

# Ahmed Yesuf Nurye

PH.D. CANDIDATE

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“Be the change you want to see in the world.”

## Research Interests

Human Interactive Robot Learning, Mathematical Human Modeling, Reinforcement Learning

## Education

### Vrije Universiteit Amsterdam

PH.D. IN COMPUTER SCIENCE

- Advisors: Prof. Kim Baraka & Prof. Herke van Hoof (UvA).

Amsterdam, The Netherlands

Oct. 2025 – Present

### Warsaw University of Technology

M.SC. IN ROBOTICS AND AUTOMATIC CONTROL

- Advisor: Prof. dr hab.inż. Elżbieta Jarzębowska.
- Thesis: Mobile Robot Navigation in Dynamic Environments.

Warsaw, Poland

Oct. 2022 – Oct. 2024

### Addis Ababa Science and Technology University

B.SC. IN ELECTRICAL ENGINEERING

- B.Sc. Project: Smart Irrigation System Powered by Dual Axis Solar Tracker.

Addis Ababa, Ethiopia

Oct. 2016 – Sep. 2021

## Publications

🎓 Google Scholar

† → Equal contribution

### CONFERENCE PROCEEDINGS

- C1. **Nurye, A. Y.** & Jarzębowska, E. *Deep Reinforcement Learning for Mobile Robot Navigation in Dynamic Environments* in 2025 29th International Conference on Methods and Models in Automation and Robotics (MMAR) (2025), 83–88.

## Experience

### Social AI Lab

PH.D. CANDIDATE

- Working on interactive robot learning algorithms from multi-modal human feedback.

Amsterdam, The Netherlands

Oct. 2025 – Present

### Scania Group

SYSTEMS ENGINEER

- Engineering requirements and implementing core BMS algorithms, such as hot-connection management and EU Battery Regulation compliance, to ensure system safety and regulatory conformance.
- Taking part in end-to-end verification & validation of BMS functions to enhance software reliability and accelerate delivery cycles.

Gdańsk, Poland

Apr. 2024 – Present

### Northvolt

SYSTEMS ENGINEER

- Did comprehensive verification & validation of battery management system functions, identifying critical issues and ensuring adherence to performance specifications.
- Developed and deployed a Python package for automated code generation using Jinja2 templates to standardize system integration workflows and reduce manual implementation effort.

Gdańsk, Poland

Apr. 2024 – Apr. 2025

### New Era Research and Development Center

RESEARCH INTERN

- Contributed to a differential-drive mobile robot's mechanical and control design.
- Implemented and evaluated classical path-planning algorithms in simulated and real environments, including bug and line-following methods.

Addis Ababa, Ethiopia

Apr. 2021 – Jun. 2021

# Teaching

## ADDIS ABABA SCIENCE AND TECHNOLOGY UNIVERSITY

- 2022    **Introduction to Control System (EEeg4155)**, Teaching Assistant & Lab Instructor
- 2021    **Electrical Measurement & Instrumentation (EEeg3153)**, Teaching Assistant

# Skills

- Programming**    Python, C/C++, MATLAB/Simulink, Octave, Shell Scripting(bash)
- Libraries**        Gymnasium, Genesis, MuJoCo, OpenCV, PyTorch, Scikit-Learn
- Other Tools**     Linux, ROS2, Gazebo, Git/GitHub, Docker,  $\LaTeX$
- Languages**      English, Amharic

# Tools and Software

## **gym-turtlebot: a turtlebot4 gymnasium environment**

[website](#)

 PYTHON | ROS2 | GAZEBO SIM

Mar. 2025 – Present

- A ROS2 and Gazebo based simulation environment for TurtleBot4 that provides a minimal setup for quickly prototyping DRL agents for navigation using gymnasium API.

## **MBD Simulink**

[GitHub](#)

MATLAB | SIMULINK

Dec. 2024 – Present

- A productivity tool that automates block insertion, naming, and connection tasks in Simulink to streamline model-based design workflows.

## **pdfx**

[PyPi](#) | [GitHub](#)

 PYTHON

May. 2025 – Present

- Command-line tool for pdf inspection and operations including merge, split, extract, remove, encrypt, decrypt, and conversion to pdf.

## **LaTeX-SoP: a modular statement of purpose template**

[GitHub](#)

$\LaTeX$

Apr. 2025



- A modular statement of purpose template for graduate school applications.

# Leadership and Outreach

- 2019    **Charity Affairs Coordinator**, Led the charity initiatives of the AASTU Students' Union, organizing fundraising and outreach efforts.

[AASTU](#)

# Awards and Honors

- 2024    **Summa Cum Laude** , Graduated with highest honors, M.Sc. in Robotics & Automatic Control.
- 2024    **Mr Tomaka's Scholarship**, Awarded for academic excellence at Warsaw University of Technology.
- 2022    **Banach Scholarship**, Fully funded 2nd-cycle studies in Poland, covering tuition and living expenses.
- 2021    **Summa Cum Laude** , Graduated with highest honors, B.Sc. in Electrical Engineering.

[WUT](#)

[WUT](#)

[NAWA](#)

[AASTU](#)

# Professional Memberships

- 2024–    **Black in AI**, Member
- 2023–    **IEEE Robotics and Automation Society**, Member
- 2023–    **Institute of Electrical and Electronics Engineers (IEEE)**, Graduate student member