Hands on activities 5 - Interrupt and Timer

DR. B. I. MORSHED

ASSOCIATE PROFESSOR COMPUTER SCIENCE TEXAS TECH UNIVERSITY

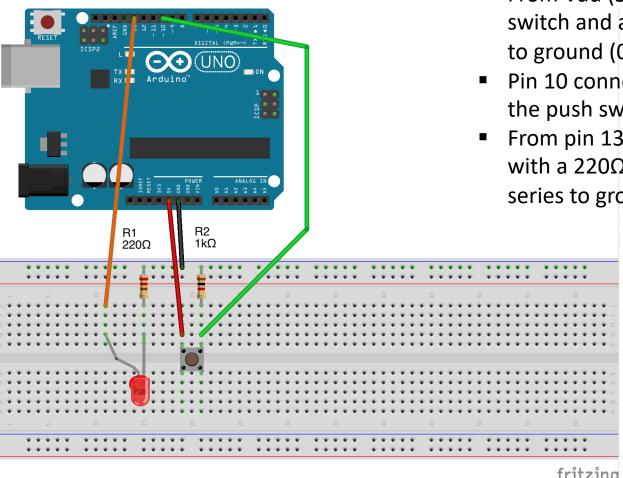
Embedded Systems/Cyber Physical Systems

CS 4380 / CS 5331

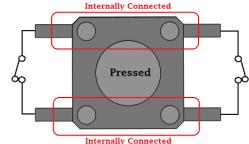
Example 1: PCINT interrupt

```
#include <avr/interrupt.h>
                                                     // ISR for pin change interrupt capture
#include <avr/sleep.h>
                                                     // Note: triggers both on rising & falling
                                                     ISR(PCINTO vect) {
                                                      // Display in serial monitor for debug
void setup() {
                                                      // Serial.println("Switch pressed");
 cli(); // Clear global interrupt
 // Set Pin 13 as output and 10 as input
                                                      // Toggle the LED
 DDRB |= B100000 ;
                                                      PORTB ^= B100000 ;
 DDRB &= B111011 :
 // Control regs for PCINT
                                                     // Main loop
 PCICR |= B00000001; // Enable PCINT0
                                                     void loop() {
 PCMSK0 |= B00000100 ; // Select PCINT0 mask
                                                      // Display in serial monitor for debug
                                                      // Serial.println("Main loop");
  // Serial.begin(9600); // Only for debug
                                                      // Do nothing!
                                                      // Put MCU to sleep
 // Use an appropriate sleep mode
 set sleep mode(SLEEP MODE PWR DOWN);
                                                      sleep mode();
sei(); // Set global Interrupt
```

Hardware setup:



- From Vdd (5 V), connect a push switch and a $1k\Omega$ resistor in series to ground (0V)
- Pin 10 connects to the midpoint of the push switch and $1k\Omega$ resistor
- From pin 13, connect an LED (red) with a 220 Ω (or 330 Ω) resistor in series to ground



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Example 2: Timer Interrupt

```
#include <avr/interrupt.h>
#include <avr/sleep.h>
void setup () {
 cli(); // Disable global interrupt - atomic
 DDRB |= B100000; // Pin 13 output
 // Set timer 1 to normal mode
 TCCR1A = B000000000;
 // Set pre-scaler to 1024
 TCCR1B = B00000101;
 // Turn ON OVF
 TIMSK1 = B00000001;
 // Initial Timer1 value for 1 sec count
 TCNT1 = 0xC2F6;
// Use an appropriate sleep mode
 set sleep mode(SLEEP MODE IDLE);
 sei(); // Enable global interrupt
```

```
// Timer1 ISR
 ISR(TIMER1 OVF vect) {
 // Toggle output pin each 1 sec
  PORTB ^= B100000;
  // Reset counter value for next
  TCNT1 = 0xC2F6;
// Main loop
void loop () {
// Do nothing
 // If including sleep mode, ensure
 // timer1 is ON while sleep
 sleep mode();
```

Hardware connection:

• Connect pin 13 to an LED in series of 220 Ω or 330 Ω resistor to ground.

Calculation:

Internal clock = 16 MHz

As the needed time is large, use maximum pre-scaler of 1024

Clock cycles needed = $16 * 10^6 / 1024 = 15,625$

Timer1 is 16-bit, so maximum value (i.e. 0xFFFF) = 65,535

So, Timer1 count value needed = 65,535 - 15,625 = 49,910