

$$(1) \quad ds^2 = \sum_{i=1}^3 \sum_{j=1}^3 g_{ij} du_i du_j = \sum_{i=1}^3 (h_i du_i)^2$$

where: g_{ij} = metric = diagonal matrix

$$= \begin{pmatrix} h_1 & 0 & 0 \\ 0 & h_2 & 0 \\ 0 & 0 & h_3 \end{pmatrix}_{3 \times 3}$$

$$\Rightarrow \text{For } i=j \Rightarrow g_{ii} = h_i^2 > 0$$

compare the above eqⁿ.

$$\Rightarrow \text{For } i \neq j \Rightarrow g_{ij} = 0$$

$$(2) \quad \{A_i(u_i)\} \xrightarrow{u \rightarrow \bar{u}} (\bar{A}_i(\bar{u}_i))$$

\Rightarrow where $A_i(u)$ means $A_i(u_1, u_2, u_3)$ means A_i as a function of u_1, u_2, u_3 .

where A_1, A_2, A_3 are components of a vector in curvilinear coordinates.

Remember this transformation is "homogenous".

It means that any component in \bar{u} system will depend on all component, in u system, of a vector \bar{A} .

$$\bar{A}_i(\bar{u}) = \sum_{j=1}^3 \frac{\partial \bar{u}_i}{\partial u_j} A_j(u_1, u_2, u_3)$$

$$(3) \quad \nabla = \frac{\hat{a}_1}{h_1} \frac{\partial}{\partial u_1} + \frac{\hat{a}_2}{h_2} \frac{\partial}{\partial u_2} + \frac{\hat{a}_3}{h_3} \frac{\partial}{\partial u_3} = \sum_{i=1}^3 \frac{\hat{a}_i}{h_i} \frac{\partial}{\partial u_i}$$

$$\Rightarrow \nabla = \sum_{i=1}^3 \frac{\hat{a}_i}{h_i} \frac{\partial}{\partial u_i} = \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z}$$

(curvilinear) (cartesian).

$$(a) \quad \vec{\nabla} \phi = \sum_{i=1}^3 \hat{e}_i \frac{1}{h_i} \frac{\partial \phi}{\partial x_i} = \text{grad } \phi = \text{gradient of } \phi.$$

where $\phi = \text{scalar, invariant.}$

$$(b) \quad \vec{\nabla} \cdot \vec{A} = \text{Divergence of } \vec{A} = \text{div } \vec{A}$$

$$= \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial x_1} (A_1 h_2 h_3) + \frac{\partial}{\partial x_2} (A_2 h_1 h_3) + \frac{\partial}{\partial x_3} (A_3 h_1 h_2) \right].$$

\Rightarrow If $\vec{A} = \vec{\nabla} \phi = \text{grad } \phi = \text{gradient of } \phi :-$

$$\Rightarrow \vec{\nabla} \cdot \vec{A} = \vec{\nabla} \cdot \vec{\nabla} \phi = \underbrace{\vec{\nabla}^2}_{\text{Laplacian operator}} \phi = \text{Laplacian on scalar field.}$$

$\#$ So: we are doing

$$\left(\hat{e}_i \rightarrow \frac{1}{h_i} \frac{\partial \phi}{\partial x_i} \right)$$

$$= \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial x_1} \left(\frac{h_2 h_3}{h_1} \frac{\partial \phi}{\partial x_1} \right) + \frac{\partial}{\partial x_2} \left(\frac{h_3 h_1}{h_2} \frac{\partial \phi}{\partial x_2} \right) + \frac{\partial}{\partial x_3} \left(\frac{h_1 h_2}{h_3} \frac{\partial \phi}{\partial x_3} \right) \right]$$

Ans

$$(c) \quad \vec{\nabla} \times \vec{A} = \vec{\nabla} \times \vec{A} = \text{curl of } \vec{A}$$

$$= \frac{1}{h_1 h_2 h_3} \begin{vmatrix} h_1 \hat{e}_1 & h_2 \hat{e}_2 & h_3 \hat{e}_3 \\ \frac{\partial}{\partial x_1} & \frac{\partial}{\partial x_2} & \frac{\partial}{\partial x_3} \\ h_1 A_1 & h_2 A_2 & h_3 A_3 \end{vmatrix}$$

Ans