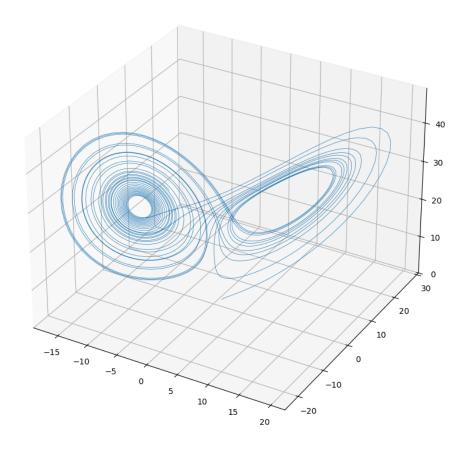
```
import numpy as np
from scipy.integrate import solve_ivp
sigma = 10
beta = 8 / 3
rho = 28
def lorenz(t, state):
   x, y, z = state
   dx_dt = sigma * (y - x)
   dy_dt = x * (rho - z) - y
   dz_dt = x * y - beta * z
   return [dx_dt, dy_dt, dz_dt]
dt = 0.01
n = 3000
T = n * dt
t_{span} = (0, T)
t_eval = np.arange(*t_span, dt)
assert n == len(t_eval)
traj = solve_ivp(fun=lorenz, y0=(1, 1, 1), t_span=t_span, t_eval=t_eval).y.T
import matplotlib.pyplot as plt
def plot_traj(traj, title=None):
    fig = plt.figure(figsize=(10, 10))
    ax = fig.add_subplot(111, projection="3d")
   ax.plot(traj[:, 0], traj[:, 1], traj[:, 2], lw=0.5)
   if title is not None:
        plt.title(title)
   plt.show()
plot_traj(traj)
```

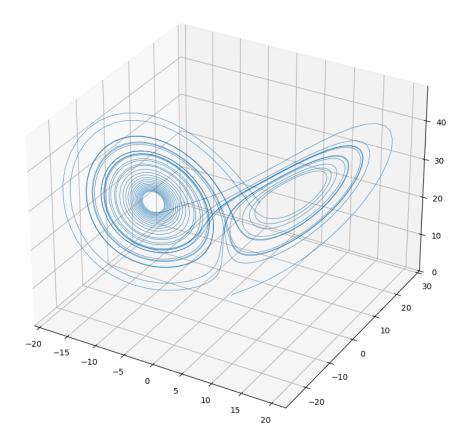


```
import pysindy as ps

poly_order = 6

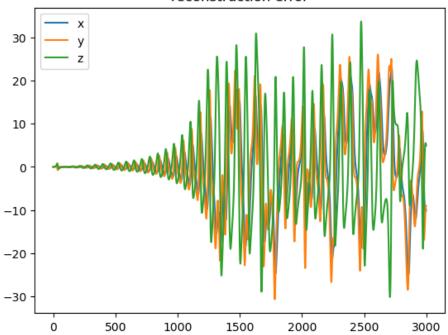
model = ps.SINDy(
    feature_library=ps.PolynomialLibrary(degree=poly_order),
).fit(
    traj,
    t=dt,
)

traj_sim = model.simulate(traj[0, :], t_eval)
plot_traj(traj_sim)
```



```
plt.plot((traj - traj_sim), label=["x", "y", "z"])
plt.title("reconstruction error")
plt.legend()
plt.show()
```





```
def fpe(model, traj, t_eval, N, first_k=None, verbose=True):
    if first_k is not None:
        traj = traj[:first_k,:]
        t_eval = t_eval[:first_k]
   T = traj.shape[0]
    sim = []
   res = 0
    for i in range(T - N):
        if verbose and i \% int(0.1 * (T-N)) == 0:
            print("*** iter %d, %.1f%% ***" % (i, 100 * i / (T - N)))
        subtraj = model.simulate(traj[i, :], t_eval[i : i + N + 1])
        sim.append(subtraj[-1,:])
   for i in range(T - N):
        i += 1
        res += ((sim[-i] - traj[-i]) ** 2 / (T - N)).sum()
   return res
```

Here we use the Lyapunov time, since it's the characteristic time of the onset of the chaotic regime. Much smaller lag values won't cause noticeable deviations, while with much larger values all models will practically lose their predictive power.

```
lam = 0.9056
lyapu_N = int((1/lam) / dt)
print(lyapu_N)
110
for N in [lyapu_N * i // 3 for i in range(1,6)]:
    print('MSE for N=%d:' % N)
   print(fpe(model, traj, t_eval, N))
MSE for N=36:
*** iter 0, 0.0% ***
*** iter 296, 10.0% ***
*** iter 592, 20.0% ***
*** iter 888, 30.0% ***
*** iter 1184, 39.9% ***
*** iter 1480, 49.9% ***
*** iter 1776, 59.9% ***
*** iter 2072, 69.9% ***
*** iter 2368, 79.9% ***
*** iter 2664, 89.9% ***
*** iter 2960, 99.9% ***
0.03259035667526703
MSE for N=73:
*** iter 0, 0.0% ***
*** iter 292, 10.0% ***
*** iter 584, 20.0% ***
*** iter 876, 29.9% ***
*** iter 1168, 39.9% ***
*** iter 1460, 49.9% ***
*** iter 1752, 59.9% ***
*** iter 2044, 69.8% ***
*** iter 2336, 79.8% ***
*** iter 2628, 89.8% ***
*** iter 2920, 99.8% ***
0.6265093651447092
MSE for N=110:
*** iter 0, 0.0% ***
*** iter 289, 10.0% ***
*** iter 578, 20.0% ***
*** iter 867, 30.0% ***
*** iter 1156, 40.0% ***
*** iter 1445, 50.0% ***
```

```
*** iter 1734, 60.0% ***

*** iter 2023, 70.0% ***

*** iter 2312, 80.0% ***

19.091299319002704

MSE for N=146:

*** iter 0, 0.0% ***

*** iter 285, 10.0% ***

*** iter 570, 20.0% ***

*** iter 855, 30.0% ***

*** iter 1140, 39.9% ***

*** iter 1425, 49.9% ***

*** iter 1710, 59.9% ***

*** iter 1995, 69.9% ***
```

It's pointless to look past N=150, since we are reaching an MSE plateau, which is the upper bound given by the diameter of the attractor.

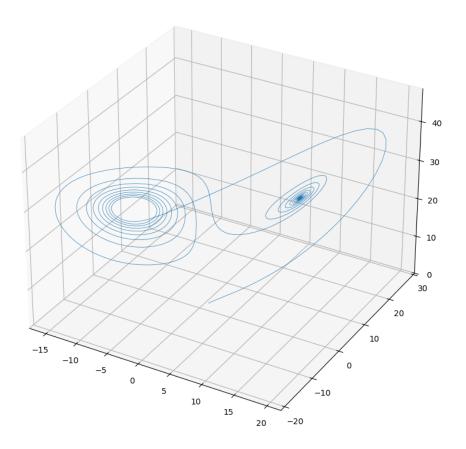
8.1.4

8.1.5

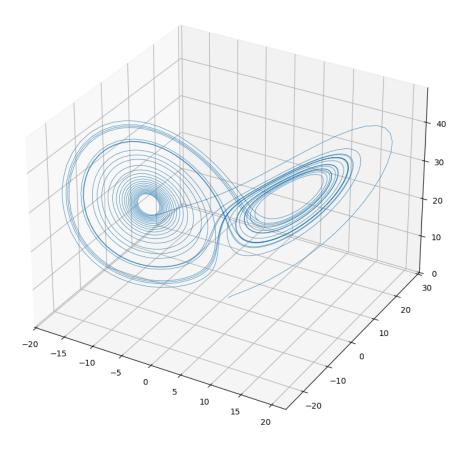
```
def subset_test(n, order=6):
    model = ps.SINDy(
        feature_library=ps.PolynomialLibrary(degree=order),
).fit(
        traj[:n,:],
        t=dt,
)
    traj_sim = model.simulate(traj[0, :], t_eval)
    plot_traj(traj_sim, title='%d points, polynomials of degree %d' % (n, order))

for i in (100, 150):
    subset_test(i, 6)
```

100 points, polynomials of degree 6

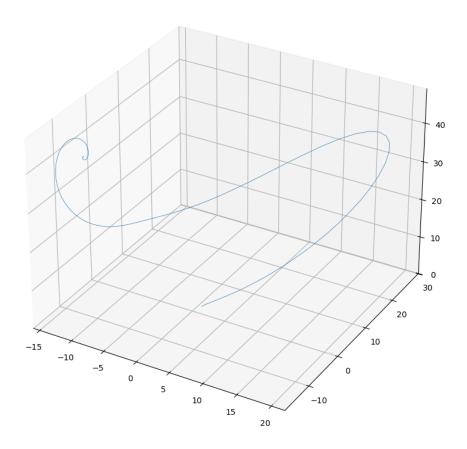


150 points, polynomials of degree 6

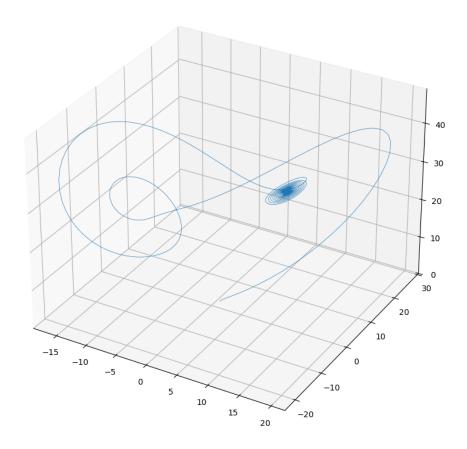


for i in (50,60,70):
 subset_test(i, 2)

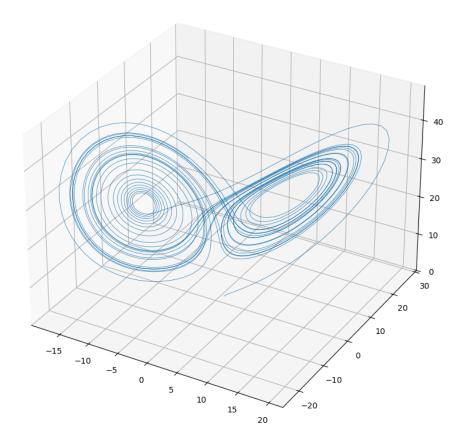
50 points, polynomials of degree 2



60 points, polynomials of degree 2



70 points, polynomials of degree 2



We can see that about 150 points is enough. For a second order polynomial library, we can get by with slightly less data, since we have less parameters to fit.