

**L** **LINE**  
L x,y  
L 20,3

**H** **HORIZONTAL LINE**  
H y  
H 90

**V** **VERTICAL LINE**  
V x  
V 90

**M** **MOVE**  
M x,y  
M 10,100

D DIRECTION

**C** **CUBIC BEZIER CURVE**  
C CP1 CP2 EP  
C 100,200 300,40 210,90

**S** **SMOOTH CUBIC BEZIER CURVE**  
S CP EP  
S 100,200 300,400

EP END POINT  
CP CONTROL POINT

**A** **ELLIPTICAL ARC**  
A S R L DEp  
A 50,50 0 11 100,100

# PATH MARK UP SYNTAX

S SIZE/RADIUS  
L ANGLE GREATER THAN 180

**Q** **QUADRIATIC BEZIER CURVE**  
Q CP EP  
Q 100,200 400,500

**T** **SMOOTH QUADRATIC BEZIER CURVE**  
T CP EP  
T 100,200 300,400

R ROTATIONAL ANGLE

**F** **FILL RULE**  
FO/I  
FO

POINT x,y

**Z** **CLOSE**  
Z  
Z