

# Anvesh Reddy Gummi

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## EDUCATION

### Carnegie Mellon University

Pittsburgh, PA

*Master of Science in Mechanical Engineering - Robotics Specialization, GPA: 4.0/4.0*

*Dec 2023*

- Relevant Coursework: Computer Vision, Visual Learning Recognition, SLAM, ML/AI, Modern Control Theory.

### BMS College Of Engineering

Bangalore, India

*Bachelor of Engineering in Mechanical Engineering, GPA: 8.84/10*

*May 2019*

- Relevant Coursework: Fundamentals of Robotics, Advanced Robotics, Controls, Mechatronics, Machine Learning.

## WORK EXPERIENCE

### Biorobotics Lab - Robotics Institute, Carnegie Mellon University

Pittsburgh, PA

*Researcher - Advised by Prof. Howie Choset*

*Sep 2022 - Dec 2022*

- Worked on collecting in transmitting Realsense - RGBD's, array of 8 Thermal cameras', and three RGB cameras' data between the robot and base station separated by 30-60ft all at real time. Used OpenCV and ROS2.
- Initiated work on providing autonomous control based on vision.

### Dassault Systemes Solutions Lab

Bangalore, India

*R&D Software Developer (C++) - Assembly Simulation Team (DELMIA)*

*July 2019 - July 2022*

- Developed and maintained Manufacturing Assembly Simulation solutions - Product Life-cycle Management.
- Implemented software features end-to-end: Planning, Development, Testing, Documentation, and Maintenance.
- Collaborated with various international cross-cultural teams for multiple application features. Provided product support for many notable customers like Mercedes Benz, Honda, etc.

## PROJECTS

### Using Diffusion Model to showcase AI-generated apparel designs on human models

Mar. 2023 - Present

- Using a pipeline of Segmentation, basic image processing, stable-diffusion (Latent space diffusion), and person image synthesis (PIDM), generated high-res images of artificially created new clothing designs on human models with multiple poses. The generation was controlled by input human model, desired texture, text prompt, and poses.

### Visual Learning and Recognition

Jan. 2023 - Present

- Implemented FCOS Object Detection:21.7% mAP on Pascal VOC; Trained GAN models on CUB2011 (FIDS: Vanilla GAN:61.2, LSGAN:65.5, W-GAN:72.5); trained AE and VAE (with  $\beta$  annealing) on CIFAR10; Performed an inference on Diffusion Models (FIDs- DDPM:31.8, DDIM:34.9); Trained Transformers to caption images on COCO captions dataset(0.03 training loss); ViT on CIFAR10 (test acc:68%, train acc:100%, training loss:0.25)

### Classical Computer Vision Projects

Sept. 2022 - Dec. 2022

- Implemented Hough Transform for Edge Detection, Bag of Visual Words for Scene Classification(60% acc on SUN image Dataset compared to VGG16 97.5%), Homography Estimation (features: Harris corners, BRIEF descriptor matching) for Augmented Reality and Stitching Images, 3D Reconstruction, LK Image Alignment, and Tracking.

### Lung cancer detection using Computer Vision

June. 2018 - May. 2019

- Trained a custom model to classify malignant cancer cells in Lung CT Scan images using Convolutional Neural Networks (CNNs) and Recurrent Neural Networks (RNNs), appended Mask-RCNN for locating malignant nodules.

### ML models to Correlate Global Climate Change with Pittsburgh's Climate

Sept. 2022 - Dec. 2022

- Performed Time Series analysis with global-scale greenhouse gases and world temperatures to forecast Pittsburgh weather, using Artificial Neural Networks, Support Vector Regression, and Random Forest to compare results.

### Super Visual-Lidar Odometry and Mapping

Mar. 2023 - Present

- For visual odometry in VLOAM, used Superpoint and Superglue deep learning models for feature extraction/matching. Compared with ORB-SLAM2, VLOAM. Requires more fine-tuning to justify GPU costs.

### Simultaneous Localization and Mapping (SLAM)

Jan. 2023 - Present

- Implemented various filtering algorithms: Bayesian Filter, Kalman Filter, Extended Kalman Filter, Unscented Kalman Filter, and Particle Filter for Localization. Used sparse-matrix methods for linear and non-linear 2D SLAM Least Square. ICP + Point-Based Fusion on RGBD data for building 3D point cloud and pose estimation.

## Additional Coursework

**Certifications:** Deep Learning Specialization (5 courses) - DeepLearning.ai, Coursera

**Programming Languages:** C++, Python, MATLAB, C, JavaScript, Bash scripting.

**Application Software:** ROS, ROS2, Gazebo, Solidworks, Ansys, 3DEXPERIENCE - CATIA, DELMIA (multiple apps)

**Tools/Libraries:** PyTorch, Keras, OpenCV, SQL, MS Office, LaTeX, GitHub, HTML, CSS.

## AWARDS

**Evangelist Award** | Dassault Systemes

**Best Project In Mechanical Engineering Dept** | BMS College Of Engineering

Jun. 2020

May. 2019