Indian Institute of Technology, Jodhpur Lab Manual

Sensors and IoT

LAB - 3

Date: 23 Sept, 2024

Lab Objective

In this lab we will go through the basics of Raspberry Pi 4 and using its on-board GPIO pins

Part 1 : Setting Up Raspberry Pi

• In order to use the on-board GPIO pins of the Raspberry Pi we need to enable support for interfaces using the configurator. In order to open the configurator run

sudo raspi-config

• Use arrow keys to select Interface Options

Figure 1: Select Interface Options

• Select I2C

Figure 2: Select I2C

• Select Yes to enable I2C interface

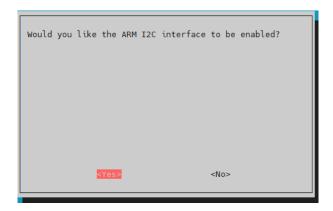


Figure 3: Enter Caption

• Use Right arrow key to select Finish

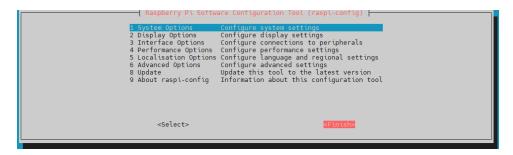


Figure 4: Enter Caption

 \bullet Open a Terminal window by pressing "CTRL + ALT + T" together or by pressing this icon on top right corner

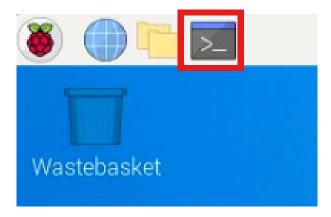


Figure 5: Open Terminal

• Go to Documents directory by entering the following command.

cd Documents/

• Once in the Documents directory enter the following command to create a virtual environment for Python

```
python -m venv IOT_LAB
```

• To activate the virtual environment run

```
source IOT_LAB/bin/activate
```

(IOT_LAB) should be visible before the username on the terminal prompt

```
pi@raspberrypi:~/Documents $ python -m venv IOT_LAB
pi@raspberrypi:~/Documents $ source IOT_LAB/bin/activate
(IOT_LAB) pi@raspberrypi:~/Documents $
```

Figure 6: Virtual Environment activation

- Copy the provided files in the Documents directory.
- Check the requirements.txt by entering the following command

```
cat requirements.txt
```

```
(IOT_LAB) pi@raspberrypi:~/Documents $ cat requirements.txt adafruit-circuitpython-ssd1306 adafruit-blinka adafruit-circuitpython-vl53l0x Pillow (IOT_LAB) pi@raspberrypi:~/Documents $ ■
```

Figure 7: Check the requirements for the LAB

• Run the following commands to install all the python dependencies.

```
pip install -r requirements.txt
```

Part 2: Using Lidar Sensor with raspberry pi 4

• In order to use the vl53l0x sensor we will make the connections as per the following diagram :-

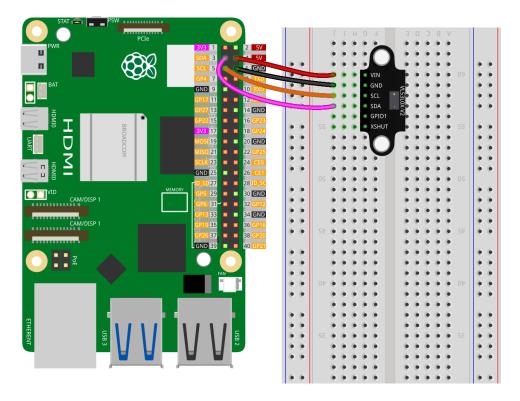


Figure 8: Lidar Connections

- Once the connections are done ensure that the environment is active in the terminal by checking the (IOT_LAB) prefix.
- Run the Lidar program by executing :-

python lidar.py

• Expected output :-

Range: 8190mm
Range: 8190mm
Range: 8190mm
Range: 27mm
Range: 23mm
Range: 23mm
Range: 149mm
Range: 177mm
Range: 8190mm

• If the error of device not found comes up, please check the connections and ensure the SDA and SCL connections are not swapped

```
Traceback (most recent call last):
   File "/home/pi/Documents/lidar.py", line 18, in <module>
    vl53 = adafruit_vi53lox.vt5310x(i2c)
   File "/home/pi/Documents/IoT_LBB/lib/python3.11/site-packages/adafruit_vl53lox.py", line 157, in __init__
    self._device = i2c_device.IZCDevice(i2c, address)
   File "/home/pi/Documents/IOT_LBB/lib/python3.11/site-packages/adafruit_bus_device/i2c_device.py", line 62, in __init__
    self._probe_for_device()
   File "/home/pi/Documents/IOT_LBB/lib/python3.11/site-packages/adafruit_bus_device/i2c_device.py", line 62, in __init__
    self._probe_for_device()
   File "/home/pi/Documents/IOT_LBB/lib/python3.11/site-packages/adafruit_bus_device/i2c_device.py", line 184, in __probe_for_device
    raise ValueError('No I2C device at address: 0%%x" % self.device_address)
ValueError: No I2C device at address: 0x29
   ValueError: points-pocuments $ ""
```

Figure 9: I2C Error

Part 3: Using OLED with raspberry pi 4

• In order to use the OLED display we will use the same I2C bus now to send the data. Please make connections as per the following diagram.

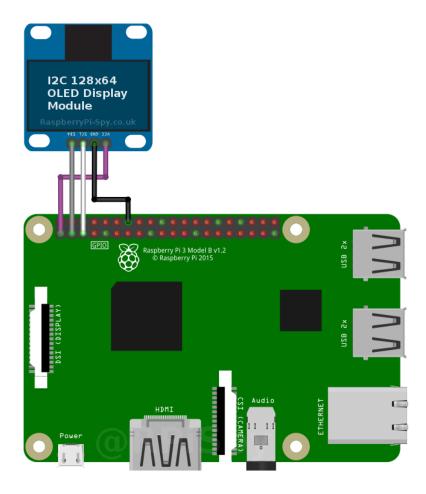


Figure 10: OLED connections

• Run the oled.py to use the display and show output

(IOT_LAB) pi@raspberrypi:~/Documents \$ python oled.py Enter text to display :- WELCOME TO IOT_LAB-2 Enter text to display :- ■

Figure 11: OLED input



Figure 12: OLED output

Assignment: Show Lidar data on OLED display

- In the LAB submission use the data from the Lidar sensor as the input to the OLED display.
- NOTE:In I2C you can use multiple devices on the same bus.
- In the final submission the display should show your roll number followed by the distance measured. EG :-

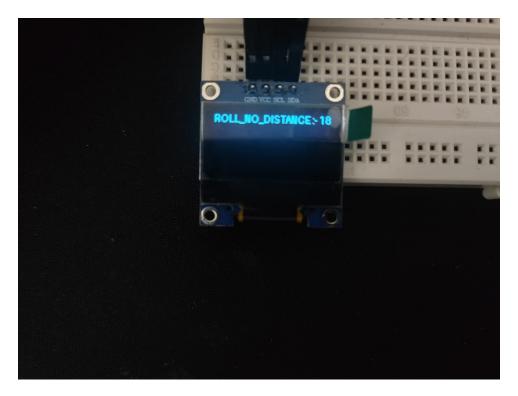


Figure 13: Example output

- In the LAB report please include the output from the provided examples, code written as part of the assignment, output images(if any).
- LAB report can be prepared on ANY platform of your choice.