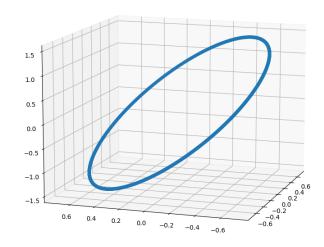
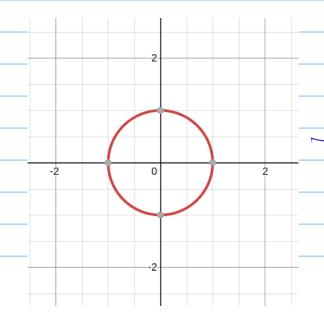
(0.1) a) (0.1) (

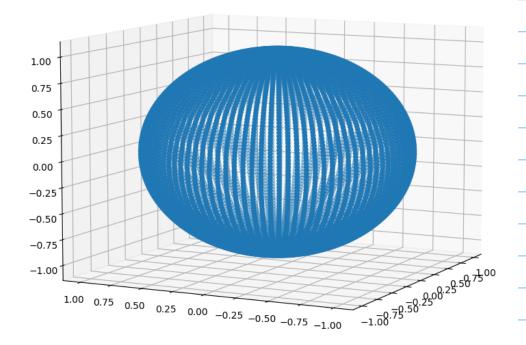
Plotting the parametric eqn in 3D in geogebra we get an ellipse

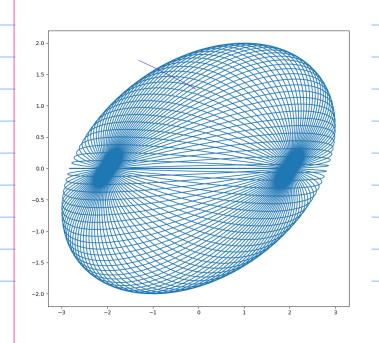




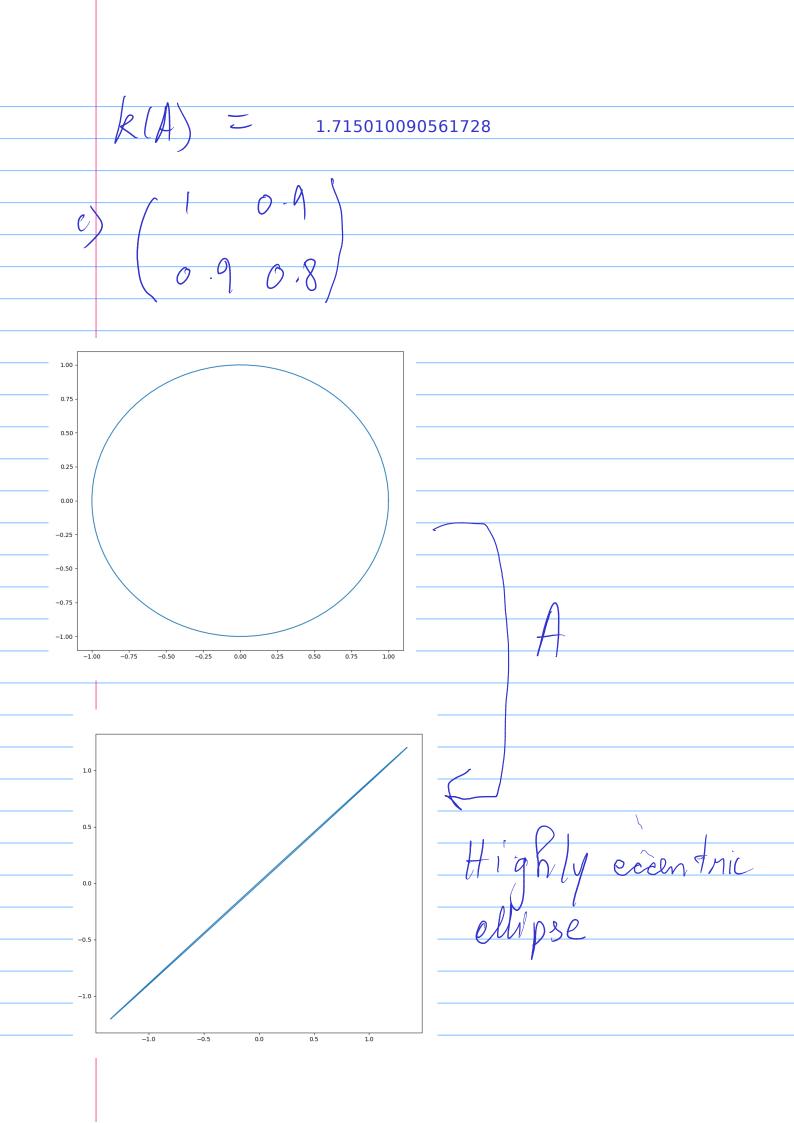
R(A) = 2.23606797749979

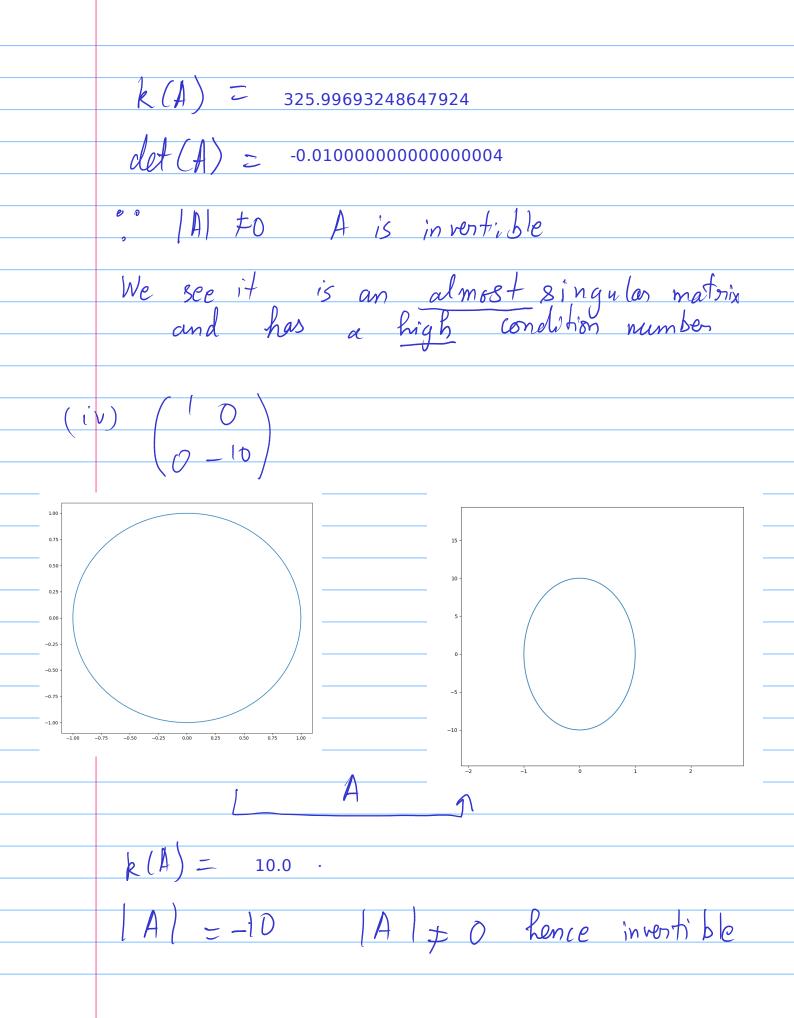
 $\begin{pmatrix} -2 & 1 & 2 \\ 0 & 2 & 0 \end{pmatrix}$

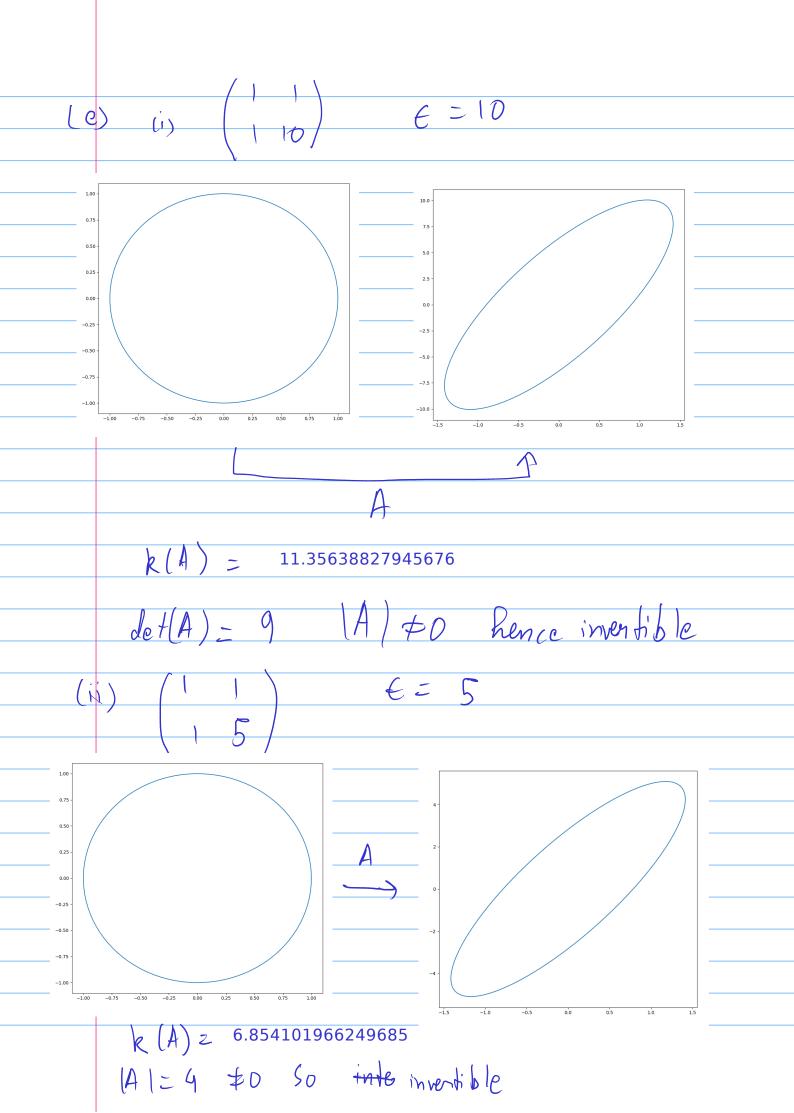


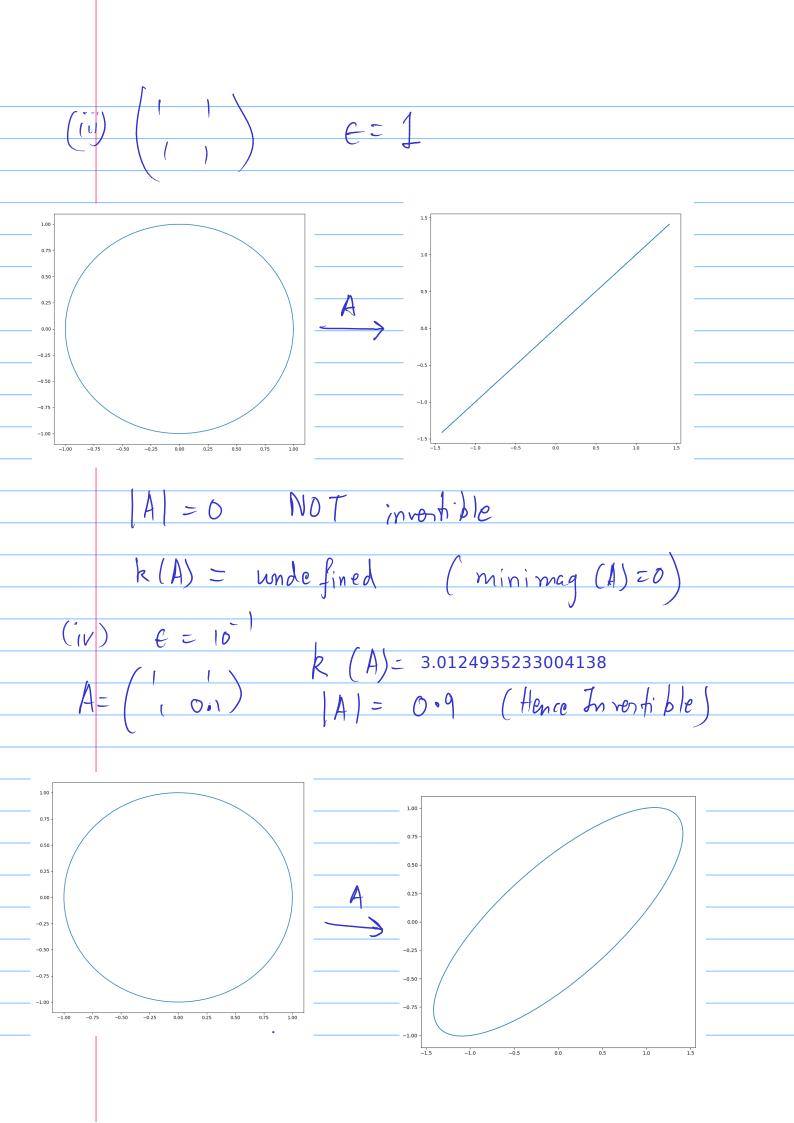


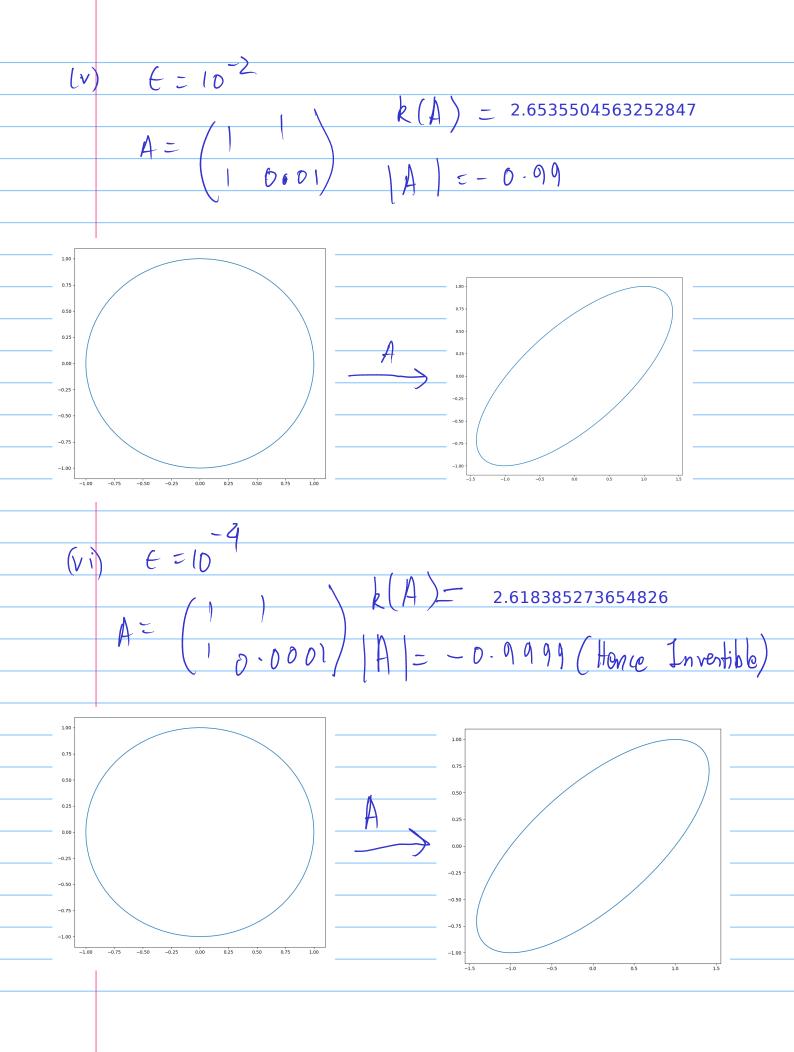
On taking mogie points we would see that the image will span the entire elliptical











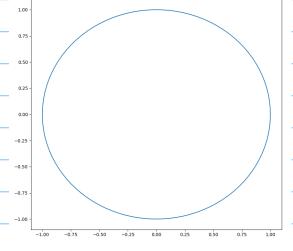
(vii)

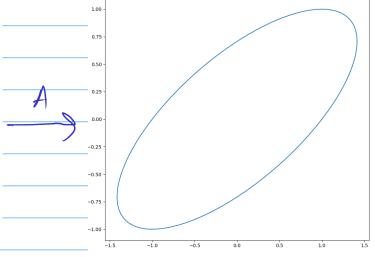
E=0

R(A) = 2.6180339887498953

A = (10)

|A| = -1 (Hence Inventible)





Observation on det & k(A)

 \rightarrow As a matrix \rightarrow singular i.e $(A) \rightarrow 0$, $k(A) \rightarrow \infty$

Code Used to plot (Parts were edited while running the different parts

```
import matplotlib.pyplot as plt
import numpy as np
plt.rcParams["figure.figsize"] = [10,10]
fig = plt.figure()
r = 1
\#u,v = np.mgrid[0:2 * np.pi:100j,0:np.pi:100j]
u = np.mgrid[0:2*np.pi:100j]
#print(u.shape)
\#X = np.array([np.cos(u)*np.sin(v),np.sin(u)*np.sin(v),np.cos(v)])
X = np.array([np.cos(u),np.sin(u)]).reshape((2,100))
\#X = X.reshape((3,1,10000))
#ax = plt.axes(projection='3d')
#ax.scatter3D(X[0], X[1], X[2])
#print(X)
plt.plot(X[0],X[1])
plt.show()
X = X.reshape((2,1,100))
#x = X[0,0]
#y = X[1,0]
#axes.plot(x, y)
#plt.show()
A = np.array([[1,1],[1,0]]).reshape((2,2))#input matrix
#Print condition number
print(np.linalg.cond(A))
#print determinant
print('Determinant : ',np.linalg.det(A))
Y = np.array([np.dot(A,X[:::,i]) for i in range(100)]).T.reshape(2,100)#do transformation
x = Y[0]
y = Y[1]
#z = Y[2]
print(x.shape)
#ax = plt.axes(projection='3d')
#ax.scatter3D(x, y, z)
plt.plot(x,y)
plt.show()
```