

# 22AIE442 –

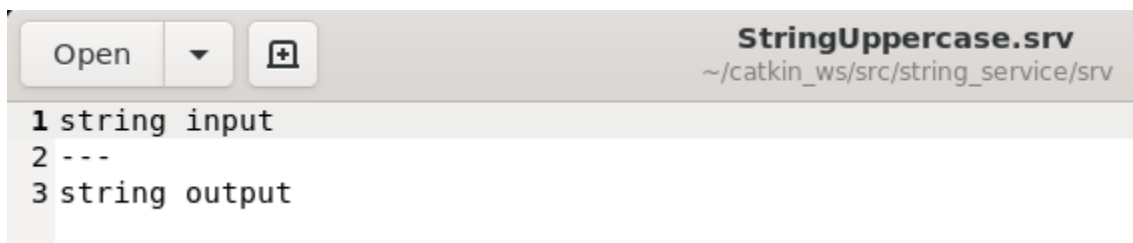
## LABSHEET – 4

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Roll no: AM.EN.U4AIE22010

1. Implement a ROS service that takes a string input through a GUI and returns it in uppercase.
  - Define a custom service that accepts a string and returns it in uppercase.
  - Create a ROS service server in Python that handles the string conversion.
  - Design a GUI to allow the user to input a string.
  - Implement a service client that calls the ROS service and displays the uppercase result in the GUI.

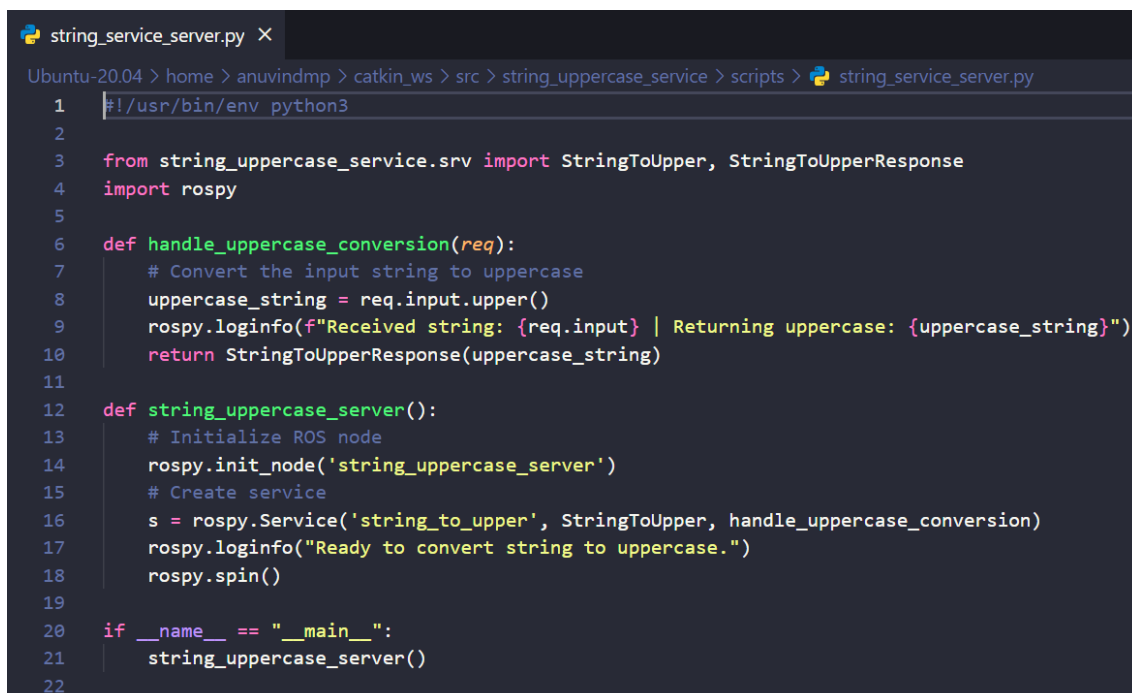
.srv file :



```
StringUppercase.srv
~/catkin_ws/src/string_service/srv

1 string input
2 ---
3 string output
```

ROS service server CODE:



```
string_service_server.py X
Ubuntu-20.04 > home > anuvindmp > catkin_ws > src > string_uppercase_service > scripts > string_service_server.py

1 #!/usr/bin/env python3
2
3 from string_uppercase_service.srv import StringToUpper, StringToUpperResponse
4 import rospy
5
6 def handle_uppercase_conversion(req):
7     # Convert the input string to uppercase
8     uppercase_string = req.input.upper()
9     rospy.loginfo(f"Received string: {req.input} | Returning uppercase: {uppercase_string}")
10    return StringToUpperResponse(uppercase_string)
11
12 def string_uppercase_server():
13     # Initialize ROS node
14     rospy.init_node('string_uppercase_server')
15     # Create service
16     s = rospy.Service('string_to_upper', StringToUpper, handle_uppercase_conversion)
17     rospy.loginfo("Ready to convert string to uppercase.")
18     rospy.spin()
19
20 if __name__ == "__main__":
21     string_uppercase_server()
22
```

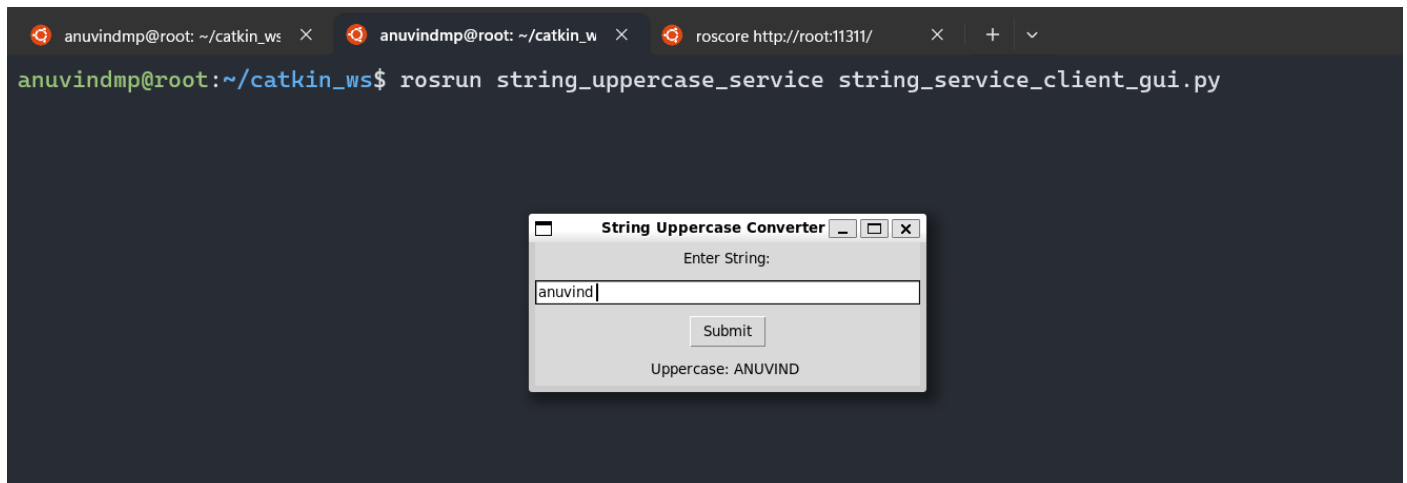
## ROS service client CODE:

```
string_service_server.py 2 string_service_client_gui.py 2 X
Ubuntu-20.04 > home > anuvindmp > catkin_ws > src > string_uppercase_service > scripts > string_service_client_gui.py > ...
1  #!/usr/bin/env python3
2  import rospy
3  from string_uppercase_service.srv import StringToUpper
4  import tkinter as tk
5  from tkinter import messagebox
6
7  def call_string_to_upper_service(input_string):
8      rospy.wait_for_service('string_to_upper')
9      try:
10         string_to_upper = rospy.ServiceProxy('string_to_upper', StringToUpper)
11         response = string_to_upper(input_string)
12         return response.output
13     except rospy.ServiceException as e:
14         rospy.logerr(f"Service call failed: {e}")
15         return None
16
17 def on_submit():
18     input_string = entry.get()
19     if input_string:
20         result = call_string_to_upper_service(input_string)
21         if result:
22             result_label.config(text=f"Uppercase: {result}")
23         else:
24             messagebox.showerror("Error", "Failed to get response from service.")
25     else:
26         messagebox.showwarning("Input Error", "Please enter a string.")
27
28 rospy.init_node('string_service_client_gui', anonymous=True)
29 root = tk.Tk()
30 root.title("String Uppercase Converter")
31 tk.Label(root, text="Enter String:").pack(pady=5)
32 entry = tk.Entry(root, width=40)
33 entry.pack(pady=5)
34 submit_button = tk.Button(root, text="Submit", command=on_submit)
35 submit_button.pack(pady=5)
36 result_label = tk.Label(root, text="Uppercase: ")
37 result_label.pack(pady=5)
38 root.mainloop()
39
```

## ROS service server output :

```
anuvindmp@root: ~/catkin_ws X anuvindmp@root: ~/catkin_ws X roscore http://root:11311/ X + v
anuvindmp@root:~/catkin_ws/src/string_uppercase_service/scripts$ rosrn string_uppercase_service string_service_server.p
y
[INFO] [1729579707.403201]: Ready to convert string to uppercase.
[INFO] [1729579793.790988]: Received string: graaahh | Returning uppercase: GRAAAHH
[INFO] [1729579806.852378]: Received string: anuvind | Returning uppercase: ANUVIND
```

ROS service client output :



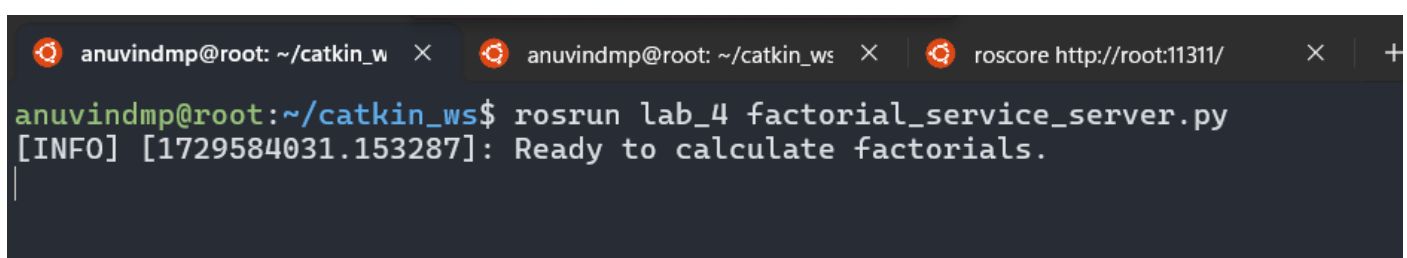
2. Implement a ROS service that calculates the factorial of a given non-negative integer input through a GUI. The service should return the factorial result

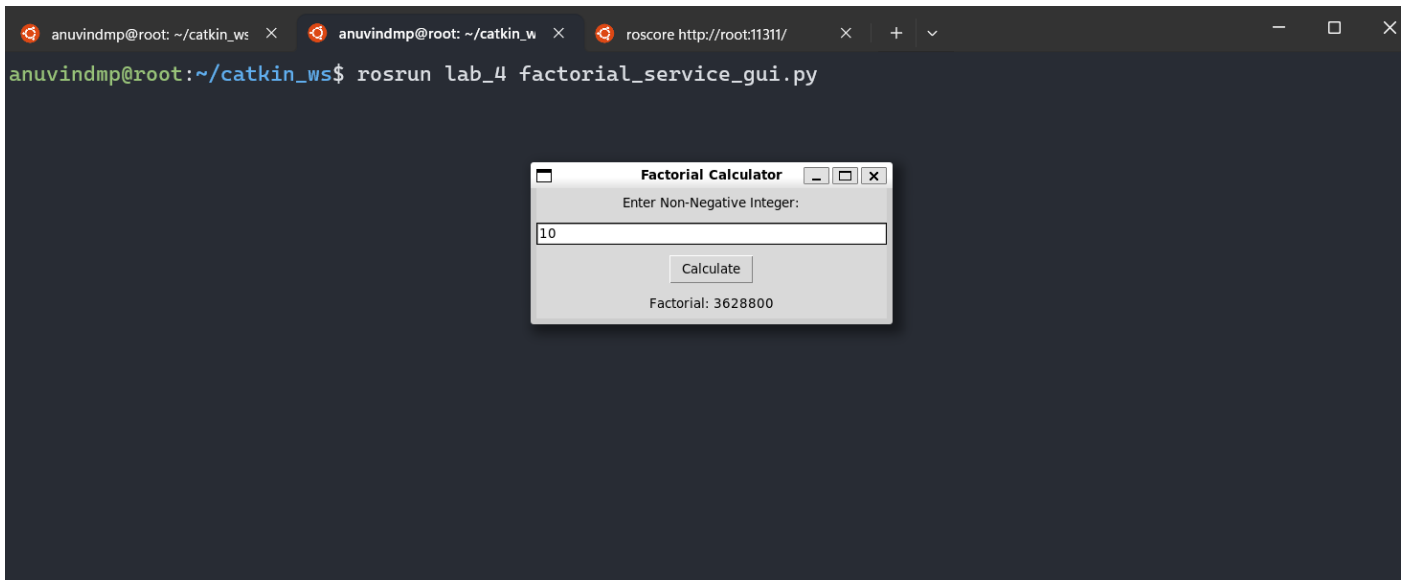
- Define a custom service that accepts a non-negative integer and returns its factorial.
- Create a ROS service server in Python that handles the factorial computation.
- Design a GUI to allow the user to input a number.
- Implement a service client that calls the ROS service and displays the factorial result in the GUI.

.srv file :



OUTPUT :





## CODE :

```
factorial_service_gui.py 2 factorial_service_server.py 2 X
Ubuntu-20.04 > home > anuvindmp > catkin_ws > src > lab_4 > scripts > factorial_service_server.py > ...
1  #!/usr/bin/env python3
2  import rospy
3  from lab_4.srv import Factorial, FactorialResponse
4
5  def calculate_factorial(req):
6      if req.input < 0:
7          return FactorialResponse(-1) # Return -1 for invalid input
8      factorial = 1
9      for i in range(1, req.input + 1):
10         factorial *= i
11     return FactorialResponse(factorial)
12
13 def factorial_service_server():
14     rospy.init_node('factorial_service_server')
15     s = rospy.Service('factorial_service', Factorial, calculate_factorial)
16     rospy.loginfo("Ready to calculate factorials.")
17     rospy.spin()
18
19 if __name__ == "__main__":
20     factorial_service_server()
21
```

```
1  #!/usr/bin/env python3
2  import rospy
3  from lab_4.srv import Factorial
4  import tkinter as tk
5  from tkinter import messagebox
6
7  def call_factorial_service(input_number):
8      rospy.wait_for_service('factorial_service')
9      try:
10         factorial_service = rospy.ServiceProxy('factorial_service', Factorial)
11         response = factorial_service(input_number)
12         return response.output
13     except rospy.ServiceException as e:
14         rospy.logerr(f"Service call failed: {e}")
15         return None
16
17  def on_submit():
18     input_number = entry.get()
19     if input_number.isdigit(): # Check if the input is a non-negative integer
20         input_number = int(input_number)
21         result = call_factorial_service(input_number)
22         if result is not None:
23             result_label.config(text=f"Factorial: {result}")
24         else:
25             messagebox.showerror("Error", "Failed to get response from service.")
26     else:
27         messagebox.showwarning("Input Error", "Please enter a non-negative integer.")
28
29  # Initialize ROS node
30  rospy.init_node('factorial_service_client_gui', anonymous=True)
31
32  # Create GUI
33  root = tk.Tk()
34  root.title("Factorial Calculator")
35
36  tk.Label(root, text="Enter Non-Negative Integer:").pack(pady=5)
37  entry = tk.Entry(root, width=40)
38  entry.pack(pady=5)
39
40  submit_button = tk.Button(root, text="Calculate", command=on_submit)
41  submit_button.pack(pady=5)
42
43  result_label = tk.Label(root, text="Factorial: ")
44  result_label.pack(pady=5)
45
46  # Start the GUI event loop
47  root.mainloop()
48
```