

# Ahmed Yesuf Nurye

PH.D. CANDIDATE

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“Be the change you want to see in the world.”

## Research Interests

Human Interactive Robot Learning, Mathematical Human Modeling, Reinforcement Learning

## Education

### Vrije Universiteit Amsterdam

Ph.D. IN COMPUTER SCIENCE

Amsterdam, The Netherlands

Oct. 2025 – Present

- Advisors: Prof. Kim Baraka & Prof. Herke van Hoof (UvA).

### Warsaw University of Technology

M.Sc. IN ROBOTICS AND AUTOMATIC CONTROL

Warsaw, Poland

Oct. 2022 – Oct. 2024

- Advisor: Prof. dr hab.inż. Elżbieta Jarzębowska.

- Thesis: Mobile Robot Navigation in Dynamic Environments.

### Addis Ababa Science and Technology University

B.Sc. IN ELECTRICAL ENGINEERING

Addis Ababa, Ethiopia

Oct. 2016 – Sep. 2021

- B.Sc. Project: Smart Irrigation System Powered by Dual Axis Solar Tracker.

## Publications



→ Equal contribution

## CONFERENCE PROCEEDINGS

- C1. **Nurye, A. Y.** & Jarzębowska, E. Deep Reinforcement Learning for Mobile Robot Navigation in Dynamic Environments in 2025 29th International Conference on Methods and Models in Automation and Robotics (MMAR) (2025), 83–88.

## Experience

### Social AI Lab

PH.D. CANDIDATE

Amsterdam, The Netherlands

Oct. 2025 – Present

- Working on interactive robot learning algorithms from multi-modal human feedback.

### Scania Group

SYSTEMS ENGINEER

Gdańsk, Poland

Apr. 2024 – Present

- Engineering requirements and implementing core BMS algorithms, such as hot-connection management and EU Battery Regulation compliance, to ensure system safety and regulatory conformance.
- Taking part in end-to-end verification & validation of BMS functions to enhance software reliability and accelerate delivery cycles.

### Northvolt

SYSTEMS ENGINEER

Gdańsk, Poland

Apr. 2024 – Apr. 2025

- Did comprehensive verification & validation of battery management system functions, identifying critical issues and ensuring adherence to performance specifications.
- Developed and deployed a Python package for automated code generation using Jinja2 templates to standardize system integration workflows and reduce manual implementation effort.

### New Era Research and Development Center

RESEARCH INTERN

Addis Ababa, Ethiopia

Apr. 2021 – Jun. 2021

- Contributed to a differential-drive mobile robot's mechanical and control design.
- Implemented and evaluated classical path-planning algorithms in simulated and real environments, including bug and line-following methods.

# Teaching

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## ADDIS ABABA SCIENCE AND TECHNOLOGY UNIVERSITY

- 2022 **Introduction to Control System (EEEg4155)**, Teaching Assistant & Lab Instructor  
2021 **Electrical Measurement & Instrumentation (EEEg3153)**, Teaching Assistant

# Skills

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<b>Programming</b>	Python, C/C++, MATLAB/Simulink, Octave, Shell Scripting(bash)
<b>Libraries</b>	Gymnasium, Genesis, MuJoCo, OpenCV, PyTorch, Scikit-Learn
<b>Other Tools</b>	Linux, ROS2, Gazebo, Git/GitHub, Docker, L <sup>A</sup> T <sub>E</sub> X
<b>Languages</b>	English, Amharic

# Tools and Software

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## **gym-turtlebot: a turtlebot4 gymnasium environment**

[website](#)

PYTHON | ROS2 | GAZEBO SIM

Mar. 2025 – Present

- A ROS2 and Gazebo based simulation environment for TurtleBot4 that provides a minimal setup for quickly prototyping DRL agents for navigation using gymnasium API.

## **MBD Simulink**

[GitHub](#)

MATLAB | SIMULINK

Dec. 2024 – Present

- A productivity tool that automates block insertion, naming, and connection tasks in Simulink to streamline model-based design workflows.

## **pdfx**

[PyPi](#) | [GitHub](#)

PYTHON

May. 2025 – Present

- Command-line tool for pdf inspection and operations including merge, split, extract, remove, encrypt, decrypt, and conversion to pdf.

## **LaTeX-SoP: a modular statement of purpose template**

[GitHub](#)

L<sup>A</sup>T<sub>E</sub>X

Apr. 2025

- A modular statement of purpose template for graduate school applications.

# Leadership and Outreach

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- 2019 **Charity Affairs Coordinator**, Led the charity initiatives of the AASTU Students' Union, organizing fundraising and outreach efforts.

[AASTU](#)

# Awards and Honors

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- 2024 **Summa Cum Laude** [], Graduated with highest honors, M.Sc. in Robotics & Automatic Control. [WUT](#)  
2024 **Mr Tomaka's Scholarship**, Awarded for academic excellence at Warsaw University of Technology. [WUT](#)  
2022 **Banach Scholarship**, Fully funded 2nd-cycle studies in Poland, covering tuition and living expenses. [NAWA](#)  
2021 **Summa Cum Laude** [], Graduated with highest honors, B.Sc. in Electrical Engineering. [AASTU](#)

# Professional Memberships

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- 2024– **Black in AI**, Member  
2023– **IEEE Robotics and Automation Society**, Member  
2023– **Institute of Electrical and Electronics Engineers (IEEE)**, Graduate student member