

General Regulations.

- Please hand in your solutions in groups of up to two people.
- Your solutions to theoretical exercises can be either handwritten notes (scanned), or typeset using \LaTeX . In case you hand in handwritten notes, please make sure that they are legible and not too blurred or low resolution.
- For the practical exercises, always provide the (commented) code as well as the output, and don't forget to explain/interpret the latter. Please hand in an exported PDF of your notebook.
- Submit all your files in the Übungsgruppenverwaltung, only once for your group.

0 Evaluation

If you haven't already, please evaluate the lecture via <https://uni-heidelberg.evasys.de/evasys/online.php?pswd=HG8WV>.

1 Paper reading

- KineticNet [1]: You already finished this paper last week.
- M-OFDFT [2]: Please read the subsection “Geometric invariance” in “Methods” and appendix A.3.

Please compare how the machine learning models of KineticNet and M-OFDFT guarantee equivariance. (3 pts)

2 Representation theory

- (a) Give the definition of a representation. What are irreducible representations? (2 pts)
- (b) A matrix A transforms as RAR^{-1} under a rotation R . Decompose A into irreducible representations of the rotation group. (3 pts)
- (c) Given a function $f: \mathcal{X} \rightarrow \mathcal{Y}$ and two representations $\rho_{\mathcal{X}}$ and $\rho_{\mathcal{Y}}$, the condition for the equivariance of f is

$$f(\rho_{\mathcal{X}}(g)x) = \rho_{\mathcal{Y}}(g)f(x) \quad \forall g \in G, x \in \mathcal{X}.$$

Why does it make sense to look at irreducible representations? (2 pts)

3 Tensor product

In this exercise, we want to use the package `e3nn` to investigate the irreducible representations of rotations.

- (a) Write down the tensor product of an l_1 -tensor and an l_2 -tensor in components. Which l -values are allowed in the result? (2 pts)
- (b) The package `e3nn` uses the class `e3nn.o3.Irreps` to represent irreducible representations. Create a tensor product of ten scalars and five vectors with `0e+1o+2e` irreps. Visualize the tensor product with the `visualize` method. Use the `FullyConnectedTensorProduct` to obtain 20 scalars and ten vectors. Explain how you can calculate the number of weights in this product. (4 pts)

- (c) Compute spherical harmonics up to order five and check the equivariance. You can generate a random rotation matrix and use the Wigner D-matrix with the method `D_from_matrix`. (2 pts)
- (d) Compute the Wigner D-matrix for the irreps `5x0e+3x1o+2x2e` for a random rotation and plot it. Explain the structure you observe. (2 pts)
- (e) Choose a radial function with more than one zero crossing, multiply it with a spherical harmonic, and plot the resulting kernel. (**Bonus:** 3 pts)

References

- [1] Roman Remme et al. “KineticNet: Deep learning a transferable kinetic energy functional for orbital-free density functional theory”. In: *The Journal of Chemical Physics* 159.14 (Oct. 2023). ISSN: 0021-9606, 1089-7690. URL: <https://pubs.aip.org/jcp/article/159/14/144113/2916356/KineticNet-Deep-learning-a-transferable-kinetic>.
- [2] He Zhang et al. “Overcoming the barrier of orbital-free density functional theory for molecular systems using deep learning”. In: *Nature Computational Science* 4.3 (Mar. 2024), pp. 210–223. ISSN: 2662-8457. DOI: [10.1038/s43588-024-00605-8](https://doi.org/10.1038/s43588-024-00605-8). URL: https://uebungen.physik.uni-heidelberg.de/c/image/d/vorlesung/20241/1883/material/zhang_24_overcoming.pdf.