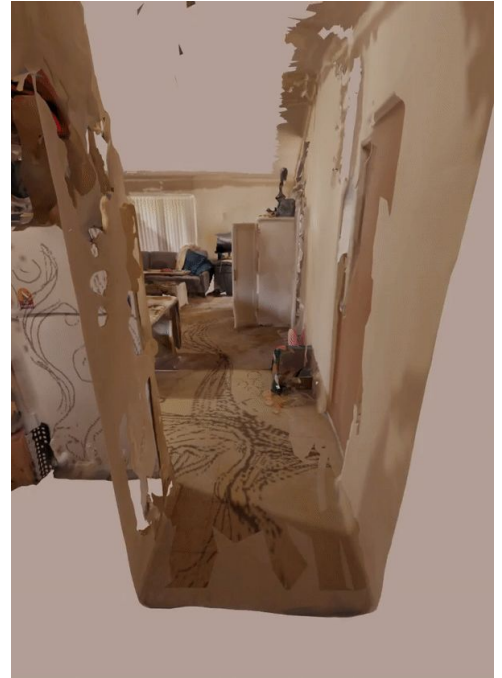
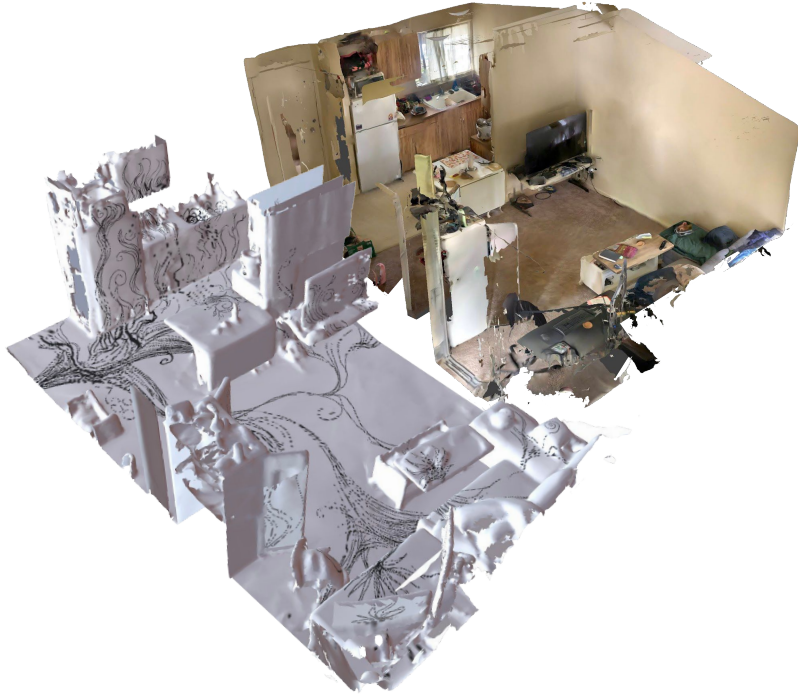


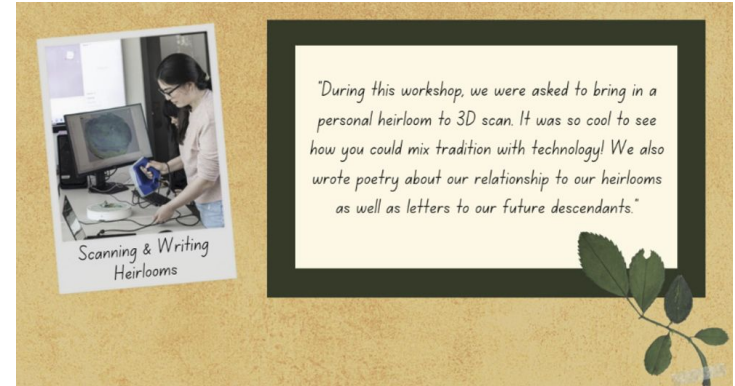
PointCloud segmentation a HCI / Media Arts perspective...

Slides: Ana M. Cárdenas

HCI for creativity support in AR



How can people easily create and edit 3D assets for immersive content?

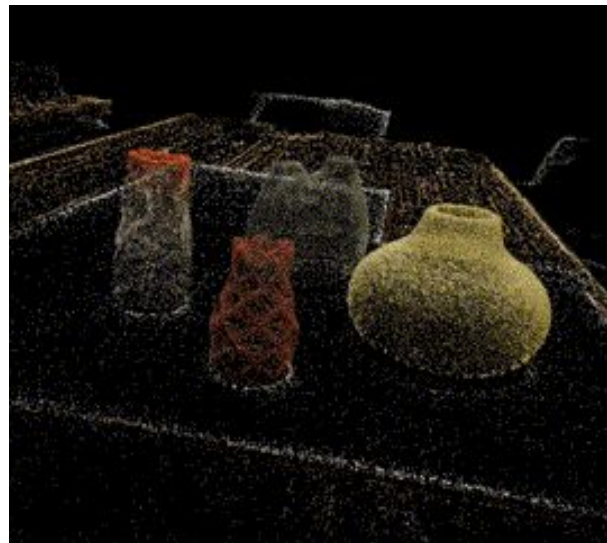
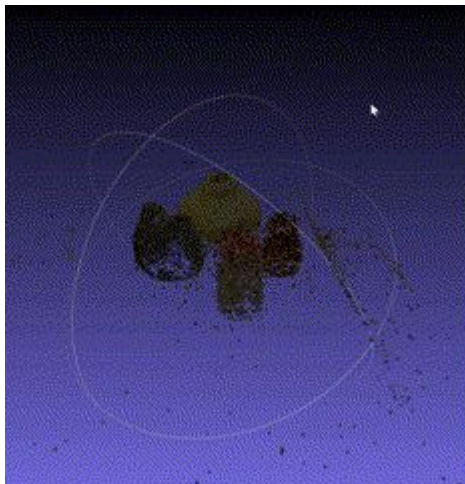


Why point clouds?

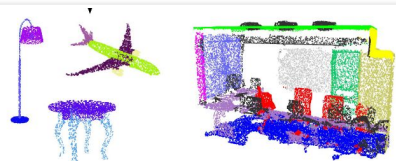
SFM (structure
from motion)
using ColMAP



Gaussian
Splatting

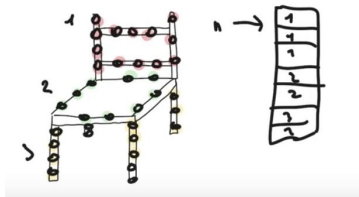


Point Cloud Segmentation



Part Segmentation

Semantic Segmentation



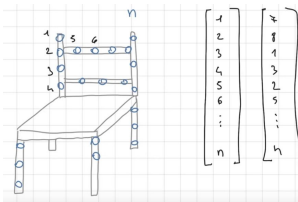
Segmentation

input: the input can be a single object for part region segmentation, or a sub-volume from a 3D scene for object region segmentation.

output: $n \times m$ scores for each of the n points and each of the m semantic sub-categories.

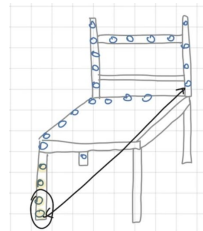
Unordered

Network should be Invariant to permutations of the input set of points



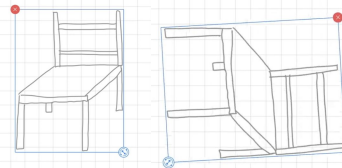
Interaction among points

Network should capture local structures from nearby points



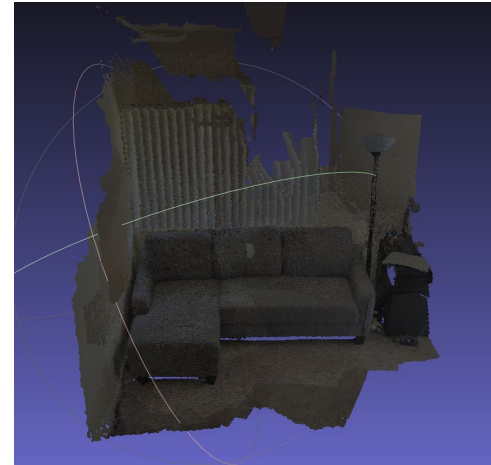
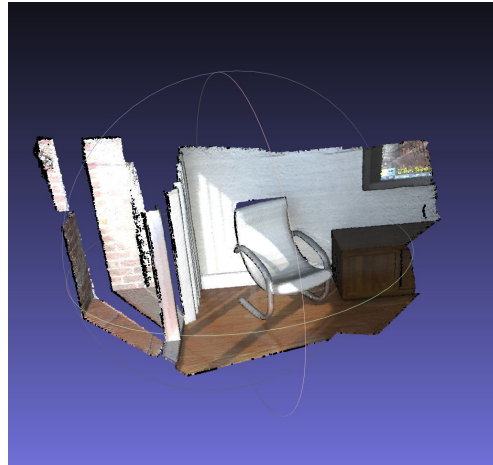
Invariance under transformations

Network should be invariant to rotating and translating set of points all together

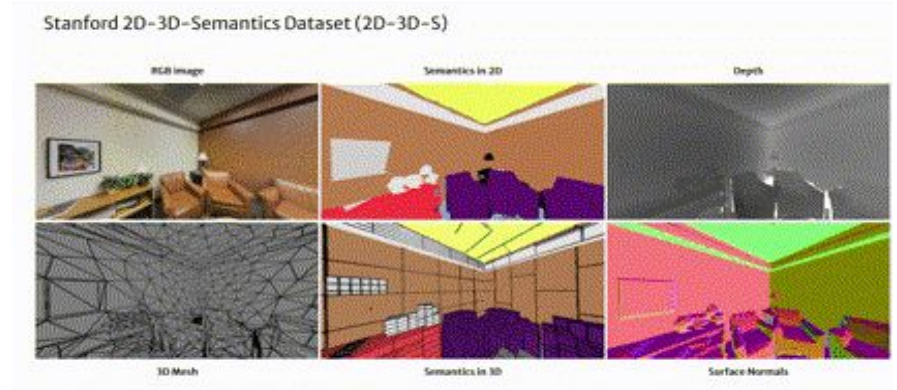
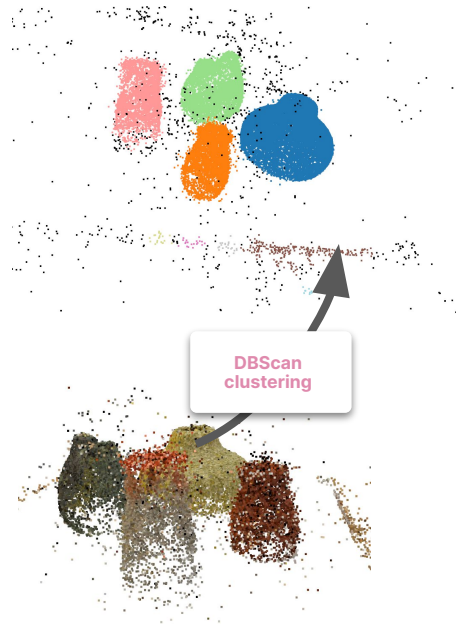


Point Cloud Segmentation could be useful to select objects from captured scenes or to create interactive 3D scenes...

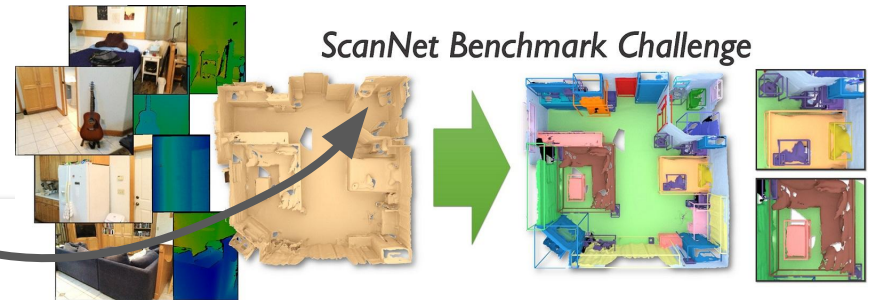
Can I use pre-trained models with my own pointclouds?



Because of current datasets, most things we can segment with existing models are labs and offices 😞 (or streets for self-driving cars)

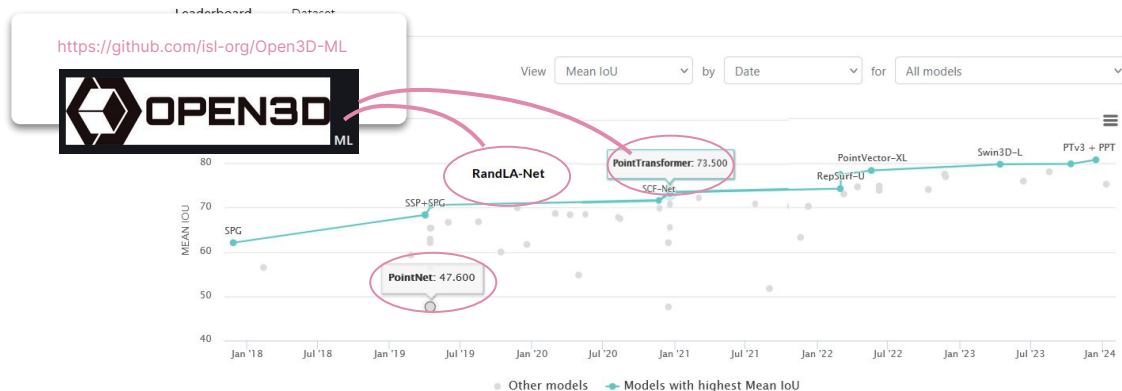


Fun Fact!
Ellings and
HFH are in
this dataset



Focus on models trained with indoors dataset... ScanNet is impossible to download so I used S3DIS

Semantic Segmentation on S3DIS



<https://github.com/Pointcept/Pointcept>



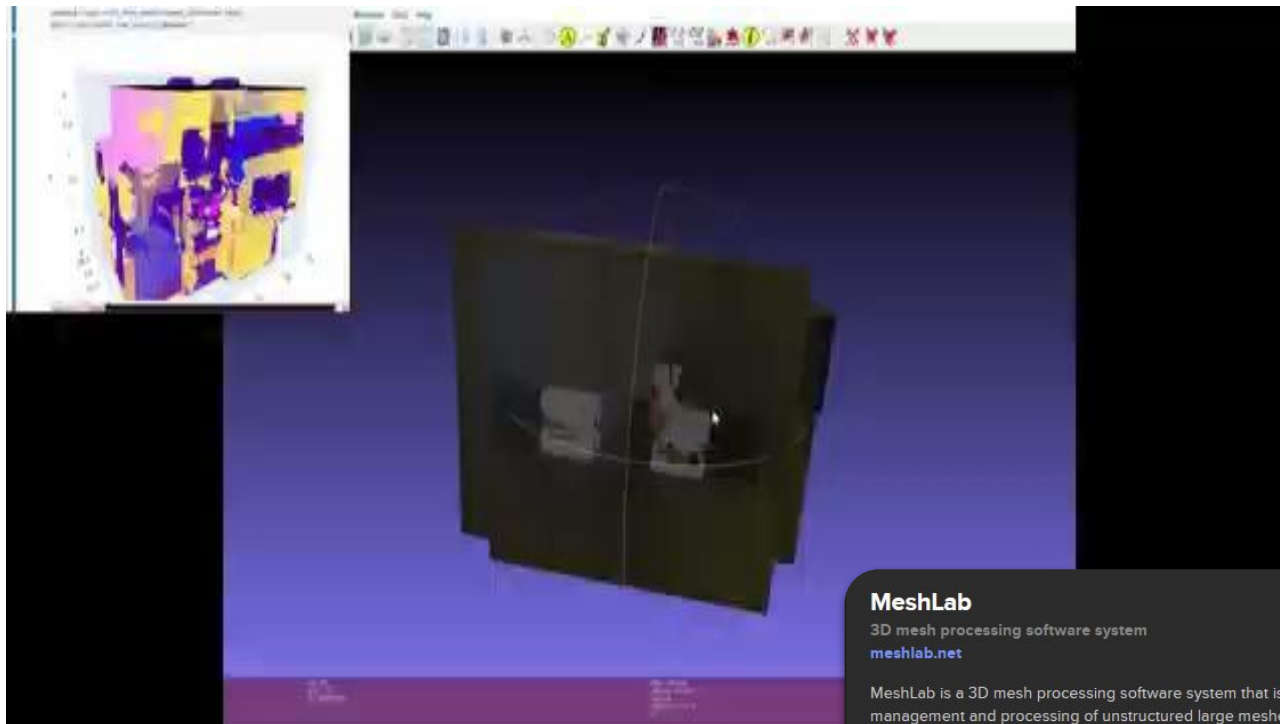
Filter: WindowNorm Transformer Multi-modal multi-view GCN untagged

Edit Leaderboard

		Mean IoU	mAcc	oAcc	FLOPs	Number of params	mIoU	Params (M)	Data
1	PTv3 + PPT	80.8	87.7	92.6		24.1M			Point Transformer V3: Simpler, Faster, Stronger
2	PonderV2 + SparseUNet	79.9	86.5	92.5					PonderV2: Pave the Way for 3D Foundation Model with A Universal Pre-training Paradigm
3	Swin3D-L	79.8	88.0	92.4		N/A			Swin3D: A Pretrained Transformer Backbone for 3D Indoor Scene Understanding

Compiling C for custom cuda components...is not for the faint hearted

Models are...not invariant under transformations



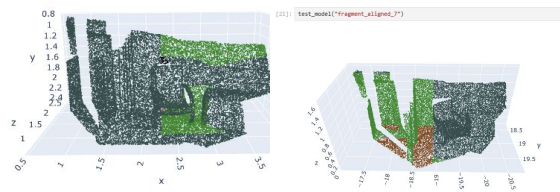
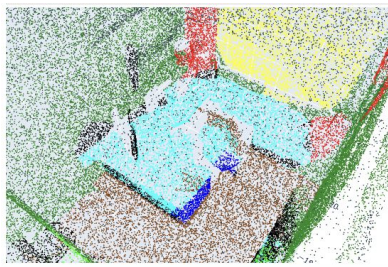
MeshLab

3D mesh processing software system
meshlab.net

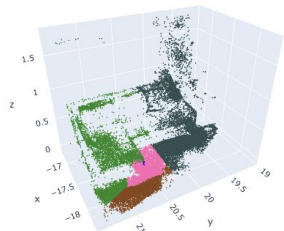
MeshLab is a 3D mesh processing software system that is oriented to the management and processing of unstructured large meshes and provides a set of tools for editing, cleaning, healing, inspecting, rendering, and converting these kinds of meshes. [Wikipedia](https://en.wikipedia.org/wiki/MeshLab)



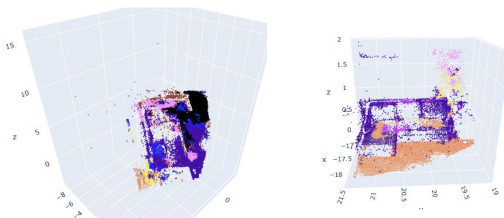
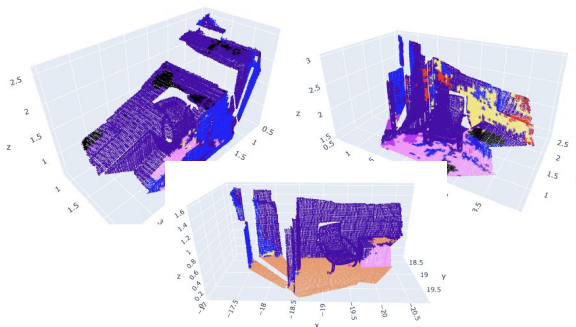
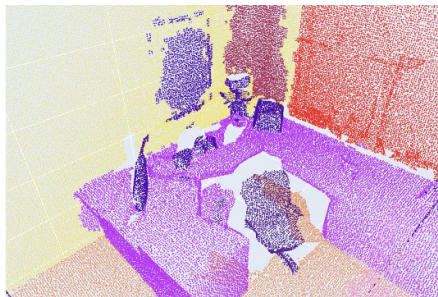
PointNet



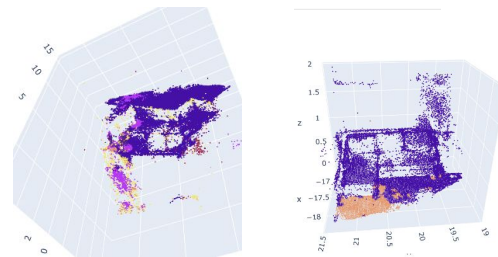
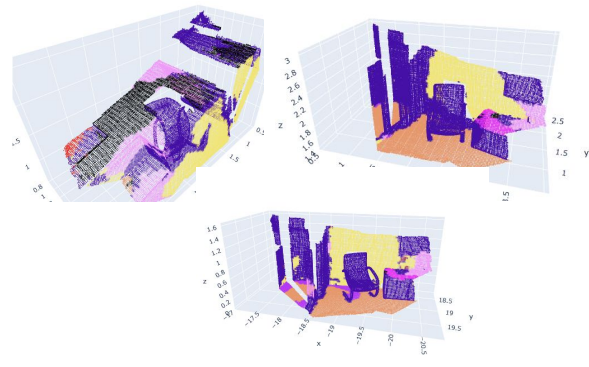
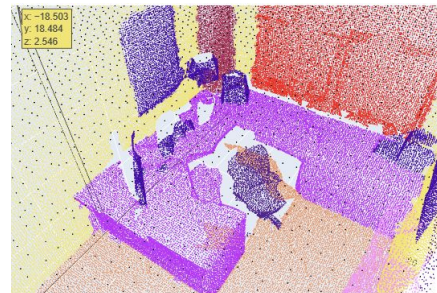
test_model("sofa_aligned")



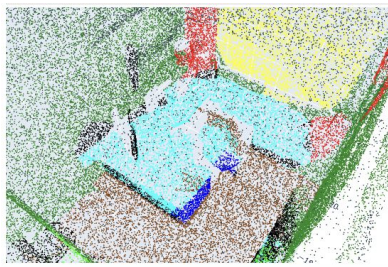
RandLANet



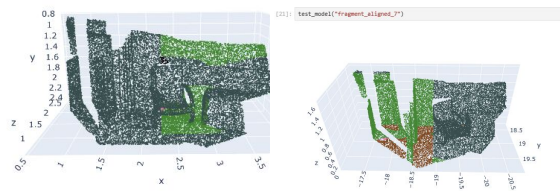
PointTransformer



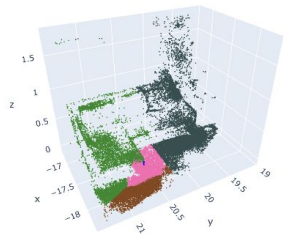
PointNet



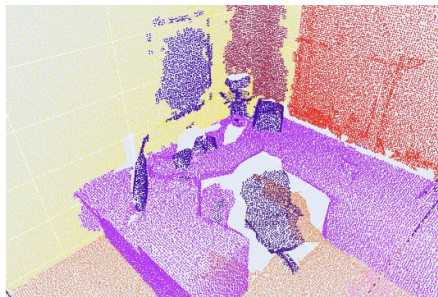
Aligned, scaled, transposed



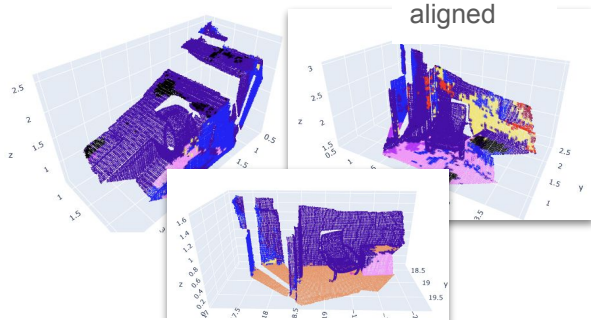
`test_model("sofa_aligned")`



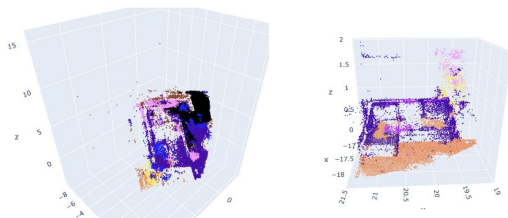
RandLANet



aligned



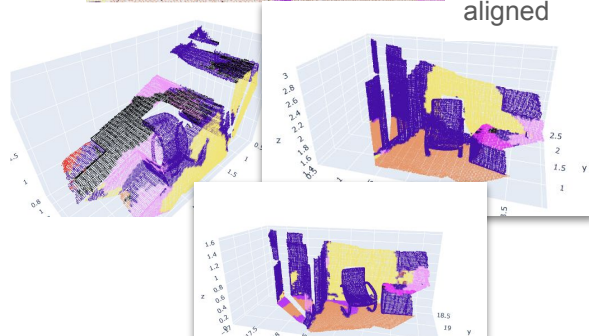
Aligned, scaled, transposed



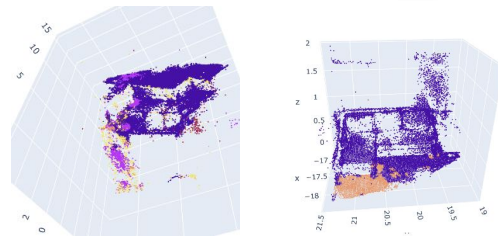
PointTransformer



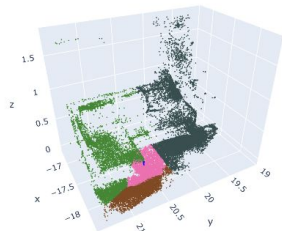
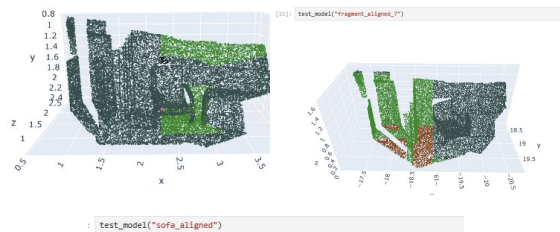
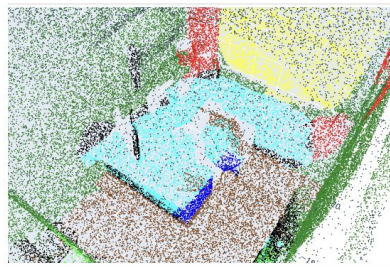
aligned



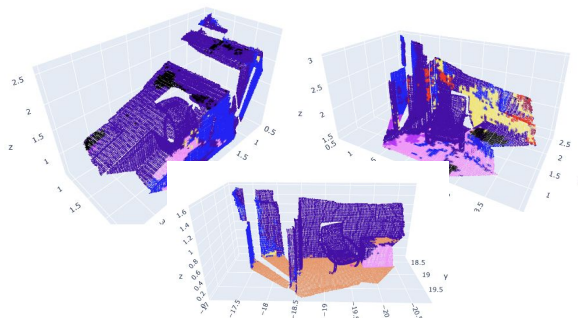
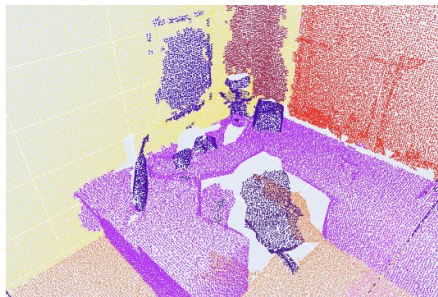
Aligned, scaled, transposed



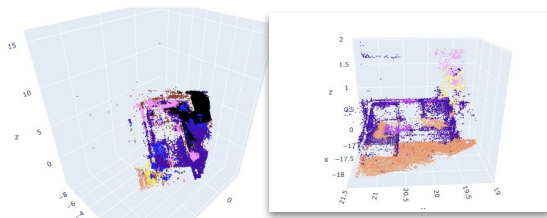
PointNet



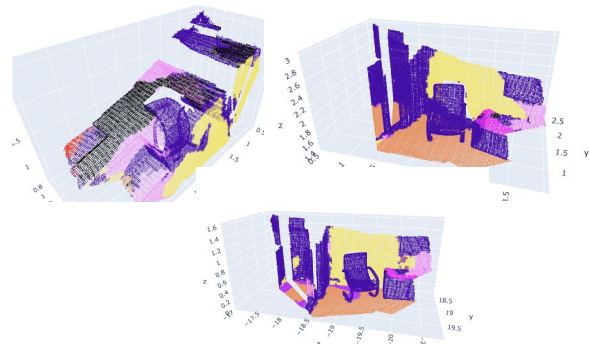
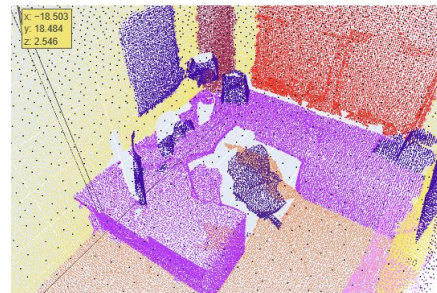
RandLANet



Aligned, scaled, transposed



PointTransformer



Aligned, scaled, transposed

