

GRAPH THEORY

Submitted by

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22pmc108

Temporary-Ordered Routing Algorithm (TORA)

1.Linear programming graphical solution .

File EditGrid

LINEAR PROGRAMMING

Problem Title:

Nbr. of Variables:

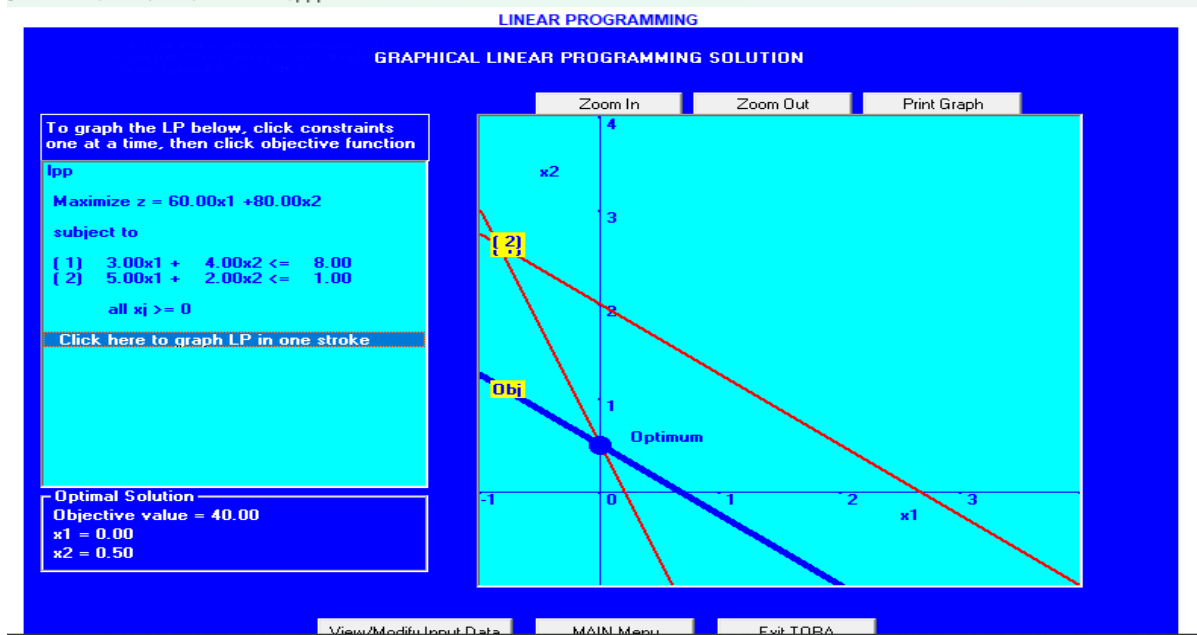
No. of Constraints:

Editing Grid:
>>Click Maximize(Minimize)-cell to change it to Minimize(Maximize)
>>To DELETE, INSERT, COPY, or PASTE a column(row), click heading cell of target column(row), then invoke pull-down EditGrid menu
>>For INSERT mode, a single(double) click of target row/column will place new row/column after(before) target row/column.

INPUT GRID - LINEAR PROGRAMMING

	x1	x2	Enter <, >, or =	R.H.S.
Var. Name	x1	y1		
Maximize	60.00	80.00		
Constr 1	3.00	4.00	<=	8.00
Constr 2	5.00	2.00	<=	1.00
Lower Bound	0.00	0.00		
Upper Bound	infinity	infinity		
Unrestr'd (y/n)?	n	n		

3 TORA C:\Users\Alfin\Downloads\lppp.txt



2. Linear programming simplex method.

LINEAR PROGRAMMING

Problem Title: **lpp**

Nbr. of Variables: **2**

No. of Constraints: **4**

Editing Grid:
 >>Click Maximize(Minimize)-cell to change it to Minimize(Maximize)
 >>To DELETE, INSERT, COPY, or PASTE a column(row), click heading cell of target column(row), then invoke pull-down EditGrid menu
 >>For INSERT mode, a single(double) click of target row/column will place new row/column after(before) target row/column.

INPUT GRID - LINEAR PROGRAMMING

	x1	x2	Enter <, >, or =	R.H.S.
Var. Name	X1	X2		
Maximize	5.00	4.00		
Constr 1	6.00	4.00	<=	24.00
Constr 2	1.00	2.00	<=	6.00
Constr 3	1.00	1.00	<=	1.00
Constr 4	0.00	1.00	<=	1
Lower Bound	0.00	0.00		
Upper Bound	infinity	infinity		
Unrestr'd (y/n)?	n	n		

LINEAR PROGRAMMING

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LINEAR PROGRAMMING OUTPUT SUMMARY

Title: **lpp**
 Final Iteration No.: **2**
 Objective Value (Max) = **5.00**

Next Iteration All Iterations Write to Printer

Variable	Value	Obj Coeff	Obj Val Contrib
x1: X1	1.00	5.00	5.00
x2: X2	0.00	4.00	0.00

Constraint	RHS	Slack-/Surplus+
1 (<=)	24.00	18.00-
2 (<=)	6.00	5.00-
3 (<=)	1.00	0.00
4 (<=)	1.00	1.00-

*****Sensitivity Analysis*****

Variable	Current Obj Coeff	Min Obj Coeff	Max Obj Coeff	Reduced Cost
x1: X1	5.00	4.00	infinity	0.00
x2: X2	4.00	-infinity	5.00	1.00

Constraint	Current RHS	Min RHS	Max RHS	Dual Price
1 (<=)	24.00	6.00	infinity	0.00
2 (<=)	6.00	1.00	infinity	0.00

View/Modify Input Data MAIN Menu Exit TORA

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LINEAR PROGRAMMING

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SIMPLEX TABLEAU - (Starting All-Slack Method)

Title: lpp (Maximize)

Steps for generating NEXT tableau from CURRENT one:

1. ENTERING variable: Click a NONBASIC variable (if correct, column turns green)
2. LEAVING variable: Click a BASIC variable (if correct, row turns red)
3. Click command button NEXT ITERATION (or ALL ITERATIONS) -- This step may be executed without Steps 1 and/or 2.

Next Iteration All Iterations Write to Printer

Iteration 1	X1	X2	sx3	sx4	sx5	Rx6	Solution
Basic	x1	x2	sx3	sx4	sx5	Rx6	Solution
z (max)	-5.00	-104.00	0.00	0.00	0.00	0.00	0.00
sx3	6.00	4.00	1.00	0.00	0.00	0.00	24.00
sx4	1.00	2.00	0.00	1.00	0.00	0.00	6.00
sx5	1.00	1.00	0.00	0.00	1.00	0.00	1.00
Rx6	0.00	1.00	0.00	0.00	0.00	1.00	0.00
Lower Bound	0.00	0.00					
Upper Bound	0.00	0.00					
Unrestr'd (y/n)?	n	n					

View/Modify Input Data MAIN Menu Exit TORA

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LINEAR PROGRAMMING

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Wednesday, March 15, 2023 23:04

SIMPLEX TABLEAU - (Starting All-Slack Method)

Title: lpp (Maximize)

Steps for generating NEXT tableau from CURRENT one:

1. ENTERING variable: Click a NONBASIC variable (if correct, column turns green)
2. LEAVING variable: Click a BASIC variable (if correct, row turns red)
3. Click command button NEXT ITERATION (or ALL ITERATIONS) -- This step may be executed without Steps 1 and/or 2.

Next Iteration All Iterations Write to Printer

Iteration 2	X1	X2	sx3	sx4	sx5	Rx6	Solution
Basic	x1	x2	sx3	sx4	sx5	Rx6	Solution
z (max)	-5.00	0.00	0.00	0.00	1.00	0.00	1.00
sx3	6.00	0.00	1.00	0.00	0.00	0.00	0.00
sx4	1.00	0.00	0.00	1.00	0.00	0.00	0.00
sx5	1.00	0.00	0.00	0.00	1.00	-1.00	1.00
x2	0.00	1.00	0.00	0.00	0.00	1.00	0.00
Lower Bound	0.00	0.00					
Upper Bound	0.00	0.00					
Unrestr'd (y/n)?	n	n					

View/Modify Input Data MAIN Menu Exit TORA

Optimal Tableau

Iteration 3 is optimal

OK

3. Linear programming transportation method.

File EditGrid

TRANSPORTATION MODEL

Problem Title: transportation No. of Sources: 4 No. of Dest'ns: 4	Editing Grid: >>To DELETE, INSERT, COPY, or PASTE a column(row), click heading cell of target column(row), then invoke pull-down EditGrid menu >>For INSERT mode, a single(double) click of target row/column will place new row/column after(before) target row/column.
--	---

INPUT GRID - TRANSPORTATION

	S/D Name	D1	D2	D3	D4	Supply
S1		19.00	30.00	50.00	10.00	12
S2		40.00	54.00	18.00	60.00	17
S3		65.00	28.00	44.00	20.00	20
S4		78.00	47.00	72.00	80.00	11
Demand		14	18	20	8	

1. North west corner method

TRANSPORTATION MODEL

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TRANSPORTATION TABLEAU - (North-West Corner Method)

Title: transportation --(minimum cost)

Steps for generating transportation tableaus:

1. (Optional step) Initialize ONE of the simplex multiplier ($u_1, u_2, \dots, v_1, v_2, \dots$) to zero value (default $u_1 = 0$)
2. Click (in any order) the cells defining the change-of-basis loop (if correct, cell changes color)
3. Click command button NEXT ITERATION (or ALL ITERATIONS) -- This step may be executed without Step 2

u1=0

Iter 1	ObjVal =	2806.00	D1	D2	D3	D4	Supply
	Name						
			$v_1=19.00$	$v_2=33.00$	$v_3=49.00$	$v_4=57.00$	
S1	$u_1=0.00$	12	19.00	30.00	50.00	10.00	12
			0.00	3.00	-1.00	47.00	
S2	$u_2=21.00$	2	40.00	54.00	18.00	60.00	17
			0.00	0.00	52.00	18.00	
S3	$u_3=-5.00$		65.00	28.00	44.00	20.00	20
			-51.00	0.00	0.00	32.00	
S4	$u_4=23.00$		78.00	47.00	72.00	80.00	11
			-36.00	9.00	0.00	0.00	

2. Least cost method

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TRANSPORTATION MODEL

TRANSPORTATION TABLEAU - (Least Cost Method)

Title: transportation --(minimum cost)

Steps for generating transportation tableaus:

- (Optional step) Initialize ONE of the simplex multiplier ($u_1, u_2, \dots, v_1, v_2, \dots$) to zero value (default $u_1 = 0$)
- Click (in any order) the cells defining the change-of-basis loop (if correct, cell changes color)
- Click command button NEXT ITERATION (or ALL ITERATIONS) -- This step may be executed without Step 2

Initialize u or v
 $u_1 = 0$

Next Iteration All Iterations Write to Printer

Iter 1	ObjVal =	1906.00	D1	D2	D3	D4	Supply
	Name						
			$v_1=19.00$	$v_2=3.00$	$v_3=13.00$	$v_4=10.00$	
			19.00	30.00	50.00	10.00	
S1	$u_1=0.00$		4			8	12
			0.00	-33.00	-37.00	0.00	
S2	$u_2=5.00$		40.00	54.00	18.00	60.00	17
			-16.00	-52.00	0.00	-45.00	
S3	$u_3=31.00$		65.00	28.00	44.00	20.00	20
			-15.00	0.00	0.00	21.00	
S4	$u_4=59.00$		78.00	47.00	72.00	80.00	11
			10		1		
			0.00	9.00	0.00	-11.00	

View/Modify Input Data MAIN Menu Exit TORA

3. Vogels Method.

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TRANSPORTATION MODEL

TRANSPORTATION TABLEAU - (Vogel's Method)

Title: transportation --(minimum cost)

Steps for generating transportation tableaus:

- (Optional step) Initialize ONE of the simplex multiplier ($u_1, u_2, \dots, v_1, v_2, \dots$) to zero value (default $u_1 = 0$)
- Click (in any order) the cells defining the change-of-basis loop (if correct, cell changes color)
- Click command button NEXT ITERATION (or ALL ITERATIONS) -- This step may be executed without Step 2

Initialize u or v
 $u_1 = 0$

Next Iteration All Iterations Write to Printer

Iter 1	ObjVal =	1657.00	D1	D2	D3	D4	Supply
	Name						
			$v_1=19.00$	$v_2=12.00$	$v_3=4.00$	$v_4=20.00$	
			19.00	30.00	50.00	10.00	
S1	$u_1=0.00$		12				12
			0.00	-42.00	-46.00	-30.00	
S2	$u_2=14.00$		40.00	54.00	18.00	60.00	17
			-7.00	-52.00	0.00	-66.00	
S3	$u_3=40.00$		65.00	28.00	44.00	20.00	20
			-6.00	0.00	0.00	0.00	
S4	$u_4=59.00$		78.00	47.00	72.00	80.00	11
			2	9			
			0.00	0.00	-9.00	-41.00	

View/Modify Input Data MAIN Menu Exit TORA

4.Spanning tree

File EditGrid

NETWORK MODELS

Problem Title: <input type="text" value="spanning tree"/>	Editing Grid: >>To DELETE, INSERT, COPY, or PASTE a column(row), click heading cell of target column(row), then invoke pull-down EditGrid menu >>For INSERT mode, a single(double) click of target row/column will place new row/column after(before) target row/column.
No. of Nodes <input type="text" value="6"/>	

INPUT GRID - MINIMAL SPANNING TREE

☒ Check here if network is symmetrical

		N1	N2	N3	N4	N5	N6
	Node Name	A	B	C	D	E	F
N1	A		2.00	5.00	infinity	8.00	infinity
N2	B	2.00		6.00	3.00	infinity	infinity
N3	C	5.00	6.00		8.00	7.00	infinity
N4	D	infinity	3.00	8.00		infinity	5.00
N5	E	8.00	infinity	7.00	infinity		9.00
N6	F	infinity	infinity	infinity	5.00	9.00	

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MINIMAL SPANNING TREE OUTPUT SUMMARY

Title: spanning tree

Steps for generating iterations:

1. Select a **STARTING NODE** from drop-down list (or assume default N1)
2. Click command button **NEXT ITERATION** (or **ALL ITERATIONS**)

Starting Node:

Next Iteration

All Iterations

Write to Printer

Updated minimal tree length = 22.00

0. Start at node N1

1. Connect N2 [B] to N1 [A]: Length = 2.00
2. Connect N4 [D] to N2 [B]: Length = 3.00
3. Connect N6 [F] to N4 [D]: Length = 5.00
4. Connect N3 [C] to N1 [A]: Length = 5.00
5. Connect N5 [E] to N3 [C]: Length = 7.00

View/Modify Input Data

MAIN Menu

Exit TORA

5.CPM

File EditGrid

PROJECT PLANNING -- PERT/CPM

Problem Title: **CPM**

Editing Grid:
 >>To DELETE, INSERT, COPY, or PASTE a column(row), click heading cell of target column(row), then invoke pull-down EditGrid menu
 >>For INSERT mode, a single(double) click of target row/column will place new row/column after(before) target row/column.

INPUT GRID - CPM (CRITICAL PATH METHOD)

Row	From Node	To Node	Activity Symbol	Duration
1	1	2	A	6.00
2	1	5	G	2.00
3	1	6	J	13.00
4	2	3	B	4.00
5	2	4	K	9.00
6	2	8	D	2.00
7	3	4	C	7.00
8	4	7	L	3.00
9	5	6	H	10.00
10	6	7	I	6.00
11	7	10	M	5.00
12	8	9	E	4.00
13	9	10	F	10

PROJECT PLANNING -- PERT/CPM

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PROJECT PLANNING - CPM

Select Output Option
CPM Calculations

Next Step All Steps Write to Printer

Title: CPM

SOLUTION STEPS

Forward Pass			Backward Pass		
Step	Node	Earliest Time	Step	Node	Latest Time
1	1	0.00	11	10	25.00
2	2	6.00	12	7	20.00
3	3	10.00	13	4	17.00
4	4	17.00	14	3	10.00
5	5	2.00	15	6	14.00
6	6	13.00	16	5	4.00
7	7	20.00	17	9	15.00
8	8	8.00	18	8	10.00
9	9	13.00	19	2	6.00
10	10	25.00	20	1	0.00
Forward pass completed			Backward pass completed		
Activity	Duration	Earliest Start	Latest Completion	Total Float	Free Float
A	6.00	0.00	6.00	0.00	0.00
G	2.00	0.00	4.00	2.00	0.00
J	13.00	0.00	13.00	0.00	0.00

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PROJECT PLANNING -- PERT/CPM

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PROJECT PLANNING - CPM

Select Output Option
 CPM Calculations

Next Step All Steps Write to Printer

Title: CPM

SOLUTION STEPS

Forward pass completed			Backward pass completed		
Activity	Duration	Earliest Start	Latest Completion	Total Float	Free Float
A	6.00	0.00	6.00	0.00	0.00
G	2.00	0.00	4.00	2.00	0.00
J	13.00	0.00	14.00	1.00	0.00
B	4.00	6.00	10.00	0.00	0.00
K	9.00	6.00	17.00	2.00	2.00
D	2.00	6.00	10.00	2.00	0.00
C	7.00	10.00	17.00	0.00	0.00
L	3.00	17.00	20.00	0.00	0.00
H	10.00	2.00	14.00	2.00	1.00
I	6.00	13.00	20.00	1.00	1.00
M	5.00	20.00	25.00	0.00	0.00
E	5.00	8.00	15.00	2.00	0.00
F	10.00	13.00	25.00	2.00	2.00

Critical activities highlighted in red

View/Modify Input Data MAIN Menu Exit TORA

6.PERT

PROJECT PLANNING -- PERT/CPM

File EditGrid

Problem Title: **PERT**

Editing Grid:
 >>To DELETE, INSERT, COPY, or PASTE a column(row), click heading cell of target column(row), then invoke pull-down EditGrid menu
 >>For INSERT mode, a single(double) click of target row/column will place new row/column after(before) target row/column.

INPUT GRID - PERT (PROGRAM EVALUATION & REVIEW TECHNIQUE)

Row	From Node	To Node	Activity Symbol	a	m	b
1	1	2	A	3.00	5.00	7.00
2	1	3	B	4.00	6.00	8.00
3	2	3	C	1.00	3.00	5.00
4	2	4	D	5.00	8.00	11.00
5	3	5	E	1.00	2.00	3.00
6	3	6	F	9.00	11.00	13.00
7	4	5	DUMMY	0.00	0.00	0.00
8	4	6	G	1.00	1.00	1.00
9	5	6	H	10.00	12.00	14.00

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PROJECT PLANNING -- PERT/CPM

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PROJECT PLANNING - PERT

Select Output Option
Activity Mean/Var

Next Step All Steps Write to Printer

Title: PERT

ACTIVITY MEAN AND VARIANCE

Activity	Activity Symbol	Mean Duration	Variance
1-2	A	5.00	0.44
1-3	B	6.00	0.44
2-3	C	3.00	0.44
2-4	D	8.00	1.00
3-5	E	2.00	0.11
3-6	F	11.00	0.44
4-5	DUMMY	0.00	0.00
4-6	G	1.00	0.00
5-6	H	12.00	0.44

View/Modify Input Data MAIN Menu Exit TORA

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PROJECT PLANNING -- PERT/CPM

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PROJECT PLANNING - PERT

Select Output Option
PERT Calculations

Next Step All Steps Write to Printer

Title: PERT

PATH MEAN AND STD. DEVIATION

Node	Longest Path Based on Mean Durations	Mean Duration	Std. Deviation
2	1-2	5.00	0.67
3	1-2-3	8.00	0.94
4	1-2-4	13.00	1.20
5	1-2-4-5	13.00	1.20
6	1-2-4-5-6	25.00	1.37

View/Modify Input Data MAIN Menu Exit TORA

7.QUEUEING MODELS

File EditGrid

QUEUEING MODELS

Problem Title: **QUEUEING**

No. of Scenarios **1**

Editing Grid:

>>To DELETE, INSERT, COPY, or PASTE a column(row), click heading cell of target column(row), then invoke pull-down EditGrid menu

>>For INSERT mode, a single(double) click of target row/column will place new row/column after(before) target row/column.

INPUT TABLE - M/M/c queues

Scenario	Lambda	Mu	Nbr. of Servers	System Limit	Source Limit
1	8.00	10	1	infinity	infinity

QUEUEING MODELS

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QUEUEING OUTPUT ANALYSIS

Select Output Option
Scenario1

Next Iteration All Iterations Write to Printer

Title: QUEUEING

Scenario 1:(M/M/1):(GD/infinity/infinity)

Lambda = 8.00000
 L'da eff = 8.00000
 Ls = 4.00000
 Ws = 0.50000

Mu = 10.00000
 Rho/c = 0.80000
 Lq = 3.20000
 Wq = 0.40000

n	Probability, pn	Cumulative, Pn	n	Probability, pn	Cumulative, Pn
0	0.20000	0.20000	23	0.00118	0.99528
1	0.16000	0.36000	24	0.00094	0.99622
2	0.12800	0.48800	25	0.00076	0.99698
3	0.10240	0.59040	26	0.00060	0.99758
4	0.08192	0.67232	27	0.00048	0.99807
5	0.06554	0.73786	28	0.00039	0.99845
6	0.05243	0.79028	29	0.00031	0.99876
7	0.04194	0.83223	30	0.00025	0.99901
8	0.03355	0.86578	31	0.00020	0.99921
9	0.02684	0.89263	32	0.00016	0.99937

View/Modify Input Data MAIN Menu Exit TORA

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QUEUEING MODELS

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QUEUEING OUTPUT ANALYSIS

Select Output Option
Comparative Analysis

Next IterationAll IterationsWrite to Printer

Title: QUEUEING

Comparative analysis

Scenario	c	Lambda	Mu	L'da eff	p0	Ls	Lq	Ws	Wq
1	1	8.00000	10.00000	8.00000	0.20000	4.00000	3.20000	0.50000	0.40000

View/Modify Input DataMAIN MenuExit TORA