatenate_4 (Concatenate) (None, 128, 128, 192 0 upsample[0][0] [0]		decoder_stage3_
decoder_stage3_conv1 (Conv2D) (None, 128, 128, 32) 55296 [0][0]		concatenate_4
decoder_stage3_bn1 (BatchNormal (None, 128, 128, 32) 128 conv1[0][0]		decoder_stage3_
decoder_stage3_relu1 (Activatio (None, 128, 128, 32) 0 bn1[0][0]		decoder_stage3_
decoder_stage3_conv2 (Conv2D) (None, 128, 128, 32) 9216 relu1[0][0]		decoder_stage3_
decoder_stage3_bn2 (BatchNormal (None, 128, 128, 32) 128 conv2[0][0]		decoder_stage3_
decoder_stage3_relu2 (Activatio (None, 128, 128, 32) 0 bn2[0][0]		decoder_stage3_
decoder_stage4_upsample (UpSamp (None, 256, 256, 32) 0 relu2[0][0]		decoder_stage3_
decoder_stage4_conv1 (Conv2D) (None, 256, 256, 16) 4608 upsample[0][0]		decoder_stage4_
decoder_stage4_bn1 (BatchNormal (None, 256, 256, 16) 64 conv1[0][0]		decoder_stage4_
decoder_stage4_relu1 (Activatio (None, 256, 256, 16) 0 bn1[0][0]		decoder_stage4_
decoder_stage4_conv2 (Conv2D) (None, 256, 256, 16) 2304 relu1[0][0]		decoder_stage4_
decoder_stage4_bn2 (BatchNormal (None, 256, 256, 16) 64 conv2[0][0]		decoder_stage4_

```

decoder_stage4_relu2 (Activation) (None, 256, 256, 16) 0 decoder_stage4_
bn2[0][0]

final_conv (Conv2D) (None, 256, 256, 21) 3045 decoder_stage4_
relu2[0][0]

softmax (Activation) (None, 256, 256, 21) 0 final_conv[0]
[0]
=====
=====

Total params: 19,032,485
Trainable params: 19,030,501
Non-trainable params: 1,984

```

```

In [65]: # https://github.com/qubvel/segmentation_models
import segmentation_models as sm
from segmentation_models.metrics import iou_score
from segmentation_models import Unet

optim = tf.keras.optimizers.Adam(0.0001)

focal_loss = sm.losses.cce_dice_loss

# actually total_loss can be imported directly from library, above example just
# show you how to manipulate with losses
# total_loss = sm.losses.binary_focal_dice_loss
# or total_loss = sm.losses.categorical_focal_dice_loss

model.compile(optim, focal_loss, metrics=[iou_score])

```

```

In [57]: his = model.fit(train_dataloader, steps_per_epoch=len(train_dataloader), epochs
=5, validation_data=test_dataloader, callbacks=call)

```

```

Epoch 1/5
222/222 [=====] - 6632s 30s/step - loss: 0.8025 - iou_
core: 0.1877 - val_loss: 0.5741 - val_iou_score: 0.3900
Epoch 2/5
222/222 [=====] - 6245s 28s/step - loss: 0.4182 - iou_
core: 0.5731 - val_loss: 0.3610 - val_iou_score: 0.6009
Epoch 3/5
222/222 [=====] - 6170s 28s/step - loss: 0.3869 - iou_
core: 0.6046 - val_loss: 0.3529 - val_iou_score: 0.6103
Epoch 4/5
222/222 [=====] - 6185s 28s/step - loss: 0.3854 - iou_
core: 0.6064 - val_loss: 0.3551 - val_iou_score: 0.6110
Epoch 5/5
222/222 [=====] - 6837s 31s/step - loss: 0.3853 - iou_
core: 0.6064 - val_loss: 0.3613 - val_iou_score: 0.6057

```

```

In [ ]: images_ = X_test['images'].values
masks_ = X_test['mask'].values
lst = np.arange(len(images_))

```

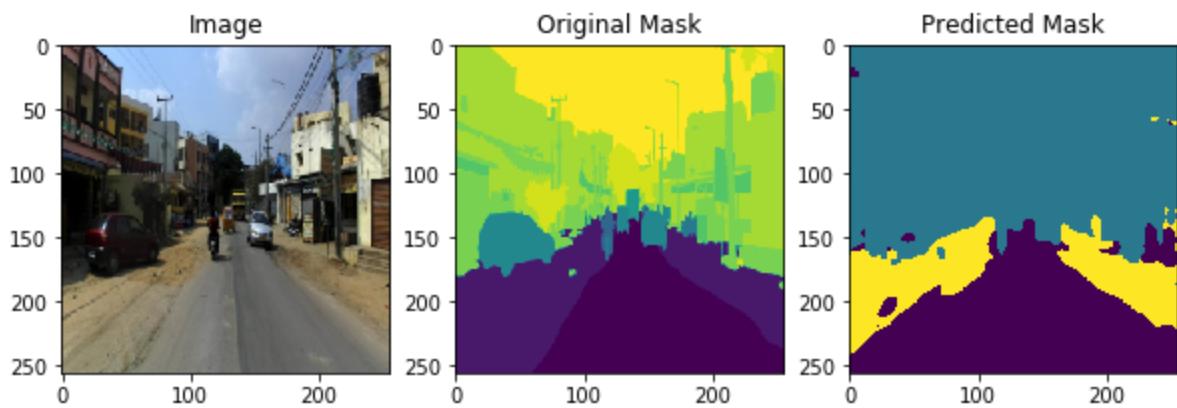
In [60]:

```
import random
ids = np.random.choice(lst, size = 15, replace = False)
for i in ids:
    image = cv2.imread(images_[i], cv2.IMREAD_UNCHANGED)
    image = cv2.resize(image, (256, 256), interpolation = cv2.INTER_AREA)
    image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
    image = np.expand_dims(image, axis=0)

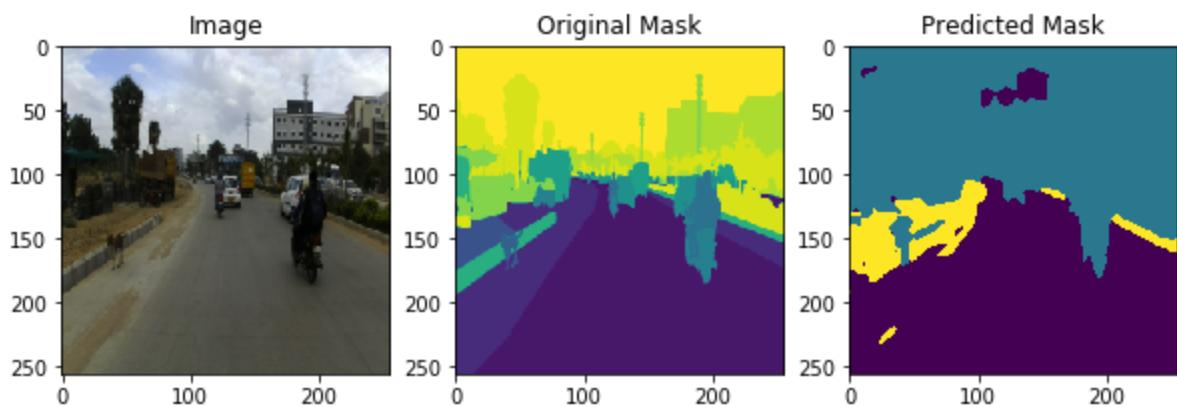
    mask = cv2.imread(masks_[i], cv2.IMREAD_UNCHANGED)
    mask = cv2.resize(mask, (256, 256), interpolation = cv2.INTER_AREA)
    mask = mask / 10
    pred = model.predict(image, verbose=1)
    pred = tf.argmax(pred, axis=-1)

    fig = plt.figure(figsize=(10,6))
# plt.figure(figsize=(10,6))
    ax1 = fig.add_subplot(131)
    ax1.imshow(image[0,:,:])
    ax2=fig.add_subplot(132)
    ax2.imshow(mask)
    ax3=fig.add_subplot(133)
    ax3.imshow(pred[0,:,:])
    ax1.title.set_text('Image')
    ax2.title.set_text('Original Mask')
    ax3.title.set_text('Predicted Mask')
    plt.show()
```

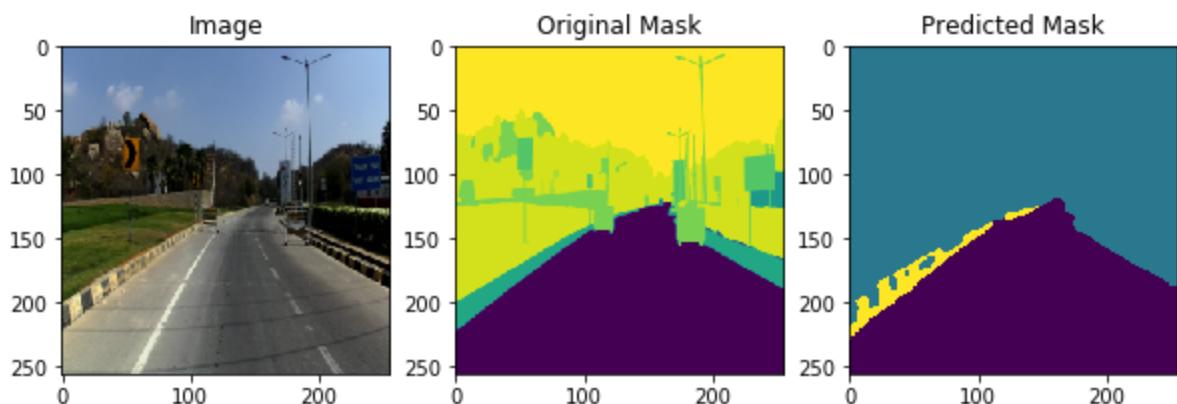
1/1 [=====] - 1s 805ms/step



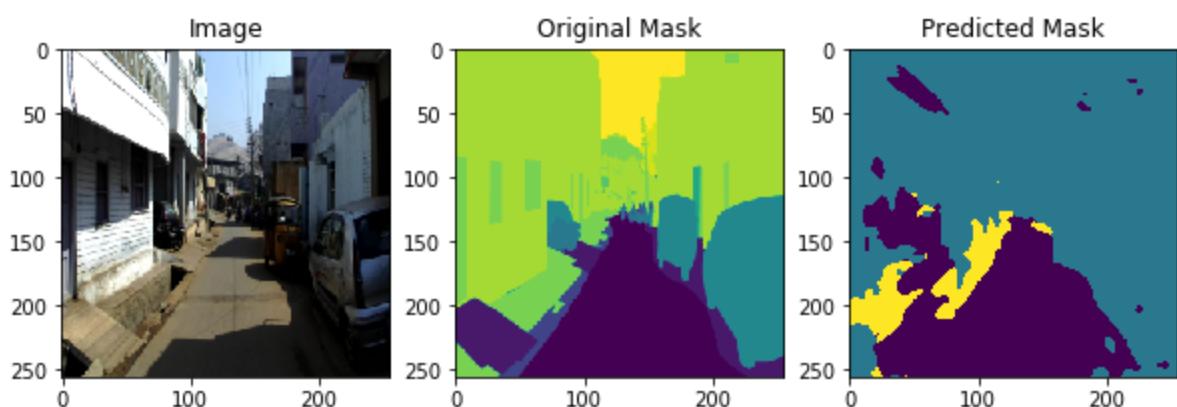
1/1 [=====] - 0s 422ms/step



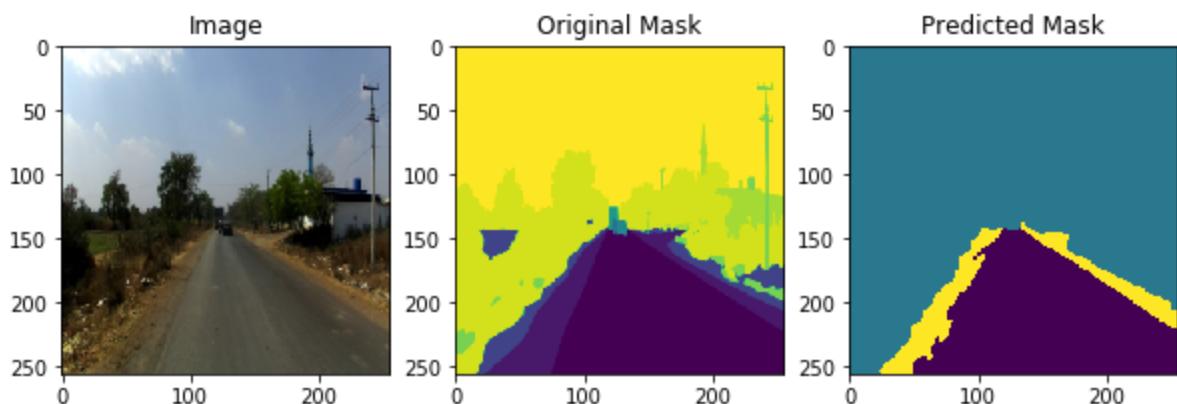
1/1 [=====] - 0s 381ms/step



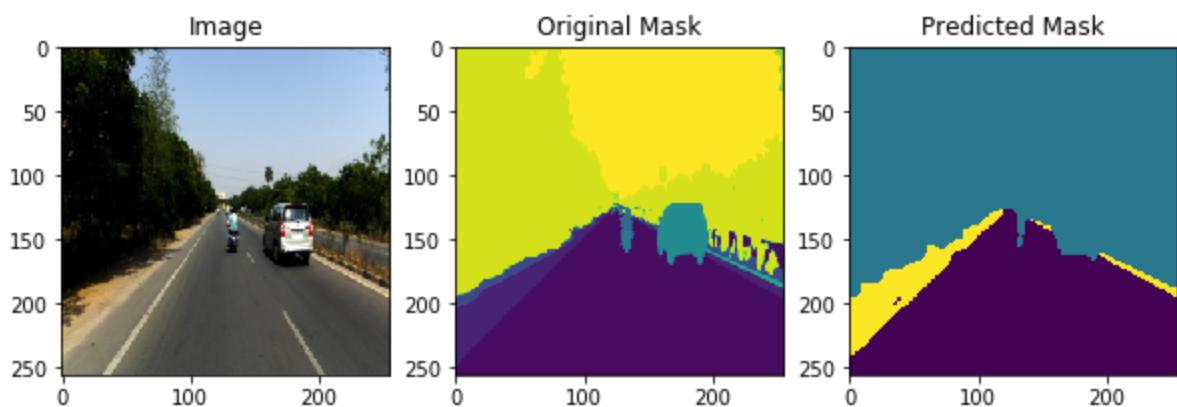
1/1 [=====] - 0s 410ms/step



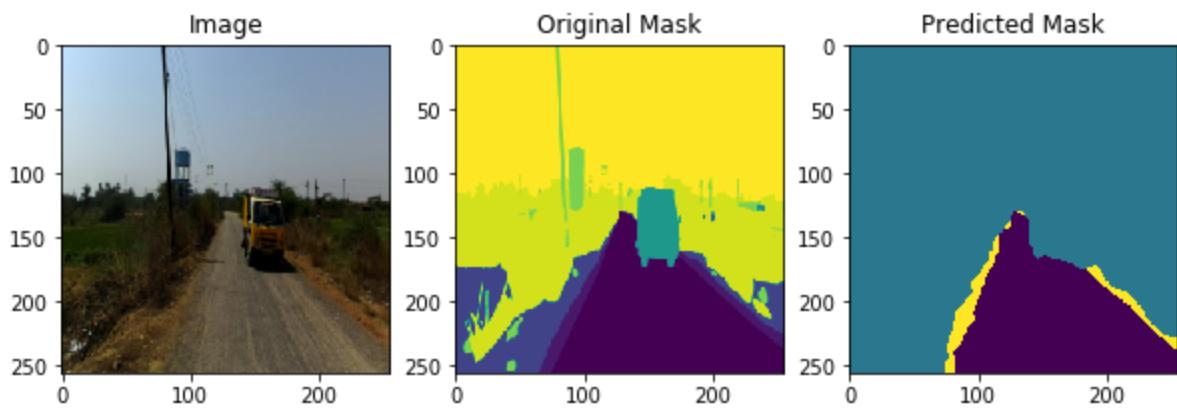
1/1 [=====] - 0s 381ms/step



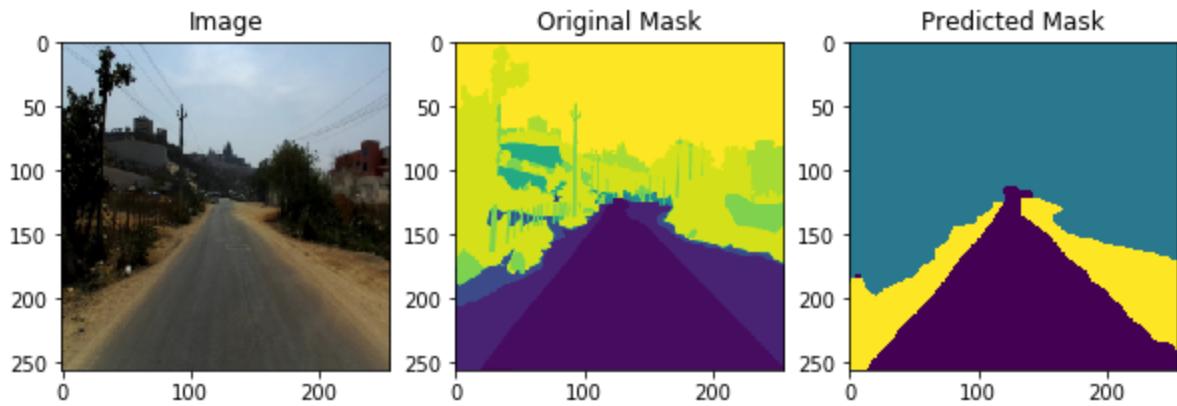
1/1 [=====] - 0s 396ms/step



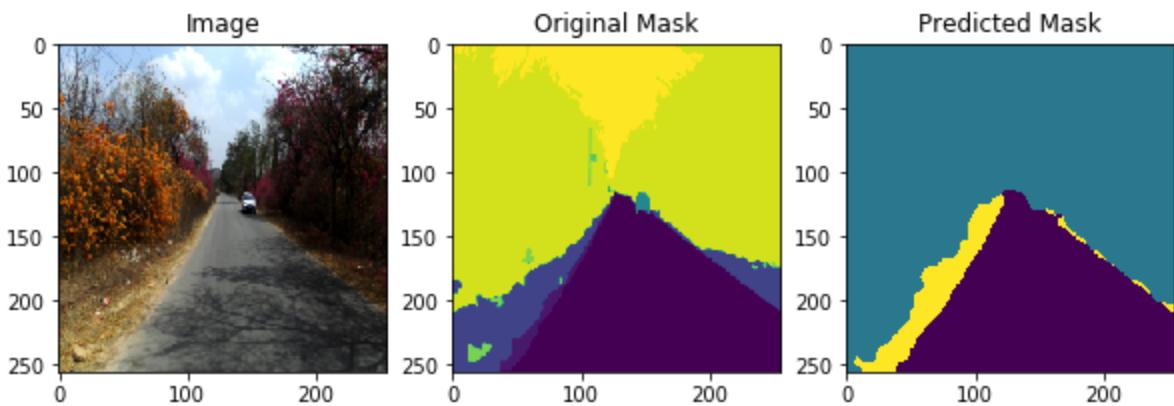
1/1 [=====] - 0s 390ms/step



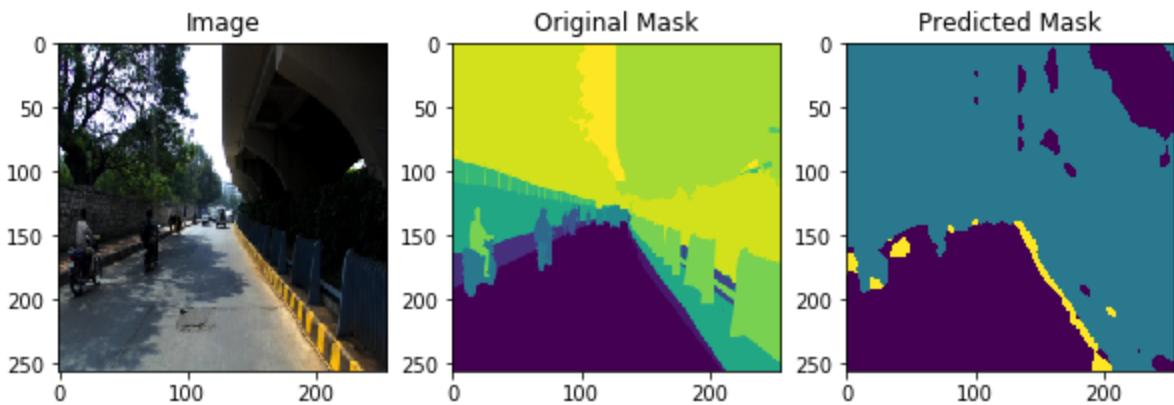
1/1 [=====] - 0s 422ms/step



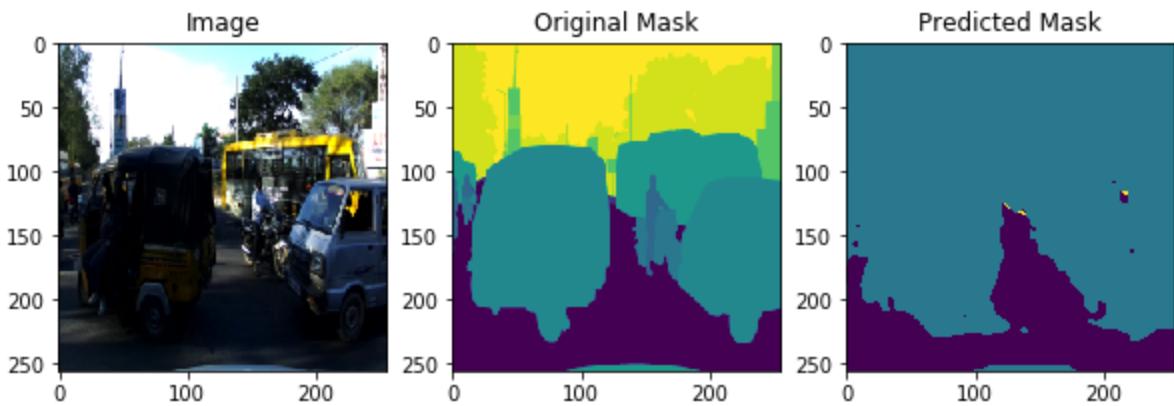
1/1 [=====] - 0s 406ms/step



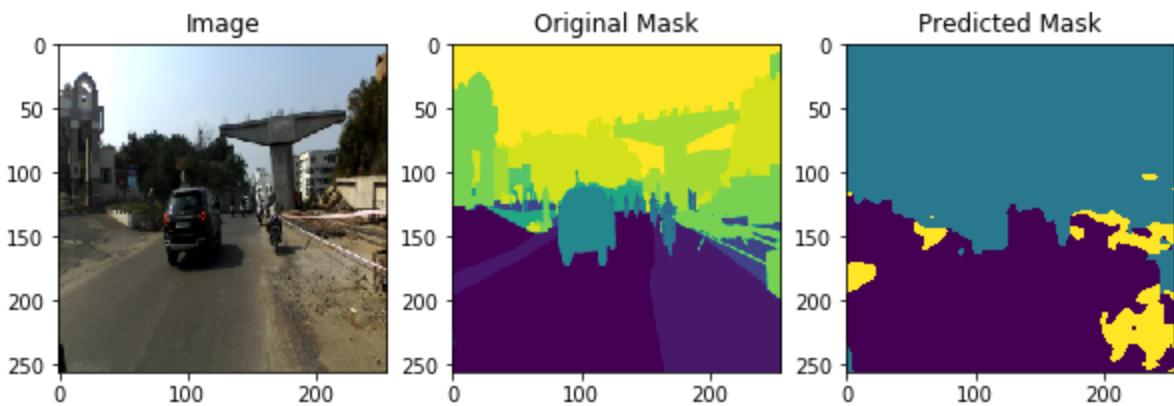
1/1 [=====] - 0s 393ms/step



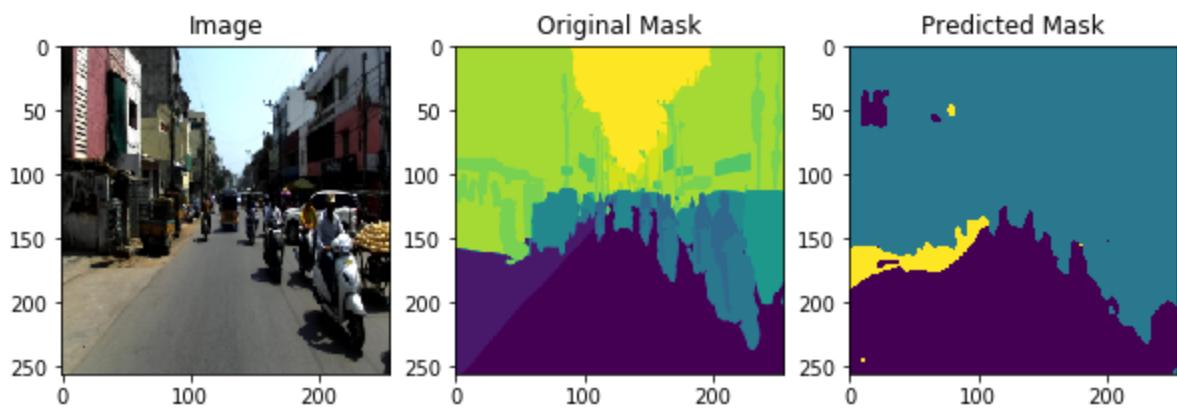
1/1 [=====] - 0s 384ms/step



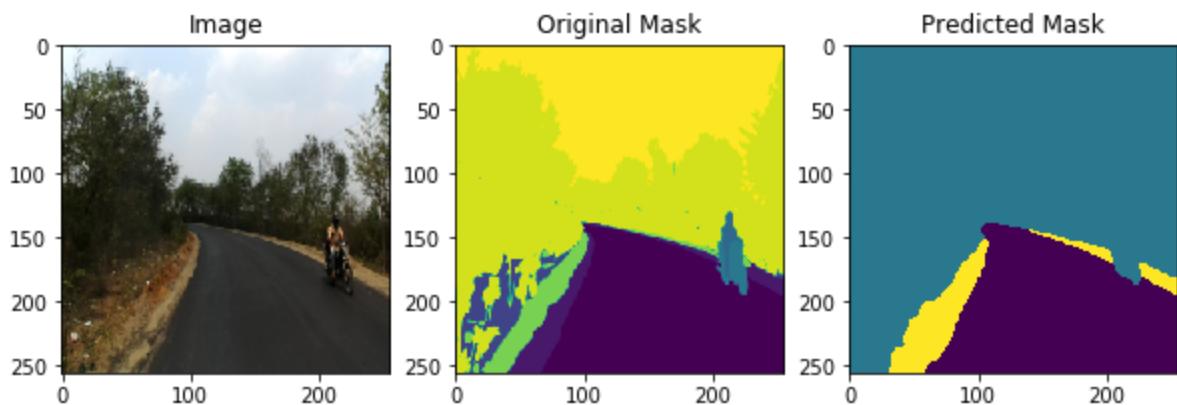
1/1 [=====] - 0s 393ms/step



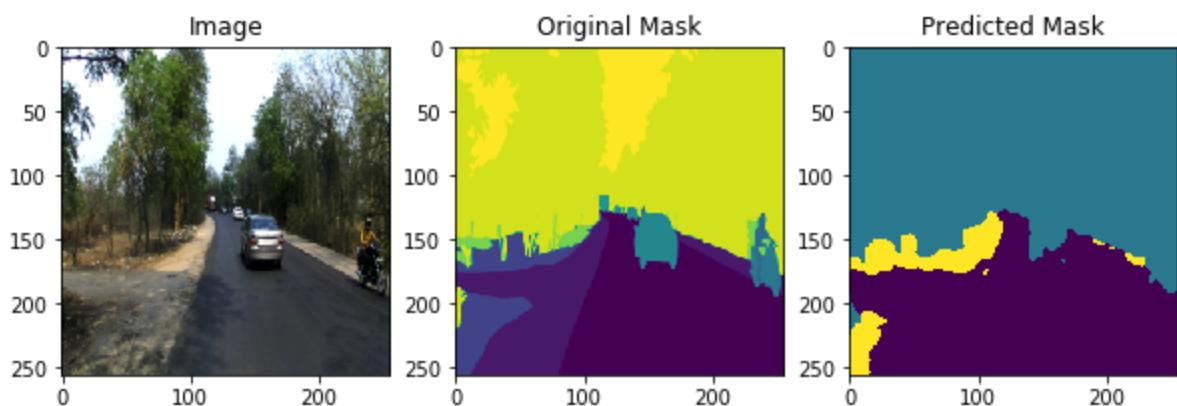
1/1 [=====] - 0s 391ms/step



1/1 [=====] - 0s 398ms/step



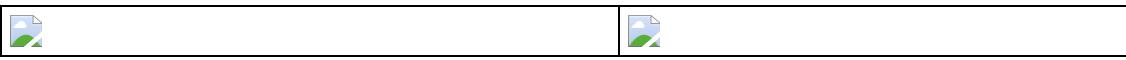
1/1 [=====] - 0s 385ms/step



Task 3: Training CANet

```
In [4]: import tensorflow as tf
# tf.compat.v1.enable_eager_execution()
from tensorflow import keras
from tensorflow.keras.layers import *
from tensorflow.keras.preprocessing import image
from tensorflow.keras.models import Model, load_model
from tensorflow.keras.layers import UpSampling2D
from tensorflow.keras.layers import MaxPooling2D, GlobalAveragePooling2D
from tensorflow.keras.layers import concatenate
from tensorflow.keras.layers import Multiply
from tensorflow.keras.callbacks import EarlyStopping, ModelCheckpoint
from tensorflow.keras import backend as K
from tensorflow.keras.layers import Input, Add, Dense, Activation, ZeroPadding2D, BatchNormalization, Flatten, Conv2D, AveragePooling2D, MaxPooling2D, GlobalMaxPooling2D
from tensorflow.keras.models import Model, load_model
from tensorflow.keras.utils import plot_model
from tensorflow.keras.initializers import glorot_uniform
K.set_image_data_format('channels_last')
K.set_learning_phase(1)
```

- as a part of this assignment we will be implementing the architecture based on this paper <https://arxiv.org/pdf/2002.12041.pdf> (<https://arxiv.org/pdf/2002.12041.pdf>)
 - We will be using the custom layers concept that we used in seq-seq assignment
 - You can devide the whole architecture can be devided into two parts
 - Encoder
 - Decoder
- Encoder:
- The first step of the encoder is to create the channel maps $[C_1, C_2, C_3, C_4]$
 - C_1 width and heights are 4x times less than the original image
 - C_2 width and heights are 8x times less than the original image
 - C_3 width and heights are 8x times less than the original image
 - C_4 width and heights are 8x times less than the original image
 - you can reduce the dimensions by using stride parameter.*
 - $[C_1, C_2, C_3, C_4]$ are formed by applying a "conv block" followed by k number of "identity block". i.e the C_k feature map will single "conv block" followed by k number of "identity blocks".



- The conv block and identity block of C_1 :** the number filters in the covolutional layers will be [4, 4, 8] and the number of filters in the parallel conv layer will also be 8.
- The conv block and identity block of C_2 :** the number filters in the covolutional layers will be [8, 8, 16] and the number of filters in the parallel conv layer will also be 16.
- The conv block and identity block of C_3 :** the number filters in the covolutional layers will be [16, 16, 32] and the number of filters in the parallel conv layer will also be 32.
- The conv block and identity block of C_4 :** the number filters in the covolutional layers will be [32, 32, 64] and the number of filters in the parallel conv layer will also be 64.
- Here \oplus represents the elementwise sum

NOTE: these filters are of your choice, you can explore more options also

- Example: if your image is of size (512, 512, 3)
 - the output after C_1 will be $128 * 128 * 8$
 - the output after C_2 will be $64 * 64 * 16$
 - the output after C_3 will be $64 * 64 * 32$
 - the output after C_4 will be $64 * 64 * 64$

```
In [18]: from tensorflow.keras.layers import Conv2D, GlobalAveragePooling2D, BatchNormalization, Activation, Multiply, UpSampling2D, Add, Concatenate, AveragePooling2D, ReLU
from tensorflow.keras.activations import sigmoid
```

```
In [5]: class convolutional_block(tf.keras.layers.Layer):
    def __init__(self, kernel=3, filters=[4,4,8], stride=2, name="conv block"):
        super(convolutional_block, self).__init__(name=name)
        self.F1, self.F2, self.F3 = filters
        self.kernel = kernel
        self.stride = stride

        self.conv1 = Conv2D(self.F1, kernel_size=(1,1), strides=(self.stride, self.stride), name="conv1")
        self.bn1 = BatchNormalization(name="bn1")
        self.act1 = Activation('relu', name="act1")

        self.conv2 = Conv2D(self.F2, kernel_size=(self.kernel, self.kernel), padding='same', name="conv2")
        self.bn2 = BatchNormalization(name="bn2")
        self.act2 = Activation('relu', name="act2")

        self.conv3 = Conv2D(self.F3, kernel_size=(1,1), name="conv3")
        self.bn3 = BatchNormalization(name="bn3")

        self.parallel_conv = Conv2D(self.F3, kernel_size=(self.kernel, self.kernel), strides=(self.stride, self.stride), padding='same', name="parallel_conv")
        self.bn4 = BatchNormalization(name="bn4")
        self.act3 = Activation('relu', name="act3")

        self.add = Add()
        self.act4 = Activation('relu', name="act4")

    def call(self, inputs):
        # conv1
        conv1 = self.conv1(inputs)
        bn1 = self.bn1(conv1)
        act1 = self.act1(bn1)

        # conv2
        conv2 = self.conv2(act1)
        bn2 = self.bn2(conv2)
        act2 = self.act2(bn2)

        # conv3
        conv3 = self.conv3(act2)
        bn3 = self.bn3(conv3)

        # parallel_conv
        parallel_conv = self.parallel_conv(inputs)
        bn4 = self.bn4(parallel_conv)
        act3 = self.act3(bn4)

        # element-wise sum
        ele_sum = self.add([act3, bn3])

        # final activation
        X = self.act4(ele_sum)

    return X
```

```
In [6]: class identity_block(tf.keras.layers.Layer):
    def __init__(self, kernel=3, filters=[4,4,8], stride=2, name="identity block"):
        super().__init__(name=name)
        self.F1, self.F2, self.F3 = filters
        self.kernel = kernel
        self.stride = stride

        self.conv1 = tf.keras.layers.Conv2D(self.F1, kernel_size=(1,1), strides=(self.stride, self.stride), padding='valid')
        self.bn1 = tf.keras.layers.BatchNormalization()
        self.act1 = tf.keras.layers.Activation('relu')

        self.conv2 = tf.keras.layers.Conv2D(self.F2, kernel_size=(self.kernel, self.kernel), strides=(1,1), padding='same')
        self.bn2 = tf.keras.layers.BatchNormalization()
        self.act2 = tf.keras.layers.Activation('relu')

        self.conv3 = tf.keras.layers.Conv2D(self.F3, kernel_size=(1,1), strides=(1,1), padding='valid')
        self.bn3 = tf.keras.layers.BatchNormalization()

        self.add = tf.keras.layers.Add()
        self.act3 = tf.keras.layers.Activation('relu')

    def call(self, X):
        # save input value for the element-wise sum
        X_shortcut = X

        # 1st component of main path
        X = self.conv1(X)
        X = self.bn1(X)
        X = self.act1(X)

        # 2nd component of main path
        X = self.conv2(X)
        X = self.bn2(X)
        X = self.act2(X)

        # 3rd component of main path
        X = self.conv3(X)
        X = self.bn3(X)

        # add shortcut value to main path, and pass through activation
        X = self.add([X, X_shortcut])
        X = self.act3(X)

    return X
```

- The output of the C_4 will be passed to Chained Context Aggregation Module (CAM)



- The CAM module will have two operations names Context flow and Global flow

- **The Global flow:**

- as shown in the above figure first we will apply global avg_pooling (https://www.tensorflow.org/api_docs/python/tf/keras/layers/GlobalAveragePooling2D) which results in (#, 1, 1, number_of_filters) then applying BN (https://www.tensorflow.org/api_docs/python/tf/keras/layers/BatchNormalization?version=nightly), RELU (https://www.tensorflow.org/api_docs/python/tf/keras/layers/ReLU), 1 * 1 Conv layer sequentially which results a matrix (#, 1, 1, number_of_filters). Finally apply upsampling (https://www.tensorflow.org/api_docs/python/tf/keras/layers/UpSampling2D) / conv2d transpose (https://www.tensorflow.org/api_docs/python/tf/keras/layers/Conv2DTranspose) to make the output same as the input dimensions (#, input_height, input_width, number_of_filters)
- If you use upsampling (https://www.tensorflow.org/api_docs/python/tf/keras/layers/UpSampling2D) then use bilinear pooling as interpolation technique

- **The Context flow:**

- as shown in the above figure (c) the context flow will get inputs from two modules a. C_4 b. From the above flow
- We will be concatinating (https://www.tensorflow.org/api_docs/python/tf/keras/layers/Concatenate) the both inputs on the last axis.
- After the concatenation we will be applying Average pooling (https://www.tensorflow.org/api_docs/python/tf/keras/layers/AveragePooling2D) which reduces the size of feature map by $N \times$ times
- In the paper it was mentioned that to apply a group convolutions, but for the assignment we will be applying the simple conv layers with kernel size (3 * 3)
- We are skipping the channel shuffling
- similarly we will be applying a simple conv layers with kernel size (3 * 3) consider this output is X
- later we will get the $Y = (X \otimes \sigma((1 \times 1)conv(relu((1 \times 1)conv(X))))) \oplus X$, here \oplus is elementwise addition and \otimes is elementwise multiplication
- Finally apply upsampling (https://www.tensorflow.org/api_docs/python/tf/keras/layers/UpSampling2D) / conv2d transpose (https://www.tensorflow.org/api_docs/python/tf/keras/layers/Conv2DTranspose) to make the output same as the input dimensions (#, input_height, input_width, number_of_filters)
- If you use upsampling (https://www.tensorflow.org/api_docs/python/tf/keras/layers/UpSampling2D) then use bilinear pooling as interpolation technique

NOTE: here N times reduction and N time increments makes the input and out shape same, you can explore with the N values, you can choose $N = 2$ or 4

- Example with $N=2$:

- Assume the C_4 is of shape (64,64,64) then the shape of GF will be (64,64,32)
- Assume the C_4 is of shape (64,64,64) and the shape of GF is (64,64,32) then the shape of CF1 will be (64,64,32)
- Assume the C_4 is of shape (64,64,64) and the shape of CF1 is (64,64,32) then the shape of CF2 will be (64,64,32)
- Assume the C_4 is of shape (64,64,64) and the shape of CF2 is (64,64,32) then the shape of CF3 will be (64,64,32)

```
In [7]: class global_flow(tf.keras.layers.Layer):
    def __init__(self, name="global_flow"):
        super().__init__(name=name)
        self.global_avg_pool = GlobalAveragePooling2D()
        self.bn = BatchNormalization()
        self.conv1 = Conv2D(filters=64, kernel_size=1, strides=1, padding="same")
        self.relu = ReLU()
        self.upsample = UpSampling2D(size=(32, 32), interpolation="bilinear")

    def call(self, X):
        # Apply global average pooling
        X = self.global_avg_pool(X)

        # Reshape the output to have shape (batch_size, 1, 1, channels)
        X = tf.reshape(X, shape=(-1, 1, 1, X.shape[-1]))

        # Apply batch normalization and ReLU activation
        X = self.bn(X)
        X = self.relu(X)

        # Apply a 1x1 convolution with 64 filters
        X = self.conv1(X)

        # Apply upsampling with bilinear interpolation to upsample the feature
        map
        X = self.upsample(X)

    return X
```

```
In [26]: class context_flow(tf.keras.layers.Layer):
    def __init__(self, name="context_flow"):
        super().__init__(name=name)
        self.concat = Concatenate()
        self.avg_pool = AveragePooling2D(pool_size=(2, 2))
        self.conv1 = Conv2D(64, kernel_size=(3,3),padding='same')
        self.conv2 = Conv2D(64, kernel_size=(3,3),padding='same')
        self.conv3 = Conv2D(64, kernel_size=(1,1),padding='same')
        self.conv4= Conv2D(64,kernel_size=(1,1),padding='same')
        self.act_relu = Activation('relu')
        self.act_sigmoid = Activation('sigmoid')
        self.upsample = UpSampling2D(size=(2,2),interpolation='bilinear')
        self.add = Add()
        self.multiply =Multiply()

    def call(self, X):
        # here X will a list of two elements
        INP, FLOW = X[0], X[1]
        # implement the context flow as mentioned in the above cell
        concat1 = self.concat([INP, FLOW])
        avg1 = self.avg_pool(concat1)
        conv_1 = self.conv1(avg1)
        conv_2 = self.conv2(conv_1)

        # side path
        conv_3 = self.conv3(conv_2)
        act1 = self.act_relu(conv_3)
        conv_4 = self.conv4(act1)
        act2 = self.act_sigmoid(conv_4)

        # element wise sum

        mul1= self.multiply([conv_2,act2])
        sum2 = self.add([conv_2,mul1])

        X= self.upsample(sum2)

    return X
```

- As shown in the above architecture we will be having 4 context flows
- if you have implemented correctly all the shapes of Global Flow, and 3 context flows will have the same dimension
- the output of these 4 modules will be [added](https://www.tensorflow.org/api_docs/python/tf/keras/layers/Add) (https://www.tensorflow.org/api_docs/python/tf/keras/layers/Add) to get the same output matrix



- The output of after the sum, will be sent to the **Feature selection module FSM**
- Example:
 - if the shapes of GF, CF1, CF2, CF3 are (64,64,32), (64,64,32), (64,64,32), (64,64,32), (64,64,32) respectively then after the sum we will be getting (64,64,32), which will be passed to the next module.

Feature selection module:

- As part of the FSM we will be applying a conv layer (3,3) with the padding="same" so that the output and input will have same shapes
- Let call the output as X
- Pass the X to global pooling which results the matrix (#, 1, 1, number_of_channels)
- Apply 1 * 1 conv layer, after the pooling
- the output of the 1 * 1 conv layer will be passed to the Batch normalization layer, followed by Sigmoid activation function.
- we will be having the output matrix of shape (#, 1, 1, number_of_channels) lets call it 'Y'
- we can interpret this as attention mechanism, i.e for each channel we will having a weight**
- the dimension of X (#, w, h, k) and output above steps Y is (#, 1, 1, k) i.e we need to multiply each channel of X will be [multiplied](https://www.tensorflow.org/api_docs/python/tf/keras/layers/Multiply) (https://www.tensorflow.org/api_docs/python/tf/keras/layers/Multiply). with corresponding channel of Y
- After creating the weighted channel map we will be doing upsampling such that it will double the height and width.
- apply [upsampling](https://www.tensorflow.org/api_docs/python/tf/keras/layers/UpSampling2D) (https://www.tensorflow.org/api_docs/python/tf/keras/layers/UpSampling2D) with bilinear pooling as interpolation technique
- Example:
 - Assume the matrix shape of the input is (64,64,32) then after upsampling it will be (128,128,32)

```
In [32]: class fsm(tf.keras.layers.Layer):
    def __init__(self, name="feature_selection"):
        super().__init__(name=name)
        self.conv_1 = Conv2D(32 ,kernel_size=(3, 3),padding='same')
        self.global_avg_pool = GlobalAveragePooling2D()
        self.conv_2 = Conv2D(32 ,kernel_size=(1,1),padding='same')
        self.bn =BatchNormalization()
        self.act_sigmoid= Activation('sigmoid')
        self.multiply =Multiply()
        self.upsample = UpSampling2D(size=(2,2),interpolation='bilinear')

    def call(self, X):
        # implement the FSM modules based on image in the above cells
        X= self.conv_1(X)
        avg = self.global_avg_pool(X)
        avg= tf.expand_dims(global_avg, 1)
        avg = tf.expand_dims(global_avg, 1)
        conv1= self.conv_2(avg)
        bn1= self.bn(conv1)
        Y = self.act_sigmoid(bn1)
        output = self.multiply([X, Y])
        FSM_Conv_T = self.upsample(output)

    return FSM_Conv_T
```

- **Adapted Global Convolutional Network (AGCN):**



- AGCN will get the input from the output of the "conv block" of C_1
- In all the above layers we will be using the padding="same" and stride=(1,1)
- so that we can have the input and output matrices of same size
- Example:
 - Assume the matrix shape of the input is (128,128,32) then the output it will be (128,128,32)

```
In [31]: class agcn(tf.keras.layers.Layer):
    def __init__(self, name="global_conv_net"):
        super().__init__(name=name)
        self.con1 = Conv2D(32,kernel_size=(1, 7),padding='same')
        self.con2 = Conv2D(32,kernel_size=(7,1),padding='same')
        self.con3 = Conv2D(32,kernel_size=(1, 7),padding='same')
        self.con4 = Conv2D(32,kernel_size=(7,1),padding='same')
        self.con3 = Conv2D(32,kernel_size=(3,3),padding='same')
        self.add = Add()

    def call(self, X):
        # please implement the above mentioned architecture
        c1 = self.con1(X)
        conv2= self.con2(c1)

        # side path
        conv3 = self.con4(X)
        conv4 = self.con3(conv3)

        add1 = self.add([conv2,conv4])

        conv5 = self.con3(add1)

        X = self.add([conv5,add1])

    return X
```



- as shown in the architecture, after we get the AGCN it will get concatenated with the FSM output
- If we observe the shapes both AGCN and FSM will have same height and weight
- we will be concatenating both these outputs over the last axis
- The concatenated output will be passed to a conv layers with filters = number of classes in our data set and the activation function = 'relu'
- we will be using padding="same" which results in the same size feature map
- If you observe the shape of matrix, it will be 4x times less than the original image
- to make it equal to the original output shape, we will do 4x times upsampling of rows and columns
- apply upsampling (https://www.tensorflow.org/api_docs/python/tf/keras/layers/UpSampling2D) with bilinear pooling as interpolation technique
- Finally we will be applying sigmoid activation.
- Example:
 - Assume the matrix shape of AGCN is (128,128,32) and FSM is (128,128,32) the concatenation will make it (128, 128, 64)
 - Applying conv layer will make it (128,128,21)
 - Finally applying upsampling will make it (512, 512, 21)
 - Applying sigmoid will result in the same matrix (512, 512, 21)

```
In [29]: from tensorflow.keras.layers import Conv2D, GlobalAveragePooling2D, BatchNormalization, Activation, Multiply, UpSampling2D, Add, Concatenate, AveragePooling2D, ReLU
from tensorflow.keras.activations import sigmoid
```

```
In [ ]: X_input = Input(shape=(256, 256, 3))
X = Conv2D(64, (3, 3), name='conv1', padding="same", kernel_initializer=glorot_uniform(seed=0))(X_input)
X = BatchNormalization(axis=3, name='bn_conv1')(X)
X = Activation('relu')(X)
X = MaxPooling2D((2, 2), strides=(2, 2))(X)
```

```
In [35]: X = convolutional_block(kernel=3,filters=[4,4,8],stride= 2,name  = 'conv_block
1')(X)
X_CC1 = X
X = identity_block(kernel = 3,filters=[4,4,8],stride=1,name='identity_block11')
(X)

X = convolutional_block(kernel=3,filters=[8,8,16],stride= 2,name  = 'conv_block
2')(X)
X = identity_block(kernel = 3,filters=[8,8,16],stride=1,name='identity_block2
1')(X)
X = identity_block(kernel = 3,filters=[8,8,16],stride=1,name='identity_block2
2')(X)

X = convolutional_block(kernel=3,filters=[16,16,32],stride= 1,name  = 'conv_blo
ck3')(X)
X = identity_block(kernel = 3,filters=[16,16,32],stride=1,name='identity_block3
1')(X)
X = identity_block(kernel = 3,filters=[16,16,32],stride=1,name='identity_block3
2')(X)
X = identity_block(kernel = 3,filters=[16,16,32],stride=1,name='identity_block3
3')(X)

X = convolutional_block(kernel=3,filters=[32,32,64],stride= 1,name  = 'conv_blo
ck4')(X)
X = identity_block(kernel = 3,filters=[32,32,64],stride=1,name='identity_block4
1')(X)
X = identity_block(kernel = 3,filters=[32,32,64],stride=1,name='identity_block4
2')(X)
X = identity_block(kernel = 3,filters=[32,32,64],stride=1,name='identity_block4
3')(X)
X_id4 = identity_block(kernel = 3,filters=[32,32,64],stride=1,name='identity_b
lock44')(X)

X = global_flow(name = 'global_flow')(X_id4)
X_GF = X
X_Ccff1 = context_flow(name='context_flow1')([X_id4,X_GF])
X_Ccff2 = context_flow(name='context_flow2')([X_id4,X_Ccff1])
X_CF3 = context_flow(name='context_flow3')([X_id4,X_Ccff2])
added = add([X,X_Ccff1,X_Ccff2,X_CF3])
X_FSM = fsm(name='fsm_stage')(added)
X_agcn = agcn(name='agcn')(X_CC1)
concat = Concatenate()([X_FSM,X_agcn])

Final1 = Conv2D(21, (3, 3), activation = 'relu', padding = 'same', name = 'Fin
alBlock1')(concat)

o_Final  = UpSampling2D((4,4), interpolation = 'bilinear')(Final1)

Final = (Activation('softmax'))(o_Final)
```

```
In [ ]: model = Model(inputs = X_input, outputs = Final, name='ResNet50')
```

- If you observe the architecture we are creating a feature map with 2x time less width and height
- we have written the first stage of the code above.
- Write the next layers by using the custom layers we have written

```
In [36]: model.summary()
```

Model: "ResNet50"

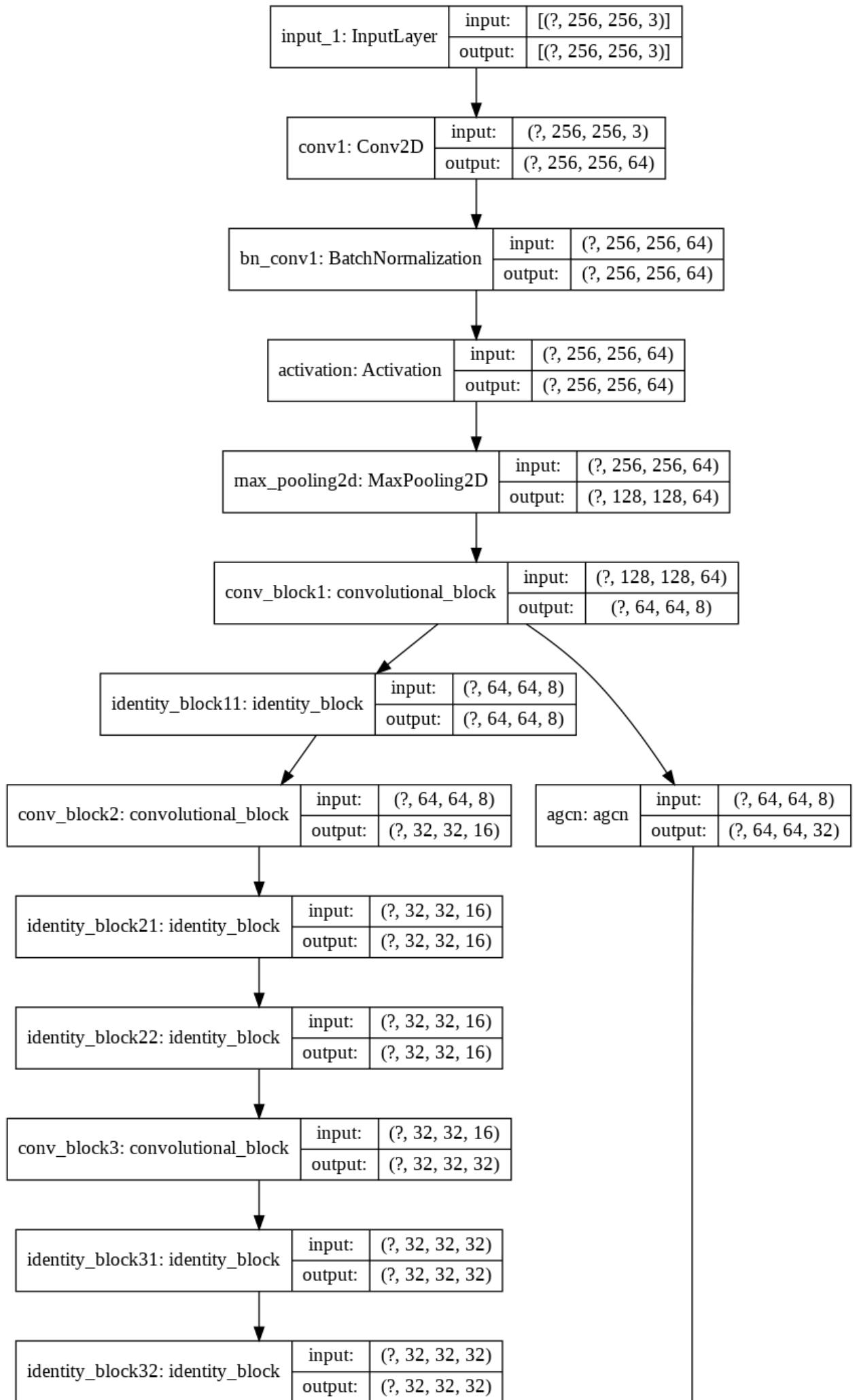
Layer (type)	Output Shape	Param #	Connected to
input_5 (InputLayer)	[None, 256, 256, 3]	0	
conv1 (Conv2D)	(None, 256, 256, 64)	1792	input_5[0][0]
bn_conv1 (BatchNormalization)	(None, 256, 256, 64)	256	conv1[0][0]
activation_227 (Activation)	(None, 256, 256, 64)	0	bn_conv1[0][0]
max_pooling2d_4 (MaxPooling2D)	(None, 128, 128, 64)	0	activation_227[0][0]
conv_block1 (convolutional_bloc [0])	(None, 64, 64, 8)	5160	max_pooling2d_4[0][0]
identity_block11 (identity_bloc [0])	(None, 64, 64, 8)	288	conv_block1[0]
conv_block2 (convolutional_bloc [0])	(None, 32, 32, 16)	2160	identity_block11[0]
identity_block21 (identity_bloc [0])	(None, 32, 32, 16)	992	conv_block2[0]
identity_block22 (identity_bloc [0])	(None, 32, 32, 16)	992	identity_block21[0]
conv_block3 (convolutional_bloc [0])	(None, 32, 32, 32)	8160	identity_block22[0]
identity_block31 (identity_bloc [0])	(None, 32, 32, 32)	3648	conv_block3[0]
identity_block32 (identity_bloc [0])	(None, 32, 32, 32)	3648	identity_block31[0]
identity_block33 (identity_bloc [0])	(None, 32, 32, 32)	3648	identity_block32[0]
conv_block4 (convolutional_bloc [0])	(None, 32, 32, 64)	31680	identity_block33[0]

identity_block41 (identity_bloc [0]	(None, 32, 32, 64)	13952	conv_block4[0]
identity_block42 (identity_bloc [0][0]	(None, 32, 32, 64)	13952	identity_block41[0][0]
identity_block43 (identity_bloc [0][0]	(None, 32, 32, 64)	13952	identity_block42[0][0]
identity_block44 (identity_bloc [0][0]	(None, 32, 32, 64)	13952	identity_block43[0][0]
global_flow (global_flow [0][0]	(None, 32, 32, 64)	4416	identity_block44[0][0]
context_flow1 (context_flow [0][0]	(None, 32, 32, 64)	119040	identity_block44[0][0]
			global_flow[0]
context_flow2 (context_flow [0][0]	(None, 32, 32, 64)	119040	identity_block44[0][0]
			context_flow1
context_flow3 (context_flow [0][0]	(None, 32, 32, 64)	119040	identity_block44[0][0]
			context_flow2
add_123 (Add [0][0]	(None, 32, 32, 64)	0	global_flow[0]
			context_flow1
			context_flow2
			context_flow3
fsm_stage (fsm [0][0]	(None, 64, 64, 32)	19648	add_123[0][0]
agcn (agcn [0]	(None, 64, 64, 32)	20096	conv_block1[0]
concatenate_12 (Concatenate [0][0]	(None, 64, 64, 64)	0	fsm_stage[0][0]
			agcn[0][0]

FinalBlock1 (Conv2D) [0][0]	(None, 64, 64, 21)	12117	concatenate_12
up_sampling2d_19 (UpSampling2D) [0]	(None, 256, 256, 21) 0		FinalBlock1[0]
activation_265 (Activation) 9[0][0]	(None, 256, 256, 21) 0		up_sampling2d_1
<hr/>			
<hr/>			
Total params: 531,629			
Trainable params: 529,021			
Non-trainable params: 2,608			
<hr/>			

```
In [ ]: tf.keras.utils.plot_model(  
    model, to_file='model4.png', show_shapes=True, show_layer_names=True,  
    rankdir='TB')
```

Out[]:



In [39]:

identity_block33: identity_block	input:	(?, 32, 32, 32)
	output:	(?, 32, 32, 32)

conv_block4: convolutional_block	input:	(?, 32, 32, 32)
	output:	(?, 32, 32, 64)

Using TensorFlow backend.

identity_block41: identity_block	input:	(?, 32, 32, 64)
	output:	(?, 32, 32, 64)

In [40]:

identity_block42: identity_block	input:	(?, 32, 32, 64)
	output:	(?, 32, 32, 64)

identity_block43: identity_block	input:	(?, 32, 32, 64)
	output:	(?, 32, 32, 64)

identity_block44: identity_block	input:	(?, 32, 32, 64)
	output:	(?, 32, 32, 64)

global_flow: global_flow	input:	(?, 32, 32, 64)
	output:	(?, 32, 32, 64)

context_flow1: context_flow	input:	[(?, 32, 32, 64), (?, 32, 32, 64)]
	output:	(?, 32, 32, 64)

context_flow2: context_flow	input:	[(?, 32, 32, 64), (?, 32, 32, 64)]
	output:	(?, 32, 32, 64)

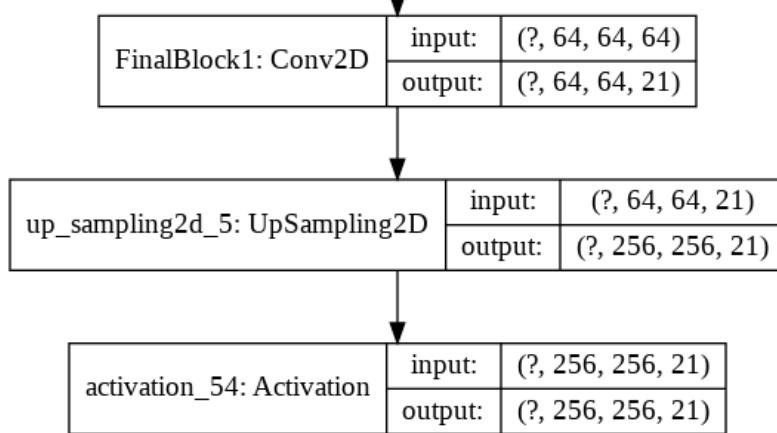
context_flow3: context_flow	input:	[(?, 32, 32, 64), (?, 32, 32, 64)]
	output:	(?, 32, 32, 64)

add_17: Add	input:	[(?, 32, 32, 64), (?, 32, 32, 64), (?, 32, 32, 64), (?, 32, 32, 64)]
	output:	(?, 32, 32, 64)

fsm_stage: fsm	input:	(?, 32, 32, 64)
	output:	(?, 64, 64, 32)

concatenate_3: Concatenate	input:	[(?, 64, 64, 32), (?, 64, 64, 32)]
	output:	(?, 64, 64, 64)

In [43]:



```
class Dataset:  
    # we will be modifying this CLASSES according to your data/problems  
    # CLASSES = a  
  
    # the parameters needs to changed based on your requirements  
    # here we are collecting the file_names because in our dataset, both our images and maks will have same file name  
    # ex: fil_name.jpg      file_name.mask.jpg  
    def __init__(self , basepath , images_file_names , mask_file_names , CLASSES):  
  
        self.image_ids = images_file_names  
        self.mask_ids = mask_file_names  
        # the paths of images  
        self.images_fps   = [os.path.join(basepath,image_id) for image_id in self.image_ids]  
  
        # the paths of segmentation images  
        self.masks_fps    = [os.path.join(basepath,mask_id) for mask_id in self.mask_ids]  
  
        # giving labels for each class  
        self.CLASSES= CLASSES  
        self.class_values = CLASSES  
  
    def __getitem__(self, i):  
  
        # read data  
        image = cv2.imread(self.images_fps[i], cv2.IMREAD_UNCHANGED)  
        image = cv2.resize(image,(256,256),interpolation=cv2.INTER_NEAREST)  
        image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)  
  
        mask = cv2.imread(self.masks_fps[i], cv2.IMREAD_UNCHANGED)  
        image_mask = cv2.resize(mask,(256,256))  
        image_masks = [(image_mask == v) for v in self.class_values]  
        image_mask = np.stack(image_masks, axis=-1).astype('float')  
  
        if self.images_fps[i] in X_train:  
            a = np.random.uniform()  
            if a<0.2:  
                image = aug2.augment_image(image)  
                image_mask = aug2.augment_image(image_mask)  
            elif a<0.4:
```

```

        image = aug3.augment_image(image)
        image_mask = aug3.augment_image(image_mask)
    elif a<0.6:
        image = aug4.augment_image(image)
        image_mask = aug4.augment_image(image_mask)
    elif a<0.8:
        image = aug5.augment_image(image)
        image_mask = image_mask
    else:
        image = aug6.augment_image(image)
        image_mask = aug6.augment_image(image_mask)

    return image, image_mask

def __len__(self):
    return len(self.image_ids)

class Dataloder(tf.keras.utils.Sequence):
    def __init__(self, dataset, batch_size=1, shuffle=False):
        self.dataset = dataset
        self.batch_size = batch_size
        self.shuffle = shuffle
        self.indexes = np.arange(len(dataset))

    def __getitem__(self, i):

        # collect batch data
        start = i * self.batch_size
        stop = (i + 1) * self.batch_size
        data = []
        for j in range(start, stop):
            data.append(self.dataset[j])

        batch = [np.stack(samples, axis=0) for samples in zip(*data)]

        return tuple(batch)

    def __len__(self):
        return len(self.indexes) // self.batch_size

    def on_epoch_end(self):
        if self.shuffle:
            self.indexes = np.random.permutation(self.indexes)

```

In [50]: `import numpy as np`

```
In [44]: # https://github.com/qubvel/segmentation_models
import segmentation_models as sm
from segmentation_models.metrics import iou_score
from segmentation_models import Unet
# optim = tf.keras.optimizers.RMSprop()
optim = tf.keras.optimizers.Adam(0.00001)
focal_loss = sm.losses.dice_loss
#iou_score = sm.metrics.IOUScore(threshold=0.5)
model.compile(optim, focal_loss, metrics=[iou_score])
```

```
C:\Anaconda3\lib\site-packages\classification_models\resnext\__init__.py:4: User
Warning: Current ResNext models are deprecated, use keras.applications.ResNeXt m
odels
    warnings.warn('Current ResNext models are deprecated, '
```

```
In [45]: CLASSES=[0,1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19,20]
n_cl=len(CLASSES)
BATCH_SIZE = 8
IMAGE_SHAPE = (256, 256, 3)
```

```
In [47]: from sklearn.model_selection import train_test_split
X_train, X_test = train_test_split(data_df, test_size=0.11, random_state=42)
X_train.shape
```

```
Out[47]: (3567, 3)
```

```
In [55]: from tensorflow.keras.callbacks import Callback, ModelCheckpoint, TensorBoard, ReduceLROnPlateau
import time

CLASSES = CLASSES
#basepath = '/content/'
basepath='C:/Users/raian/COMPUTER VISION SEGMENTATION/'
train_dataset = Dataset(basepath, X_train['images'].values, X_train['mask'].values, CLASSES=CLASSES)
test_dataset = Dataset(basepath, X_test['images'].values, X_test['mask'].values, CLASSES=CLASSES)

train_dataloader = Dataloder(train_dataset, batch_size=8, shuffle=True)
test_dataloader = Dataloder(test_dataset, batch_size=8, shuffle=True)
```

```
In [56]: print(train_dataloader[0][0].shape)
print(train_dataloader[0][1].shape)
```

```
(8, 256, 256, 3)
(8, 256, 256, 21)
```

```
In [54]: assert train_dataloader[0][0].shape == (BATCH_SIZE, 256, 256, 3)
assert train_dataloader[0][1].shape == (BATCH_SIZE, 256, 256, n_cl)
```

```
In [57]: ten = TensorBoard(log_dir="logs/".format(time.time()), histogram_freq=1, write_graph=True, write_grads=True)
che = ModelCheckpoint('./best_model.h5', save_weights_only=True, save_best_only=True, mode='min', monitor='val_iou_score')
re = ReduceLROnPlateau(monitor='val_iou_score', factor=0.2, min_lr=0.0000001, patience=2)
call = [ten, re]
```

WARNING:tensorflow: `write_grads` will be ignored in TensorFlow 2.0 for the `TensorBoard` Callback.

```
In [74]: his = model.fit(train_dataloader, steps_per_epoch=len(train_dataloader), epochs=3, validation_data=test_dataloader)
```

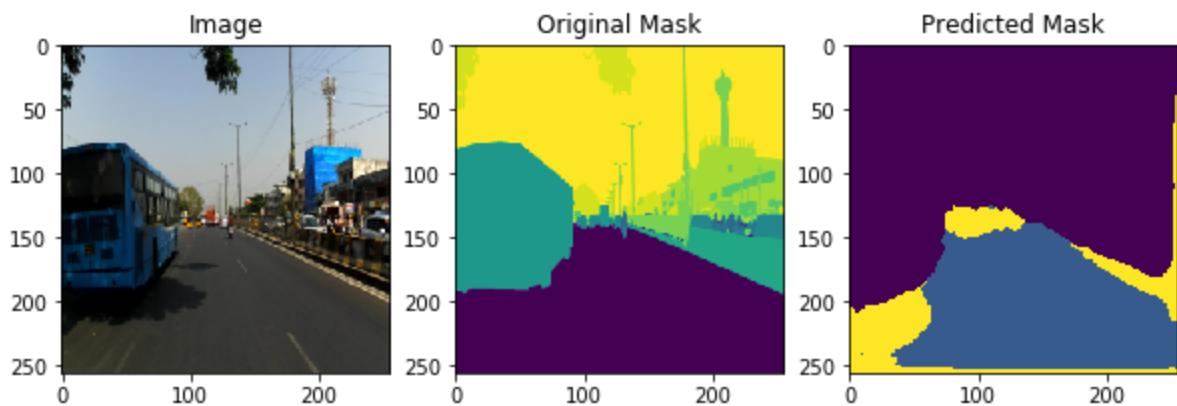
```
Epoch 1/3
445/445 [=====] - 1278s 3s/step - loss: 0.5486 - iou_score: 0.4425 - val_loss: 0.4398 - val_iou_score: 0.5513
Epoch 2/3
445/445 [=====] - 1219s 3s/step - loss: 0.4412 - iou_score: 0.5490 - val_loss: 0.4342 - val_iou_score: 0.5563
Epoch 3/3
445/445 [=====] - 1216s 3s/step - loss: 0.4367 - iou_score: 0.5531 - val_loss: 0.4294 - val_iou_score: 0.5609
```

```
In [75]: images_ = X_test['images'].values
masks_ = X_test['mask'].values
lst = np.arange(len(images_))
import random
ids = np.random.choice(lst, size = 15, replace = False)
for i in ids:
    image = cv2.imread(images_[i], cv2.IMREAD_UNCHANGED)
    image = cv2.resize(image, (256, 256), interpolation = cv2.INTER_AREA)
    image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
    image = np.expand_dims(image, axis=0)

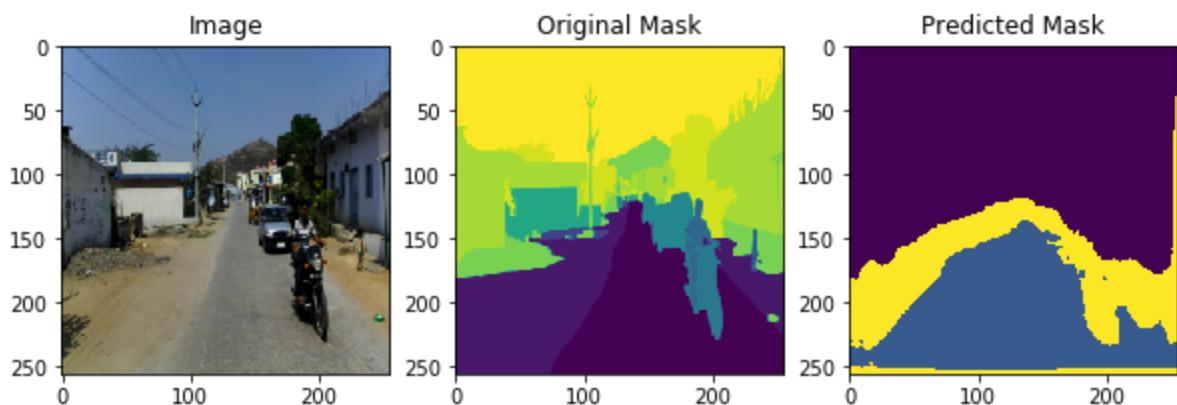
    mask = cv2.imread(masks_[i], cv2.IMREAD_UNCHANGED)
    mask = cv2.resize(mask, (256, 256), interpolation = cv2.INTER_AREA)
    mask = mask / 10
    pred = model.predict(image, verbose=1)
    pred = tf.argmax(pred, axis=-1)

    fig = plt.figure(figsize=(10,6))
#plt.figure(figsize=(10,6))
    ax1 = fig.add_subplot(131)
    ax1.imshow(image[0,:,:])
    ax2=fig.add_subplot(132)
    ax2.imshow(mask)
    ax3=fig.add_subplot(133)
    ax3.imshow(pred[0,:,:])
    ax1.title.set_text('Image')
    ax2.title.set_text('Original Mask')
    ax3.title.set_text('Predicted Mask')
    plt.show()
```

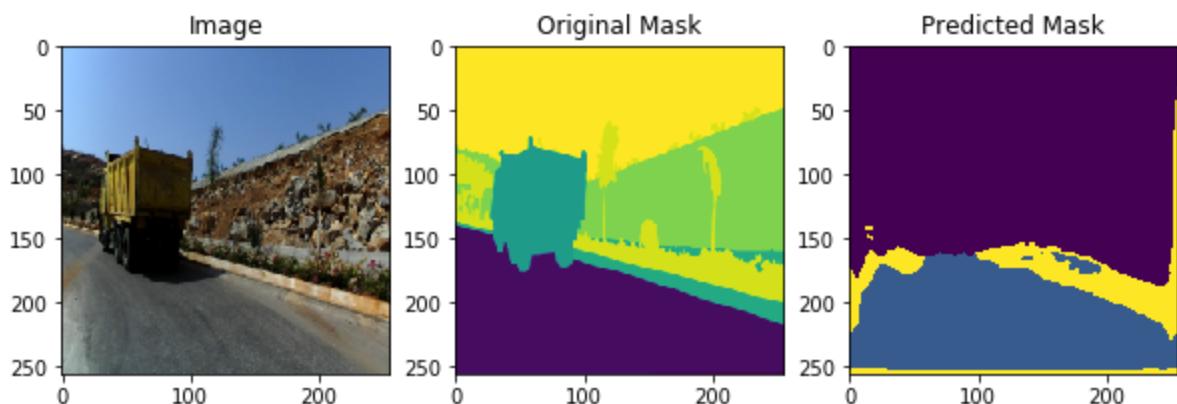
1/1 [=====] - 0s 0s/step



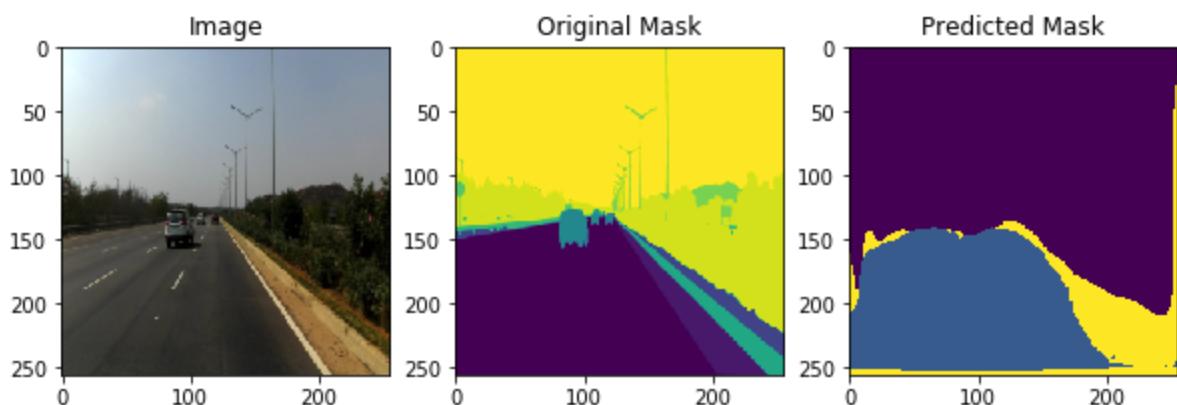
1/1 [=====] - 0s 0s/step



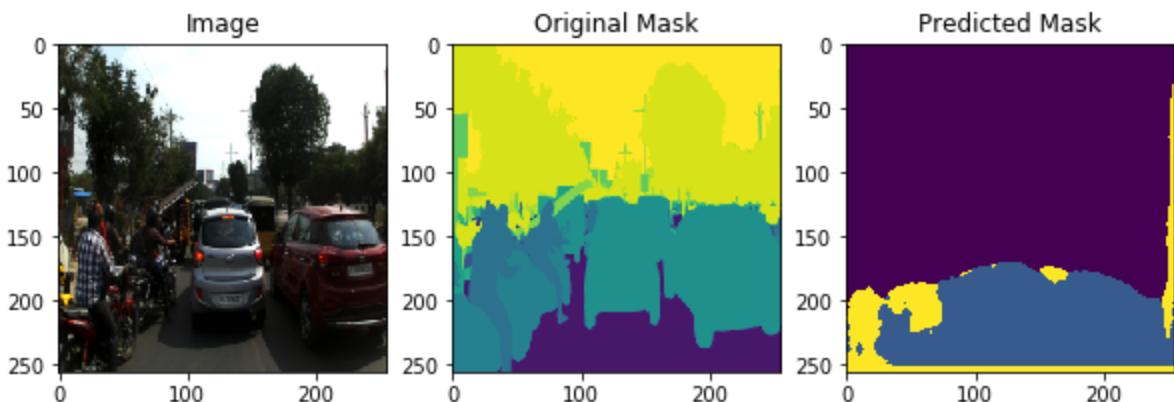
1/1 [=====] - 0s 0s/step



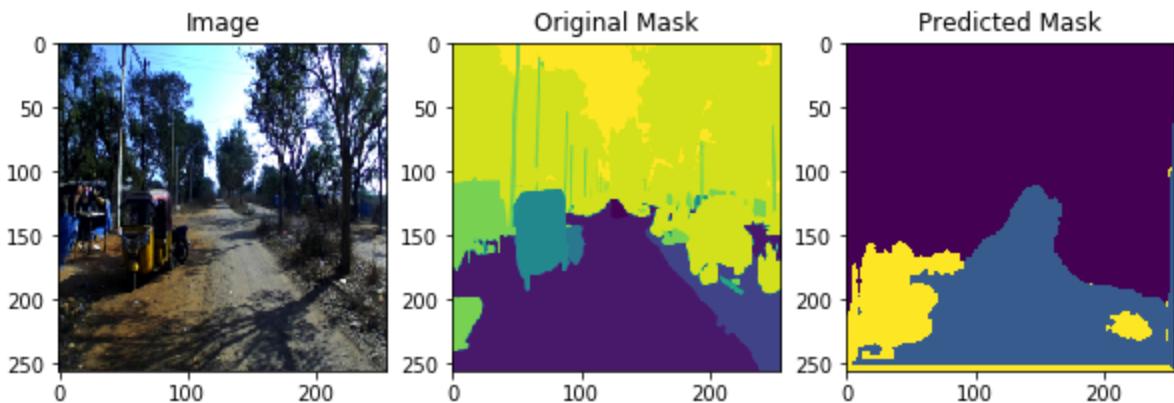
1/1 [=====] - 0s 0s/step



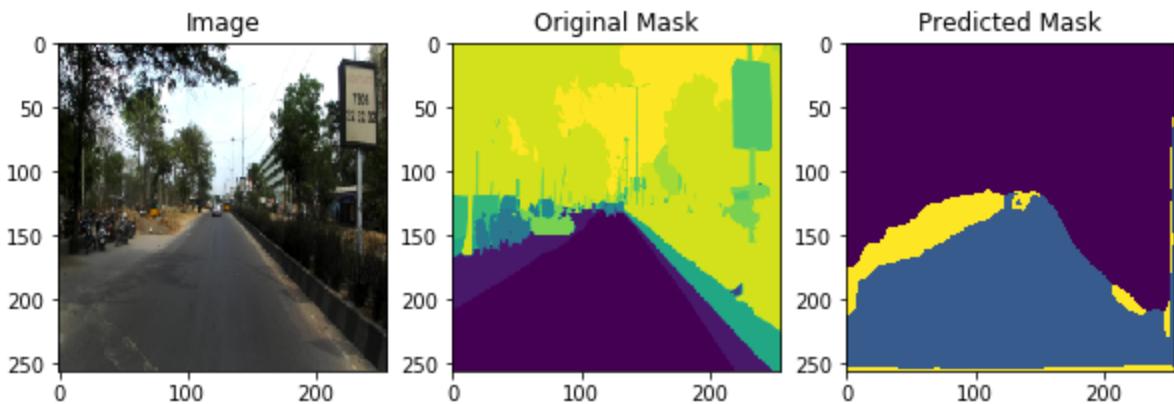
1/1 [=====] - 0s 0s/step



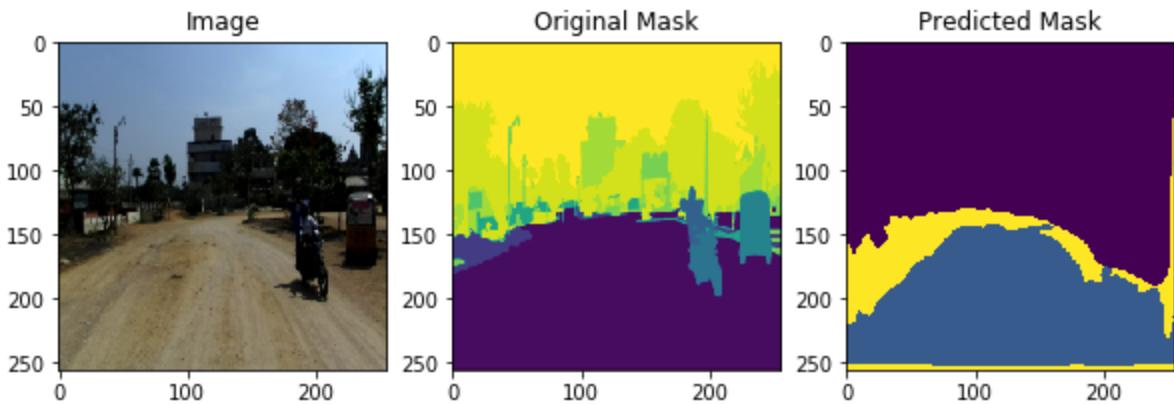
1/1 [=====] - 0s 0s/step



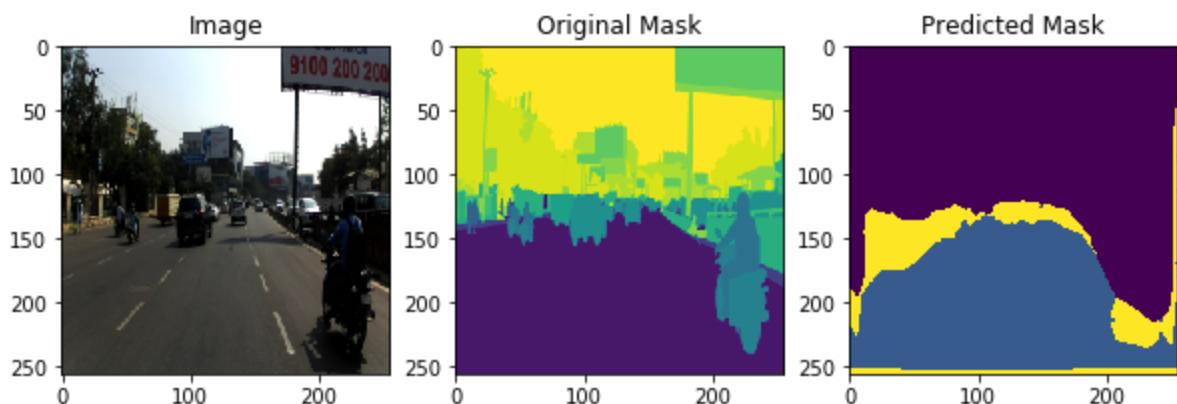
1/1 [=====] - 0s 2ms/step



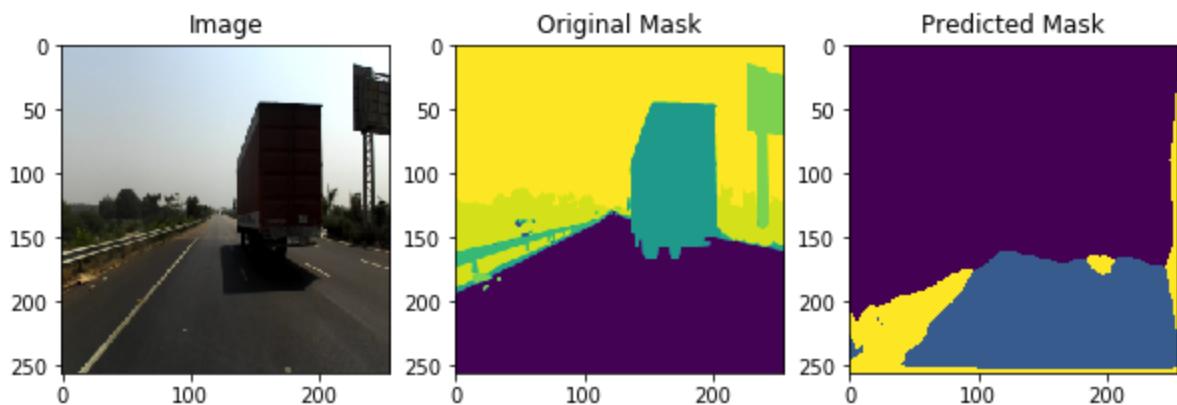
1/1 [=====] - 0s 0s/step



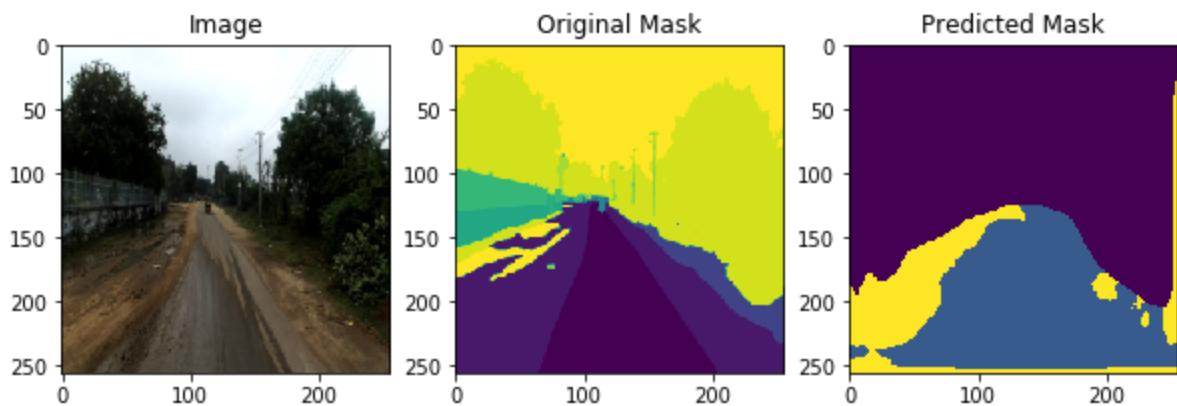
1/1 [=====] - 0s 0s/step



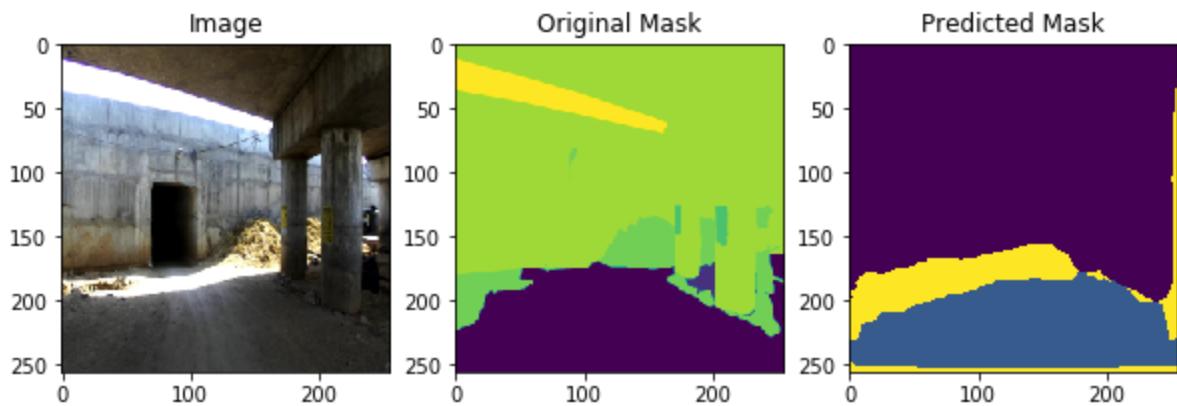
1/1 [=====] - 0s 0s/step



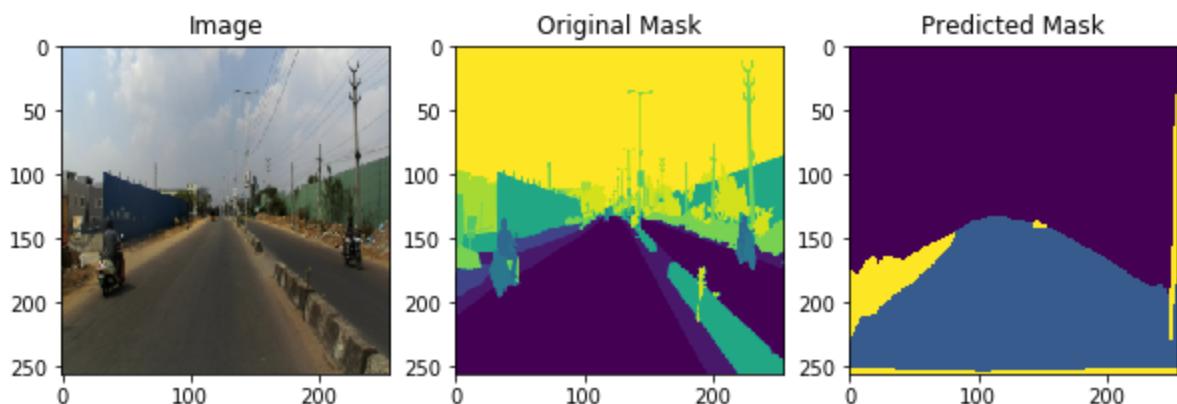
1/1 [=====] - 0s 22ms/step



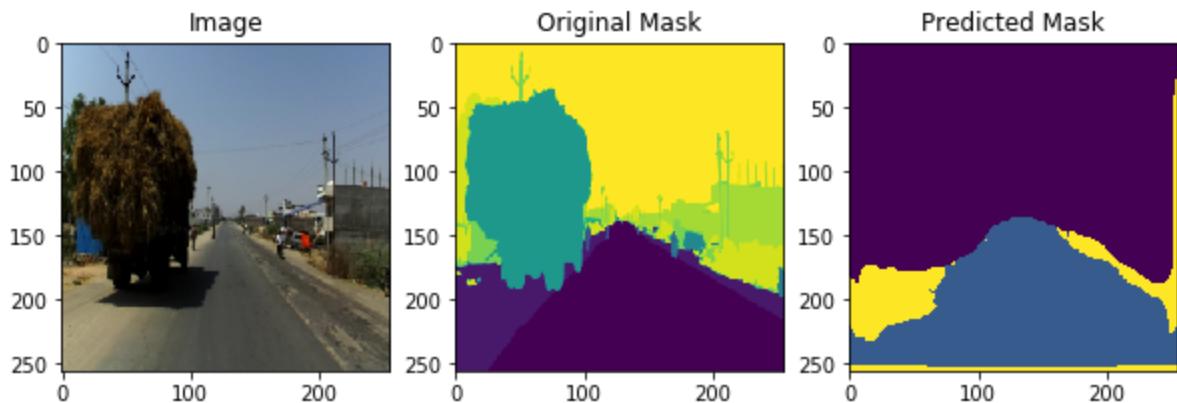
1/1 [=====] - 0s 0s/step



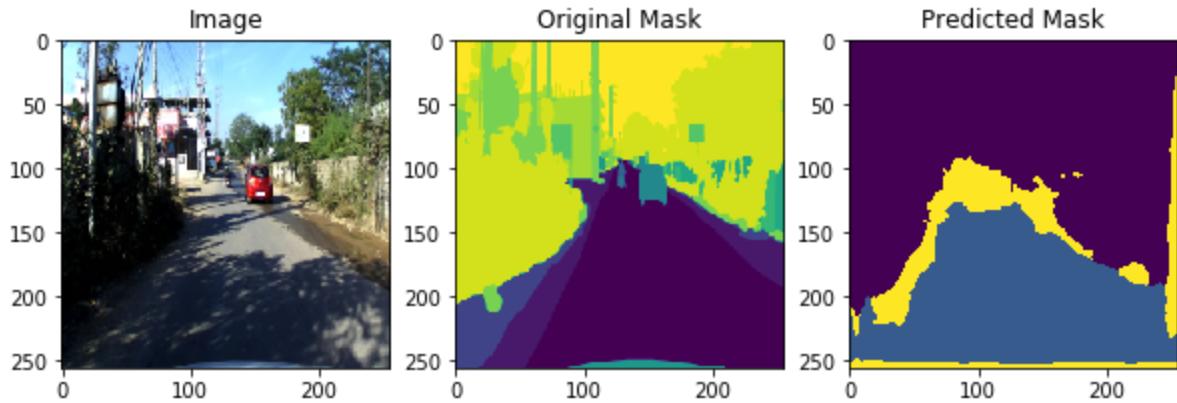
1/1 [=====] - 0s 0s/step



1/1 [=====] - 0s 0s/step



1/1 [=====] - 0s 0s/step



Usefull tips:

- use "interpolation=cv2.INTER_NEAREST" when you are resizing the image, so that it won't mess with the number of classes
- keep the images in the square shape like 256 * 256 or 512 * 512
- Carefull when you are converting the (W, H) output image into (W, H, Classes)
- Even for the canet, use the segmentation model's losses and the metrics
- The goal of this assignment is make you familiar in with computer vision problems, image preprocessing, building complex architectures and implementing research papers, so that in future you will be very confident in industry
- you can use the tensorboard logss to see how is yours model's training happening
- use callbacks that you have implemented in previous assignments

Things to keep in mind

- You need to train above built model and plot the train and test losses.
- Make sure there is no overfitting, you are free play with the identity blocks in C1, C2, C3, C4
- before we apply the final sigmoid activation, you can add more conv layers or BN or dropouts etc
- you are free to use any other optimizer or learning rate or weights init or regularizations