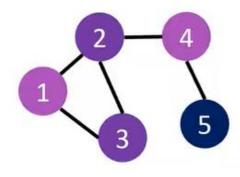
Graph Neural Network

A Simple Graph

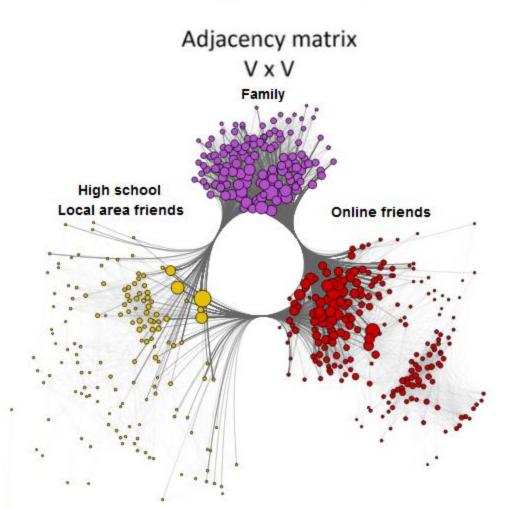
The most fundamental part of GNN is a Graph.

A graph can represent things like social media networks, or molecules. Think of nodes as users, and edges as connections.

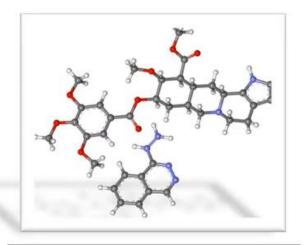


$$G = (V,E)$$

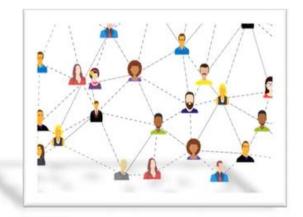
	V1	V2	***
V1	0	1	
V2	1	0	
V3	1	1	***



Graph Data is everywhere



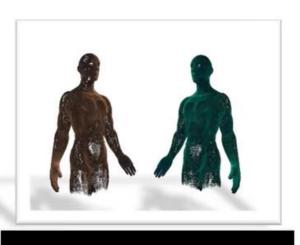
Medicine / Pharmacy



Social Networks

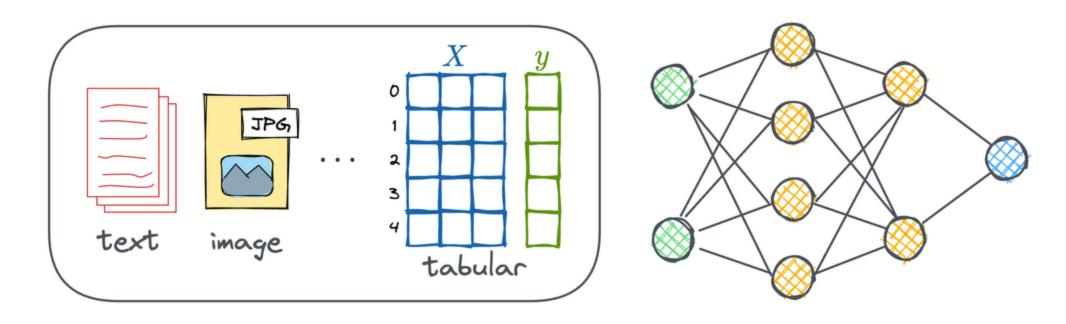


Recommender Systems



3D Games / Meshes

Traditional DL

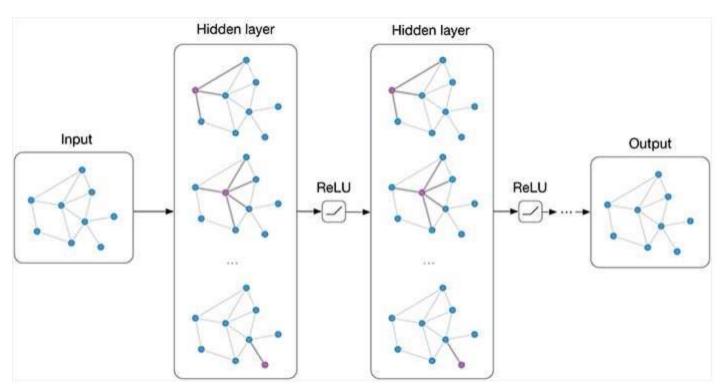


data formats that are tabular, image-based, or sequential (like language) in nature.

a significant proportion of our real-world data often exists in the form of graphs,

What is a Graph Neural Network (GNN)?

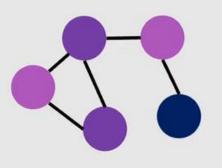
- To fill this gap, offering a way to extend deep learning techniques to graph-structured data.
- Processes and analyzes data represented as nodes (entities) and edges (relationships).
- Components:
- Nodes: Represent entities in the graph.
- Edges: Represent relationships or connections between nodes.
- Features: Attributes of nodes or edges.



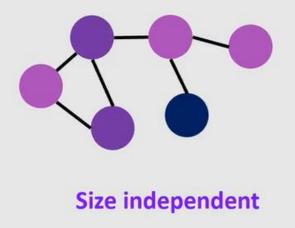
Problem: Graph Data is different!

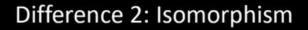
Difference 1: Size and Shape





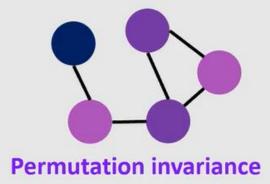






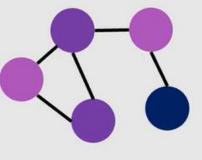






Difference 3: Grid structure



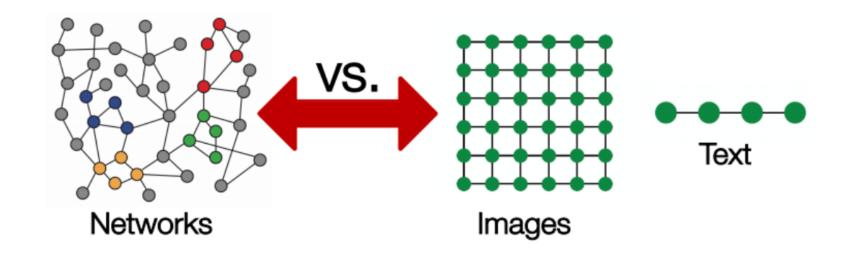


Non-euclidean space

Why is it hard to analyze a graph?

Complex Nature of Graph Data:

- Graph data lacks fixed forms and has variable-sized, unordered nodes.
- Nodes can have varying numbers of neighbors.
- Limitations of Conventional ML/DL Tools:
- Specialized for structured data like:
- Images (fixed-size grid graphs).
- Text and speech (line graphs).
- Dependency Issue:
- Existing ML algorithms assume independent instances.
- Graph data violates this due to interrelated nodes with various link types.

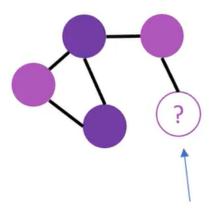


Types of Graph Neural Networks Tasks

- Graph Classification: Classify entire graphs into categories.
- Example: Social network analysis (e.g., professional vs. friendship networks).
- Node Classification: Predict missing node labels using neighboring node information.
- Example: Fraud detection in transaction networks.
- Link Prediction: Predict potential or missing links between nodes in an incomplete graph.
- Example: Friend recommendation in social networks.
- Community Detection: Identify clusters of nodes based on edge structure, weights, and distances.
- Example: Detecting communities in social media platforms.
- Graph Embedding: Convert graph data into vector representations while preserving structure and relationships.
- Example: Input for machine learning tasks like graph-based recommendation systems.

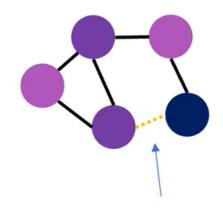
Examples for Machine Learning Problems with Graph Data

Node-level predictions



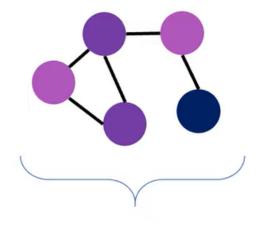
Does this person smoke? (unlabeled node)

Edge-level predictions (Link prediction)

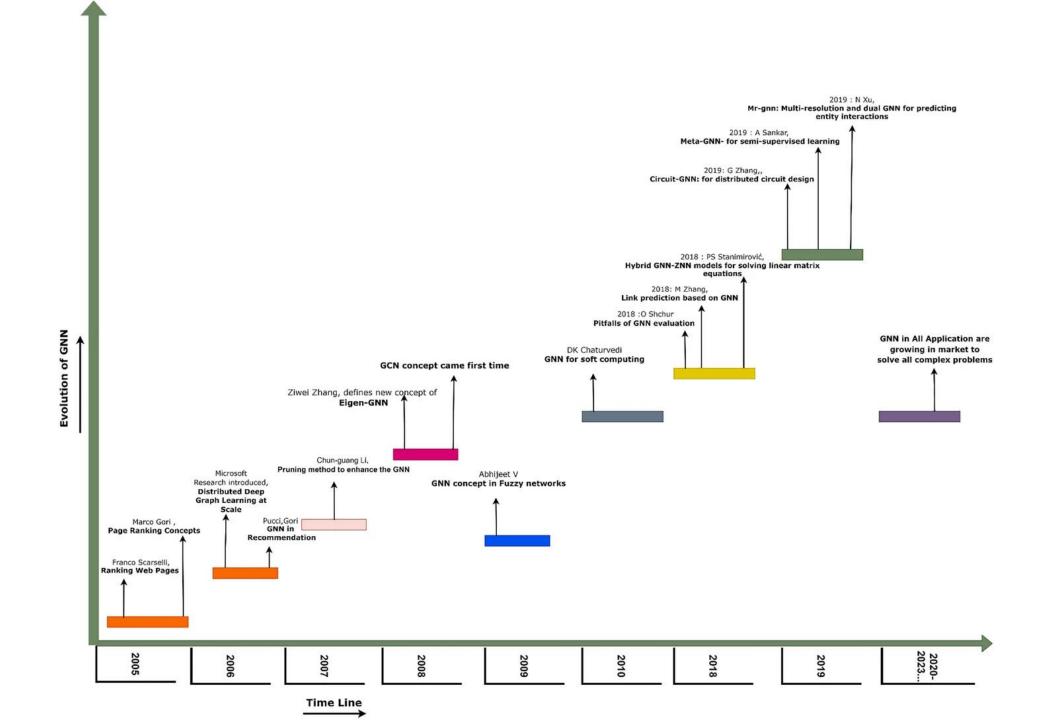


Next Netflix video?

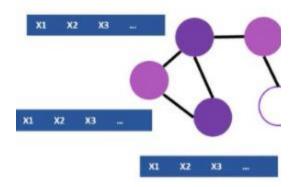
Graph-level predictions



Is this molecule a suitable drug?



Node Embedding



- Each node is represented as a vector in a **low-dimensional space** (d-dimensional), which is much smaller than the size of the graph itself (e.g., the adjacency matrix or feature matrix).
- The goal of node embedding is to learn an informative representation of each node in the graph.
- Capturing Structural and Feature Information:
 - Neighborhood: The structure and types of connections it has with other nodes.
 - Node Features: Any attributes or labels associated with the node.
 - o Graph Context: The broader context of the graph, which helps the node embedding reflect not just the local connections but also global graph structure.
- Node embeddings are learned through a series of graph convolutional layers that aggregate information from neighboring nodes, progressively refining the embeddings.

Neighborhood: The Structure and Types of Connections

- Node embeddings capture how a node is connected to its neighbors.
- Example:
- Consider a social network with the following relationships:
 - Node A (Alice) is friends with Node B (Bob) and Node C (Charlie).
 - Node B (Bob) is friends with Node A (Alice), Node C (Charlie), and Node D (David).
 - Node C (Charlie) is friends with Node A (Alice), Node B (Bob), and Node E (Eve).
 - o For Node A (Alice):
 - Neighborhood Information: Alice's direct neighbors are Bob and Charlie. So, her node embedding will reflect the structure of these relationships.
 - Alice's embedding will consider the properties of her neighbors

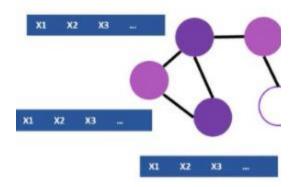
Node Features: Attributes or Labels Associated with the Node

- Example:
- Let's assume each individual in the social network has the following features:
- Age
- Interests (e.g., books, technology, sports)
- Occupation (e.g., teacher, engineer)
- For Node A (Alice):
- Node Features: Alice may have the following features:
 - Age: 30
 - Interest: Books, technology

Graph Context

- **global context** even though a node has specific neighborhood relationships, it is also influenced by the structure and distribution of the entire graph.
- Example:
- If the network has distinct **communities** or **groups** (e.g., people interested in different types of activities like sports, literature, or technology), the **global context** might show that Alice, who is interested in books and technology, is part of a group of people with similar interests, even if some of her direct neighbors are from different groups.
- For Node A (Alice):
- Global Context: The embedding for Alice will take into account not only her direct neighbors (Bob and Charlie) but also the broader structure of the entire network.

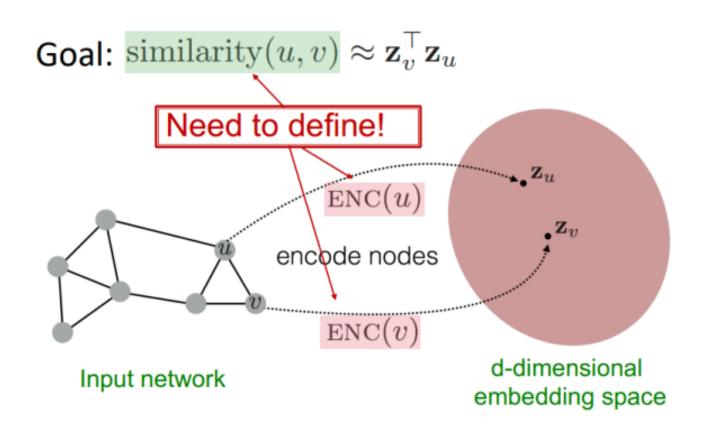
Node Embedding



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Similarity

Node embedding represent each node in such a way that similar nodes in terms of structure, attributes, or role in the graph are embedded close to each other in the vector space.

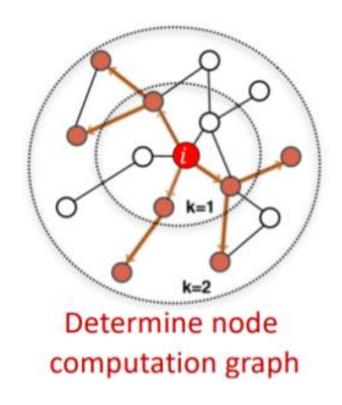


 x_u and x_v are two feature vectors. Now we'll define the encoder function Enc(u) and Enc(v), which convert the feature vectors to z_u and z_v .

The encoder function should be able to perform:

- Locality (local network neighborhoods)
- Aggregate information
- Stacking multiple layers (computation)

Locality- computational graph

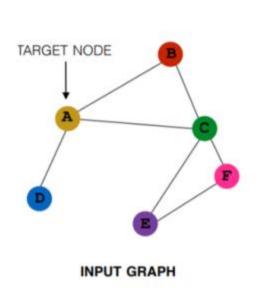


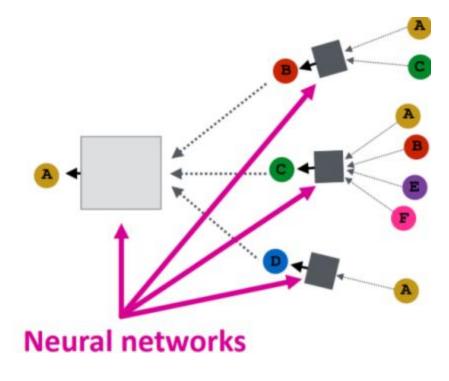


Propagate and transform information

how this node is connected to its neighbors and those neighbors' neighbors

Aggregation (Message Passing)



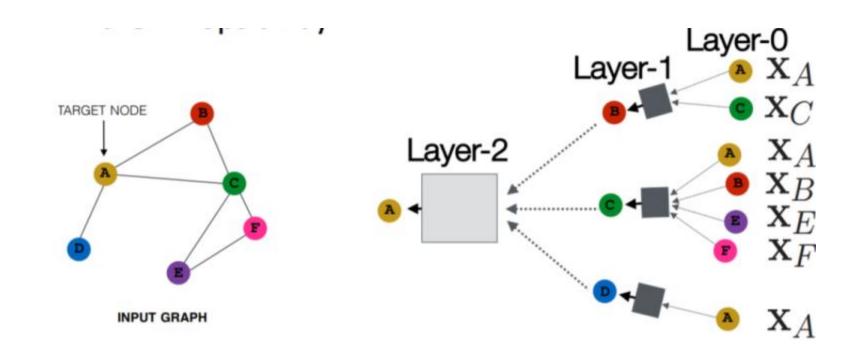


process of collecting and combining information from neighboring nodes in a computational graph.

Aggregation Functions:

- Sum: Add the features of the neighboring nodes.
- Mean: Take the average of the features of the neighboring nodes.
- Max: Select the maximum value of features across neighbors.

Forward propagation



Forward propagation

1. Initial Node Embeddings:

• Each node v is represented by an initial feature vector $h_v^{(0)} \in \mathbb{R}^d$, where d is the dimension of the feature space.

2. Message Passing (Aggregation):

• At layer l, each node aggregates information from its neighbors N(v) (neighbors of node v):

$$m_v^{(l)} = \sum_{u \in N(v)} \mathrm{Aggregate}(h_u^{(l-1)}, A_{uv})$$

where $m_v^{(l)}$ is the aggregated message for node v at layer l, $h_u^{(l-1)}$ is the feature vector of neighbor node u at the previous layer, and A_{uv} is the edge weight (or adjacency relation) between nodes u and v.

Forward propagation

3. Node Update (Transformation):

 After aggregation, the node's feature vector is updated using a transformation function, typically a linear transformation followed by a non-linear activation function (e.g., ReLU):

$$h_v^{(l)} = \sigma \left(W^{(l)} \cdot m_v^{(l)} + b^{(l)}
ight)$$

where $W^{(l)}$ is the weight matrix, $b^{(l)}$ is the bias, and σ is the activation function (e.g., ReLU).

4. Multiple Layers:

 The process is repeated across multiple layers L of the network, with the final representation of each node reflecting both local and global graph structure:

$$h_v^{(L)} = \operatorname{Update} \operatorname{function}(h_v^{(L-1)}, \{m_u^{(L-1)}\})$$

Final Node Representation:

• After passing through all layers, the node embeddings $h_v^{(L)}$ are used for downstream tasks such as classification, regression, or link prediction.

Back propagation

2. Loss Calculation:

After obtaining the final embeddings $h_v^{(L)}$, calculate the loss $\mathcal L$ for the task (e.g., node classification):

$$\mathcal{L} = \sum_{v \in V} \mathrm{Loss}(y_v, \hat{y}_v)$$

Where:

• \hat{y}_v is the predicted label (or output) for node v based on its embedding $h_v^{(L)}$.

Back propagation

a. Compute Gradients for the Output Layer L:

For each node v, compute the gradient of the loss with respect to the node embedding $h_v^{(L)}$:

$$rac{\partial \mathcal{L}}{\partial h_v^{(L)}} = rac{\partial \mathcal{L}}{\partial \hat{y}_v} \cdot rac{\partial \hat{y}_v}{\partial h_v^{(L)}}$$

Then, backpropagate this gradient to compute the gradients for the weight matrix $W^{(L)}$ and bias vector $b^{(L)}$ at the output layer.

b. Compute Gradients for Intermediate Layers:

For each intermediate layer l, compute the gradient of the loss with respect to the node embedding $h_v^{(l)}$:

$$rac{\partial \mathcal{L}}{\partial h_v^{(l)}} = \sum_{u \in N(v)} rac{\partial \mathcal{L}}{\partial h_u^{(l+1)}} \cdot rac{\partial h_u^{(l+1)}}{\partial h_v^{(l)}}$$

This allows the gradient to be propagated backward through the layers.

c. Gradient of the Aggregation Function:

During the backpropagation, the gradient with respect to the aggregation function (e.g., summation of neighbors' embeddings) is also computed:

$$rac{\partial \mathcal{L}}{\partial m_v^{(l)}} = \sum_{u \in N(v)} rac{\partial \mathcal{L}}{\partial h_u^{(l+1)}} \cdot rac{\partial h_u^{(l+1)}}{\partial m_v^{(l)}}$$

Back propagation

4. Parameter Update:

After computing the gradients for the loss with respect to the model parameters, update the weigh $W^{(l)}$ and biases $b^{(l)}$ using an optimization algorithm like **Stochastic Gradient Descent (SGD)** or **Adam**:

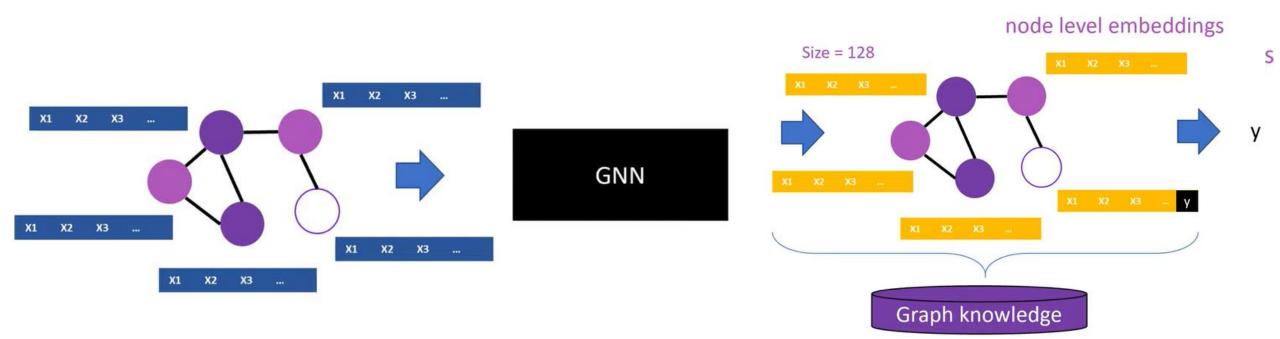
$$egin{aligned} W^{(l)} \leftarrow W^{(l)} - lpha \cdot rac{\partial \mathcal{L}}{\partial W^{(l)}} \ b^{(l)} \leftarrow b^{(l)} - lpha \cdot rac{\partial \mathcal{L}}{\partial b^{(l)}} \end{aligned}$$

Where α is the learning rate, which controls how much to adjust the weights during each step.

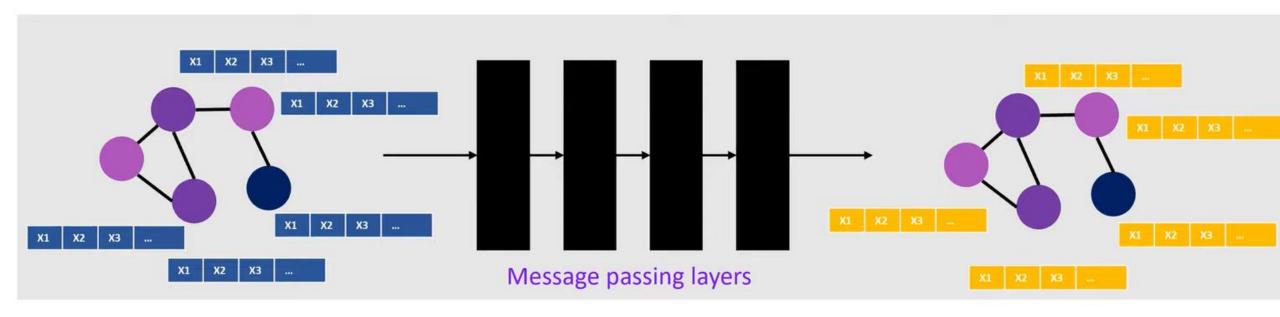
Fundamental Idea of GNNs

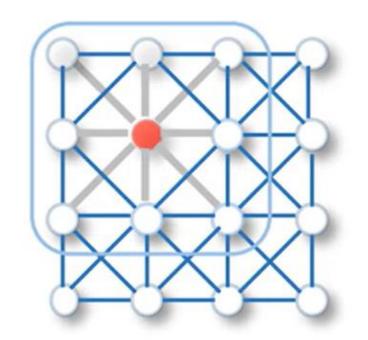
>> Learning a for neural networks <u>suitable representation</u> of graph data. <-

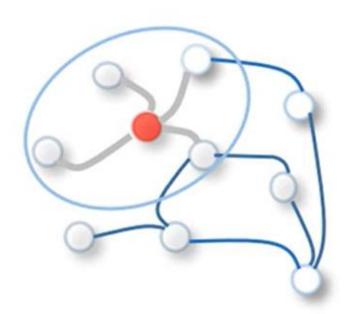
= Representation learning

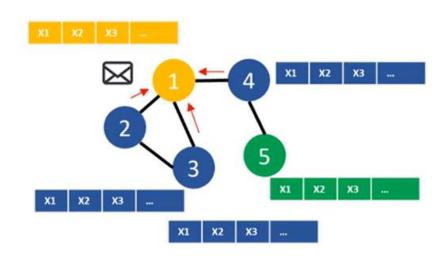


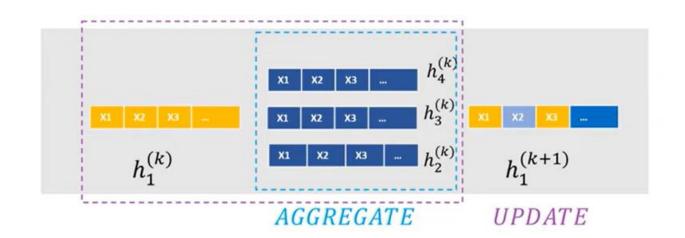
How do Graph Neural Networks work?

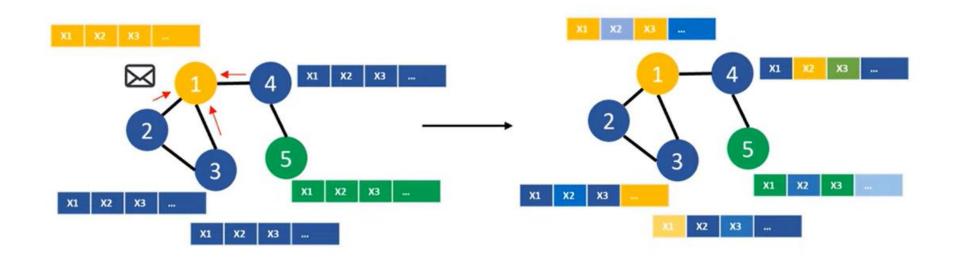


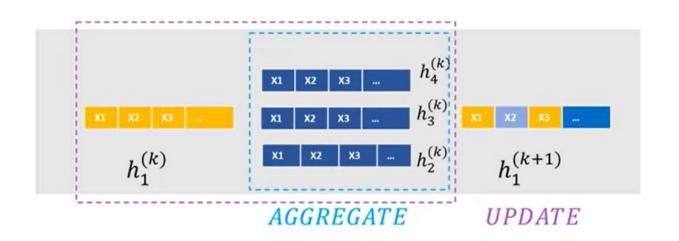


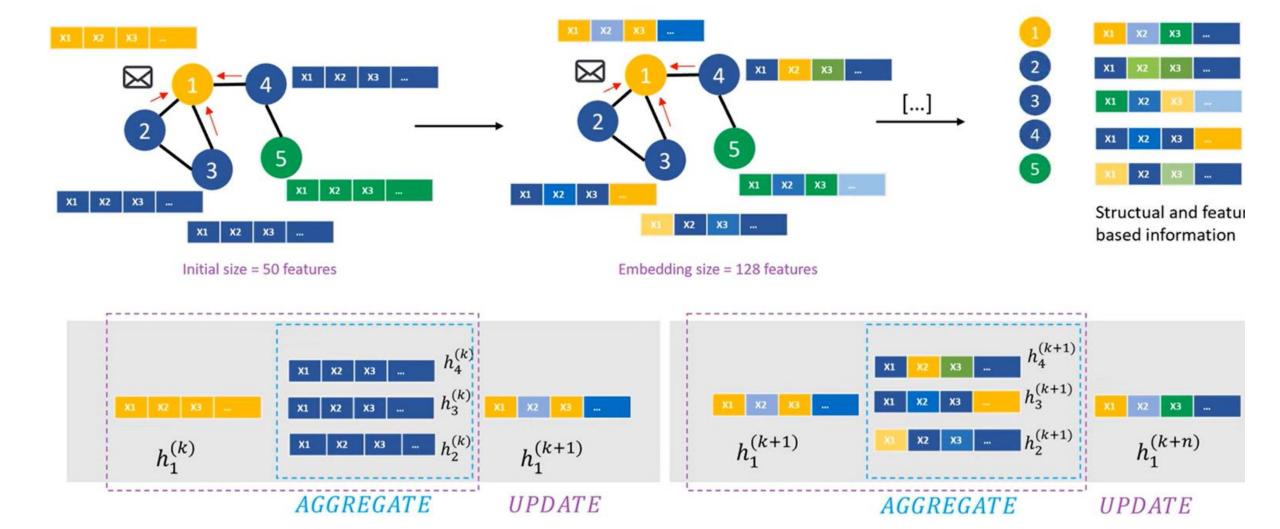




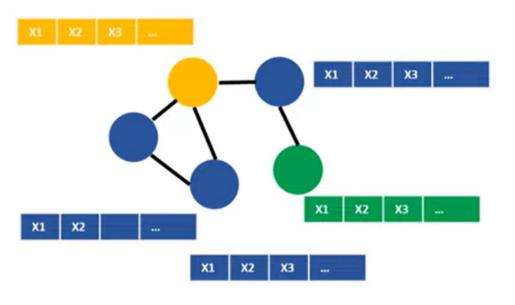






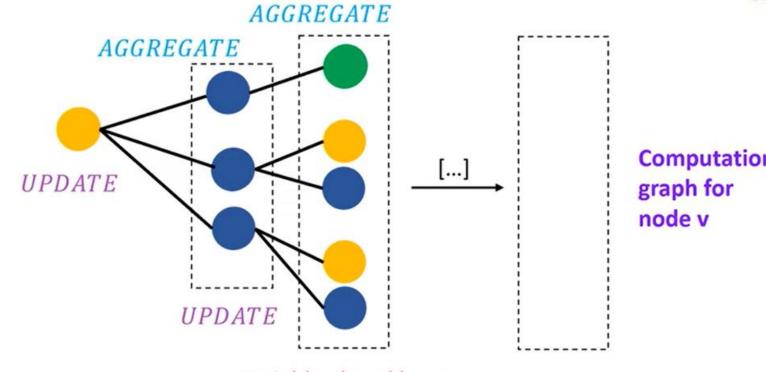


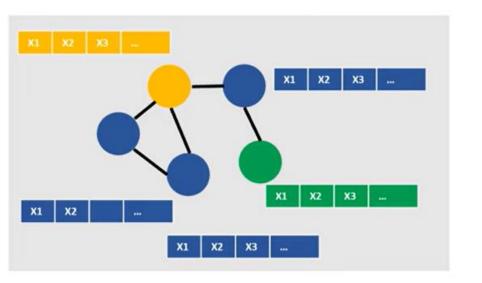
Computation Graph Representation

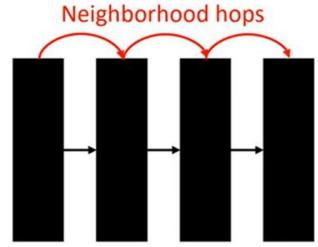


Computation Graph Representation





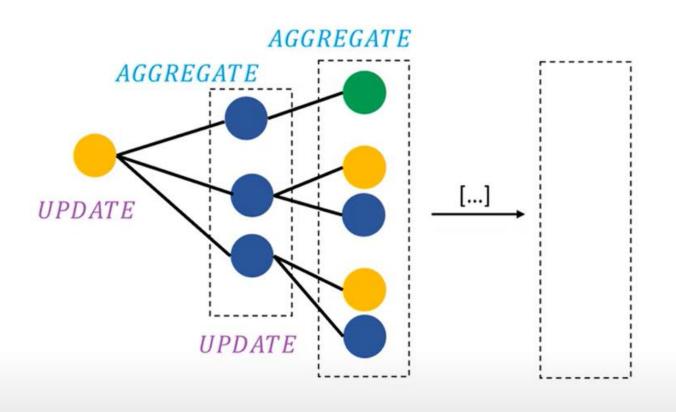


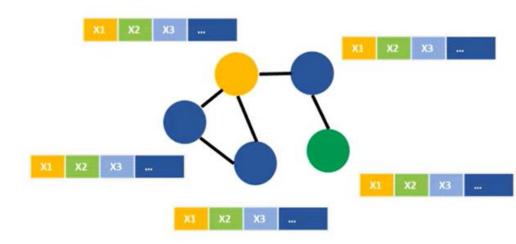


The number of MP-layers is a hyperparameter

Over-smoothing in GNNs

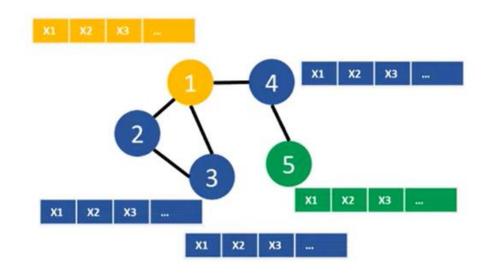




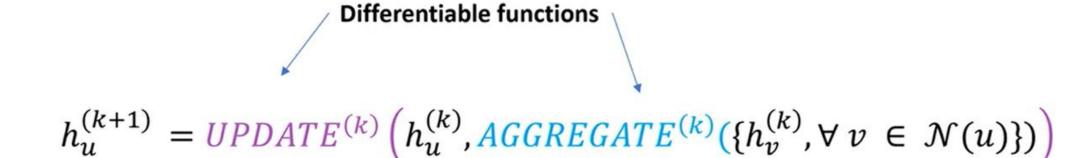


Message Passing Update and Aggregation Functions





Message Passing Update and Aggregation Functions



- Mean
- Max
- Neural Network
- Recurrent NN

- Mean
- Max
- Normalized Sum
- Neural Network



GNN variants

GNN variants



AGGREGATE (permutation invariant)



UPDATE

Graph Convolutional Networks, Kipf and Welling [2016]

$$\mathbf{h}_v^{(k)} = \sigma \left(\mathbf{W}^{(k)} \sum_{v \in \mathcal{N}(u) \cup \{u\}} \frac{\mathbf{h}_v}{\sqrt{|\mathcal{N}(u)||\mathcal{N}(v)|}} \right) \quad \begin{array}{l} \text{Sum of normalized} \\ \text{neighbor embeddings} \end{array}$$

Multi-Layer-Perceptron as Aggregator, Zaheer et al. [2017]

$$\mathbf{m}_{\mathcal{N}(u)} = \underbrace{\mathbf{MLP}_{\theta}}_{\text{trainable!}} \left(\sum_{v \in N(u)} \mathbf{MLP}_{\phi}(\mathbf{h}_v) \right) \quad \text{Send states through a MLP}$$

Graph Attention Networks, Veličković et al. [2017]

$$\mathbf{m}_{\mathcal{N}(u)} = \sum_{v \in \mathcal{N}(u)} \alpha_{u,v} \mathbf{h}_v \qquad \alpha_{u,v} = \frac{\exp\left(\mathbf{a}^\top [\mathbf{W} \mathbf{h}_u \oplus \mathbf{W} \mathbf{h}_v]\right)}{\sum_{v' \in \mathcal{N}(u)} \exp\left(\mathbf{a}^\top [\mathbf{W} \mathbf{h}_u \oplus \mathbf{W} \mathbf{h}_{v'}]\right)}$$

Gated Graph Neural Networks, Li et al. [2015]

$$\mathbf{h}_{u}^{(k)} = \text{GRU}(\mathbf{h}_{u}^{(k-1)}, \mathbf{m}_{\mathcal{N}(u)}^{(k)})$$

Recurrent update of the state

Types of Graph Neural Networks

- **Graph Convolutional Networks (GCNs)**: Learn node features by aggregating information from neighboring nodes using graph convolution and activation functions.
- Graph Auto-Encoder Networks: Encode and reconstruct graph representations for tasks like link prediction, using an encoder-decoder structure.
- Recurrent Graph Neural Networks (RGNNs): Handle multi-relational graphs and optimize diffusion patterns while reducing computational complexity.
- Gated Graph Neural Networks (GGNNs): Enhance RGNNs with gating mechanisms for better handling of long-term dependencies.

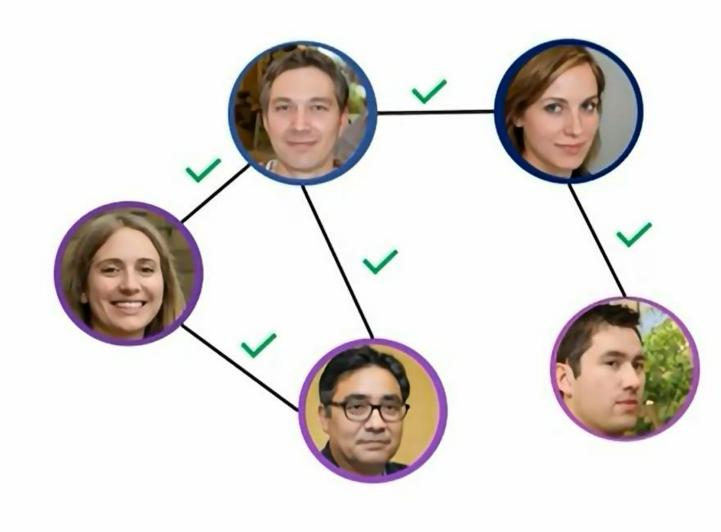
Implementation

- https://journalofbigdata.springeropen.com/articles/10.1186/s405
 37-023-00876-4
- Code
- https://colab.research.google.com/drive/16GBgwYR2ECiXVxA1Bo LxYshKczNMeEAQ?usp=sharing
- Video
- https://www.youtube.com/watch?v=0YLZXjMHA-8&list=PLV8yxwGOxvvoNkzPfCx2i8an--Tkt7O8Z&index=3

Edge features

Simple binary edge features

		0		9	
	0	1	0	1	0
0	1	0	1	1	0
	0	1	0	0	1
9	1	1	0	0	0
	0	0	1	0	0



The general process in GNNs



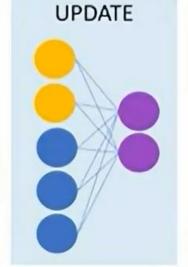


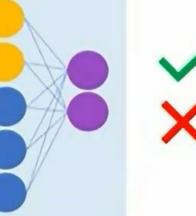






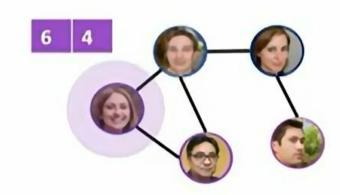






$$h_{Alice}^{(k+1)} = UPDATE\left(h_{Alice}^{(k)}, AGGREGATE_{j \in N(Alice)} TRANSFORM(h_{j}^{(k)})\right)$$

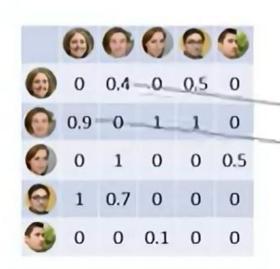
$$h_{Alice}^{(k+1)} = AGGREGATE_{j \in N(Alice)} TRANSFORM(h_{j}^{(k)})$$

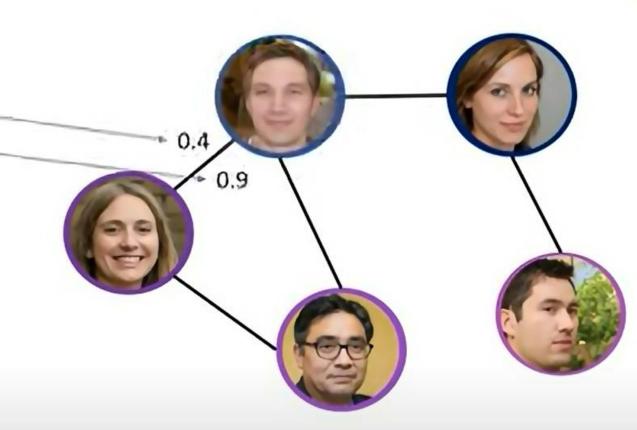


Using edge weights



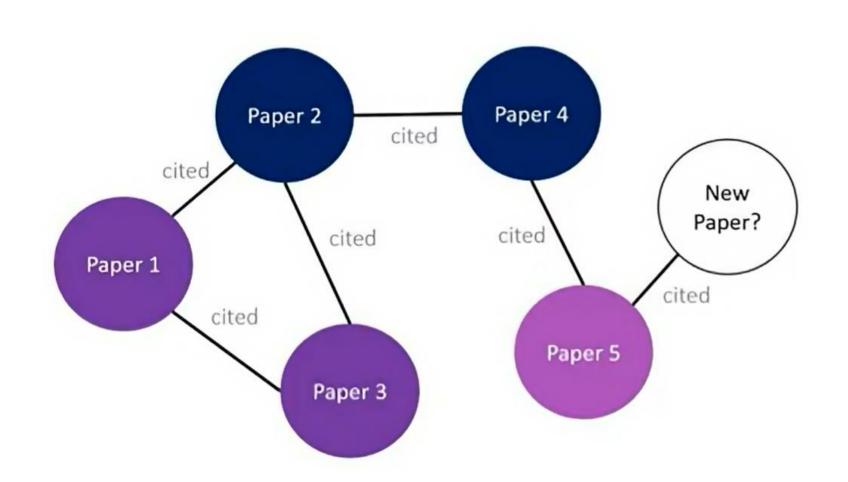
	0	0	9	9	0
(2)	0	1	0	1	0
0	1	0	1	1	0
0	0	1	0	0	1
9	1	1	0	0	0
0	0	0	1	0	0

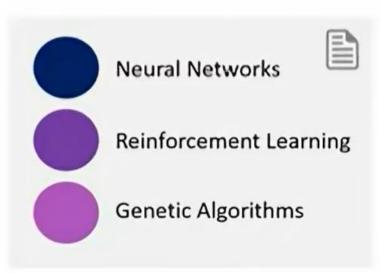




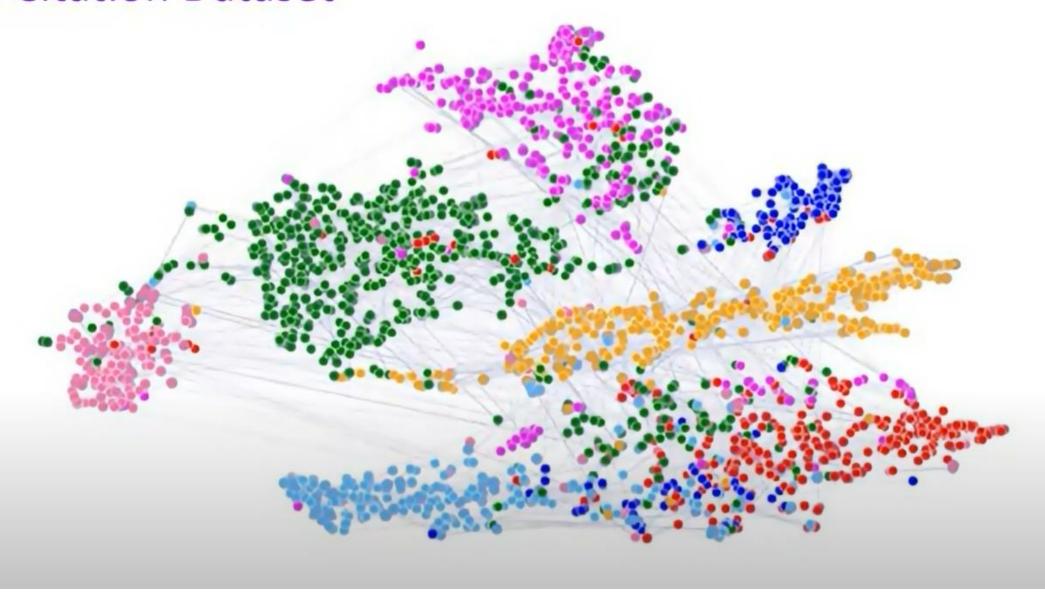
Cora Citation Dataset



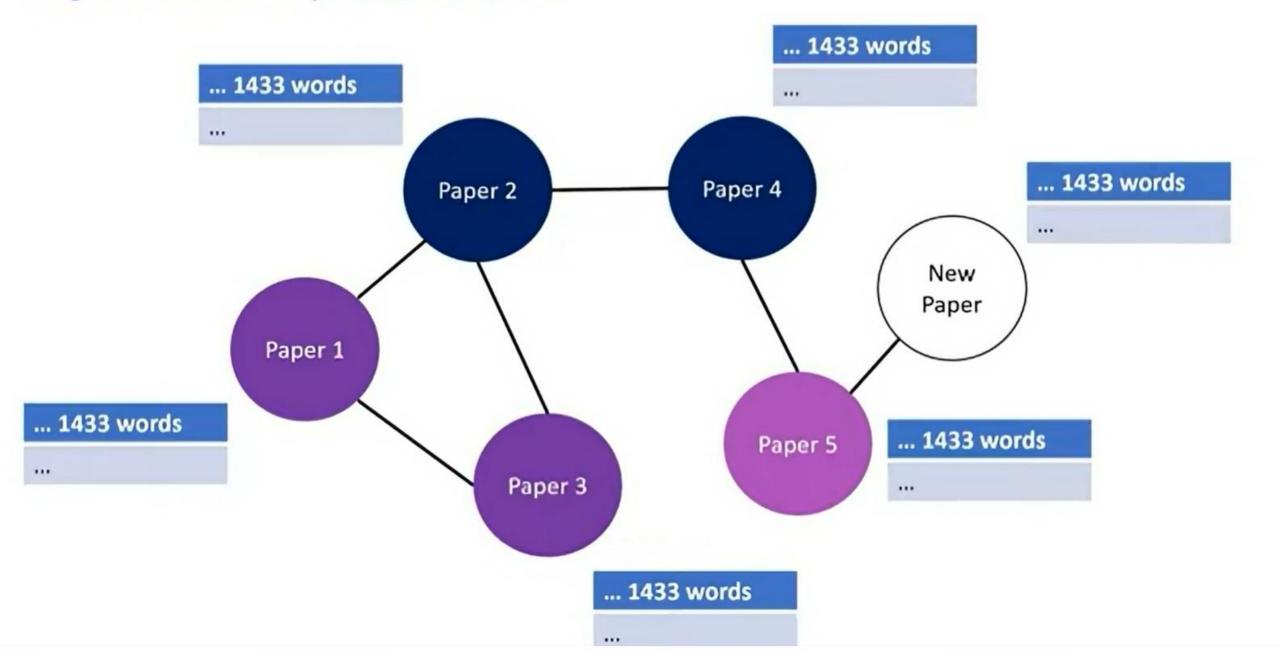




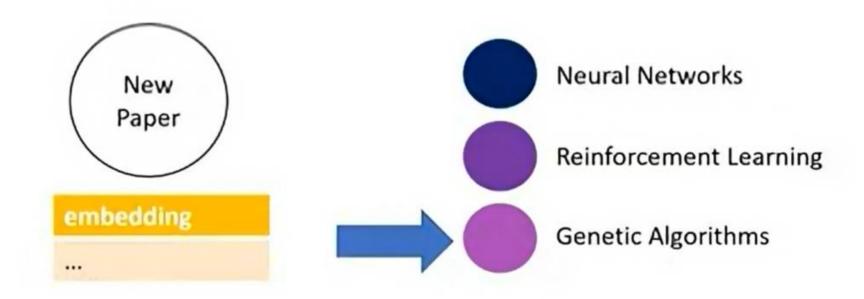
Cora Citation Dataset



Bag of words representation



Representation learning



https://colab.research.go ogle.com/drive/1LJir3T6M 6Omc2Vn2GV2cDW_GV2 Yfl53_?usp=sharing