(ST) Consider E-LS evoron = 
$$\|\hat{y}-y\|\|_{2}^{2} = \|Ax-b\|\|_{2}^{2}$$

$$\therefore \frac{\delta E}{\delta n} = (A^{T}(An-b))$$

$$2A^{T}(An-b) = 0 \Rightarrow A^{T}(An-b)$$

$$= x^{k+1} = x^{k} - \frac{1}{|A|^{2}}A^{T}(A^{k} - b)$$

$$= x^{k} - \frac{1}{|A|^{2}}A^{T}(A(x^{k}) - b)$$

$$\Rightarrow x^{k+1} = x^{k} + \frac{1}{|A|^{2}}A^{T}(A(x^{k}) - b)$$

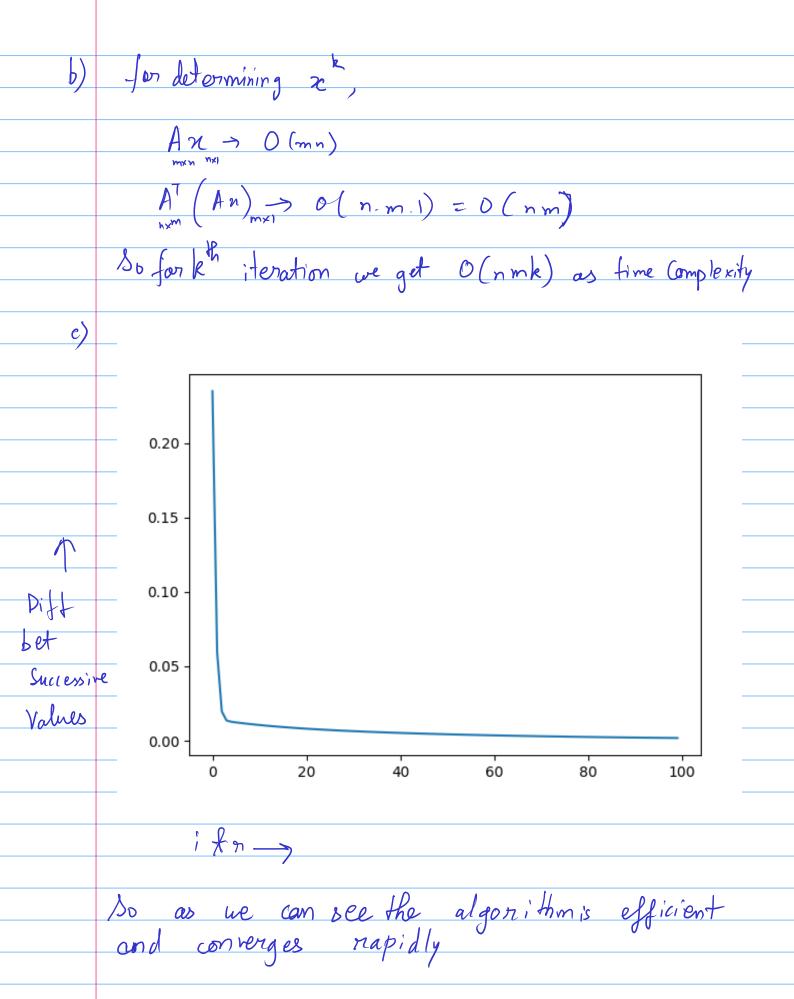
$$\Rightarrow x^{k+1} = x^{k} - \frac{1}{|A|^{2}}A^{T}(A(x^{k}) - b)$$
Let  $x^{k} = x^{k} - \frac{1}{|A|^{2}}A^{T}(A(x^{k}) - b)$ 

$$= x^{k} - \frac{1}{|A|^{2}}A^{T}(A(x^{k}) - b)$$

$$\Rightarrow x^{k+1} = x^{k} - \frac{1}{|A|^{2}}A^{T}(A(x^{k}) - b)$$
Let  $x^{k} = x^{k} - \frac{1}{|A|^{2}}A^{T}(A(x^{k}) - b)$ 

$$= x^{k} - \frac{1}{|A|^{2}}A^{T}(A(x^{k}) - b)$$

$$\Rightarrow x^{k+1} = x^{k} - \frac{1}{|A|^{2}}A^{T}(A(x^{k}) -$$



## Python Code

```
import numpy as np
import matplotlib.pyplot as plt
A = np.random.rand(30,10)
b = np.random.rand(30,1)
while np.linalg.matrix rank(A)<10:
  A = np.random.rand(30,10)
x = np.zeros((10,1))
X = []
Y = []
for i in range(100):
  oldx = x
  x = x-np.dot(A.T,(np.dot(A,x)-b))/(np.linalg.norm(A)**2)
  diff = np.linalg.norm(oldx-x)
  print('Iteration ',i,'Norm of Difference between old and new x: ',diff)
  X.append(i)
  Y.append(diff)
plt.plot(X,Y)
plt.show()
```

d) Yes it is more efficient than normal way of computation using A+x on using QR factoris ation to compute A+x