

Alberto Andrés Valdés González.

Degree: Mathematical Engineer.

Work position: ML-Engineer.

Mail: anvaldes@uc.cl/alberto.valdes.gonzalez.96@gmail.com

Location: Santiago, Chile.

Multidimensional Scaling

We have n vectors X_1, X_2, \dots, X_n of dimension r .

We want a representation of every vector by a vector of dimension t .

How will we do that?

First of all we have to define the distance matrix $\delta \in \mathbb{R}^{n \times n}$.

$$B = H \cdot \delta^{(2)} \cdot H$$

$$\delta_{i,j}^{(2)} = (\delta_{i,j})^2$$

$$H = I_n - \frac{1}{n} \cdot J_n$$

$$J_{n(i,j)} = 1$$

You can see that B is symmetric and positive definite. We can do a decomposition on its singular values.

$$B = V \cdot \Delta \cdot V^T$$

$$V \in \mathbb{R}^{n \times n}, \Delta \in \mathbb{R}^{n \times n}$$

$$V = \begin{bmatrix} | & | & \vdots & | \\ v_1 & v_2 & \vdots & v_n \\ | & | & \vdots & | \end{bmatrix} \quad \Delta = \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{bmatrix}$$

If $rg(B) = \hat{r}$ then we can define:

$$B = V_{\hat{r}} \cdot \Delta_{\hat{r}} \cdot (V_{\hat{r}})^T$$

$$V \in \mathbb{R}^{n \times \hat{r}}, \Delta \in \mathbb{R}^{\hat{r} \times \hat{r}}$$

$$V_{\hat{r}} = \begin{bmatrix} | & | & \vdots & | \\ v_1 & v_2 & \vdots & v_{\hat{r}} \\ | & | & \vdots & | \end{bmatrix} \quad \Delta_{\hat{r}} = \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_{\hat{r}} \end{bmatrix}$$

$$Y = V_{\hat{r}} \cdot \Delta_{\hat{r}}^{1/2}$$

$$Y = \begin{bmatrix} y_1^T \\ y_2^T \\ \vdots \\ y_n^T \end{bmatrix}$$

$$y_1 \in \mathbb{R}^{\hat{r}}, y_2 \in \mathbb{R}^{\hat{r}}, \dots, y_n \in \mathbb{R}^{\hat{r}}$$

We want to find \tilde{B} of range $t \leq \hat{r}$ very similar to B .

$$\boxed{tr_{rg(\tilde{B})=t} \left[(B - \tilde{B}) \cdot (B - \tilde{B})^T \right] \approx 0}$$

The solution of this problem is:

$$V_t = \begin{bmatrix} | & | & \vdots & | \\ v_1 & v_2 & \vdots & v_t \\ | & | & \vdots & | \end{bmatrix} \quad \Delta_t = \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_t \end{bmatrix}$$
