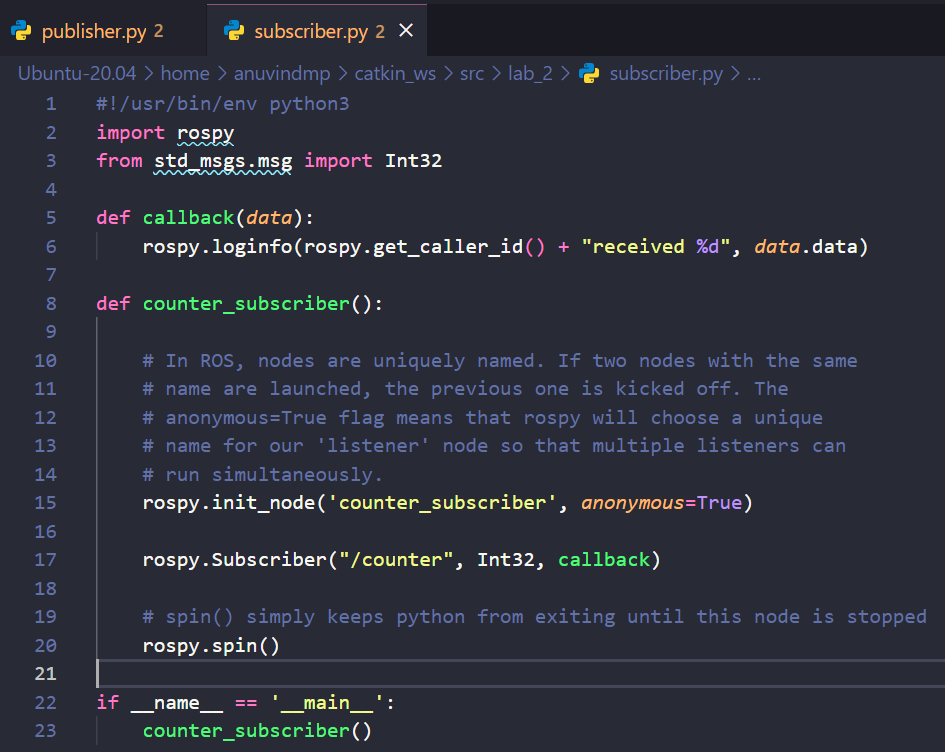
**LABSHEET-2**

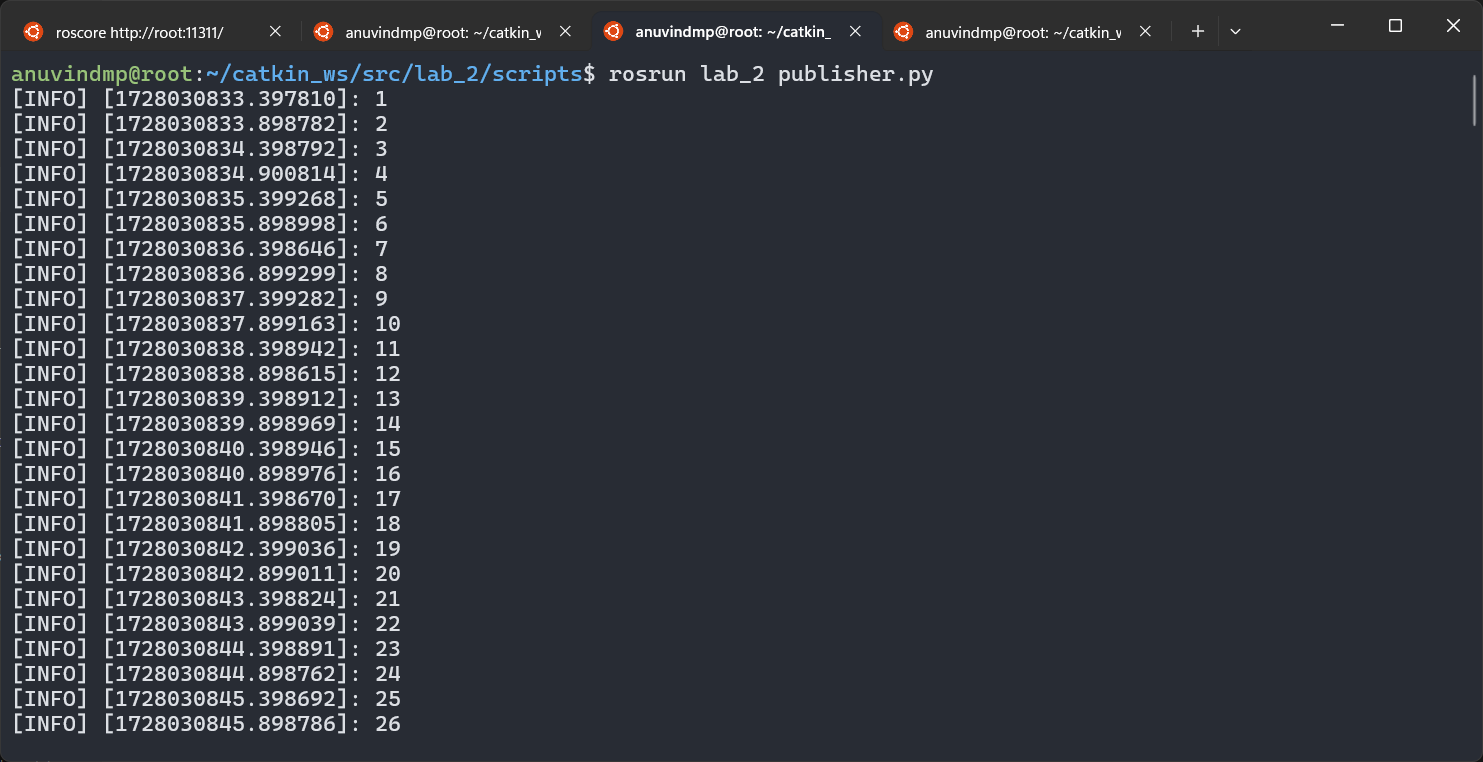
1. **Create a publisher node subscriber node to publishes consecutive integers on the topic counter at a rate of 2Hz and subscribe the count .**

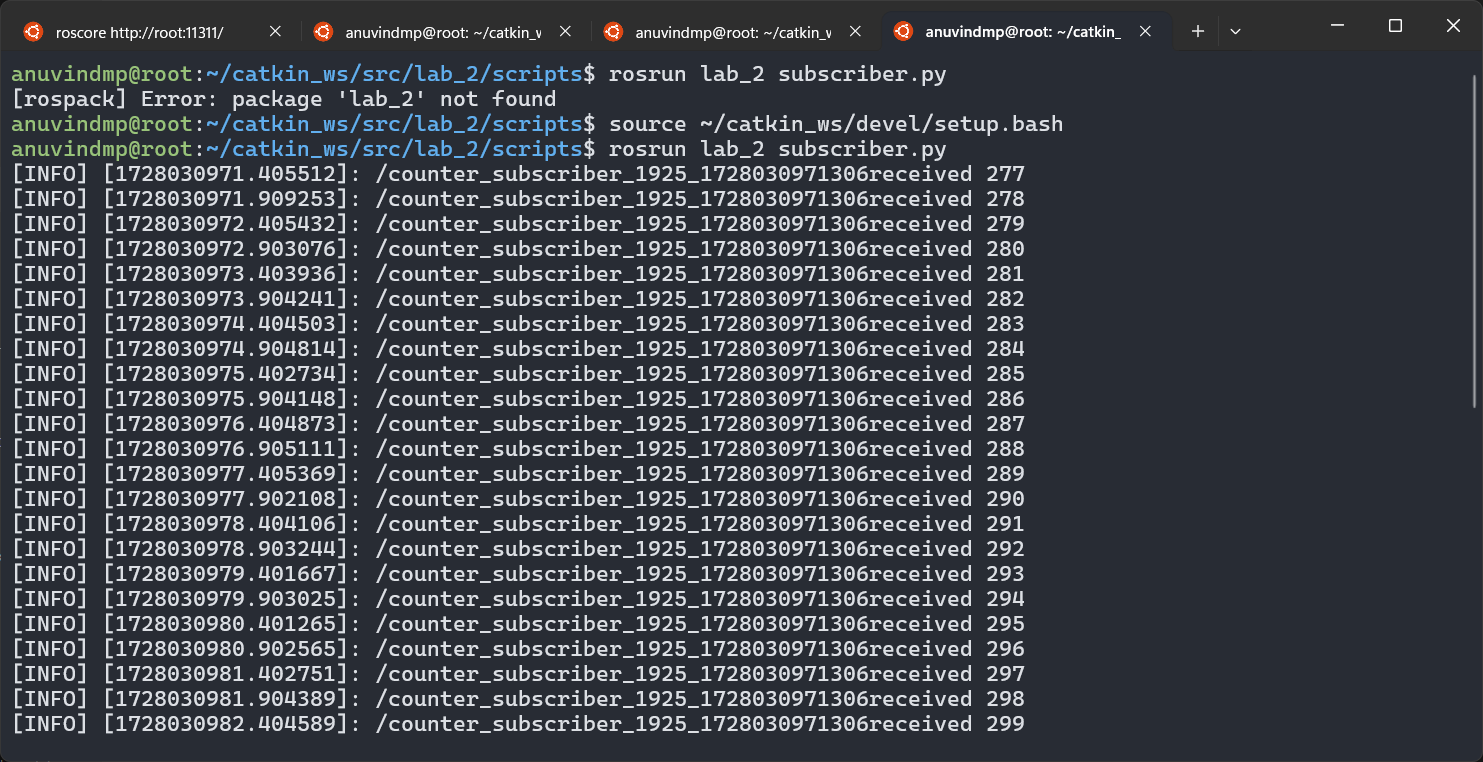
**Code :**

****

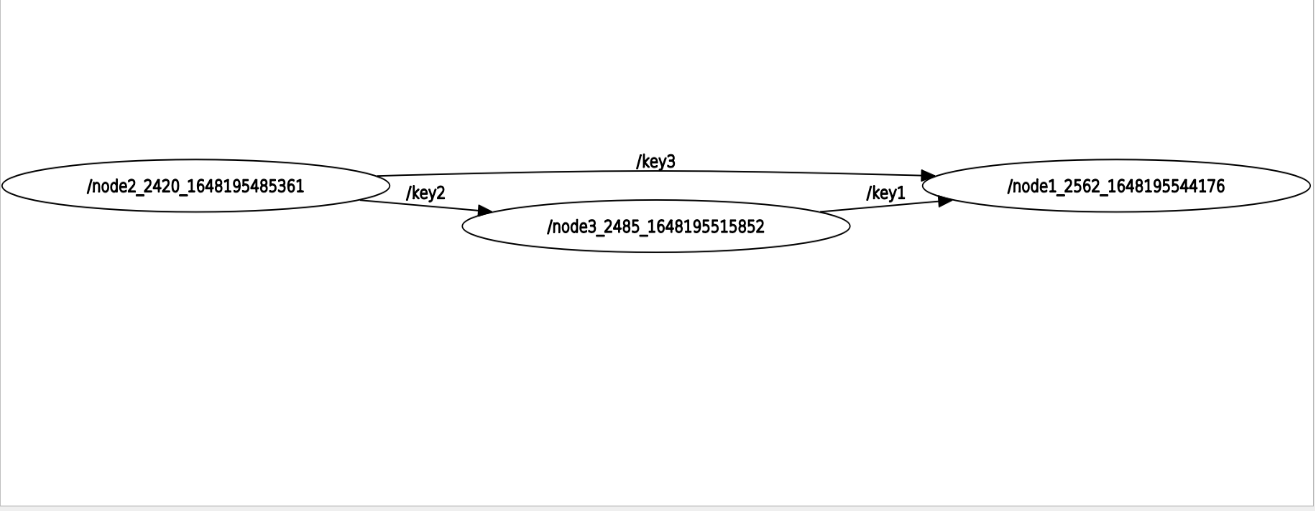
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**Output :**





1. **Create a Communication System in ROS with multiple publisher and subscriber.**



Key1-int

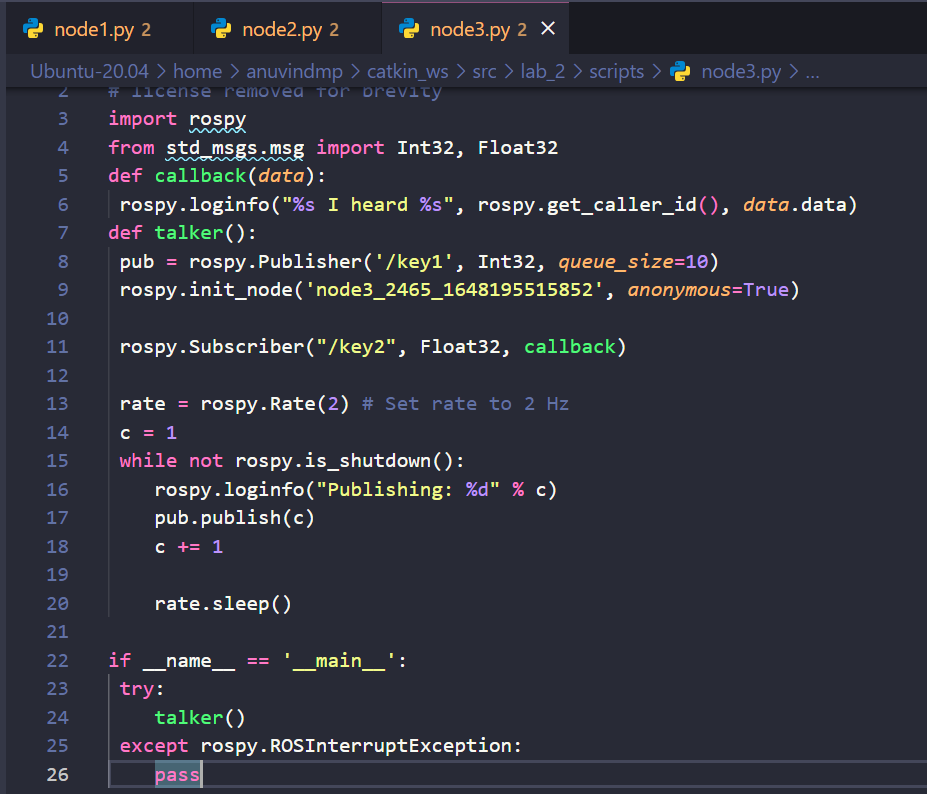
Key2-float

Key3-String

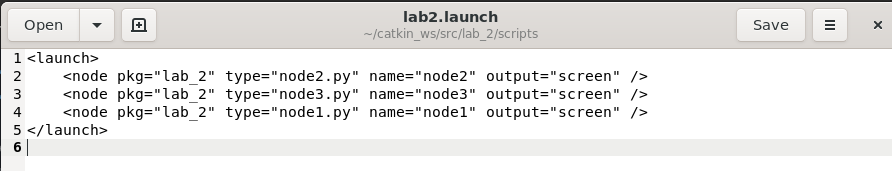
**Code :**

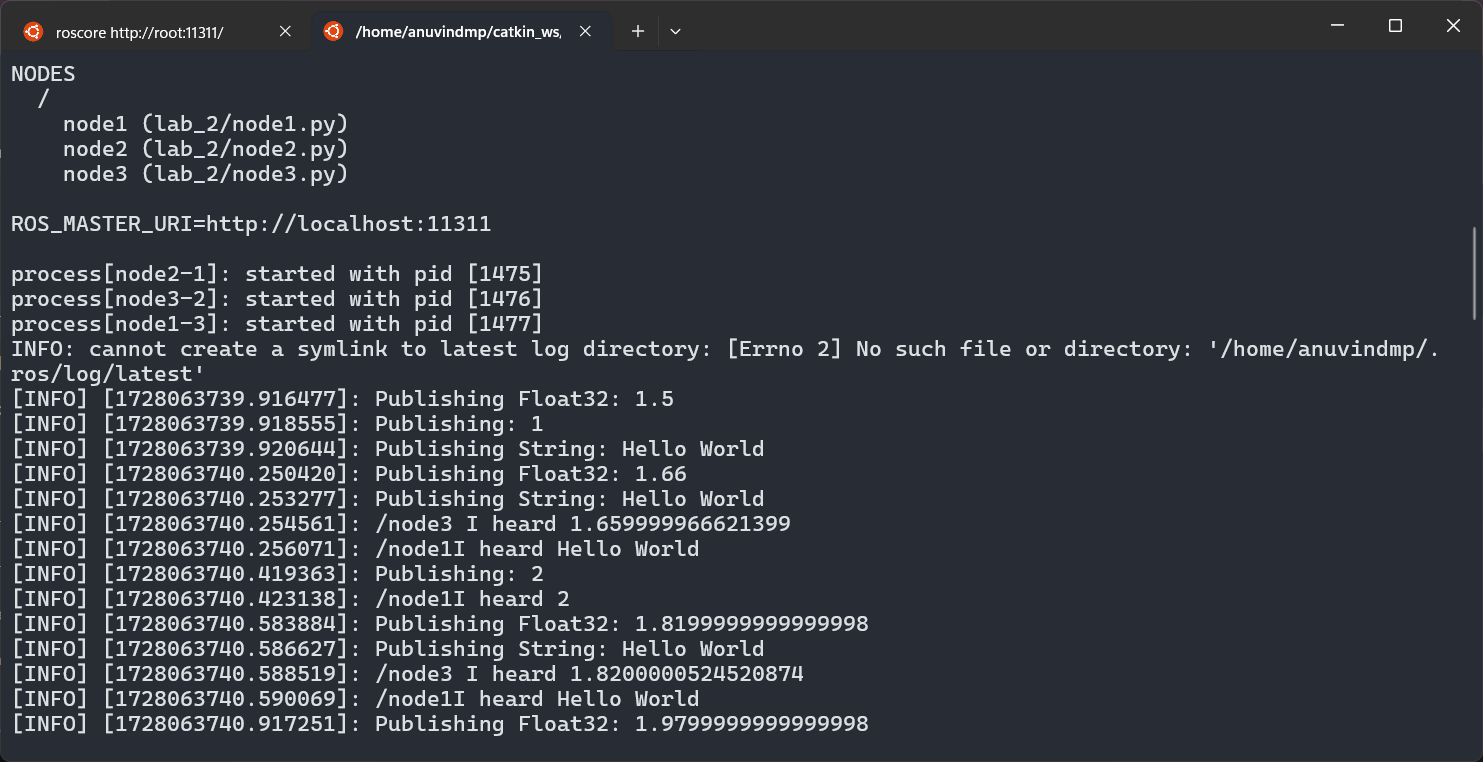






**Output :**

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